

Aug 23, 2023

Prof Dennis

First Econometrics Class

① Use Teams

② Probability

[This semester] Real Analysis / Measure Theory

Topic:-

Used across Micro/Macro/Fin.

• Estimators (extreme value theories)

Model as a lens to see the data

• Testing

⇒ We are not required to memorize anything. If you are memorizing anything, talk to Dennis

⇒ Problem Sets → extension of classes.

↓
[Open book tests.]

= Programming → Jupyter // Python
(Ask ChatGPT)

Probability Theory

- Origin $\rightarrow 11^{\text{th}}/12^{\text{th}}$ century. \rightarrow which is when people were thinking of gambling.
- Formalized in 1950s \rightarrow relatively new // to shake off the gambling stuff.
Calculus comes from 1700s.
Geometry is 2nd century AD

The phenomenon is abstract. \rightarrow can be anything.

- $x \rightarrow$ single element
- $A \rightarrow$ a set is a collection of elements.
In python, set is going to be lists.
- $B \subset A$: all elements in B are in A but not vice versa.
and $\exists x \in A$, s.t. $x \notin B$
- $B \subseteq A$:
- \emptyset : empty set. (collection with no items/elements in it)
- Ω : sample space
 - All the sets are going to be subsets of this sample space.
 - Always need to define sample space.
- $A \cup B = \{x : \text{s.t. } x \in A \text{ or } x \in B\}$
- $A \cap B = \{x : \text{s.t. } x \in A \text{ and } x \in B\}$
- $A^C = \{x : x \in \Omega, x \notin A\}$
- $A \cap A^C = \emptyset$, $A \cup A^C = \Omega$
- $A \setminus B = \{x : \text{s.t. } x \in A, x \notin B\}$
- $A^C = \Omega \setminus A$

A^c

Properties:

$$1. A \cup B = B \cup A$$

$$2. A \cap B = B \cap A$$

$$3. (A \cup B) \cup C = A \cup (B \cup C), (A \cap B) \cap C = A \cap (B \cap C)$$

$$4. A \cup (B \cap C) = (A \cup B) \cap (A \cup C)$$

$$5. A \cap (B \cup C) = (A \cap B) \cup (A \cap C)$$

Can see these pictorially
but can't use that
as a proof.

* Try these properties with complements.
(De Morgan Laws).

Algebra: is a set system \mathcal{A} s.t.

$$1. \text{ If } A \in \mathcal{A} \Rightarrow A^c \in \mathcal{A}$$

2. If a finite collection of sets

$$A_1, A_2, \dots, A_n \in \mathcal{A}$$

$$\text{then } \bigcup_{i=1}^n A_i \in \mathcal{A}$$

$$3. \emptyset \in \mathcal{A}$$

Very algorithmic
approach to
algebra.

Aug 28, 2023 : Class 2

Algebra

1 Infinite Union

of $A_1, A_2, \dots, A_n, \dots$ ext $\Rightarrow \bigcup_{i=1}^{\infty} A_i$

Countably infinite

then of is σ -algebra

~~prime~~ Example:

Ω = sample space = {H, T}

Measurable states = (Ω, \mathcal{A})

We arrange the space to infuse it with probability.

$$\Omega = \{H, T\}$$

Trivial Algebra:

$$\text{from step 1, } \mathcal{A} = \{\Omega, \emptyset\}$$

Another example $\mathcal{A} = \{H, T, H \cup T, \emptyset\}$

$\left. \begin{array}{l} \text{This is from the three steps} \\ H \in \mathcal{A}, H \subseteq \Omega \\ H \cup T \in \mathcal{A} \\ \Rightarrow \emptyset \in \mathcal{A} \end{array} \right\}$ because $(H \cup T)^c = \emptyset$

- Function $f: \mathcal{A} \rightarrow \mathcal{F}$ is measurable if

$$F \in \mathcal{F}, f^{-1}(F) = A \in \mathcal{A}$$

$\left. \begin{array}{l} \text{from now on} \\ \text{in the course,} \\ \text{we are only} \\ \text{looking at } \sigma\text{-algebra} \end{array} \right\}$

$$f(A) = \{f(x) : x \in A\} \rightarrow \text{evaluating at each } x.$$

\mathcal{B} is a σ -algebra of $(-\infty, x]$, $x \in \mathbb{R}$. It is called Borel's σ -algebra.

[all x s.]

- ④ Is this surjective function?
 A measurable function $X: F \rightarrow \mathcal{B}$ (F is σ -algebra on Ω)
 is called a random variable.
 (just a representation of the original space)

Example mapping:
 $H \rightarrow 1, 2$ 2 can be either H or T, so it is not
 $T \rightarrow 0, 2$ measurable.

$$\emptyset \rightarrow \emptyset$$

so we see it's not random or a variable, it's just a mapping.

- Probability Measure is set function of the elements of \mathcal{F}

of \mathcal{F} s.t.

$$1. \forall A \in \mathcal{F} \Rightarrow P(A) \geq 0$$

$$2. P(\Omega) = 1$$

$$3. \{A_i\}_{i=1}^{\infty} \text{ is s.t. } A_i \in \mathcal{F}, A_i \cap A_j = \emptyset \text{ if } i \neq j$$

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$$

(σ -additivity)
 of probability measure.

Doesn't have to add up to 1 (wowl)
 Can have something like a swiss cheese

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Set function \rightarrow Takes sets as inputs & outputs number

(*) Probability space : tuple of (Ω, \mathcal{F}, P)

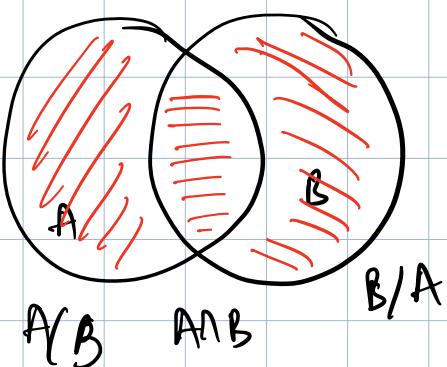
Properties of Probability space:

1. A, A^c , $P(A \cup A^c) = P(\Omega) = 1 = P(A) + P(A^c)$

(when A is considered Ω , we'll have this implication.)

2. $P(\emptyset) = 0$, $P(A^c) = 1 - P(A)$

3. $P(A) = 1 - P(A^c) \leq 1$



$$A = (A \setminus B) \cup (A \cap B)$$

$$B = (B \setminus A) \cup (A \cap B)$$

$$A \cup B = (A \setminus B) \cup (A \cap B) \cup (B \setminus A)$$

$$P(A) = P(A \setminus B) + P(A \cap B)$$

$$P(B) = P(B \setminus A) + P(A \cap B)$$

$$P(A \cup B) = P(A \setminus B) + P(A \cap B) + P(B \setminus A)$$

$$\Rightarrow P(A \cup B) - P(A) - P(B) = -P(A \cap B)$$

$$\Rightarrow P(A \cup B) \leq P(A) + P(B)$$

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Class 3

$\{A_i\}_{i=1}^{\infty} \in \mathcal{F}$, $A_i \cap A_j = \emptyset$ if $i \neq j \Rightarrow P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i)$

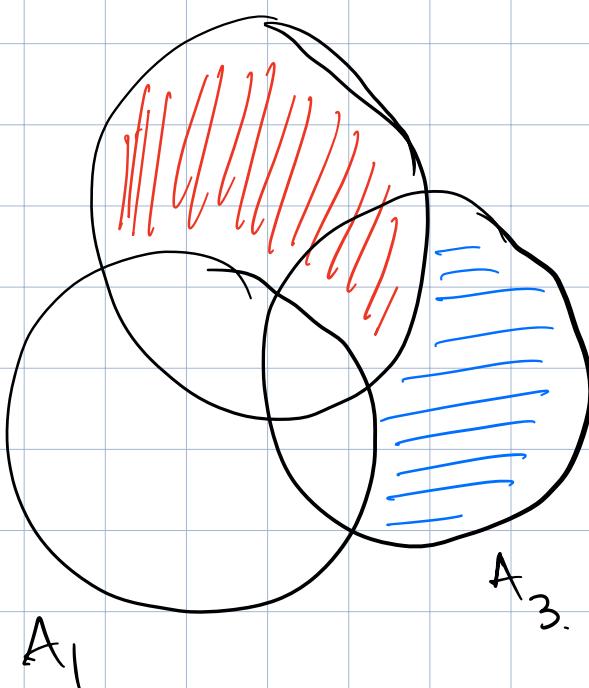
$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) \text{ where } A_i \cap A_j \neq \emptyset$$

$$\text{Set } B_1 = A_1$$

$$B_2 = A_2 \setminus A_1$$

$$B_3 = A_3 \setminus (A_1 \cup A_2)$$



$$B_K = A_K \setminus \left(\bigcup_{i < K} A_i \right)$$

$$\Rightarrow \bigcup_{i=1}^K B_i = \bigcup_{i=1}^K A_i$$

$$B_{K+1} = A_{K+1} \setminus \left(\bigcup_{i=1}^K A_i \right)$$

The B sets are disjoint.

$$B_k \subseteq A_k \Rightarrow P(B_k) \leq P(A_k)$$

$$P\left(\bigcup_{i=1}^n A_i\right) = P\left(\bigcup_{i=1}^n B_i\right) = \sum_{i=1}^n P(B_i) \leq \sum_{i=1}^n P(A_i)$$

$$\Rightarrow P\left(\bigcup_{i=1}^{\infty} A_i\right) \leq \sum_{i=1}^{\infty} P(A_i)$$

$$(a+b)^n = (a+b)(a+b) \dots (a+b)$$

The concept of urns came from mathematics looking at governance in Athens, where people put black/white marble in an urn as a vote! - wow

Permutations :

$$\frac{n \text{ items}}{n(n-1)(n-2) \dots 1} = n!$$

- A collection with replacement

Collection = ~~k~~ ~~items~~ marbles
 $k \leq n$ (total number of marbles)

... numbered ...

	ordered	un. collec	
w/o replacement	$\frac{n!}{(n-k)!}$	$\frac{n!}{(n-k)!k!} = \binom{n}{k}$	
with replacement	n^k	$\frac{(n+k-1)!}{k!(n-1)!} = \binom{n+k-1}{k}$	

$\begin{matrix} n & | & n & | & n & | & n \\ 1 & & 2 & & 3 & & 4 & \dots & k \end{matrix}$
 $\Rightarrow n^k$

$$\frac{n | n-1 | n-2 | \dots | 1 | \dots | n}{1 | 2 | 3 | 4 | \dots | \dots | k} = \frac{n!}{(n-k)!}$$

Unordered, w/o replacement.

In the above example, we can have an ordered collection, so we are overcounting. So we divide by $k!$.

$$= \frac{n!}{(n-k)!k!}$$

$$(a+b)(a+b)\dots(a+b) = \sum_{k=0}^n \binom{n}{k} a^k b^{n-k}$$



Unordered, with replacement.

100 | 101 | 100

$(n-1)$ → lines

$k \rightarrow 0$

$\frac{(n+k-1)!}{k! (n-1)!}$

Permutations

To account
for shuffling

Events A & B are independent

$$\text{if } P(A \cap B) = P(A) P(B) = A \perp B$$

Conditional Probability

$$P(A|B) = \frac{P(A) P(B)}{P(B)} = \frac{A \cap B}{P(B)}$$

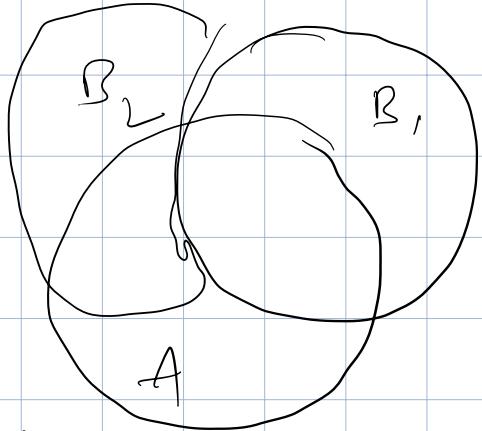
To normalize by the probability of B.

Sept 4

$$B_i \cap B_j = \emptyset, \text{ if } i \neq j$$

$$\bigcup_{j=1}^n B_j \supseteq A$$

As long as A is completely covered by B_j .



$$P(A) = \sum_{i=1}^n P(A|B_j) P(B_j)$$

weighting by the proportion

$$P(A) = P(A \cap B_j)$$

of individuals in B_j .

This is correct when the

following holds

$$\bigcup_{j=1}^n B_j \supseteq A \Rightarrow \bigcup_{j=1}^n (A \cap B_j) = A$$

The above tells us how to recover A from the B_j s. (The disjoint sets).

$$B_i \cap B_j = \emptyset$$

Posterior

$$\bigcup_{j=1}^n B_j \geq A$$

$$P(B_i | A) = \frac{P(A | B_i) P(B_i)}{\sum_{j=1}^n P(A | B_j) P(B_j)}$$

[Bayes law]

Prior

Likelihood function

(from the model)

We'll do this in more detail later.

Random Variables

Measurable function mapping from sigma algebra to real domain.

① Translate abstract set to a borel set / real number. → rainbows/cumulants etc.

Measurable space $(\mathbb{R}, \mathcal{B})$

Distribution of random variable

$$P(\{w : X(w) \in B\}) = P_x(B)$$

$\underbrace{\phantom{P(\{w : X(w) \in B\})}}_A = P(X(w) \in B)$

Probability Space: $(\Omega, \mathcal{B}, P_x)$

- Mapped everything on real line
- Borel Algebra works on real line.
- Standardized probability

After the mapping, RV converted everything to reals, so we are only concerned about real lines. We are no longer concerned about Ω (elements of the abstract space). But should remember that this is a contraction & we may lose some info in the process.

Side Note:
 $P_x(B) = P(X^{-1}(B))$
 $X(A) = \{X(w), w \in A\}$

To make things simpler, we need not look at the entire distribution of R.V.

$$F_x(x) = P_x((-\infty, x]), x \in \mathbb{R}$$

is the cumulative distⁿ function.

Properties of cdf:

1) If $x_1 \leq x_2$, then $F_x(x_1) \leq F_x(x_2)$

2) (cadlag) : $\lim_{x \downarrow x_0} f_x(x) = F(x_0)$

(Approaching x_0
from right)

$\lim_{x \uparrow x_0} f_x(x)$ exists

(Approaching x_0
from left)

⇒ the function can exhibit weird jumps.



jumps are only \Rightarrow post jump, the function has
one way \Rightarrow behave properly.

$$3) \lim_{x \rightarrow -\infty} f_x(x) = 0, \lim_{x \rightarrow \infty} F_x(x) = 1.$$

Kolmogorov

Theorem: Suppose that f satisfy properties

1-3,

then \exists probability space (Ω, \mathcal{F}, P) and r.v. X on it s.t. $f(x) = F_x(x)$

Kolmogorov → One of the most accessible real analysis textbooks. // Another is Rudin.

Definition: R.v. X is called absolutely continuous if $\exists f_x(\cdot)$, s.t. $P_x(B) = \int_B f_x(x) \cdot dx$

Example :-

1. Bernoulli r.v. (p)

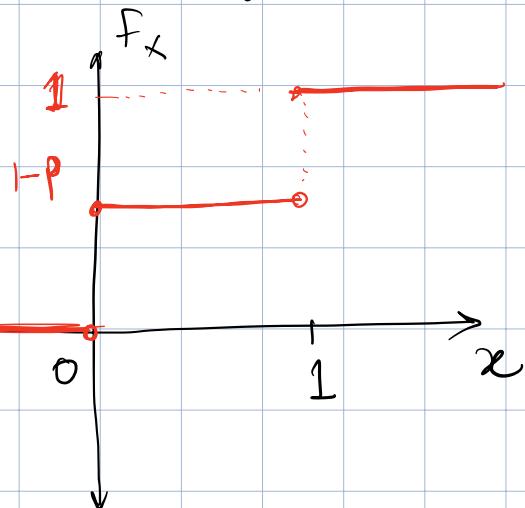
Coin tosses

r.v. X

$$X = \begin{cases} 1, & \text{with prob } p \\ 0, & \text{with prob } 1-p \end{cases}$$

$$P_X((-\infty, x])$$

$$P_X((-\infty, 1])$$



This is not an absolutely continuous R.V.

2. Binomial R.V. (p, n) number of coin tosses.

(n independent Bernoulli experiments)

$$P(X = k) = \binom{n}{k} p^k (1-p)^{n-k}$$

Our summation of the combinations $\sum_{k=0}^n \binom{n}{k} p^k (1-p)^{n-k} = 1$.
 (Newton's Binomial.)
 probability of 1s.
 probability of 0s
 $\binom{n}{k}$
 we don't care about the orders.

3. Poisson Random Variable.

$$P(X=k) = \frac{\lambda^k e^{-\lambda}}{k!}$$

$k = 0, 1, \dots, +\infty$

$$\sum_{k=0}^{+\infty} P(X=k) = e^{-\lambda} \sum_{k=0}^{+\infty} \frac{\lambda^k}{k!} = e^{-\lambda} e^\lambda = 1$$

6 Sep

4. Uniform Random Variable

$U[a, b] \rightarrow$ uniform on segment b/w a & b

$$P_X(B) = \int_{b-a}^1 \cdot dx$$

$B \cap [a, b]$

5. Exponential Distribution (α)

$$P_X(B) = \int_B^\infty \alpha e^{-\alpha x} dx$$

$B \cap (0, +\infty)$

6. Normal Distribution (μ, σ^2)

$$P_X(B) = \int_B^\infty \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} dx$$

Functional transformation of random variables :-

$$Y = g(X)$$

$$F_Y(y) = P(g(X) \leq y) = P(X \in g^{-1}((-\infty, y]))$$

If $g()$ is invertible (is increasing w.l.g), then

$$\begin{aligned} F_Y(y) &= P(g(x) \leq y) = P(X \leq g^{-1}(y)) \\ &= F_X(g^{-1}(y)) \end{aligned}$$

$$\begin{aligned} & b(t) \\ \frac{d}{dt} \int_{a(t)}^{b(t)} f(x, t) dx &= f(b(t), t) b'(t) - f(a(t), t) a'(t) \\ &+ \int_{a(t)}^{b(t)} \frac{\partial f(x, t)}{\partial t} dx \end{aligned}$$

Example $X \sim U[0, 1]$, $Y = -\log(X)$



X is uniform on 0 to 1

CDF of RV Y :

$$F_Y(y) = P(-\log X \leq y)$$
$$= P(\log X \geq -y)$$

$$= P(X \geq e^{-y})$$

$$= 1 - P(X \leq e^{-y})$$

$$P_X(b) = \int_{B \cap [0, 1]} dx = \int_0^b dx = e^{-y}$$

$$\Rightarrow = 1 - e^{-y}$$

Example

{
the square
RP with 1
dof}

$$X \sim N(0, 1) , Y = X^2$$

$$F_Y(y) = P(Y \leq y)$$

$$\begin{aligned} &= P(-\sqrt{y} \leq X \leq \sqrt{y}) \\ &= \int_{-\sqrt{y}}^{\sqrt{y}} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx \end{aligned}$$

We need to apply

If the density exists (which it does because the RHS is differentiable)

$$f_Y(y) = F'_Y(y) = \frac{1}{\sqrt{2\pi y}} e^{-y/2}$$

Multiple Dimensions

Multi dimensional extension of the analysis above

(Ω, \mathcal{F}, P) → in ~~2D~~ single dimension

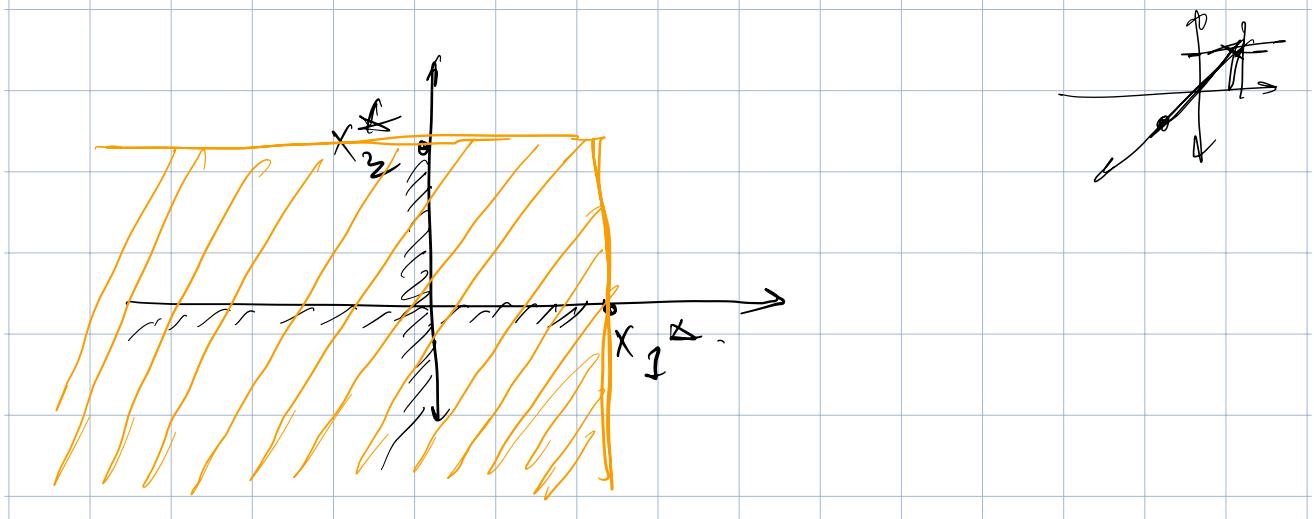
$$X(\omega) = \begin{pmatrix} X_1(\omega) \\ X_2(\omega) \\ \vdots \\ X_n(\omega) \end{pmatrix}$$

↓
vector

$X : \Omega \rightarrow \mathbb{R}^n$ is
a random vector.

Cartesian Product Across Dimensions:-

$$[-\infty, x_1] \times [-\infty, x_2] \times \dots \times [-\infty, x_n]$$



$$F_X(x_1, \dots, x_n) = P(X_1 \leq x_1, \dots, X_n \leq x_n)$$

$$f_X(x_1, \dots, x_n) = \lim_{x_n \rightarrow +\infty} F_X(x_1, \dots, x_n)$$

$$\lim_{x_n \rightarrow -\infty} (x_1, \dots, x_n) = 0$$

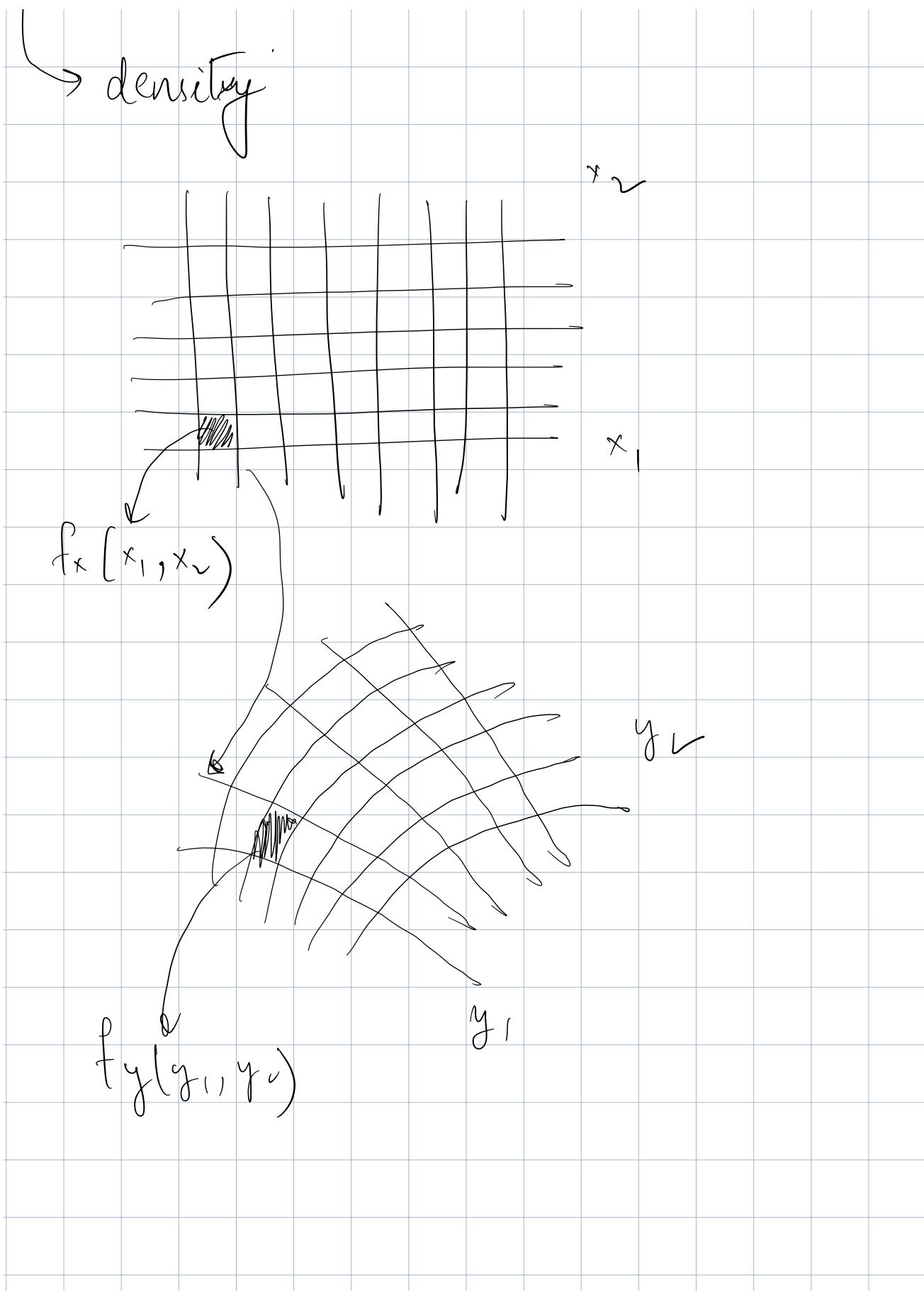
* If a f^n is not differentiable at some point \rightarrow it should be a concern. for problems etc. (Need to look into how to find that.)

If X is abs. continuous

$$\lim_{x_n \rightarrow \infty} F_X(x_1, \dots, x_n) = \int_{-\infty}^{x_1} \int_{-\infty}^{x_n} f_X(t_1, t_n) dt_1 \dots dt_n$$

CDF

$$f_X(x_1, \dots, x_{n-1}) = \int_{-\infty}^{x_n} f_X(x_1, \dots, x_{n-1}, t_n) dt_n$$



On transforming f_x to f_y the volumes of the density would no longer be preserved.

Jacobian is used to adjust for the change.

$$x_1, \dots, x_n$$

$$f_{x_1, \dots, x_n}(x_1, \dots, x_n)$$

$$y_1 = g_1(x_1, \dots, x_n)$$

$$x_1 = r_1(y_1, \dots, y_n)$$

$$\vdots$$

$$\Rightarrow$$

$$y_n = g_n(x_1, \dots, x_n)$$

$$x_n = r_n(y_1, \dots, y_n)$$

Computing density at particular points.

$$J = \begin{pmatrix} \frac{\partial g_1}{\partial x_1} & \dots & \frac{\partial g_1}{\partial x_n} \\ \vdots & & \vdots \\ \frac{\partial g_n}{\partial x_1} & \dots & \frac{\partial g_n}{\partial x_n} \end{pmatrix}$$

$$f_{x_1, \dots, x_n} \left(r_1(y_1, \dots, y_n), \dots, r_n(y_1, \dots, y_n) \right) \left| \frac{d\mathbf{t}}{dt} (J^{-1}) \right|$$

density of $f_{y_1, \dots, y_n}(y_1, \dots, y_n)$

[transformed variable.]

To correct for
the change
in the
volume.

1 Sep 11

- $P(A \cap B) = P(A)P(B)$ if $A \perp B$
when events are independent.

- Independence of random variables

Random variables x_1, \dots, x_n are independent iff

$$f_{x_1, \dots, x_n}(x_1, \dots, x_n) = f_{x_1}(x_1) \cdot \dots \cdot f_{x_n}(x_n)$$

We don't need all the distⁿ of the random variables. We can simplify no further & work with statistics

② Expectation

$$E[X] = \int_{\Omega} X(\omega) P(d\omega)$$

Lébesgue-Stieltjes integral.

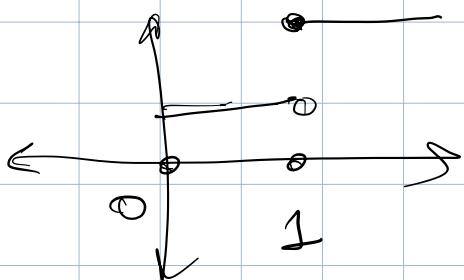
this does not matter except ~~to~~ knowing that when the space is discrete, then its all around more spaces (~~*~~?)

$$= \int_{-\infty}^{\infty} x dF(x)$$

\downarrow
then we need to take the sum

interpret it as a switching device.

For Bernoulli random variable, we can't integrate but have to take sum



$$E(x) = 0(1-p) + 1 \cdot p = p.$$

When dealing with continuous r.v.; the above integral would be fully defined.

For absolutely continuous r.v.

$$E[X] = \int_{-\infty}^{+\infty} x \cdot f_x(x) \cdot dx$$

Continuity
here is about
the probability density f.

When expectation is not defined:

Cauchy's distribution: Absolutely continuous
or \rightarrow density is defined as:

$$f_x(x) = \frac{1}{\pi(1+x^2)}$$

$$E = \int_{-C}^{C} x f_x(x) \cdot dx = \int_{-C}^{C} \frac{1}{\pi(1+x^2)} \cdot x \cdot dx$$

$$= \int_{-\infty}^c \log(1+x^2) dx$$

$$= \frac{1}{2\pi} \log(1+c^2)$$

The expectation does not exist. The integral does not converge.

But if $f(x) = \frac{c}{1+x^{2+\delta}}$ (integral converges.)

Properties of expectations :-

1) $E(a+bX) = a + bE(X)$

2) For any X_1 & X_2 (r.v. where expectations exist), s.t. $|E[X_1]|, |E[X_2]| < \infty$

$$E[X_1 + X_2] = E[X_1] + E[X_2]$$

3) if $a \leq X \leq b$, then

$$a \leq E[X] \leq b$$

$$|E[X]| \leq E[|X|]$$

Q what does it mean to not have an expectation?

When we do "sampling", we won't have the same ^{sample} expectation in different samples from the pop".

- Bootstrapping fails too

4) If $X \geq 0$ & $E[X] = 0 \Rightarrow X = 0$

$$E[g(X)]$$

$g(X)$ is
also a R.V.

$$\mathbb{1}_{\{X \in A\}} = \begin{cases} 1, & \text{if } x \in A \\ 0, & \text{otherwise} \end{cases}$$

$$E[\mathbb{1}_{\{X \in A\}}] = \int_A P(dw) = P(A)$$

Examples :-

1. Bernoulli (p) $E[X] = p$

2. Binomial R.V. (n, p)

$$E[X_1 + X_2 + \dots + X_n] \quad (\text{Bernoulli R.V.})$$

$$= np$$

$$\sum_{k=0}^n \binom{n}{k} p^k (1-p)^{n-k} k \leftarrow \text{Can also do like this, just more tedious.}$$

~~= np.~~

3. Poisson (λ)

$$E[X] = \sum_{k=0}^{\infty} k \frac{\lambda^k e^{-\lambda}}{k!}$$

$$= \sum_{k=1}^{\infty} \frac{\lambda^k}{(k-1)!} e^{-\lambda}$$

$$\text{let } k-1 = i \Rightarrow \sum_{i=0}^{\infty} \frac{\lambda^{i+1}}{i!} e^{-\lambda}$$

$$= \lambda e^{-\lambda} \sum_{i=0}^{\infty} \frac{\lambda^i}{i!}$$

e^{λ}

$$= \lambda$$

4. Normal R.V. :-

$$(\mu, \sigma^2)$$

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$$E(X) = \int_{-\infty}^{+\infty} x \cdot \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} dx$$

$$= \int_{-\infty}^{+\infty} x \cdot \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} (x-\mu) dx$$

$$= \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{t^2}{2\sigma^2}} t dt + \mu \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}} dx$$

$$= 0 + 1$$

$$= 1$$

Conditional Expectations :-

$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

$$\Rightarrow P(Y \in A | X \in B)$$

$$E[Y | X \in B] = \int y(\omega) P(dy | X \in B)$$

Example (survival ~~D~~istribution)

$$F(x \leq x) = 1 - e^{-\alpha x}$$

$$F(x \leq x | x \geq a)$$

$$f_x(x) = E[\mathbb{1}\{x \leq x\}]$$

$$A = \mathbb{1}\{x \leq x\}$$

$$B = \mathbb{1}\{x \geq a\}$$

$$P(B) = E[\mathbb{1}\{x \geq a\}] = e^{-\alpha a}$$

$$A \cap B = \begin{cases} \emptyset, & \text{if } x < a \\ [a, x], & \text{if } x \geq a \end{cases}$$

$$P(A \cap B) = E[\mathbb{1}\{x \in [a, x]\}]$$

$$= e^{-\alpha a} - e^{-\alpha x}$$

$$P(X \leq x | X \geq a) = 1 - e^{-\alpha(x-a)}$$

September 13

Machine learning // Making

predictions

Minimization problem :-

loss function $\hat{X} - a$

Risk function : $E[(\hat{X} - a)^2]$

What we are predicting
modelled as \hat{X} .
Our prediction.

Expectation is linear operator (inherited from the integral we did).

$$E = [X^2 - 2aX + a^2]$$

$$= E[X^2] - 2aE[X] + a^2$$

a is a constant

Minimize wrt a .

$$a^* = E[\hat{X}]$$

Including a confounding variable :-

Regression function (part 2)

$$E[(X-a)^2 | z] \Rightarrow a^*(z) = E[X | z]$$

A correlator which helps us to estimate better.

OLS is trying to solve the following problem:-

$$E[(x - a(z))^2] = \int_{-\infty}^{\infty} (x - a(z))^2 f(x|z) dx,$$

Here the problem is to find an unknown function. Under some conditions, it would be conditional expectation.

We find a for each z .

$$a = E[x | z = z]$$

(*) This is solved point-wise

$$\min_a E[(x - a)^2] = \text{Var}(x)$$

$$\text{Var}(x) = E[(x - E[x])^2] = E[x^2] - E[x]^2$$

(*) Non-central

$$k^{\text{th}} \text{ moment of r.v.} : E[x^k]$$

① Central moments : $X - E[X]$

② k^{th} central moments : $E[(X - E[X])^k]$

Knowing moments of a r.v. can help us to find the whole distribution.

Examples :

1) Bernoulli R.V.

$$\begin{aligned}\text{Var}(X) &= p - p^2 \\ &= p(1-p).\end{aligned}$$

Using this def:

$$\left. \begin{aligned} &E[X^2] - E[X]^2 \\ &\{ \end{aligned} \right\}$$

Properties of variance (non-exhaustive) :-

1. $\text{Var}(X) \geq 0$, if $\text{Var}(X)=0 \Rightarrow X=c$
a.e. (almost everywhere) / with probability = 1.

$$\left(\min_a E \{ (X-a)^2 \} = 0 \right) \xrightarrow{\text{solving this}}$$

2. $\text{Var}(a+bX) = b^2 \text{Var}(X)$

Covariance

$$\text{cov}(X, Y) = E[(X - E[X])(Y - E[Y])]$$

3. $\text{Var}(X+Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{cov}(X, Y)$

If $X \perp Y$ (X & Y are independent)

Independence of joint distribution \Rightarrow multiplication
of marginal density distribution.

$$E[(X - E(X))(Y - E(Y))] = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} (x - E(x))(y - E(y)) f_{X,Y}(x,y) dx dy$$

$$= E[X - E(X)]E[Y - E(Y)] = 0$$

Examples :

1) Bernoulli R.V.

$$\begin{aligned} \text{Var}(X) &= p - p^2 \\ &= p(1-p). \end{aligned}$$

Using this def:

$$\left\{ \begin{aligned} &E[X^2] - E[X]^2 \end{aligned} \right\}$$

2) Binomial Distribution

Binomial (n, p)

$$X_1 + X_2 + \dots + X_n$$

$$\text{Var}(X_1 + X_2 + \dots + X_n)$$

All r.v. have

$$n \text{ Var}(X_1)$$

bernoulli distⁿ.

Var of bernoulli

$$1 \quad np(1-p)$$

3) Poisson (λ)

$$E[X^2] = \sum_{k=0}^{+\infty} k^2 \frac{\lambda^k}{k!} e^{-\lambda}$$

$$= \sum_{k=0}^{\infty} k \frac{\lambda^k}{(k-1)!} e^{-\lambda}$$

We know

$$(\lambda^k)' = k \lambda^{k-1}$$

$$= e^{-\lambda} \lambda \sum_{k=0}^{\infty} \frac{k \lambda^{k-1}}{(k-1)!} (\lambda^k)'$$

$$\sum_{k=0}^{\infty} \frac{k \lambda^{k-1}}{(k-1)!} = \sum_{k=1}^{\infty} \frac{(\lambda^k)'}{(k-1)!} = \left(\sum_{k=1}^{\infty} \frac{\lambda^k}{(k-1)!} \right)' \quad *$$

$$\sum_{k=0}^{\infty} \frac{\lambda^k}{(k-1)!} = \lambda \sum_{i=0}^{\infty} \frac{\lambda^i}{i!} = \lambda e^\lambda$$

Put in *

$$(\lambda e^\lambda)' = e^\lambda + \lambda e^\lambda$$

Plugging in **

$$\lambda + \lambda^2$$

$$\text{Var}(x) = \lambda$$

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Inequalities

• Cauchy - Schwarz Inequality

$$E[|XY|] \leq \sqrt{E[X^2] E[Y^2]}$$

Take

$$(|a| - |b|)^2 \geq 0$$

$$\Rightarrow 2|ab| \leq a^2 + b^2$$

$$a = \frac{x}{\sqrt{E[X^2]}}$$

$$b = \frac{y}{\sqrt{E[Y^2]}}$$

$$2 \cdot \frac{|XY|}{\sqrt{E[X^2] E[Y^2]}} \leq \frac{x^2}{E[X^2]} + \frac{y^2}{E[Y^2]}$$

The inequality holds point wise, so it would also hold for expectation.

Taking expectation both side :-

$$\frac{E[|XY|]}{2\sqrt{E[X^2]E[Y^2]}} \leq \frac{E[X^2]}{E[X^2]} + \frac{E[Y^2]}{E[Y^2]} = 2$$

$$\Rightarrow E[|XY|] \leq \sqrt{E[X^2]E[Y^2]}$$

• Correlation Coefficient.

$$r_{xy} = \frac{\text{Cov}(x, y)}{\sqrt{\text{Var}(x)\text{Var}(y)}}$$

Properties :-

1. If $x \perp y \Rightarrow \rho_{xy} = 0$

2. By Cauchy-Schwarz inequality:

$$E[|(x - E(x))(y - E(y))|] \leq \sqrt{\text{Var}(x) \text{Var}(y)}$$

∴ $|E[g(x)]| \leq E[|g(x)|]$, (property of expectation)

$$\Rightarrow \underbrace{|E[(x - E(x))(y - E(y))]|}_{\leq |\text{Cov}(x, y)|} \leq \sqrt{\text{Var}(x) \text{Var}(y)}$$

$$\Rightarrow |\rho_{xy}| \leq 1 \Rightarrow -1 \leq \rho_{xy} \leq 1$$

3. If $|\rho_{xy}| = 1$, then with probability 1,
 $y = a + b x$ (linear dependence)

{ In applied work, when we look at ρ_{xy} ,
it's to remember it's only telling us about
the linear relationship, there could be another
one too.]

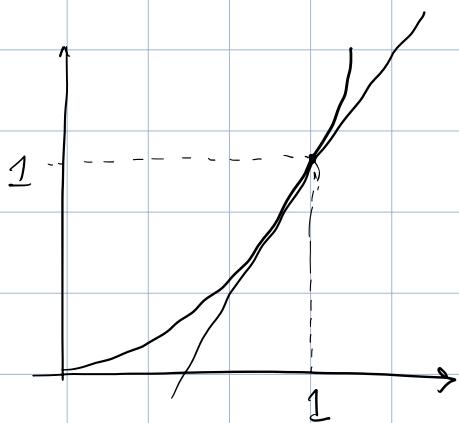
★ Hölder's Inequality :

suppose $r > 1$, then take $s > 0$ s.t.

$$\frac{1}{r} + \frac{1}{s} = 1$$

$$E[|XY|] \leq E[|X|^r]^{1/r} E[|Y|^s]^{1/s}$$

Proof :-



Inequality b/w convex f & tangent line

Convex fu always lie above the tangent line.

$$x^r - 1 \geq r(x-1)$$

* why do we take 1 here?

how is
this tangent
line?
Derivative?

$$\text{Set } a = \frac{|X|^r}{E[|X|^r]}, \quad b = \frac{|Y|^s}{E[|Y|^s]}$$

$$\text{Set } x = \left(\frac{a}{b}\right)^{1/s}$$

$$\text{Dividing by } r, \quad r \left(\frac{a^{1/r}}{b^{1/s}} - 1 \right) \leq \frac{a}{b} - 1$$

Multiplying both sides by b

$$r(a^{1/r} \cdot b^{1/s} - b) \leq a - b$$

Using the value of a & b.

$$r \left(\frac{|x|}{(E[|x|^r])^{1/r}} \frac{|y|}{(E[|y|^s])^{1/s}} - \frac{|y|^s}{E[|y|^s]} \right) \leq \frac{|x|^r}{E[|x|^r]} - \frac{|y|^s}{E[|y|^s]}$$

$$= r \left(\frac{|xy|}{(E[|x|^r])^{1/r} (E[|y|^s])^{1/s}} - \frac{|y|^s}{E[|y|^s]} \right) \leq \frac{|x|^r}{E[|x|^r]} - \frac{|y|^s}{E[|y|^s]}$$

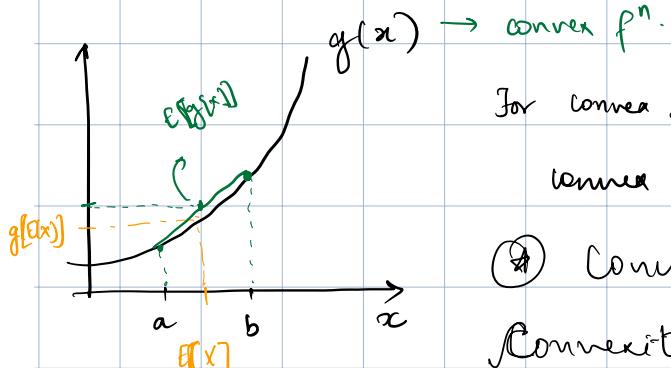
Taking expectations both sides

$$= r \left(\frac{E[|xy|]}{(E[|x|^r])^{1/r} (E[|y|^s])^{1/s}} - \frac{E[|y|^s]}{E[|y|^s]} \right) \stackrel{1}{\leq} \frac{E[|x|^r]}{E[|x|^r]} - \frac{E[|y|^s]}{E[|y|^s]} \stackrel{1}{=} 1$$

$$= \frac{E[|xy|]}{E[|x|^r]^{1/r} E[|y|^s]^{1/s}} \leq 1$$

* Cauchy-Schwarz is a special case of Hölder's inequality

- Jensen's Inequality (pronounced as Yenssen) $\xrightarrow{\text{Danish}}$



For convex f^n : $E[g(x)] \geq g(E[x])$ for convex $f^n g(\cdot)$

④ Convexity does not need differentiability
Convexity without differentiability

leads to kinder.

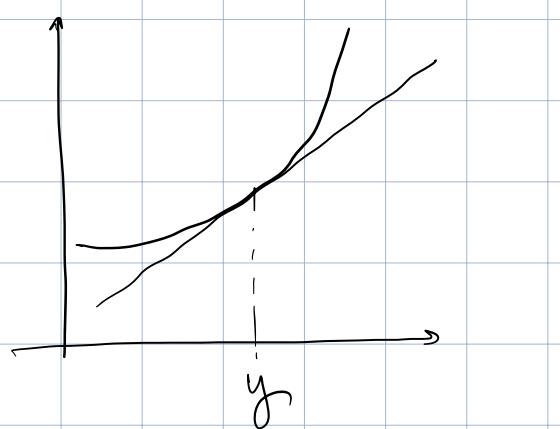
Proof:

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$$\int_S dx = 0 \quad \xrightarrow{\hspace{1cm}} \text{measle.}$$

real analysis book: Kolmogorov, Fomin "Intro real analysis"

Jensen's Inequality



$$g(x) \geq g(y) + \nabla g(y)(x-y)$$

Let $y = E[X]$
 $x = \tilde{x}$

$$g(\tilde{x}) \geq g(E[X]) + \nabla g(E[X])(\tilde{x} - E[X])$$

$$E[g(\tilde{x})] \geq g(E[X]) + \nabla g(E[X])(E[\tilde{x}] - E[X])$$

For concave f^u , the inequality is flipped.

Markov's inequality

$$P(|X| \geq \varepsilon) \leq \frac{E[|X|]}{\varepsilon}$$

$$E[|X|] = \int_{-\infty}^{+\infty} |x| f_x(x) dx$$

$$= \int_{|x| \geq \varepsilon} |x| f_x(x) dx + \int_{|x| < \varepsilon} |x| f_x(x) dx$$

$$\geq \int_{|x| \geq \varepsilon} |x| f_x(x) dx.$$

$$\geq \int_{|x| \geq \varepsilon} \varepsilon f_x(x) dx \geq \varepsilon \int_{|x| \geq \varepsilon} f_x(x) dx.$$
$$\geq \varepsilon P(|X| \geq \varepsilon)$$

$$\Rightarrow P(|X| \geq \varepsilon) \leq \frac{E[|X|]}{\varepsilon}$$

(how do you
visualize this?)



Markov's inequality generalizes to arbitrary moments of r.v. if they exist! —

$$P(|X| \geq \epsilon) \leq \frac{E[|X|^k]}{\epsilon^k}$$

- ① Existence of moments very deeply connected to the tail behaviour.

Chebachev Inequality

$$\begin{aligned} P(|Y - E[Y]| \geq \epsilon) &\leq \frac{E[(Y - E(Y))^2]}{\epsilon^2} \\ &\leq \frac{\text{Var}(Y)}{\epsilon^2} \end{aligned}$$

$$|E[X]| \leq \underbrace{E[|X|]}_{\substack{\text{This would} \\ \text{exist}}}$$

\hookrightarrow of no exist

but not the other way around .



COMPLEX VARIABLES

• Roots of polynomials. \rightarrow solving for engineering seasons.

• n^{th} degree polynomial should have k roots.

$$a_k x^k + a_{k-1} x^{k-1} + \dots + a_0 = 0$$

Initially held belief but shortly found wrong.

$$x^2 = -1$$

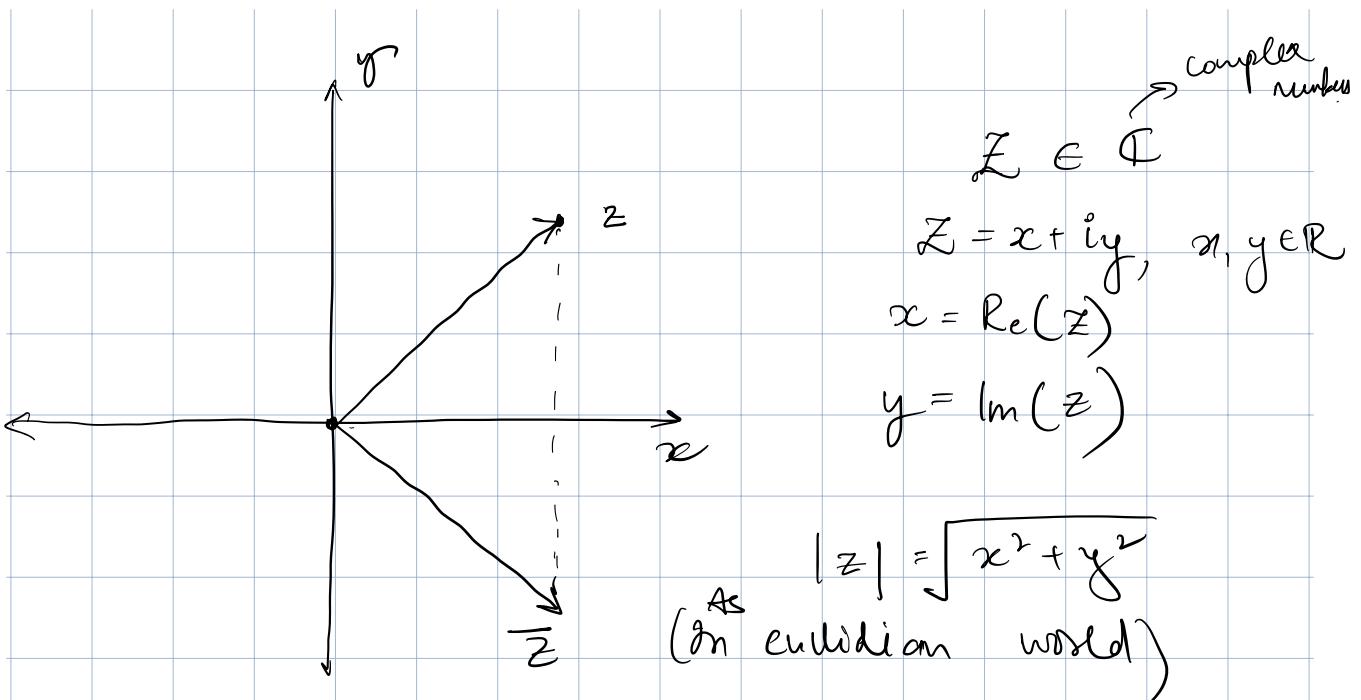
Imaginary number: $i = \sqrt{-1}$

$$x = \pm i$$

$$x^2 = -1 ; \text{ similarly } 8$$

$$x = \sqrt{-1}$$

Take real numbers and expand them to the complex domain:



$$z^* = \bar{z} = x - iy.$$

Complex conjugate of z .

$$\begin{aligned} z\bar{z} &= |z|^2 = (x+iy)(x-iy) \\ &= x^2 + ixy - ixy - (1)^2 y^2 \\ &= x^2 + y^2 \end{aligned}$$

① Try to plot $\sin(z)$

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Cn. form of complex no.

$$x = a + bi$$

$$x^2 = -1$$

$$\Rightarrow (x^2)^2 = -1$$

$$\Rightarrow x^2 = \pm i$$

$$x = a + bi$$

$$x^2 = a^2 + b^2(i)^2 + 2abi = i$$

$$= a^2 - b^2 + 2abi = i$$

$$a^2 - b^2 = 0$$

$$2ab = 1 \Rightarrow ab = \frac{1}{2}$$

$$|a| = |b|$$

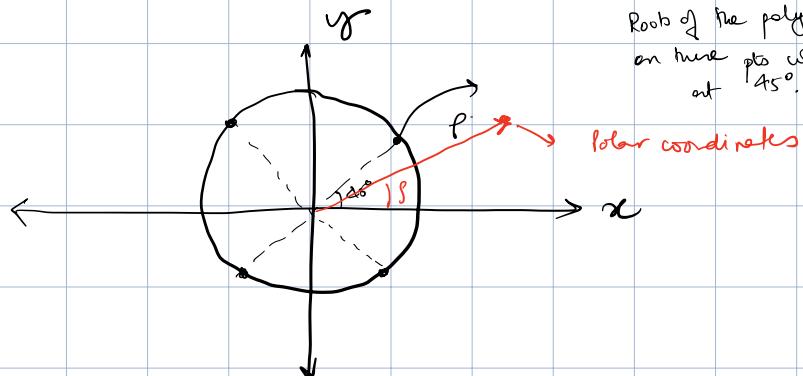
$$a = b = \frac{1}{\sqrt{2}}, \quad a = b = -\frac{1}{\sqrt{2}}$$

Rots :-

$$\frac{1+i}{\sqrt{2}}, \quad -\frac{(1+i)}{\sqrt{2}}$$

$$\frac{1-i}{\sqrt{2}}, \quad -\frac{1+i}{\sqrt{2}}$$

Complex numbers can be expressed as points on the number line:



Polar coordinates :

$$\text{complex no.} \quad z = \rho \cos \theta + i \rho \sin \theta = \rho (\cos \theta + i \sin \theta) \quad *$$

Euler's formula : $z = \rho e^{i\theta}$ (Using Taylor series expansion)

$$z^4 = -1 \Rightarrow \rho = 1 \quad \text{modulus} \rightarrow 1. \rightarrow \rho^4 e^{4i\theta} = -1$$

$$e^{i\pi} = -1 = e^{i\pi}$$

General expression $e^{i(\pi + 2\pi k)}$

$$\rho = \frac{\pi}{4} + \frac{\pi k}{2}$$

as it is distance, it has to be positive.

use the graph to see where -1 lies. can also confirm using $*$

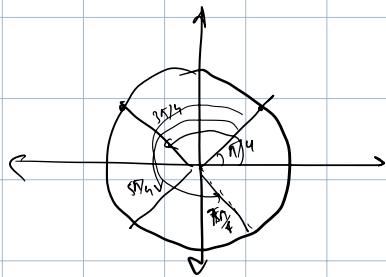
when $k=0$; $\rho = \frac{\pi}{4} \rightarrow$ first 45° degree pt.

$$k=1; \rho = \frac{\pi}{4} + \frac{\pi}{2} = \frac{3\pi}{4}$$

$$\begin{aligned} e^{i\pi/4} &= \cos\left(\frac{\pi}{4}\right) + i \sin\left(\frac{\pi}{4}\right) \\ &= \frac{1}{\sqrt{2}} + \frac{i}{\sqrt{2}} \end{aligned}$$

$$k=2; \rho = \frac{\pi}{4} + \pi = \frac{5\pi}{4}$$

$$k=3; \rho = \frac{\pi}{4} + \frac{3\pi}{2} = \frac{\pi + 6\pi}{4} = \frac{7\pi}{4}$$



$$e^{i\pi/4} = \frac{1}{\sqrt{2}} + \frac{i}{\sqrt{2}}$$

$$e^{i3\pi/4} = -\frac{1}{\sqrt{2}} + \frac{i}{\sqrt{2}}$$

$$e^{i5\pi/4} = -\frac{1}{\sqrt{2}} - \frac{i}{\sqrt{2}}$$

$$z^6 = -1 \quad (\text{exact same logic})$$

* Characteristic Function of RV X

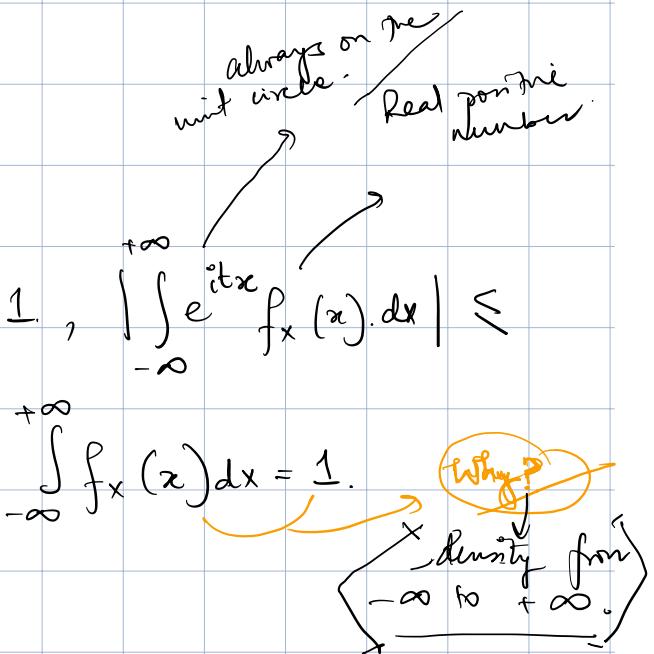
$$\phi_x(t) = E[e^{itX}] \quad (\text{complex valued R.V.}), \quad t \in \mathbb{R}$$

If X is abs cont., $\phi_x(t) = \int_{-\infty}^{+\infty} e^{itx} f_x(x) dx$

* Knowing ^{the} characteristic fn is equivalent to knowing the distⁿ function.

Properties

$$1. \phi(0) = 1, \quad |\phi_x(t)| \leq 1, \quad \left| \int_{-\infty}^{+\infty} e^{itx} f_x(x) dx \right| \leq$$



$$\begin{aligned}
 2. \quad \phi_{a+bx}(t) &= E[e^{it(a+bx)}] = E[e^{ita} \cdot e^{itbx}] \\
 &= e^{ita} \cdot E[e^{itbx}] \\
 &= e^{ita} \phi_x(bt)
 \end{aligned}$$

3. If x_1, \dots, x_n are independent,

$$\begin{aligned}
 \phi_{x_1+x_2+\dots+x_n}(t) &= \phi_{x_1}(t) \cdots \phi_{x_n}(t) \\
 E[e^{it(x_1+x_2+\dots+x_n)}] &= E[e^{itx_1} e^{itx_2} \cdots e^{itx_n}] = \phi_{x_1}(t) \phi_{x_2}(t) \cdots \phi_{x_n}(t)
 \end{aligned}$$

This is equal to the product of expectations.

Examples

1. Bernoulli (p)

$$\phi_x(t) = p e^{it} + 1-p = p(e^{it}-1) + 1$$

$\nearrow \text{RV(1)}$ $\searrow \text{RV(0)}$

2. Binomial (n, p) $\Sigma = x_1 + x_2 + \dots + x_n$, x_i is

Bernoulli (p)

$$\phi_y(t) = (p(e^{it}-1) + 1)^n$$

3. Poisson (λ)

$$\phi_x(t) = \sum_{k=0}^{\infty} e^{itk} \frac{\lambda^k}{k!} e^{-\lambda}$$

$$= e^{-\lambda} \sum_{k=0}^{\infty} \frac{(e^{it}\lambda)^k}{k!}$$

(Taylor expansion)
of the exponent

$$= e^{(e^{it}-1)\lambda}$$

Back to properties :-

4. $\phi_x(t)$ is uniformly continuous.

[CBB define $m_x(t) = E[e^{tx}]$ instead of defining the complex numbers. That is bad because this requires the existence of expectation of the exponent of rv X which may not exist for many rvs.]

5. If k -th moment r.v. X exists, then

$$\phi_x^{(k)}(0) = (i)^k E[X^k]$$

$$E[e^{itx}]' = E[iXe^{itx}]$$

$$t \rightarrow 0 \Rightarrow iE[X]$$

$$E[e^{itx}]'' = E[i^2 X^2 e^{itx}]$$

$$t \rightarrow 0 \Rightarrow (i)^2 [X^2]$$

(Assuming can take
differential inside the
expectation.)

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• $X = a$, w.p. = 1
 $\phi_X(t) = e^{iat}$

Theorem: function $\phi(t)$, s.t. $\phi(0) = 1$ is a characteristic function iff it is positive semi-definite.

Def: Function $f(t)$ is PSD if $t = t_1, \dots, t_n \in \mathbb{R}$
matrix F with $F_{ij} = f(t_i - t_j)$ is PSD.

Theorem: If r.v. X is absolutely continuous, then

$\lim_{t \rightarrow \infty} \phi(t) = 0$. Eg \rightarrow [bernoulli is not abs
continuous, so this property does not
hold for it.]

Theorem: For r.v. X and Y , $F_x(z) = F_y(z) \forall z \in \mathbb{R}$

iff $\phi_X(t) = \phi_Y(t) \forall t \in \mathbb{R}$

X is uniform on $[a, b] \rightarrow$ continuous R.V.

$$\phi_X(t) = \int_a^b e^{itx} \frac{1}{b-a} dx$$

Integrate over
the density

$$= \frac{1}{b-a} \left[\frac{1}{it} e^{itx} \right]_a^b$$
$$= \frac{e^{itb} - e^{ita}}{itb - ita}$$

$$\frac{1}{i} = a + bi$$

$$= 1 = a - b. \quad (i^2 = -1)$$

$$\Rightarrow a = 0; \quad b = -1.$$

$$\frac{1}{i} = -i$$

Moment Generating Function (Mgf)

$$m_x(t) = E[e^{tX}]$$

$$m_x(t) = \int_{-\infty}^{\infty} e^{tx} f_x(x) \cdot dx$$

(Not sure what this is called.)

More on this, in the book. Dennis does not like this because it may not always exist as already listed ~~noted~~ in the notes before.

$$e^{tX} = \sum_{k=0}^{\infty} \frac{(tX)^k}{k!}$$

$$\begin{aligned} m_x(t) &= E \left[\sum_{k=0}^{\infty} \frac{(tX)^k}{k!} \right] \\ &= \sum_{k=0}^{\infty} \frac{t^k}{k!} E[X^k] \end{aligned}$$

{ We may not always be able to swap \sum & E . because of the summation to infinity }

* [Stochastic Convergence]

$X_n (\Omega, \mathcal{F}, P)$, $n = 1, 2, \dots$

$$L_2: \|X_n\|_{L_2}^2 = \int_{-\infty}^{+\infty} X_n^2(\omega) F_{X_n}(d\omega) = E[X_n^2]$$

Did'nt understand why usual convergence doesn't work, but it doesn't so we have to define it differently now:

Need not be
a constant!

X_n converges in probability to r.v. X

(notation: $X_n \xrightarrow{P} X$) if $\forall \varepsilon > 0$,

$$P(|X_n - X| > \varepsilon) \rightarrow 0, \text{ as } n \rightarrow \infty$$

[The correlation b/w X_n & X as $n \rightarrow \infty$, becomes 1.]
(Question on case)

Convergence almost surely (a.s)

X_n converges to r.v. X almost surely
(notation $X_n \xrightarrow{a.s.} X$) if:

$$P\left(\{\omega : X_n(\omega) \rightarrow X(\omega)\}\right) = 0$$

Almost because it could converge with probability 0.

Eg :-

$$X_n = \begin{cases} 1, & \omega \in P \cdot \frac{1}{n} \\ 0, & \omega \in P \setminus \frac{1}{n} \end{cases} \quad (\text{Bernoulli})$$

$$P(X_n = 1) \equiv P(|X_n - 0| > \epsilon) = \frac{1}{n} \rightarrow 0$$

deviating from 0 by more than ϵ for any ϵ . R.V. only takes 2 values (0, 1).

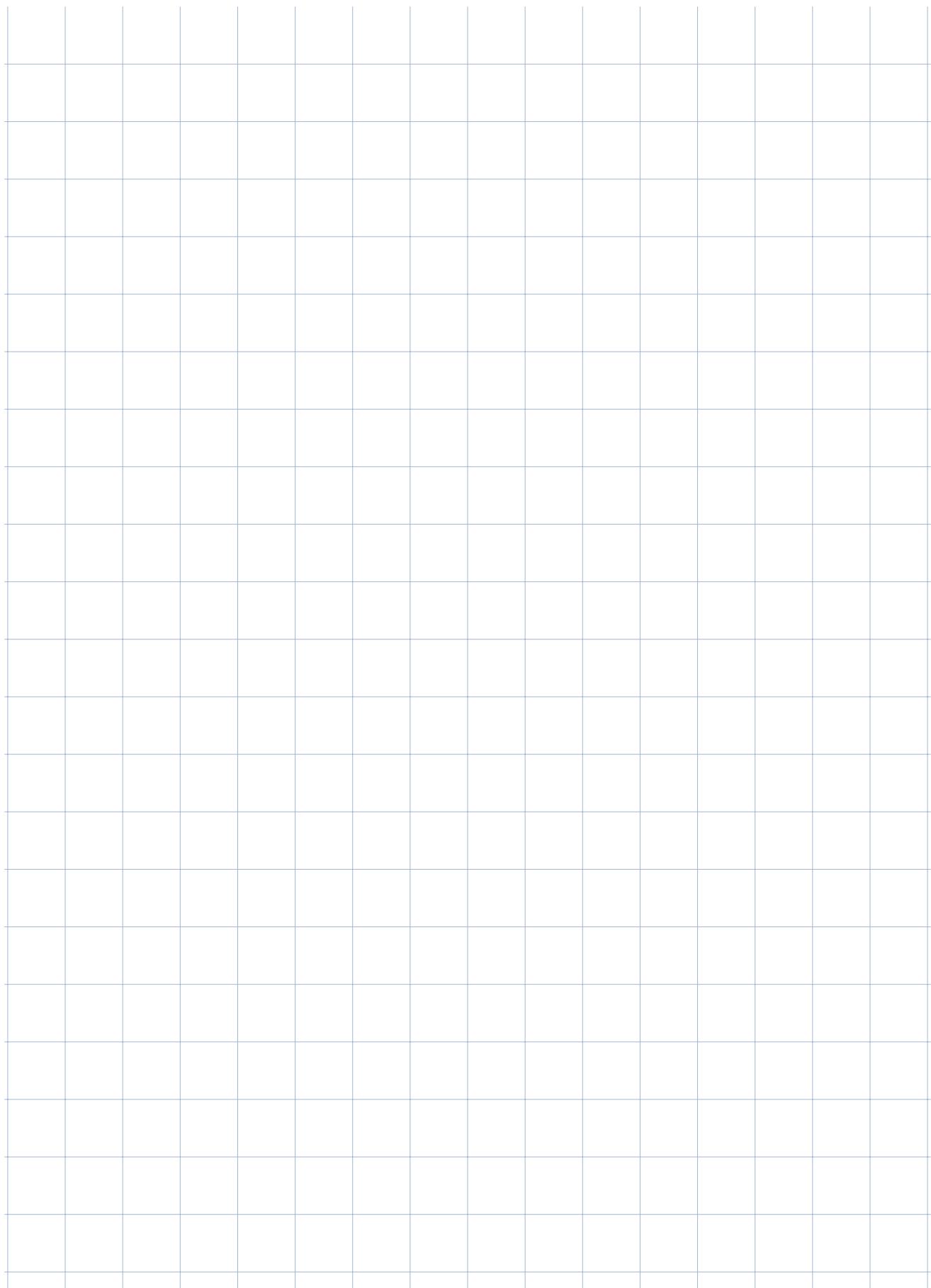
$$X_n \xrightarrow{P} 0$$

This will not converge almost surely. (To be done formally in the next class).

Q) When are they equivalent?

Theorem: Suppose that x_n is monotone (wlog $x_n \geq x_{n+1}$)

then $x_n \xrightarrow{P} x \Leftrightarrow x_n \xrightarrow{a.s.} x$



September 18

(Mid Term : Around Oct 21)

Properties of profit & supply functions

$$\Pi(p) = \max_{y \in Y} p \cdot y$$

$$y^*(p) = \arg \max_{y \in Y} p \cdot y$$

$$\Pi : \mathbb{R}^n \rightarrow \mathbb{R} \quad (\text{function})$$

$$y^* : \mathbb{R}^n \rightrightarrows \mathbb{R}^n \quad (\text{correspondence})$$

Note: results do not rely on regularity assumptions (convexity, differentiability etc.) unless stated differently.

i) $\Pi(p)$ is non-increasing in input prices and non-decreasing in output prices.

Proof: Take 2 price vectors p, p' and choose

$$y \in y^*(p) \text{ and } y' \in y^*(p')$$

Let $p'_i \geq p_i$ for all outputs, $p'_i \leq p_i$ for all inputs.

By WAPM; $p \cdot y' \geq p \cdot y$

$$\text{consider } (p' - p) \cdot y = (p_1' - p_1)y_1 + \dots + (p_n' - p_n)y_n$$

$$y_i \geq 0 : p'_i \geq p_i \quad y_i \leq 0 : p'_i \leq p_i$$

$$(p' - p) \cdot y \geq 0 \Rightarrow p \cdot y \geq p' \cdot y$$

$$\pi(p') = p' \cdot y^* \geq p \cdot y \geq p \cdot y = \pi(p)$$

$$\pi(p') \geq \pi(p)$$

② $\pi(p)$ is homogeneous of degree 1.

$$\text{WTS: } \pi(tp) = t\pi(p)$$

$$\text{Proof: } \pi(tp) = \max_{y \in \gamma} (tp) \cdot y$$

$$= \max_{y \in \gamma} t(p \cdot y)$$

$$= t \max_{y \in \gamma} p \cdot y$$

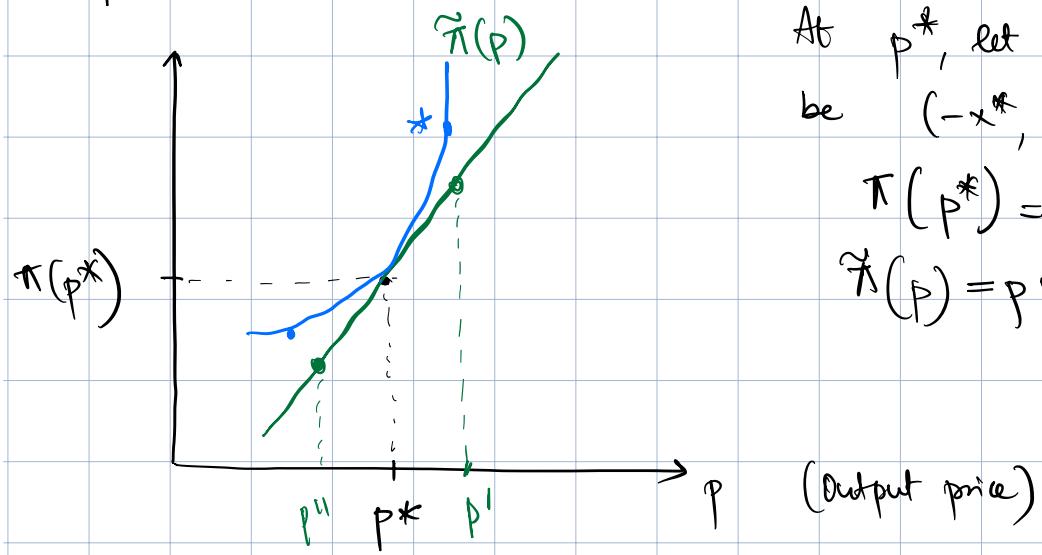
$$= t\pi(p)$$

③

$\pi(p)$ is convex in p

$$\text{i.e. } \pi(\alpha p + (1-\alpha)p') \leq \alpha \pi(p) + (1-\alpha)\pi(p')$$

Graphical intuition.



Single Output Case

At p^* , let optimal prod^u be $(-x^*, y^*)$

$$\pi(p^*) = p^* y^* - w^* x^*$$

$$\tilde{\pi}(p) = p y^* - w^* x^*$$

④ Re-optimized points. When the price changes, either the profit is on the tangent line or above it

If we do assume π is differentiable:

$$H(p) = D^2\pi(p) = \begin{bmatrix} \frac{\partial^2 \pi}{\partial p_1^2} & \dots & \frac{\partial^2 \pi}{\partial p_1 \partial p_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 \pi}{\partial p_n \partial p_1} & \dots & \frac{\partial^2 \pi}{\partial p_n^2} \end{bmatrix}$$

$\mathbf{D}^T \mathbf{D}(p)$ is positive semi-definite.

Properties of $y(p)$:-

(1) $y(p)$ is homogeneous of degree 0.

Proof:-

$$\max_{y \in \mathcal{Y}} (\alpha p) \cdot y$$
$$= \alpha \max_{y \in \mathcal{Y}} p \cdot y$$

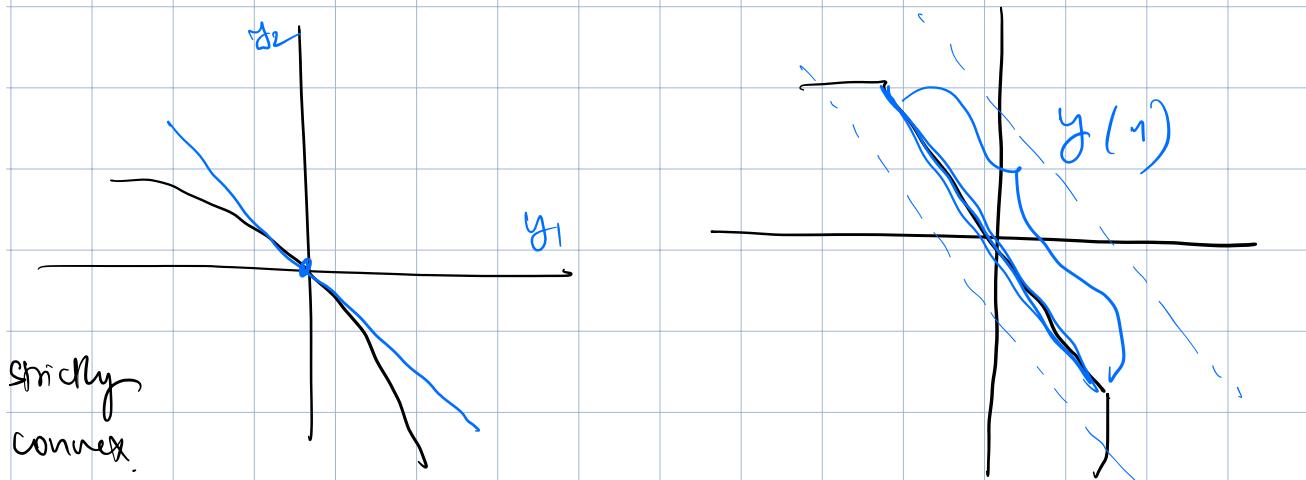
* includes both inputs & outputs whenever you see αp y .

(Scaling all the prices shouldn't change your optimal choices.)

(2) (a) If \mathcal{Y} is convex, then $y(p)$ is convex set.

(b) If \mathcal{Y} is strictly convex, then $y(p)$ is a singleton - (?).

Proof by graph: —



④ Envelope Theorem $\rightarrow V.$ imp.

Q: How does the optimal value of a maximization problem changes as a parameter changes?

$$\max_x f(x, \theta)$$

x : choice variable

θ : parameter eq. prices.

Define the value function $\rightarrow f^V$ of the parameters

$$V(\theta) = \max_x f(x, \theta)$$

[what is $\frac{dV}{d\theta}$?]

One way:

$$V(\theta) = f(x^*(\theta), \theta)$$

A change in θ has 2 effects :-

- Direct Effect : θ changes f directly through the second argument.
- Indirect Effect : θ changes x^* , which changes f .

$$\frac{dV}{d\theta} = \left. \frac{\partial f}{\partial x} \right|_{x=x^*(\theta)} + \left. \frac{\partial f}{\partial \theta} \right|_{x=x^*(\theta)}$$

$\Downarrow \theta \text{ as optimal}$
pr. (FOC)
evaluating at
optimal θ_p .

$$\therefore \frac{dV}{d\theta} = \left. \frac{\partial f}{\partial \theta} \right|_{x=x^*(\theta)}$$

- Found all over economics! -

- Hotelling's lemma
- Shephard's lemma
- Myerson's lemma
- Benveniste-Schocknon formula (Mars)

When there are constraints :

$$\max_x f(x, \theta)$$

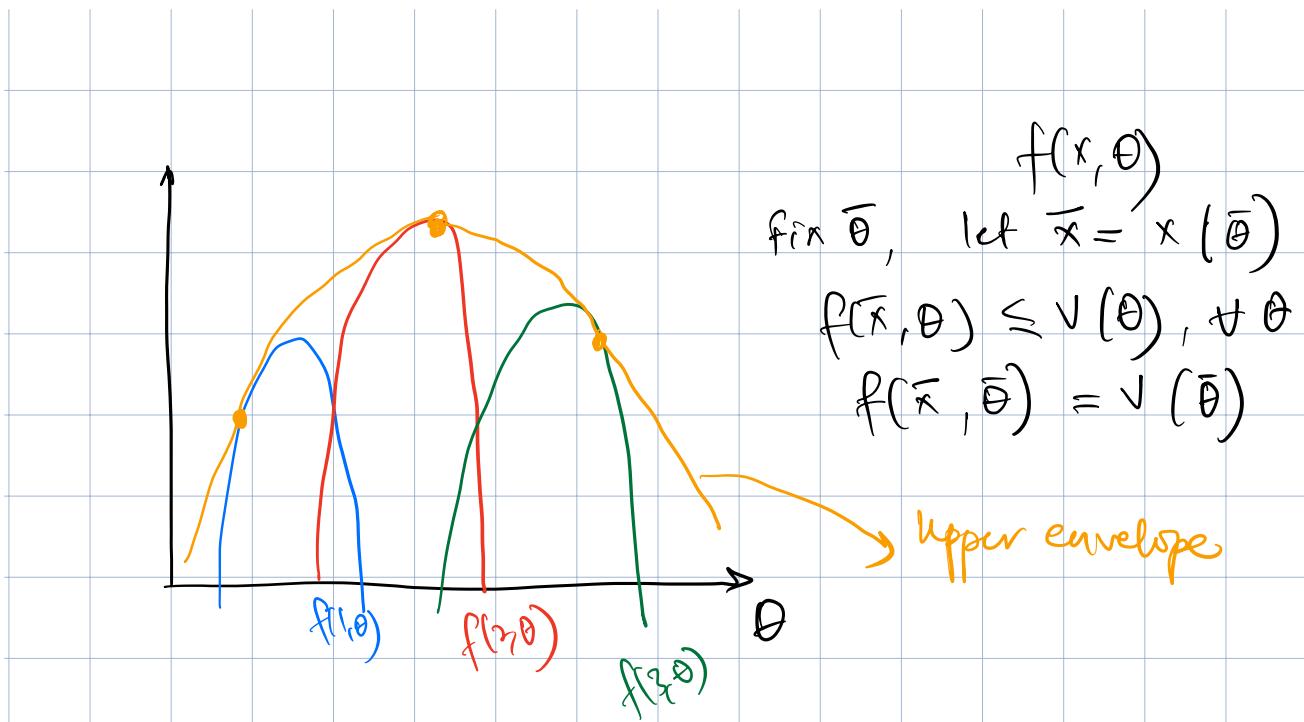
constraint

s.t. $g_r(x, \theta) \leq c_r$ for $r = 1, \dots, k$

$$\frac{\partial V}{\partial \theta} = \frac{\partial f}{\partial \theta} - \lambda_1 \frac{\partial g_1}{\partial \theta} - \dots - \lambda_k \frac{\partial g_k}{\partial \theta}$$

To remember: $\mathcal{L} = f(x, \theta) + \lambda_1(c_1 - g_1(x, \theta)) + \dots + \lambda_k(c_k - g_k(x, \theta))$

$$\frac{\partial V}{\partial \theta} = \frac{\partial \mathcal{L}}{\partial \theta}$$



Hotelling's Lemma :-

If $\Pi(p)$ is differentiable at \bar{p} , $\bar{p}_i > 0$, then

$$\frac{\partial \Pi(\bar{p})}{\partial p_i} = y_i(\bar{p})$$

Proof : Restrict to single output case.
(assume interior solⁿ)

$$\Pi(p, w) = \max_{x \geq 0} \underbrace{pf(x) - w_0 x}_{h(x)}$$

By the envelope theorem

$$\frac{d\Pi}{dp}(p, w) = \left. \frac{\partial h}{\partial p} \right|_{x=x^*(p, w)}$$

$$= f(x^*(p, w)) = y^*(p, w)$$

$$\frac{d\Pi}{dw_i} \leq \frac{\partial h}{\partial w_i} = -x_i \Big|_{x=x^*(p, w)} = -x_i^*(p, w)$$

Example 8

$$f(x_1, x_2) = 30x_1^{2/5}x_2^{2/5}$$

$$\max 30 p x_1^{2/5} x_2^{2/5} - w_1 x_1 - w_2 x_2$$

$$\text{FOCs } x_1 : 12 p x_1^{-3/5} x_2^{2/5} = w_1$$

$$12 p x_1^{2/5} x_2^{-3/5} = w_2$$

$$x_1^*(p, w) = \frac{12^5 p^5}{w_1^3 w_2^2}$$

$$x_2^*(p, w) = \frac{12^5 p^5}{w_1^2 w_2^3}$$

$$\pi(p, w) = 30 p \cdot \frac{12^4 p^4}{(w_1 w_2)^2} - \frac{12^5 p^5}{(w_1 w_2)^2} - \frac{12^5 p^5}{(w_1 w_2)^2}$$

$$= \frac{1}{2} \left[\frac{12^5 p^5}{w_1^2 w_2^2} \right]$$

To find x_1^*

$$\frac{\partial \pi}{\partial w_1} = -2 \left[\frac{12^5 p^5}{w_1^3 w_2^2} \right]$$

This is same as
(* *)

So envelope theorem gives
you a way to recover
 x_1^* .

(Recover supply from profit f^u)

④ Integral form of Hotelling's lemma

Hold all prices other than p_j fixed at

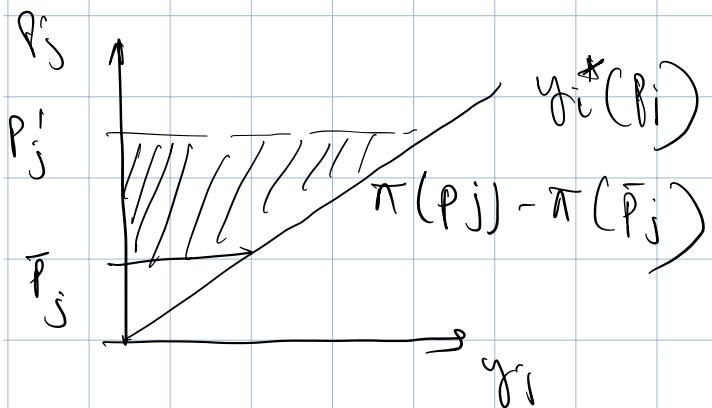
$$\bar{p}_{-j}.$$

$$\text{Then, } \pi(p_j, \bar{p}_{-j}) - \pi(\bar{p}_j, \bar{p}_{-j}) = \int_{\bar{p}_j}^{p_j} y_i(s, \bar{p}_{-j}) ds$$

By original notching:

$$\int_{\bar{p}_j}^{p_j} y_j(s, \bar{p}_{-j}) ds = \int_{\bar{p}_j}^{p_j} \frac{d\pi(s, \bar{p}_{-j})}{dp_j} \cdot ds$$

$$= \pi(p_j, \bar{p}_{-j}) - \pi(\bar{p}_j, \bar{p}_{-j})$$



September 20

Hotelling's lemma:

$$\frac{\partial \pi}{\partial p_i} = y_i(p)$$

$Dy(p)$ = $\begin{bmatrix} \frac{\partial y_1}{\partial p_1} & \dots & \frac{\partial y_n}{\partial p_1} \\ \vdots & \ddots & \vdots \\ \frac{\partial y_1}{\partial p_n} & \dots & \frac{\partial y_n}{\partial p_n} \end{bmatrix}$

(Jacobian)
Substitution
matrix
↳ In vector

$$\frac{\partial y_i(p)}{\partial p_j} = \frac{\partial^2 \pi}{\partial p_j \partial p_i}$$

$$Dy(p) \begin{bmatrix} \frac{\partial^2 \pi}{\partial p_1^2} & \dots & \frac{\partial^2 \pi}{\partial p_1 \partial p_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 \pi}{\partial p_n \partial p_1} & \dots & \frac{\partial^2 \pi}{\partial p_n^2} \end{bmatrix}$$

This matrix is positive semi-definite.

This implies:-

$$\textcircled{1} \quad \frac{\partial y_i}{\partial p_i} = \frac{\partial^2 \pi}{\partial p_i^2} \geq 0 \quad (\text{Law of Supply})$$

$$\textcircled{2} \quad \frac{\partial y_i}{\partial p_j} = \frac{\partial^2 \pi}{\partial p_i \cdot \partial p_j} = \frac{\partial^2 \pi}{\partial p_i \partial p_j} = \frac{\partial y_i}{\partial p_i}$$

Substitution matrix is symmetric. (Not intuitive \Rightarrow math shows this.)

Le Chatelier Principle

"Firms should respond more to price changes in the long run than the short run."

All the inputs are variable.

↳ Some inputs are fixed
(factory, contracts etc.)

Suppose, (y^*, x^*) (single input model)
 $= (y(p^*, w^*), x(p^*, w^*))$
at price (p^*, w^*)

lets fix one input z_i^* in the short run variable
in the long run.

z_i^* is optimal at (p^*, w^*)

Q: How does x_j depend on w_j in the short vs.
the long run?

$$\Pi(p, w) = \max p f(x) - w \cdot x \text{ s.t. } x_j \geq 0$$

$$\frac{\partial x_j(p, w)}{\partial w_j} \quad \Big| \quad (p, w) = (p^*, w^*)$$

$$\pi^s(p, w) = \max p f(x) - w \cdot x$$

st. $x_j \geq 0$
 $x_i = z_i^*$

$$\left. \frac{\partial x_j^s(p, w)}{\partial w_j} \right|_{(p, w) = (p^*, w^*)}$$

$$\text{let } h(p, w) = \pi(p, w) - \pi^s(p, w)$$

Profit in the LH
 always have to be
 greater than in SR
 as more constant
 can only reduce

By def., $h(p, w) \geq 0$ & $h(p^*, w^*) = 0$
 (p^*, w^*) is a local minima.

$$\Rightarrow \frac{\partial^2 h(p^*, w^*)}{\partial w_j^2} \geq 0$$

{ Diagonal elements of
 Hessian matrix
 has to be non-negative for
 locally convex. }

$$\frac{\partial^2 \pi(p^*, w^*)}{\partial w_j^2} - \frac{\partial^2 \pi^s(p^*, w^*)}{\partial w_j^2} \geq 0$$

$$\text{Hotelling: } \frac{\partial \pi(p, w)}{\partial w_j} = -x_j(p, w)$$

$$-\frac{\partial x_j(p^*, w^*)}{\partial w_j} + \frac{\partial x_j^c(p^*, w^*)}{\partial w_j} \geq 0$$

These are negative
so when we take
absolute values
we flip the signs.

$$\left| \frac{\partial x_j^c(p^*, w^*)}{\partial w_j} \right| \leq \left| \frac{\partial x_j(p^*, w^*)}{\partial w_j} \right|$$

~~Cost Minimization~~

- Single output good firm.
 - Pricing power in output market, but not input markets.
 - Previous analysis does not work but we can do the following: —
- (1) Find the cheapest way to make any target output y .
 (2) Use the "cost function" $c(y)$ to choose optimal p/y combination.
- cost minimization problem.

CMP (Cost Minimization Problem) :-

- Fix a target level of output y .

$$c(w, y) = \min_x w \cdot x \quad \text{s.t.} \\ x_i \geq 0 \\ f(x) \geq y$$

↓
parameters

Ignore non-negativity for now! —

$$L = w \cdot x - \lambda (f(x) - y)$$

FOC:

$$w_i - \lambda \frac{\partial f}{\partial x_i} = 0$$

or

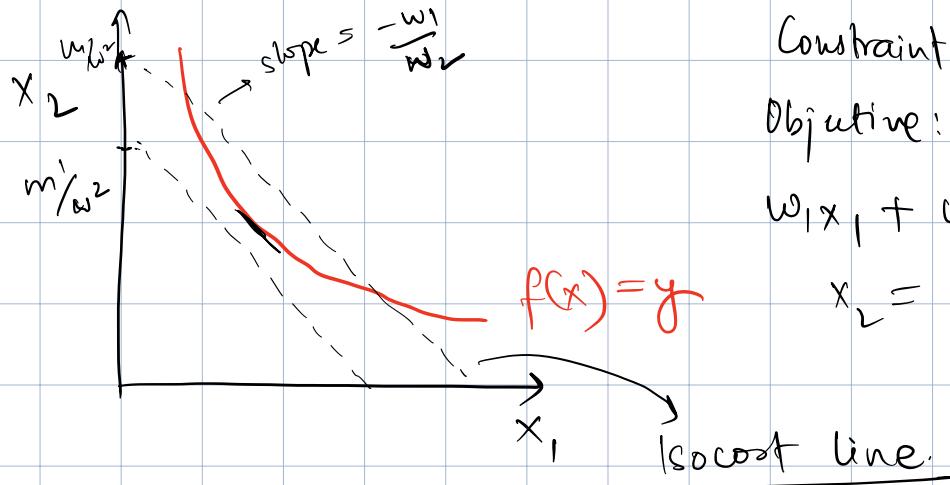
$$w_i = \lambda \frac{\partial f}{\partial x_i} + \sigma_i$$

Divide i by j

$$\frac{w_i}{w_j} = \frac{\frac{\partial f}{\partial x_i}}{\frac{\partial f}{\partial x_j}} \quad (\text{for } x_i^*, x_j^* > 0)$$

↓
Economic
rate of
substitution

MRTS



Constraint: Isoquant

Objective: Isocost

$$w_1x_1 + w_2x_2 = m$$

$$x_2 = \frac{m}{w_2} - \frac{w_1}{w_2}x_1$$

Isocost line.

The slope remains the same

Looking for tangency as the optimal point.

$x^*(w, y)$ conditional factor demand correspondence

$$c(w, y) = w \cdot x^*(w, y) = \min_{\substack{\text{st.} \\ x_i \geq 0 \\ f(x) \geq y}} w \cdot x$$

Envelope Theorem $\frac{dV}{d\theta} = \frac{\partial L}{\partial \theta}$

Here set $V=C$, $\theta=y$

$$\frac{\partial C}{\partial y} = \frac{\partial L}{\partial y}$$

$$\boxed{\frac{\partial C}{\partial y} = \lambda}$$

$\Rightarrow \lambda$ is the marginal cost of increasing "prod" by one unit.

"Shadow Prices" \rightarrow Cost of tightening the constraint.
 $[f(x) \geq y]$

Relationship with
 Profit Maximization Problem (PMP)

$$\max_{y \geq 0} py - c(w, y)$$

$$\text{FOC: } p = \frac{\partial c}{\partial y} = (\lambda \text{ from CMP})$$

Things to keep in mind :-

- We have assumed a differentiable f , interior solutions.
 - General FOCs :
- $$\frac{\partial f(x^*)}{\partial x_i} - w_i \leq 0 \quad \forall i,$$
- with equality if $x_i^* > 0$.
- KT conditions are necessary but not sufficient in general.
 They will be sufficient if $f(x)$ is ^{→ prod} concave.
 - Existence / uniqueness issues.

Weak Axiom of Cost Minimization (WACM)

$$\{(w^t, x^t, y^t), \dots, (w^s, x^s, y^s)\}$$

WACM:

- what you did.
- $w^t \cdot x^t \leq w^s \cdot x^s$ could have done
for all $y^s \geq y^t$.
- the cost you paid in a month
- Produced what you needed to produce in that month.
- Any firm that violates WACM is "irrational" / are not minimizing costs.
 - If it should be less than any other cost plan for that month.
- If WACM does not hold \Rightarrow you are not cost minimizing.

Implication of WACM: — downward sloping demand.

Take $y^s = y^t$, WACM gives 2 inequalities

$$① w^t \cdot x^t \leq w^s \cdot x^s$$

$$② w^s \cdot x^s \leq w^t \cdot x^t$$

$$\text{Add } ① \text{ & } ② \quad w^t \cdot x^t + w^s \cdot x^s \leq w^s \cdot x^s + w^t \cdot x^t$$

$$\Rightarrow w^t \cdot x^t + w^s \cdot x^s - w^s \cdot x^s - w^t \cdot x^t \leq 0$$

$$\Rightarrow (w^t - w^s) \cdot (x^t - x^s) \leq 0$$

$$\Delta w \cdot \Delta x \leq 0$$

(Talks about vector of price changes & not just a price change)

$$c(w, y) = \min_{\mathbf{x}} w \cdot \mathbf{x}$$

s.t. $f(\mathbf{x}) \geq y$

(1) $c(w, y)$ is non decreasing in w .

Proof: Take $w' \geq w$ b/c $\mathbf{x} \in x^*(w, y)$, $\mathbf{x}' \in x^*(w', y)$

$$c(w, y) = w \cdot \mathbf{x} \leq w \cdot \mathbf{x}' \leq w' \cdot \mathbf{x}' = c(w', y)$$

\downarrow
WACM.

$w' > w$

$$\Rightarrow c(w, y) \leq c(w', y)$$

(2) $c(w, y)$ is non decreasing in y

Let $y'' \geq y'$, $\mathbf{x}' \in x^*(w, y')$, $\mathbf{x}'' \in x^*(w, y'')$

$$c(w, y') = \min_{\mathbf{x}} w \cdot \mathbf{x} = w \cdot \mathbf{x}' \leq w \cdot \mathbf{x}''$$

s.t.
 $f(\mathbf{x}) \geq y'$

\downarrow
WACM

$\Rightarrow \min_{\mathbf{x}} w \cdot \mathbf{x} = c(w, y'')$

s.t.
 $f(\mathbf{x}) \geq y''$

Inequality works because $f(x'') \geq y'' \geq y'$.

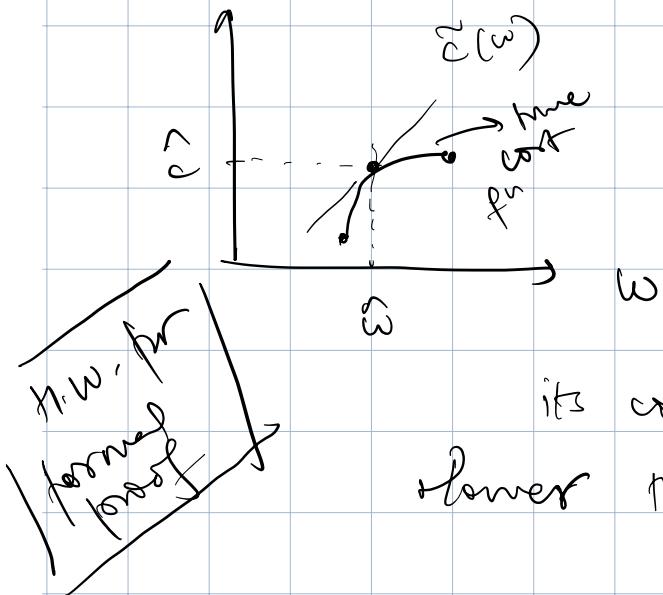
(3) $c(w, y)$ is $hd-1$ in w .

$$\Leftrightarrow c(tw, y) = tc(w, y)$$

NOT true
for y

(4) $c(w, y)$ is concave in w .

{ Proof is same as that of the π
maximization being convex. }



when price increases, costs increase
linearly & vice versa.

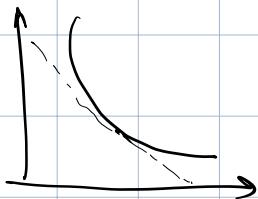
↓
don't let the firm respond.

When the firm responds;
its cost would be equal or
lower than the $\hat{c}(w)$.

X.W. for
formed profit

(5) If $v(y)$ is convex, then $x^*(w, y)$ is convex valued.

If $v(y)$ is strictly convex, then $x^*(w, y)$ is single-valued.



(6) $x^*(w, y)$ is hd-0 in w .

$x^*(tw, y) = x^*(w, y)$ } Relative prices of the 2 goods are the same.

Implication :- (Looking for one good)

$$x_i^*(t, w, y) = x_i^*(w, y)$$

Differentiate wrt t , eval $\big|_{t=1}$.

$$\nabla_w x_i^*(tw, y) \cdot w = 0$$

$$\sum_{j=1}^n \underbrace{\frac{\partial x_i^*(tw, y)}{\partial w_j}}_{\partial w_j} \cdot w_j = 0$$

We know : $\frac{\partial x_i^*}{\partial w_i} \leq 0$

Say $n=2$

$$\frac{\partial x_i^*}{\partial w_i} \underset{\text{negative}}{\cancel{w_1}} + \frac{\partial x_j^*}{\partial w_2} \underset{\text{positive}}{\cancel{w_2}} = 0$$

$\frac{\partial x_1^*}{\partial w_2} \geq 0$: goods 1 & 2 are substitutes.

If $n > 2$, then $\frac{\partial x_i^*}{\partial w_j} \geq 0$ for some good j .

(*) Shephard's Lemma

If $c(w, y)$ is differentiable, and $\bar{w} > 0$, then:

$$x_i(\bar{w}, y) = \frac{\partial c(\bar{w}, y)}{\partial w_i}$$

Proof 1: Envelope Theorem

$$\mathcal{L} = w \cdot x - \lambda (f(x) - y)$$

$$\frac{\partial c(w, y)}{\partial w_i} = \left. \frac{\partial \mathcal{L}}{\partial w_i} \right|_{x=x^*(w, y)}$$

$$\boxed{\frac{\partial c}{\partial w_i} = x_i^*(w, y)}$$

~~Proof 2:~~ $C(w, y) = w \cdot x^*(w, y)$

$$\textcircled{*} \quad \frac{\partial C}{\partial w_i} = x_i^*(w, y) + \sum_{j=1}^n w_j \frac{\partial x_j^*(w, y)}{\partial w_i}$$

Recall the FOCs of CMP:—

$$\textcircled{1} \quad \lambda \frac{\partial f}{\partial x_i} = w_i$$

$$\textcircled{2} \quad f(x^*(w, y)) = y$$

let's differentiate $\textcircled{2}$ w.r.t w_i :

$$\sum_{j=1}^n \frac{\partial f}{\partial x_j} \frac{\partial x_j^*}{\partial w_i} = 0$$

let's plug $\textcircled{1}$ into $\textcircled{*}$

$$\frac{\partial C}{\partial w_i} = x_i^*(w, y) + \sum_{j=1}^n \lambda \frac{\partial f}{\partial x_j} \frac{\partial x_j^*}{\partial w_i} = 0$$

$$\boxed{\frac{\partial C}{\partial w_i} = x_i^*(w, y)}$$

Substitution Matrix:

$$\begin{bmatrix} \frac{\partial x_i^*}{\partial w_1} & \cdots & \frac{\partial x_i^*}{\partial w_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial x_n^*}{\partial w_1} & \cdots & \frac{\partial x_n^*}{\partial w_n} \end{bmatrix} = \begin{bmatrix} \frac{\partial^2 c}{\partial w_1^2} & \cdots & \frac{\partial^2 c}{\partial w_1 \partial w_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial^2 c}{\partial w_n \partial w_1} & \cdots & \frac{\partial^2 c}{\partial w_n^2} \end{bmatrix}$$

Hessian of c which is concave.

* Law of Demand : $\frac{\partial x_i^*}{\partial w_j} \leq 0 \quad \forall i$ Diagonal elements of Hessian matrix of concave f^n is negative!

* Symmetric cross-price effects

$$\frac{\partial x_i^*}{\partial w_j} = \frac{\partial x_j^*}{\partial w_i}$$

Theorem : If f is CRS, then $c(w, y) = y c(w, 1)$

unit cost of f^n

Proof :-

Assume f is differentiable, interior solution

POCs at $y = 1$.

$$\frac{w_i}{w_j} = \frac{F_i(x^*)}{F_j(x^*)} \quad \text{and} \quad F(x^*) = 1$$

For general \hat{y} :

$$\frac{w_j}{w_i} = \frac{f_i(\hat{x})}{f_i(\hat{x}_j)} \quad f(\hat{x}) = \hat{y}$$

Consider inputs $\hat{x} = \hat{y} x^*$

claim: \hat{x} solves the FOCs at \hat{y} .

$$\frac{f_i(\hat{x})}{f_f(\hat{x})} = \frac{f_i(\hat{y} x^*)}{f_j(\hat{y} x^*)} = \frac{f_i(x^*)}{f_j(x^*)} = \frac{w_i}{w_j}$$

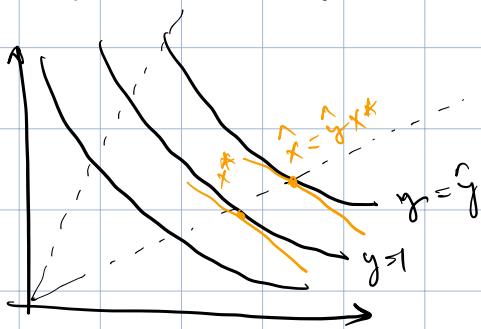
CRS

$$f(\hat{y} x^*) = \hat{y} \quad f(x^*) = \hat{y}$$

by CRS.

so, $\hat{x} = \hat{y} x^*$ solves the problem at target output \hat{y} .

$$c(w, \hat{y}) = w \cdot (\hat{y} x^*) = \hat{y} (w \cdot x^*) = \hat{y} c(w, 1)$$



The slope of the tangent lines are the same.