

# LECTURE 8

## BOOK CHAPTER 9

(Center of Mass and Linear Momentum)

## Center of Mass:



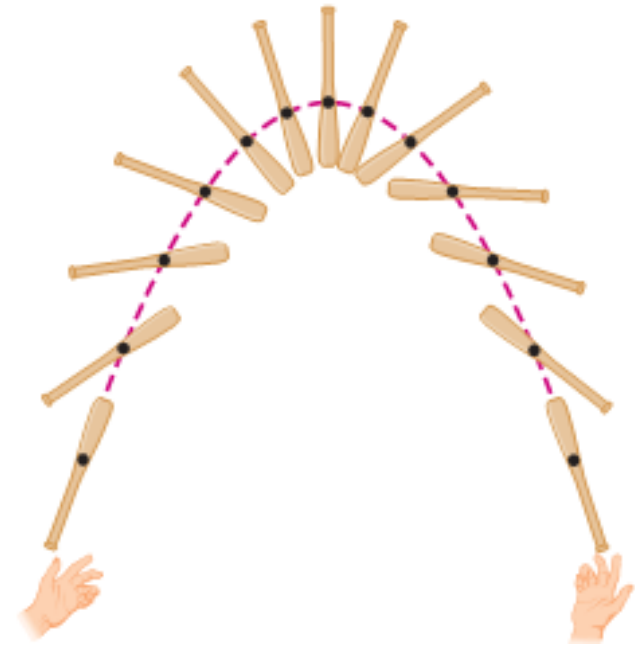
The center of mass of a system of particles is the **point** that moves as though (1) all of the **system's mass** were **concentrated there** and (2) all **external forces** were applied **there**.

### How to find the center of mass?

The center of mass of a system of  $n$  particles is defined to be the point whose coordinates are given by

$$x_c = \frac{1}{M} \sum_{i=1}^n m_i x_i$$
$$y_c = \frac{1}{M} \sum_{i=1}^n m_i y_i \quad \text{OR} \quad \vec{r}_c = \frac{1}{M} \sum_{i=1}^n m_i \vec{r}_i$$
$$z_c = \frac{1}{M} \sum_{i=1}^n m_i z_i$$

Where  $M$  is the total mass of the system.



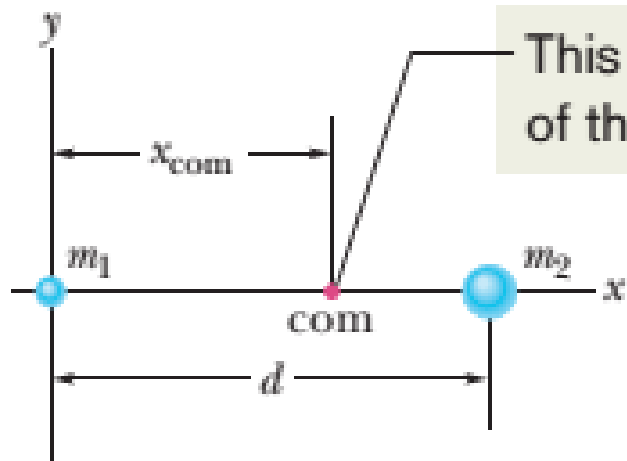
**Figure.** The **center of mass** (black dot) of a baseball bat flipped into the air follows a parabolic path, but all other points of the bat follow more complicated curved paths.

# The center of mass of the two-particle system:

## Case-1

The position of the center of mass of this two-particle system to be

$$x_c = \frac{m_2 d}{m_1 + m_2}$$

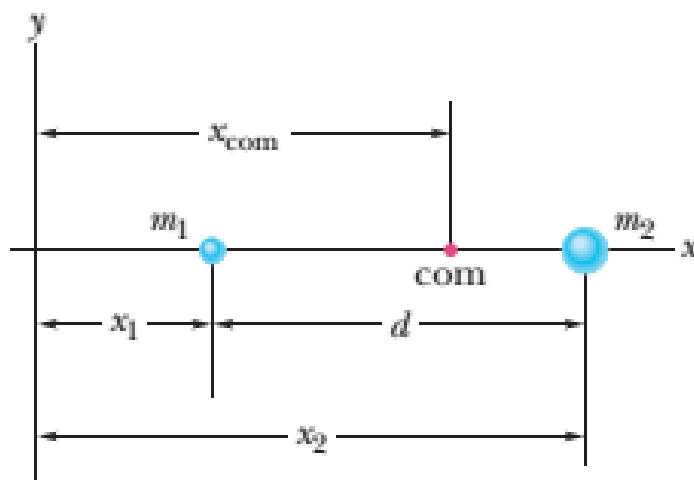


Case-1

## Case-2

The position of the center of mass of this two-particle system to be

$$x_c = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2}$$



Shifting the axis does not change the relative position of the com.

Case-2

The location of the center of mass with respect to the particles is the same in both cases.

The velocity of the system's (two body system) center of mass:

$$x_c = \frac{m_1 x_1 + m_2 x_2}{m_1 + m_2} = \frac{m_1 x_1 + m_2 x_2}{M}$$

Where,  $M = m_1 + m_2$

$$M x_c = m_1 x_1 + m_2 x_2$$

Differentiating with respect to time gives

$$M \frac{dx_c}{dt} = m_1 \frac{dx_1}{dt} + m_2 \frac{dx_2}{dt}$$

$$M v_c = m_1 v_1 + m_2 v_2$$

$$v_c = \frac{m_1 v_1 + m_2 v_2}{M}$$

## Linear Momentum:

The **linear momentum** of a particle is a vector quantity  $\vec{p}$  that is defined as

$$\vec{p} = m\vec{v}$$

in which  $m$  is the mass of the particle and  $\vec{v}$  is its velocity.

A particle's momentum  $\vec{p}$  has the same direction as its velocity  $\vec{v}$ .

The SI unit for momentum is the kilogram-meter per second ( $kg \cdot m/s$ ).

**Force and Momentum:** Differentiating with respect to time gives

$$\frac{d\vec{p}}{dt} = m \frac{d\vec{v}}{dt} = m\vec{a} \quad \text{Thus} \quad \vec{F} = \frac{d\vec{p}}{dt} \quad \text{Where } \vec{F} = m\vec{a}$$

Which is Newton's second law in terms of momentum.

In words, the time rate of change of the momentum of a particle is equal to the net force acting on the particle and is in the direction of that force.

9-4: Linear momentum: a single particle

$$\vec{p} = m \vec{v}, \text{ vector}$$

$\hookrightarrow$  +ve scalar

Same direction

SI unit:  $\text{kg} \cdot \text{m/s}$

Newton's 2nd law of motion: in terms of momentum

$$\vec{F}_{\text{net}} = \frac{d\vec{p}}{dt}$$

$\hookrightarrow$  net external force

if  $F_{\text{net}} = 0$

$$\frac{d\vec{p}}{dt} = 0$$

$p = \text{constant}$  (cannot change)

$$\vec{F}_{\text{net}} = \frac{d\vec{p}}{dt} = \frac{d}{dt}(m\vec{v}) = m \frac{d\vec{v}}{dt}$$

$$\vec{F}_{\text{net}} = m \vec{a} \quad [\text{Newton's 2nd law of motion for a particle}]$$

Total linear momentum,  $\vec{P} = \vec{p}_1 + \vec{p}_2 + \vec{p}_3 + \dots + \vec{p}_n$

Total linear momentum,  $\vec{P} = \vec{p}_1 + \vec{p}_2 + \vec{p}_3 + \dots + \vec{p}_n$

$$= m_1 \bar{V}_1 + m_2 \bar{V}_2 + m_3 \bar{V}_3 + \dots + m_n \bar{V}_n$$

$$\vec{p} = M \vec{v}_{\text{com}}$$

$\vec{v}_{\text{com}}$   $\rightarrow$  velocity of the center of mass  
 $M$   $\rightarrow$  total mass of the system

$$\frac{d\vec{P}}{dt} = \frac{d}{dt}(M\vec{v}_{\text{com}}) = M\left(\frac{d\vec{v}_{\text{com}}}{dt}\right)$$

$$\vec{F}_{\text{net}} = M \vec{a}_{\text{com}} \quad \text{Newton's 2nd law for a system of particles}$$

↳ net external force acting on the system

$$\bar{F}_{\text{net}} = \frac{d\bar{P}}{dt} \quad (\text{system of particles})$$

if  $\vec{F}_{\text{net}} = 0$   
(no net external force)

$\frac{d\vec{P}}{dt} = 0$   
 $\vec{P} = \text{constant}$   
(cannot change)

## The Linear Momentum of a System of Particles:

The linear momentum ( $\vec{P}$ ) of a system of particles is equal to the product of the total mass  $M$  of the system and the velocity of the center of mass ( $\vec{v}_c$ ).

That is  $\vec{P} = M\vec{v}_c$

## Collision and Impulse:

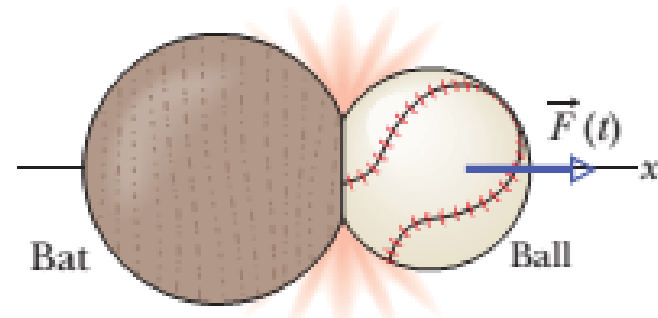
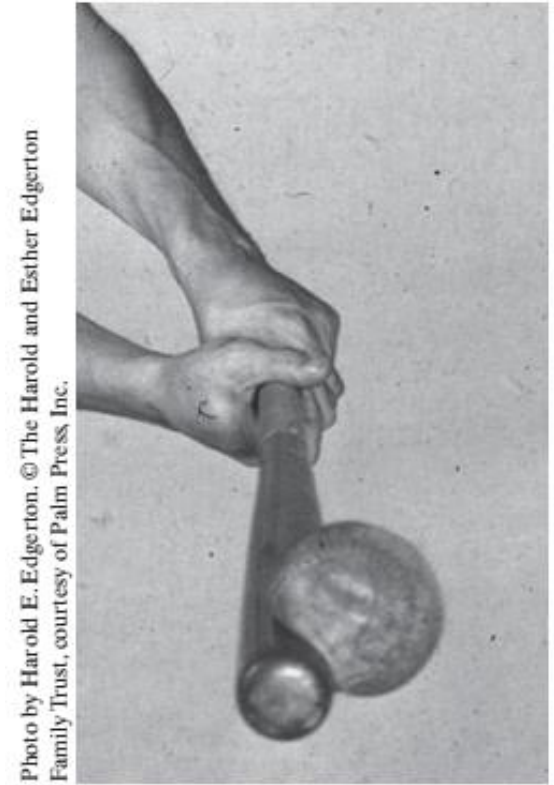
Newton's second law in terms of momentum,

$$\vec{F} = \frac{d\vec{p}}{dt}$$

In time interval  $dt$ , the change in the ball's momentum is

$$d\vec{p} = \vec{F}(t)dt$$

[**Note:** The ball experiences a force  $\vec{F}(t)$  that varies during the collision and changes the linear momentum  $\vec{p}$  of the ball.]





We can find the net change in the ball's momentum due to the collision if we integrate both sides of the equation ( $d\vec{p} = \vec{F}(t)dt$ ) from a time  $t_i$  just before the collision to a time  $t_f$  just after the collision:

$$\int_{t_i}^{t_f} d\vec{p} = \int_{t_i}^{t_f} \vec{F}(t)dt$$

$$\vec{p}_f - \vec{p}_i = \int_{t_i}^{t_f} \vec{F}(t)dt$$

The **left side** of this equation gives us the **change in momentum**:  $\Delta\vec{p} = \vec{p}_f - \vec{p}_i$ . The **right side**, which is a measure of both the magnitude and the duration of the collision force, is called the **impulse ( $\vec{J}$ ) of the collision**:

$$\vec{J} = \int_{t_i}^{t_f} \vec{F}(t)dt$$

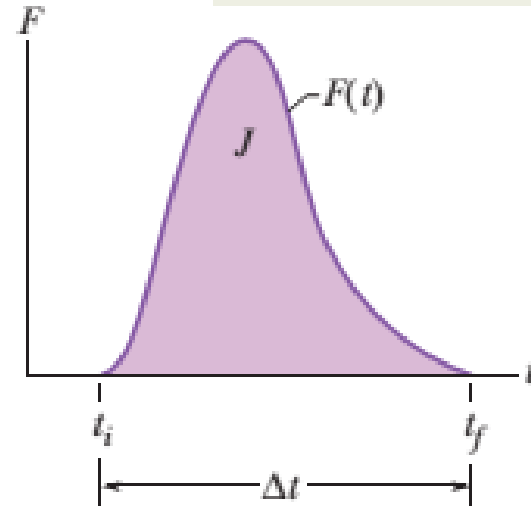
Thus, the **change in an object's momentum** is equal to the **impulse on the object**:

$$\vec{J} = \vec{p}_f - \vec{p}_i = \Delta\vec{p}$$

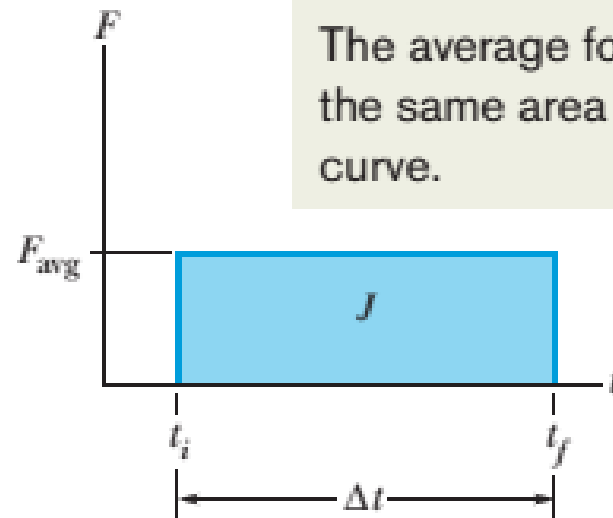
If  $F_{avg}$  is the average magnitude of  $\vec{F}(t)$  during the collision and  $\Delta t$  is the duration of the collision, then for one-dimensional motion

$$J = F_{avg} \Delta t$$

The impulse in the collision is equal to the area under the curve.



The average force gives the same area under the curve.



## The law of conservation of linear momentum:

If a system is closed and isolated so that no net external force acts on it, then the linear momentum must be constant even if there are internal changes:

$$\vec{P} = \text{constant}$$

That means,  $\vec{P}_i = \vec{P}_f$

In words, this equation says that, for a closed, isolated system,

$$\left( \begin{array}{c} \text{Total linear momentum at some} \\ \text{initial time } t_i \end{array} \right) = \left( \begin{array}{c} \text{Total linear momentum at some} \\ \text{later time } t_f \end{array} \right)$$

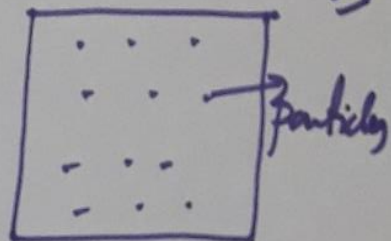
9-7: Conservation of linear momentum:

$$\vec{F}_{\text{net}} = \frac{d\vec{P}}{dt}$$

$\vec{F}_{\text{net}} = 0$  [net external force acting on a system of particles is zero (the system is isolated)]  
and

No particles leave or enter the system (system is closed)]

$$\frac{d\vec{P}}{dt} = 0$$



$\vec{P} = \text{constant}$  (cannot change), <sup>system</sup> law of conservation of linear momentum

$\vec{P}_i = \vec{P}_f \rightarrow$  total linear momentum at some later time,  $t_f$   
 $\rightarrow$  total linear momentum at some initial time,  $t_i$

Thank You