

Machine Learning I: Supervised Methods

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Announcements

- No Slido poll questions today
- Homework 7 is due Friday
- Homework 8 will be posted early next week
- Project report template and instructions will be posted soon

Reading

- Bishop 2.5 (density estimation)

Today's lecture

- Statistical classification and Bayes Decision Theory

- Minimum-error classifiers and P_e ($C=2$)
- Minimum-error classifiers and P_e ($C>2$)
- Summary
- Minimum-risk criterion
- Mahalanobis distance
- Classifiers: Gaussian density case
 - Linear Bayes (LDA)
 - Quadratic Bayes (QDA)
- Density estimation techniques for machine learning (time permitting)
 - Preliminaries

$$(1) \quad P_e = P(S_1) \int_{\Gamma_1} p(\underline{x}|S_1) d\underline{x} + P(S_2) \int_{\Gamma_2} p(\underline{x}|S_2) d\underline{x} \quad p-2$$

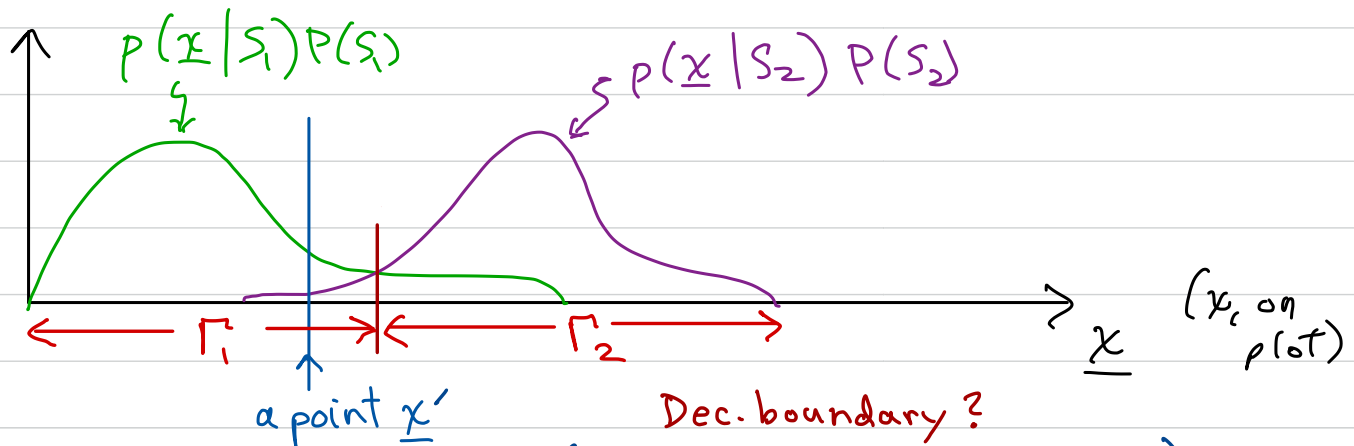
→ P_e is our criterion fcn.

Goal: find Γ_1 and Γ_2 that minimize P_e .

Requirements: Γ_1 and Γ_2 must be non-overlapping.

$\Gamma_1 \cup \Gamma_2$ covers all of feature space.

(except possibly boundaries that have area (or volume) = 0)



⇒ assign to Γ_1 (for min. contribution to P_e).

In P_e , each pt. \underline{x} must be included in 1 of the 2 terms; pick the smaller term.

⇒ minimizes P_e .

∴ Assign \underline{x} to Γ_1 if $p(\underline{x}|S_2)P(S_2) < p(\underline{x}|S_1)P(S_1)$

Assign \underline{x} to Γ_2 if $p(\underline{x}|S_2)P(S_2) > p(\underline{x}|S_1)P(S_1)$

or

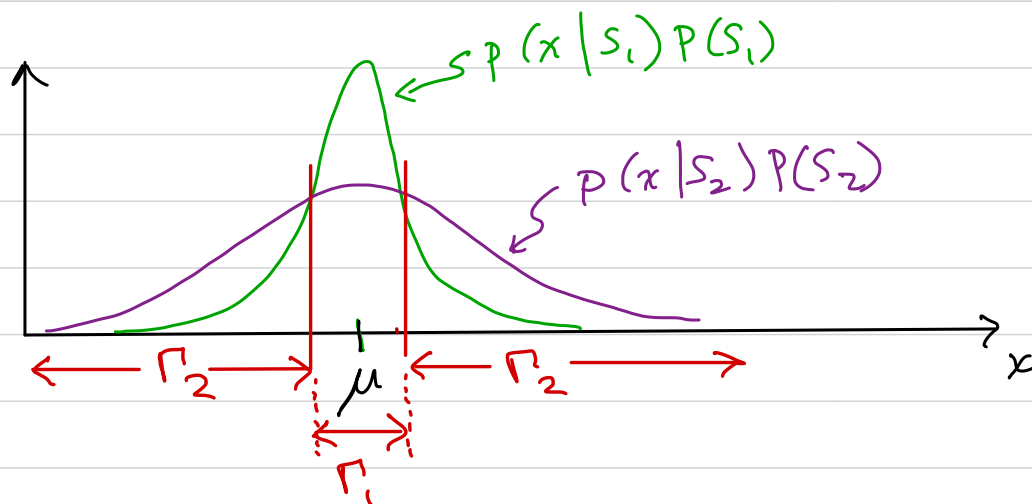
(2)

$$p(\underline{x}|S_1)P(S_1) \underset{\Gamma_2}{\overset{\Gamma_1}{>}} p(\underline{x}|S_2)P(S_2)$$

Bayes decision rule for min. error ($c=2$)

or $\ln [\cdot] \underset{\Gamma_2}{\overset{\Gamma_1}{>}} \ln [\cdot]$

Example: suppose $\mu_1 = \mu_2 = \mu$, $\sigma_1 < \sigma_2$: (Normal densities $p(x|S_i)$)

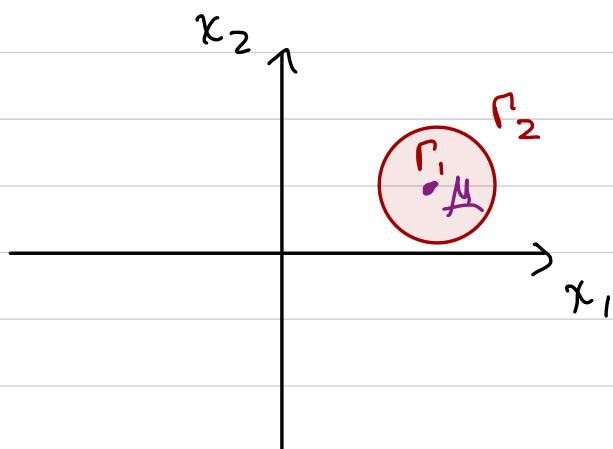


> Decision boundaries and regions? ↗

> | Is this classifier linear? → No.

2D version: $p(\underline{x}|S_i) = N(\underline{x} | \underline{\mu}, \sigma_i^2 \underline{I})$
 $P(S_1) = P(S_2)$

$$\sigma_1^2 < \sigma_2^2$$



Use Bayes theorem:

$$P(S_k | \underline{x}) P(\underline{x}) = p(\underline{x} | S_k) P(S_k)$$

$$p(\underline{x}) = \sum_{i=1}^C p(\underline{x} | S_i) P(S_i)$$

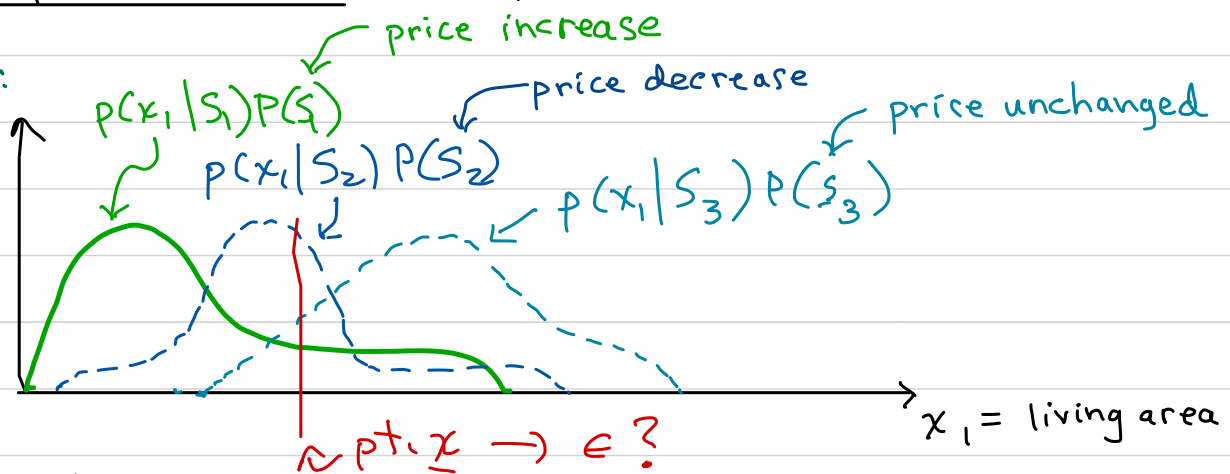
$$\Rightarrow P(S_1 | \underline{x}) \cancel{P(\underline{x})} \stackrel{\Gamma_1}{>} \stackrel{\Gamma_2}{<} P(S_2 | \underline{x}) \cancel{P(\underline{x})}$$

$$(3) \quad P(S_1 | \underline{x}) \stackrel{\Gamma_1}{>} \stackrel{\Gamma_2}{<} P(S_2 | \underline{x})$$

↗ Bayes min. error dec. rule, in terms of posterior probabilities.

Bayes min error ($C > 2$)

Ex: $C=3$:



$$P_e = 1 - P_{\text{correct}}$$

$$P_{\text{correct}} = \sum_{i=1}^C P(S_i) \int_{\Gamma_i} p(\underline{x} | S_i) d\underline{x}$$

$$P_e = 1 - P_{\text{correct}} = 1 - \left\{ P(S_1) \int_{\Gamma_1} p(\underline{x} | S_1) d\underline{x} + P(S_2) \int_{\Gamma_2} p(\underline{x} | S_2) d\underline{x} + P(S_3) \int_{\Gamma_3} p(\underline{x} | S_3) d\underline{x} \right\}$$

$$\Rightarrow \begin{array}{c} g_k(\underline{x}) \\ \downarrow \end{array} \quad \begin{array}{c} g_j(\underline{x}) \\ \downarrow \end{array} \quad \boxed{\begin{array}{l} p(\underline{x} | S_k) P(S_k) > p(\underline{x} | S_j) P(S_j) \quad \forall j \neq k \\ \Rightarrow \underline{x} \in \Gamma_k \end{array}}$$

↙ Bayes min. error decision rule, $C > 2$.

Is this OvR, OvO, MVM, or something different?

This is a maximal value method.

Can define:

$$\begin{array}{l} \text{or} \\ \text{could choose } g_i(\underline{x}) = \ln[p(\underline{x} | S_i) P(S_i)] \\ = \ln p(\underline{x} | S_i) + \ln P(S_i) \end{array}$$

SUMMARY OF BAYES DECISION THEORY SO FAR

1. Bayes minimum error classifier

Decision rule:

$$p(\underline{x}|S_i)P(S_i) > p(\underline{x}|S_j)P(S_j) \quad \forall j \neq i \Rightarrow \underline{x} \in \Gamma_i$$

2-class case:

$$p(\underline{x}|S_1)P(S_1) \underset{\Gamma_2}{\overset{\Gamma_1}{>}} p(\underline{x}|S_2)P(S_2)$$

2. Probability of error

$$P_e = 1 - P_{\text{correct}} = 1 - \sum_{i=1}^C \int_{\Gamma_i} p(\underline{x}|S_i)P(S_i) d\underline{x}$$

2-class case:

$$P_e = \int_{\Gamma_2} p(\underline{x}|S_1)P(S_1) d\underline{x} + \int_{\Gamma_1} p(\underline{x}|S_2)P(S_2) d\underline{x}$$

3. Note: for discrete-valued features x_k ,

$$\int dx_k \text{ becomes } \sum_{x_k}$$

and same decision rules apply.

Minimum Risk Criterion [Bishop 1.5.2]

For cases in which minimizing P_e is not optimal; e.g. misclassifying S_1 datap. as S_2 is significantly more costly than vice versa.

Ex: medical test that screens for cancer. $S_1 = \text{positive} \Rightarrow \text{cancer}$
 False negative is worse than false positive. $S_2 = \text{negative} \Rightarrow \text{no cancer}$
 \hookrightarrow (miss the cancer)

\rightarrow Allow different costs for different kinds of error.

Let L_{ji} = loss of assigning \underline{x} to Γ_i when it actually belongs to S_j .

Total expected loss is then:
$$E\{L\} = \underbrace{\sum_{j=1}^C}_{\text{average over all classes}} \underbrace{\sum_{i=1}^C \left[\int_{\Gamma_i} L_{ji} p(S_j | \underline{x}) d\underline{x} \right]}_{\text{Expected loss of assigning } \underline{x} \text{ to } \Gamma_i}$$

\Rightarrow Instead of $p(S_i | \underline{x}) > p(S_k | \underline{x}) \quad \forall k \neq i \Rightarrow \underline{x} \in \Gamma_i$
 we have:

Decision rule
$$\sum_{j=1}^C L_{ji} p(S_j | \underline{x}) < \sum_{j=1}^C L_{jk} p(S_j | \underline{x}) \quad \forall k \neq i \Rightarrow \underline{x} \in \Gamma_i$$

$R(\alpha_i | \underline{x}) \triangleq$ conditional risk of taking action α_i ($\underline{x} \in \Gamma_i$)
 given $\underline{x} \in S_j$.

$$\underline{L} = \begin{bmatrix} L_{11} & L_{12} & & \\ L_{21} & L_{22} & & \\ & & \ddots & \\ & & & L_{cc} \end{bmatrix}, \quad \text{typically } L_{ii} = 0 \quad \forall i.$$

MAHALANOBIS DISTANCE [Bishop 2.3.0]

$$d_m^2(\underline{x}, \underline{m}) = (\underline{x} - \underline{m})^T \underline{\Sigma}^{-1} (\underline{x} - \underline{m})$$

$$\underline{\Sigma} = \begin{bmatrix} \sigma_{11} & \sigma_{12} & \dots \\ \sigma_{21} & \ddots & \\ \vdots & & \sigma_{DD} \end{bmatrix}$$

CASE 1 :

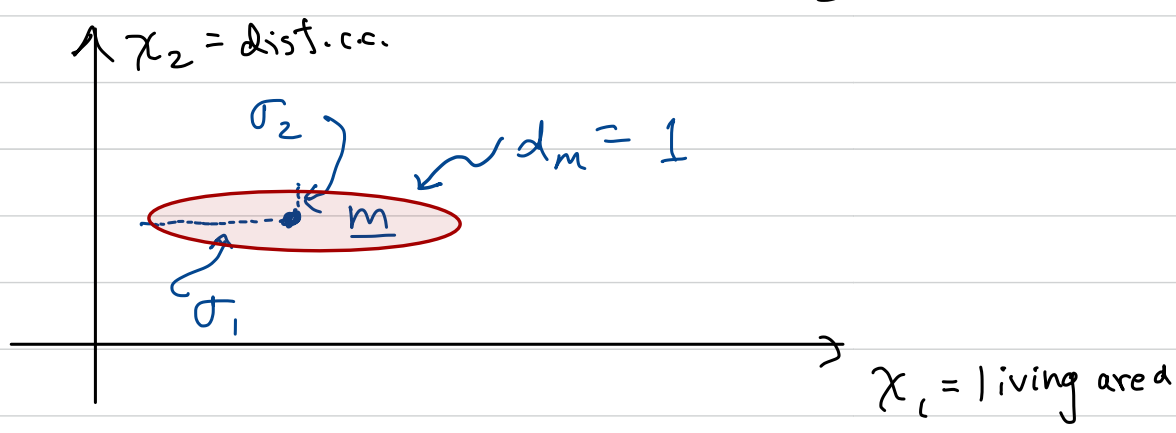
$$\underline{\Sigma} = \begin{bmatrix} \sigma_1^2 & & & 0 \\ & \sigma_2^2 & & \\ & & \ddots & \\ 0 & & & \sigma_D^2 \end{bmatrix}$$

$$\underline{\Sigma}^{-1} = \begin{bmatrix} \frac{1}{\sigma_1^2} & & & 0 \\ & \frac{1}{\sigma_2^2} & & \\ & & \ddots & \\ 0 & & & \frac{1}{\sigma_D^2} \end{bmatrix}$$

$$d_m^2(\underline{x}, \underline{m}) = \sum_{i=1}^D \frac{1}{\sigma_i^2} (\underline{x}_i - m_i)^2$$

$$d_m^2(\underline{x}, \underline{m}) = \text{const.} \Rightarrow ?$$

2-space: $d_m^2 = \frac{(\chi_1 - m_1)^2}{\sigma_1^2} + \frac{(\chi_2 - m_2)^2}{\sigma_2^2} = \text{const.}$



- Ellipse (2D)
- Hyperellipsoid (D dim.)

CASE 2:

Σ = general

$$= \begin{bmatrix} \sigma_{11} & \sigma_{12} & \dots \\ \sigma_{21} & & \\ \vdots & & \\ & & \sigma_{DD} \end{bmatrix}$$

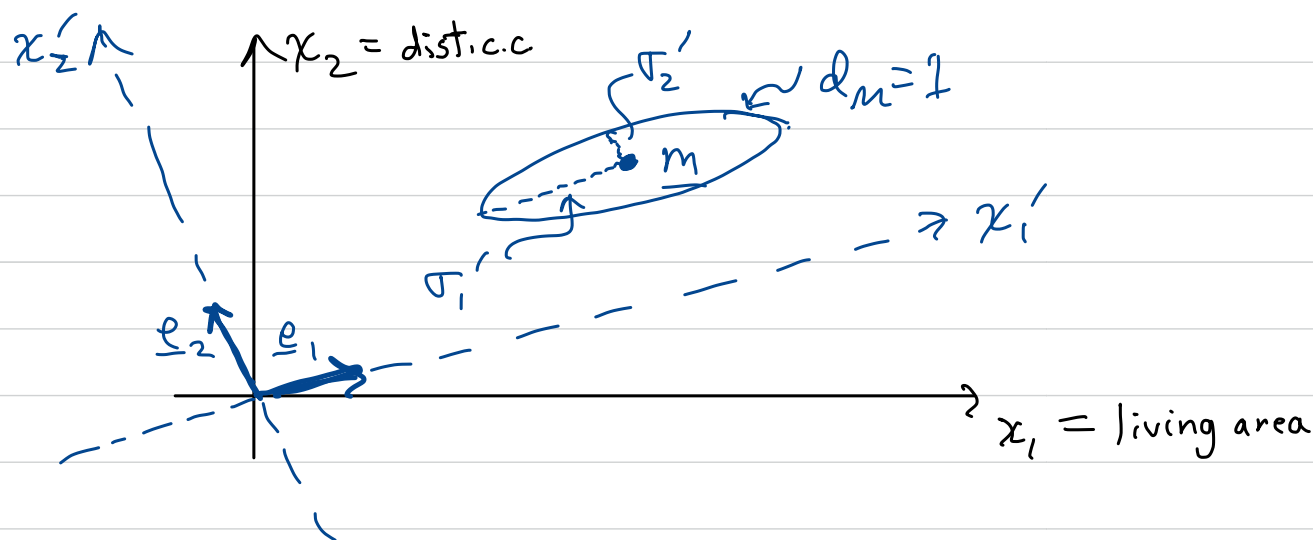
$$d_m^2(\underline{x}, \underline{m}) = (\underline{x} - \underline{m})^T \underline{\Sigma}^{-1} (\underline{x} - \underline{m})$$

Apply orthonormal transformation (rotate basis):

$$\underline{x}' = \underline{E}^T \underline{x}$$

$$\underline{\Sigma}' = \underline{E}^T \underline{\Sigma} \underline{E} = \underline{\Lambda} = \text{diagonal} \rightarrow \text{CASE 1.}$$

$\Rightarrow d_m^2 = \text{const.} \Rightarrow$ hyperellipsoids (axes rotated)



BAYES MIN. ERROR CLASSIFIERS — GAUSSIAN DENSITY CASE

[Bishop 2.3.3 — optional reading]

$$p(\underline{x} | S_k) = N(\underline{x} | \underline{m}_k, \underline{\Sigma}_k)$$

$$= \frac{1}{(2\pi)^{D/2} |\underline{\Sigma}_k|^{1/2}} \exp \left\{ -\frac{1}{2} \left[(\underline{x} - \underline{m}_k)^T \underline{\Sigma}_k^{-1} (\underline{x} - \underline{m}_k) \right] \right\}$$

$$\text{Maximize}_i p(\underline{x} | S_i) P(S_i)$$

$$g_i(\underline{x}) = \ln \{ p(\underline{x} | S_i) P(S_i) \} = \ln p(\underline{x} | S_i) + \ln P(S_i)$$

$$(1) \quad g_i(\underline{x}) = -\frac{1}{2} \ln |\underline{\Sigma}_i| - \frac{1}{2} (\underline{x} - \underline{m}_i)^T \underline{\Sigma}_i^{-1} (\underline{x} - \underline{m}_i) + \ln P(S_i)$$

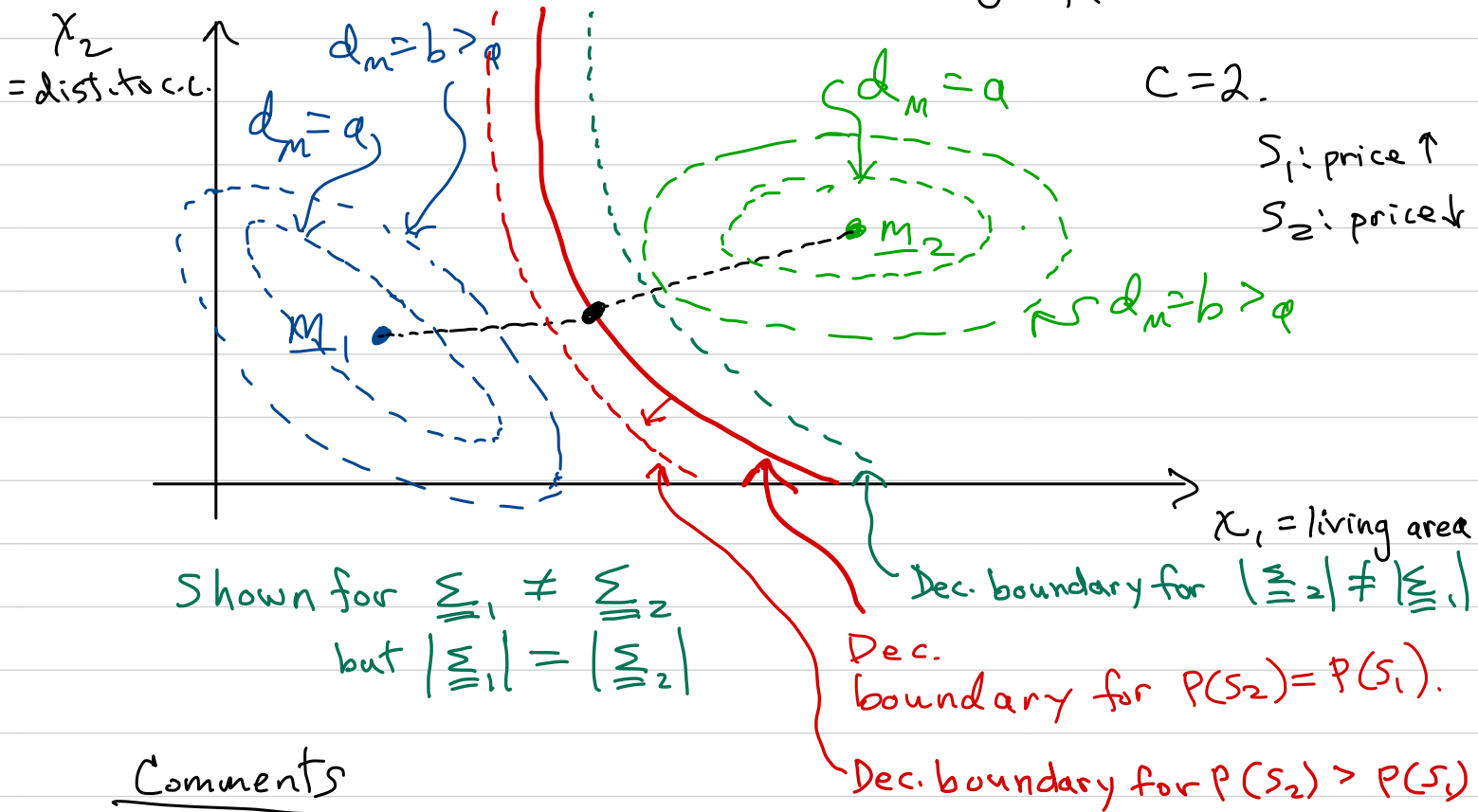
$$\text{Let: } |\underline{\Sigma}_1| = |\underline{\Sigma}_2| = \dots$$

$$\text{and: } P(S_1) = P(S_2) = \dots$$

Then;

$$g_i(\underline{x}) = -(\underline{x} - \underline{m}_i)^T \underline{\Sigma}_i^{-1} (\underline{x} - \underline{m}_i) = -d_m^2(\underline{x}, \underline{m}_i)$$

\Rightarrow Nearest-means classifier using d_m instead of d_E .



1. Include: $P(S_i) \neq P(S_j)$

\Rightarrow Boundary shifts

e.g.: $P(S_2) > P(S_1)$ (see plot)

2. Include: $|\underline{\Sigma}_i| \neq |\underline{\Sigma}_j|$

\Rightarrow incorporates differences in ellipsoid volumes from class to class.

CASE A $\underline{\underline{\Sigma}}_i = \underline{\underline{\Sigma}}$

$$g_i(\underline{x}) = -\frac{1}{2}(\underline{x} - \underline{m}_i)^T \underline{\underline{\Sigma}}^{-1}(\underline{x} - \underline{m}_i) + \ln P(S_i)$$

$$= -\frac{1}{2} \left[\underline{x}^T \underline{\underline{\Sigma}}^{-1} \underline{x} - 2 \underline{m}_i^T \underline{\underline{\Sigma}}^{-1} \underline{x} + \underline{m}_i^T \underline{\underline{\Sigma}}^{-1} \underline{m}_i \right] + \ln P(S_i)$$

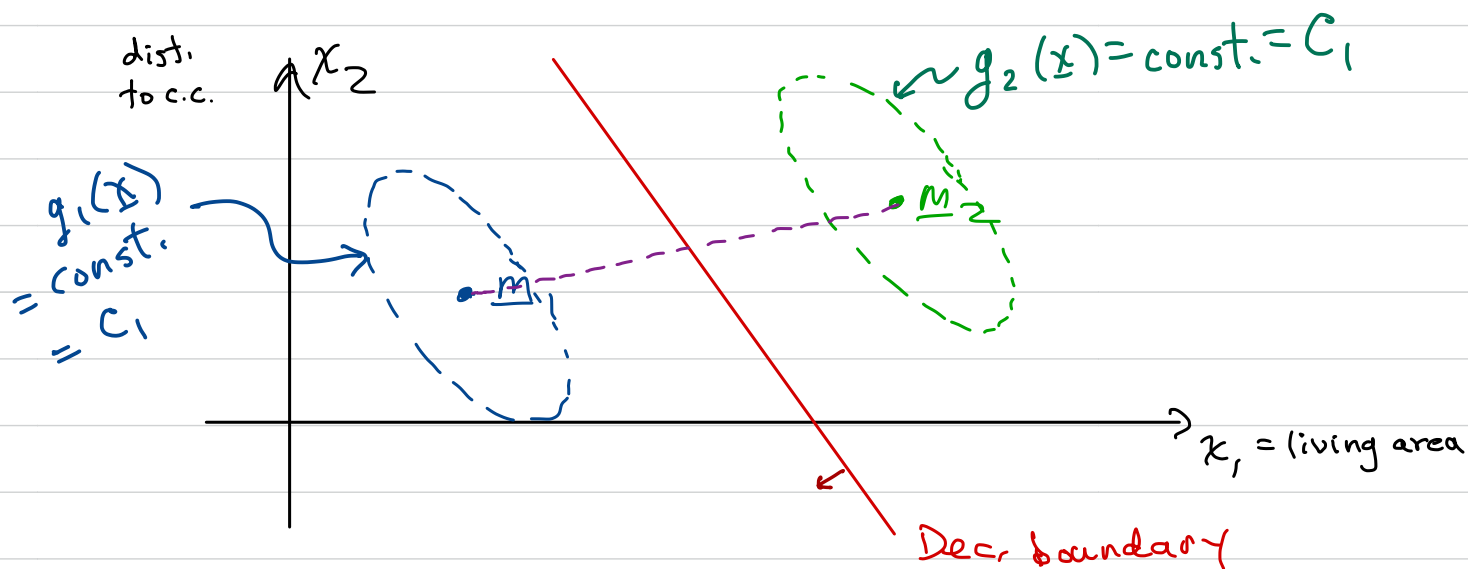
Let $g_i(\underline{x}) = \underline{m}_i^T \underline{\underline{\Sigma}}^{-1} \underline{x} - \frac{1}{2} \underline{m}_i^T \underline{\underline{\Sigma}}^{-1} \underline{m}_i + \ln P(S_i)$

$$= \underline{w}^T \underline{x} + w_0$$

is this classifier linear? \rightarrow Yes!

\Rightarrow Classifier is linear.

Often called Linear Bayes.



Also called: LDA: linear discriminant analysis.
(if parameters are estimated from the data)

Case B: $\Sigma_i = \text{arbitrary}$

$$g_i(\underline{x}) = -\frac{1}{2} \ln |\Sigma_i| - \frac{1}{2} d_m^2(\underline{x}, \underline{m}_i) + \ln P(S_i)$$

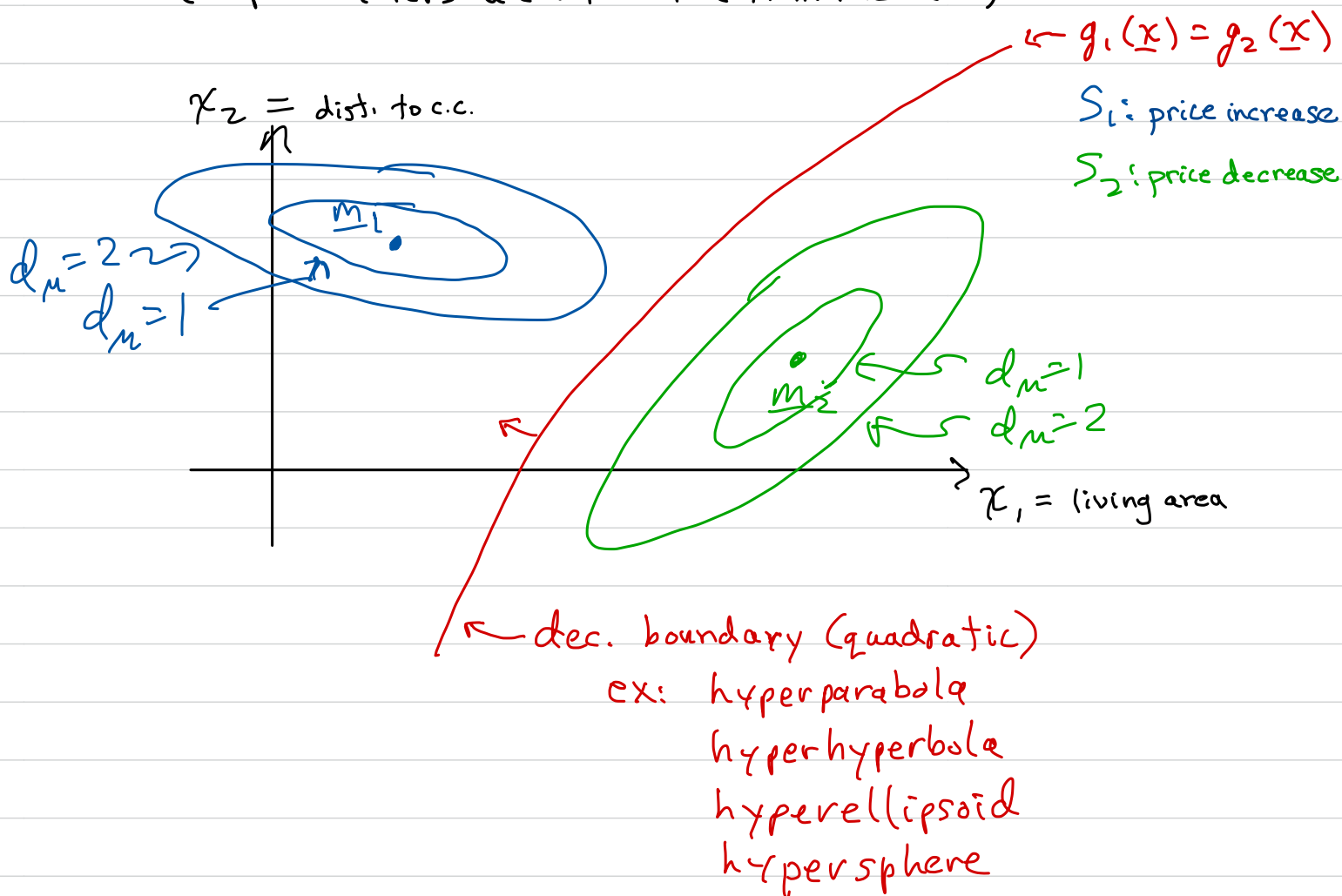
$$\underbrace{(\underline{x} - \underline{m}_i)^T \Sigma_i^{-1} (\underline{x} - \underline{m}_i)}_{d_m^2(\underline{x}, \underline{m}_i)}$$

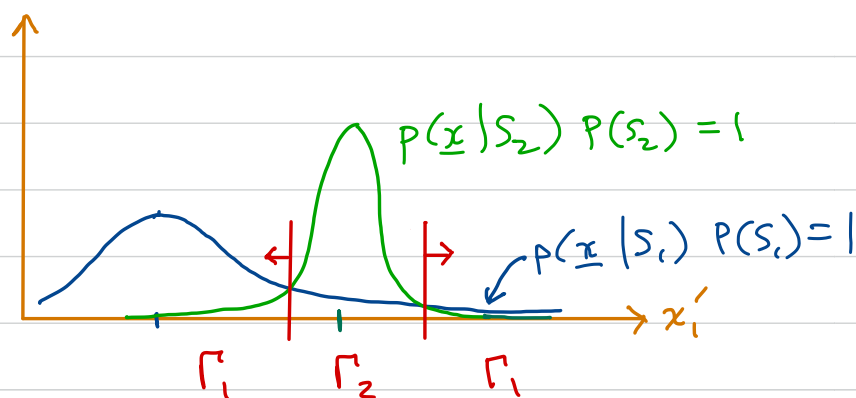
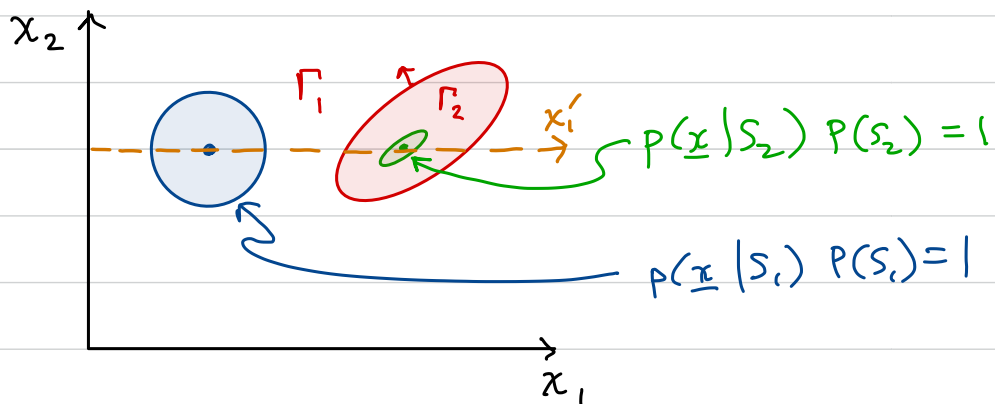
$g_i(\underline{x})$ is quadratic fcn. of \underline{x} .

\Rightarrow Dec. boundaries are quadratic

\rightarrow Quadratic Bayes

Also called QDA: quadratic discriminant analysis
(if parameters are estimated from the data)



Ex 1:Ex 2: