

ECON 7710
Econometrics I
Lecture notes 3.

Extremum estimation:

- Object of extremum estimation
 - Parameter of interest: $\theta \in \Theta \subset \mathbb{R}^p$
 - Work with convex compacts (usually)
 - Structural variable Y w. realizations y
 - Economic model $Y \sim F(\cdot, \theta)$
 - “True” DGP corresponds to $\theta = \theta_0 \in \text{int}(\Theta)$
 - Function $Q(\theta) = E_{\theta_0}[g(Y, \theta)] = \int g(y, \theta) F(dy, \theta_0)$
 - Note: integrate against true distribution
 - Extremum estimation:

$$\theta_0 = \operatorname{argmax}_{\theta \in \Theta} Q(\theta)$$

- So far we don’t know where $g(\cdot)$ is coming from
- Example (OLS)

- Observable structural variables W, X
 - Dgp

$$W = X'\theta + \varepsilon$$

- $E[\varepsilon] = 0, E[\varepsilon^2] = \sigma^2$
 - $g(w, x; \theta) = \varepsilon^2 = (w - x'\theta)^2$
 - $Q(\theta) = E[(w - x'\theta)^2]$
 - Computing true expectation is not feasible

- Why? The distribution $F(\cdot)$ is not known (because θ_0 is not known!)
- So, somehow, need to approximate expectation $E_{\theta_0}[\cdot]$ without knowing the true parameter
- Have sample y_1, \dots, y_T (i.i.d.)
- Note: $\frac{1}{T} \sum_{t=1}^T y_t \xrightarrow{p} E_{\theta_0}[Y]$
- This seems to give a solution!

- **Analogy principle**

- Use sample analog to approximate expectation:

$$\hat{Q}(\theta) = \frac{1}{T} \sum_{t=1}^T g(y_t; \theta) \equiv E_T[g(Y; \theta)]$$

- Define sample analog

$$\hat{\theta} = \operatorname{argmax}_{\theta \in \Theta} \hat{Q}(\theta)$$

- How close is $\hat{\theta}$ to θ_0 ?
- Note that have two pieces: function of θ and approximation of expectation by sample sum
- Need convergence concept to see approach of $\hat{\theta}$ to θ_0

- **Definition:** Let $\{Q_T(\theta)\}_{T=1}^\infty$ -non-negative sequence of random functions. Then if

- (i) $\Pr \left(\lim_{T \rightarrow \infty} \sup_{\theta \in \Theta} Q_T(\theta) = 0 \right) = 1$ then $Q_T(\theta)$ converges to 0 a.s. uniformly in θ
- (ii) For any $\varepsilon > 0$ $\lim_{T \rightarrow \infty} \Pr \left(\sup_{\theta \in \Theta} Q_T(\theta) < \varepsilon \right) = 1$ then $Q_T(\theta)$ converges to 0 in probability uniformly in θ

- **Theorem:** Assume that

- (a) Θ is compact
- (b) $\hat{Q}_T(\theta)$ is continuous in Θ
- (c) $\hat{Q}_T(\theta)$ converges in probability to $Q(\theta)$ uniformly in Θ

- (d) $Q(\cdot)$ attains a unique global maximum at θ_0 (identification)

Then if $\hat{\theta} = \operatorname{argmax}_{\theta \in \Theta} \hat{Q}_T(\theta)$ then $\hat{\theta} \xrightarrow{p} \theta_0$

- Example (NLLS)

- $W = m(X, \theta) + \varepsilon$, function $m(\cdot)$ is known
- $m(\cdot)$ is twice differentiable in θ
- Conditions $E[\varepsilon] = 0$, and $E[\varepsilon^2] < \infty$
- Objective $Q(\theta) = E \left[(W - m(X, \theta))^2 \right]$
- Identification (local): necessary and sufficient conditions for minimum are satisfied
- Necessary condition: $\frac{\partial}{\partial \theta} Q(\theta_0) = 0$
- $Q(\theta) = \int \int (w - m(x, \theta))^2 f(w, x; \theta_0) dw dx$
- FOC:

$$\frac{\partial}{\partial \theta} Q(\theta_0) = -2 \int \int (w - m(x, \theta)) \frac{\partial m}{\partial \theta} f(w, x; \theta_0) dw dx$$

- SOC:

$$\frac{\partial^2}{\partial \theta^2} Q(\theta_0) = -2 \int \int \left[(w - m(x, \theta)) \frac{\partial^2 m}{\partial \theta^2} \right. \quad (1)$$

$$\left. - \left(\frac{\partial m}{\partial \theta} \right)^2 \right] f(w, x; \theta_0) dw dx \quad (2)$$

$$(3)$$

- Identification condition:

- * Equation $E \left[(w - m(x, \theta)) \frac{\partial m}{\partial \theta} \right] = 0$ has a unique solution

- * OR $E \left[(w - m(x, \theta)) \frac{\partial^2 m}{\partial \theta^2} - \left(\frac{\partial m}{\partial \theta} \right)^2 \right] < 0$

at point θ_0

- Sample analog $\hat{Q}(\theta) = \frac{1}{T} \sum_{t=1}^T (w_t - m(x_t, \theta))^2$
- Verify conditions of theorem?
- (a) and (b) are satisfied automatically

- (d) is satisfied if SOC holds
- (c) can be tricky
- Rough idea to prove uniform convergence is to slice the parameter space and show convergence in slices
- Very tedious. In the rest of the course we just assume uniformity
- In real problems have pre-packaged results (HE)
- From our Theorem conclude that minimizer of sample NLLS will converge to population NLLS
- Turns out that can also provide asymptotic results
- Asymptotic distribution

– Mean-value expansion: main work tool!

– From FOC

$$\frac{\partial \hat{Q}(\hat{\theta})}{\partial \theta} = 0$$

– Mean-value expansion at θ_0

$$\frac{\partial \hat{Q}(\theta_0)}{\partial \theta} + \frac{\partial^2 \hat{Q}(\theta^*)}{\partial \theta^2}(\hat{\theta} - \theta_0)$$

– Know that $\frac{\partial Q(\theta_0)}{\partial \theta} = 0$

– $\sqrt{T} \frac{\partial \hat{Q}(\theta_0)}{\partial \theta} = \frac{1}{\sqrt{T}} \sum_{t=1}^T \frac{\partial g(y_t; \theta_0)}{\partial \theta}$

– CLT

$$\frac{1}{\sqrt{T}} \frac{\partial g(y_t; \theta_0)}{\partial \theta} \xrightarrow{d} N(0, \Sigma)$$

– LLN and continuous mapping

$$\frac{\partial^2 \hat{Q}(\theta^*)}{\partial \theta^2} \xrightarrow{p} \frac{\partial^2 Q(\theta_0)}{\partial \theta^2}$$

– $\hat{\theta} - \theta_0$ - asymptotically normal

- **Theorem:** Assume (a)-(d) in the previous theorem and

- (e) $\frac{\partial^2 \widehat{Q}}{\partial \theta \partial \theta'}$ exists in the neighborhood of θ_0
- (f) $\frac{\partial^2 \widehat{Q}(\theta_T)}{\partial \theta \partial \theta'} \xrightarrow{p} A(\theta_0)$ for any $\theta_T \xrightarrow{p} \theta_0$
- (g) $\sqrt{T} \frac{\partial \widehat{Q}(\theta_0)}{\partial \theta} \xrightarrow{d} N(0, B(\theta_0))$

Then if $\hat{\theta}$ solves FOC, then

$$\sqrt{T}(\hat{\theta} - \theta_0) \xrightarrow{d} N(0, A(\theta_0)^{-1'} B(\theta_0) A(\theta_0)^{-1})$$

Maximum likelihood:

- MLE assumptions

- $Y \sim F(\cdot, \theta_0)$
- y_t are i.i.d.
- $F(\cdot, \theta)$ is parametrized by $\theta \in \Theta \subset \mathbb{R}^p$
- Distribution $F(\cdot, \theta)$ is dictated by our economic model (examples below)

- MLE objective

- “Single observation” likelihood function: density of Y
- Log-likelihood of single observation: $l(Y, \theta) = \log f(Y, \theta)$
- Population objective function

$$L(\theta) = E_{\theta_0} [\log f(Y, \theta)] = \int \log f(y, \theta) f(y, \theta_0) dy$$

- Search to maximize this objective

- MLE as “distance” minimization

- Consider objective $-L(\theta) = E_{\theta_0} [-\log f(Y, \theta)]$
- This needs to be minimized
- Now consider **constant**: $E_{\theta_0} [\log f(Y, \theta_0)]$ (fixed function integrated against fixed distribution)

- Define objective:

$$KL(\theta) = E_{\theta_0} [\log f(Y, \theta_0)] - L(\theta) = E_{\theta_0} \left[\log \frac{f(Y, \theta_0)}{f(Y, \theta)} \right]$$

- This is called Lullback-Leibler information (KLIC)
- This is “distance” between true and estimated distributions that we minimize
- Not true distance because it is asymmetric

- Sample analogs

- KL cannot be used for estimation directly because θ_0 (and $f(Y, \theta_0)$) are unknown
- As before, use sample analog $\frac{1}{T} \sum_{t=1}^T$ to approximate expectation
- Construct sample log-likelihood function

$$\hat{L}(\theta) = \frac{1}{T} \sum_{t=1}^T \log f(y_t, \theta)$$

- Find sample analog estimate

- Example: Linear regression

- $W = X'\beta + \varepsilon, \varepsilon \sim N(0, \sigma^2)$
- $\theta = (\beta, \sigma^2)$
- Conditional density of dependent variable

$$f(W | x; \beta, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(w - x'\theta)}{2\sigma^2}\right)$$

- Log-likelihood in the sample

$$\hat{L}(\beta, \sigma^2) = -\frac{T}{2} \log(2\pi\sigma^2) - \frac{(w - x'\theta)}{2\sigma^2}$$

- Example: Discrete choice

- Unobserved utility: $W = X'\beta + \varepsilon, \varepsilon \sim N(0, \sigma^2)$

- Make choice if utility is positive

$$D = \mathbf{1}\{W > 0\}$$

- Observe D and X : choices and covariates
- Now estimate only one parameter β (soon we will see why!)
- Conditional distribution of outcome is discrete:

$$\Pr(D = 1 \mid X = x, \beta) = P(x'\beta + \varepsilon > 0) = 1 - \Phi(-x'\beta) = \Phi(x'\beta)$$

- Make choice if utility is positive

$$D = \mathbf{1}\{W > 0\}$$

- Observe D and X : choices and covariates
- Now estimate only one parameter β (soon we will see why!)
- Log-likelihood in the sample

$$\hat{L}(\beta) = \sum_{t=1}^T d_t \log \Phi(x'_t \beta) + (1 - d_t) \log (1 - \Phi(x'_t \beta))$$

- **Definition:** The likelihood function of a random variable Y with density $f(\cdot, \theta)$ is a function of parameter θ : $l(\theta; y) = f(y, \theta)$

Log-likelihood function: $L(\theta; y) = \log l(\theta; y)$

Conditional likelihood: $l(\theta; w|z) = f(w, \theta|z)$

- For discrete distribution, use the pmf instead of pdf
- Likelihood function is function of parameters, provided the sample
- Interpretation: Maximize the probability of observing a given sample of data

- **MLE assumptions**

- $Y \sim f(\cdot, \theta_0)$, i.i.d., $\theta \in \Theta$ - convex compact set
- $E \left\{ \sup_{\theta \in \Theta} |\log f(Y, \theta)| \right\} < \infty$ (Note: expectation is taken wrt to $f(\cdot, \theta_0)$)

– $-\log f(y_t, \theta)$ is continuous in θ

• **Lemma:** $E[\log f(Y, \theta)] \leq E[\log f(Y, \theta_0)]$

• *Proof:* For concave $h(\cdot)$: $E[h(Y)] \leq h(E[Y])$. As a result:

$$E\left[\log \frac{f(Y, \theta)}{f(Y, \theta_0)}\right] \leq \log E\left[\frac{f(Y, \theta)}{f(Y, \theta_0)}\right].$$

Note $E\left[\frac{f(Y, \theta)}{f(Y, \theta_0)}\right] = \int \frac{f(y, \theta)}{f(y, \theta_0)} f(y, \theta_0) dy = 1$ Thus $E\left[\log \frac{f(Y, \theta)}{f(Y, \theta_0)}\right] \leq 0$. This proves the lemma

• Takeaway points

- Population log-likelihood takes the highest value at true parameter value
- This justifies why we focus on maximum likelihood
- KLIC is always non-negative
- We would also prefer that KLIC=0 if and only if $\theta = \theta_0$
- This is actually required for identification!

• Dependence on support

- Condition that $E\left\{\sup_{\theta \in \Theta} |\log f(Y, \theta)|\right\} < \infty$ is very important
- This condition is violated when support of $f(\cdot)$ depends on θ
- This could be bad: violated in case of uniform distribution
- This case is called “superconsistent” MLE case

• Example

– Exponential distribution

$$f(y, \theta) = \begin{cases} 0, & \text{if } y < \theta, \\ \exp(-(y - \theta)), & \text{if } y \geq \theta. \end{cases}$$

– Leads to log-likelihood

$$\log f(y, \theta) = \begin{cases} -\infty, & \text{if } y < \theta, \\ -(y - \theta), & \text{if } y \geq \theta. \end{cases}$$

- $\sup_{\theta \in \Theta} |\log f(y, \theta)| \rightarrow +\infty$
- Our assumption is violated
- Possible solution: pick the parameter space $\Theta = (-\infty, \theta_0]$
- Then $E \left\{ \sup_{\theta \leq \theta_0} |\log f(Y, \theta)| \right\} < \infty$
- Not feasible: don't know θ_0 !

• **Definition:**

- (i) Population likelihood function $L(\theta) = E [\log f(Y, \theta)]$
- (ii) Sample likelihood function (for i.i.d. data) $\hat{L}(\theta) = \frac{1}{T} \sum_{t=1}^T \log f(y_t, \theta)$
- (iii) Maximum likelihood estimator $\hat{\theta}_{MLE} = \operatorname{argmax}_{\theta \in \Theta} \hat{L}(\theta)$

• **Example: Discrete choice model**

- $W = X'\beta + \varepsilon, \varepsilon \sim N(0, 1)$
- $D = \mathbf{1}\{W > 0\}$
- $P(D = d|x) = \Phi(x'\beta)^d (1 - \Phi(x'\beta))^{1-d}$
- Conditional log-likelihood (one element)

$$\log P(D = d|x) = d \log \Phi(x'\beta) + (1 - d) \log (1 - \Phi(x'\beta))$$

- For full likelihood: need also density of X : $f_X(\cdot)$ (assume known)
- Full likelihood is separable in X and D distributions
- Population conditional log-likelihood

$$L(\theta|x) = E [\log P(D = d|x) | x]$$

- Thus

$$L(\theta|x) = \Phi(x'\beta) \log \Phi(x'\beta) + (1 - \Phi(x'\beta)) \log (1 - \Phi(x'\beta))$$

- Full likelihood

$$L(\theta) = E [\Phi(X'\beta) \log \Phi(X'\beta) + (1 - \Phi(X'\beta)) \log (1 - \Phi(X'\beta))]$$

- Sample log-likelihood function

$$\widehat{L}(\theta) = \frac{1}{T} \sum_{t=1}^T d_t \log \Phi(x'_t \beta) + (1 - d_t) \log (1 - \Phi(x'_t \beta))$$

- Maximization requires that FOC is satisfied

$$\frac{\partial \widehat{L}(\theta)}{\partial \theta} = \frac{1}{T} \sum_{t=1}^T \frac{d_t - \Phi(x'_t \beta)}{\Phi(x'_t \beta) (1 - \Phi(x'_t \beta))} \phi(x'_t \beta) x_t = 0.$$

- Log-likelihood function is globally concave, thus the MLE estimator is a unique maximizer

- **Definition:** Suppose that $Y \sim f(\cdot, \theta_0)$ are i.i.d. and $\theta \in \Theta$. Then parameter θ_0 is not identified if there exists θ^* such that $\theta^* \neq \theta_0$ and $L(\theta_0) = E[\log f(Y, \theta_0)] = L(\theta^*) = E[\log f(Y, \theta^*)]$

- Identification

- Note that we don't need $f(y, \theta_0) \equiv f(y, \theta^*)$ for lack of identification
- Provided that our information is coming from distribution, cannot distinguish parameters and functions that lead to the same result on different distributions
- Non-identification in the sense of previous definition is sometimes called global non-identification
- Natural definition of identification
- Parameter θ_0 is identified in Θ if for all $\theta \in \Theta$ and $\theta \neq \theta_0$

$$\Pr \{ \log f(Y, \theta_0) \neq \log f(Y, \theta^*) \} > 0$$

- Example: discrete choice model

- $W = X'\beta + \varepsilon, \varepsilon \sim N(0, \sigma^2)$
- $D = \mathbf{1}\{W > 0\}$
- New parameter $\theta = (\beta, \sigma^2)$

- This new parameter is **NOT** identified
- $P(D = d|x) = \Phi\left(\frac{x'\beta}{\sigma}\right)^d (1 - \Phi\left(\frac{x'\beta}{\sigma}\right))^{1-d}$
- Pick new parameter $\beta^* = \alpha\beta_0$ and $\sigma^* = \alpha\sigma_0$
- Then

$$\begin{aligned} & \Phi\left(\frac{x'\beta^*}{\sigma^*}\right)^d \left(1 - \Phi\left(\frac{x'\beta^*}{\sigma^*}\right)\right)^{1-d} \\ & \equiv \\ & \Phi\left(\frac{x'\beta_0}{\sigma_0}\right)^d \left(1 - \Phi\left(\frac{x'\beta_0}{\sigma_0}\right)\right)^{1-d} \end{aligned}$$

- $W = X'\beta + \varepsilon, \varepsilon \sim N(0, 1)$
- $D = \mathbf{1}\{W > 0\}$
- New parameter $\theta = (\beta)$
- This new parameter is globally identified
- $P(D = d|x) = \Phi(x'\beta)^d (1 - \Phi(x'\beta))^{1-d}$
- Given that log-likelihood is globally concave, it has a unique global maximum
- As a result if $|\beta^* - \beta_0| > \varepsilon$ then

$$\log P(D = d|x; \beta_0) - \log P(D = d|x; \beta^*) > 0$$

- Equality possible only when $\beta^* \equiv \beta_0$

- **Theorem:** Under MLE Assumptions and provided that $\theta_0 \in \text{int}(\Theta)$ is identified it follows that $\theta \neq \theta_0$ implies

$$L(\theta) = E[\log f(Y, \theta)] < E[\log f(Y, \theta_0)] = L(\theta_0)$$

- **Assumption:** $f(y, \theta)$ is twice continuously differentiable in Θ and the support of $f(\cdot)$ does not depend on θ . We also assume that Fubini theorem can be applied and the differentiation can be taken inside the integral

$$\begin{aligned} \frac{\partial}{\partial \theta} \int f(y, \theta) f(y, \theta_0) dy &= \int \frac{\partial f(y, \theta)}{\partial \theta} f(y, \theta_0) dy \\ \frac{\partial^2}{\partial \theta^2} \int f(y, \theta) f(y, \theta_0) dy &= \int \frac{\partial^2 f(y, \theta)}{\partial \theta^2} f(y, \theta_0) dy \end{aligned}$$

- For twice continuously differentiable objectives finding the maximum of $L(\theta)$ can be represented by the solution of FOC
- As a result, find the roots of FOC
- Also from the previous assumption this will be equivalent to finding roots of

$$E \left[\frac{\partial \log f(Y, \theta)}{\partial \theta} \right] = 0$$

in Θ

- **Definition:** The score function

$$s(\theta, y) = \frac{\partial \log f(y, \theta)}{\partial \theta}$$

is the gradient of the log-likelihood

- **Lemma:** Under Assumptions 1 and 2

$$E[s(\theta, y)] = 0.$$

- *Proof:* Note that $\int f(y, \theta) dy = 1$. Thus

$$\int \frac{\partial}{\partial \theta} f(y, \theta) dy = 0 = \int \frac{\frac{\partial f(y, \theta)}{\partial \theta}}{f(y, \theta)} f(y, \theta) dy = E[s(\theta, y)].$$

- **Definition:** Information of the model

$$I_\theta = \text{Var}(s(\theta, y))$$

is the variance of the score

- I_θ is also called the information matrix. We will deal with cases $\|I_\theta\| > 0$, where $\|\cdot\|$ is the defined as the smallest eigenvalue.
- Example: Estimating the mean

– Model

$$w_t = \alpha\beta + \alpha\varepsilon_t, \quad \varepsilon \sim N(0, \sigma^2)$$

- Can we identify α , β and σ^2 ? No!

- Log-likelihood

$$l(\theta) = -\frac{1}{2} \log(2\pi\sigma^2\alpha^2) - \frac{(w - \alpha\beta)^2}{2\alpha^2\sigma^2}$$

- We note that parameters α and σ^2 deliver the same log-likelihood value as $k\alpha$ and σ^2/k^2

- Compute the score

- $\frac{\partial l(\theta)}{\partial \alpha} = \frac{\varepsilon^2 - \sigma^2}{\alpha\sigma^2} + \frac{\beta\varepsilon}{\alpha\sigma^2}$

- $\frac{\partial l(\theta)}{\partial \beta} = \frac{\varepsilon}{\alpha\sigma^2}$

- $\frac{\partial l(\theta)}{\partial \sigma} = \frac{\varepsilon^2 - \sigma^2}{\sigma^3}$

- Score

$$s(\theta) = \begin{pmatrix} \beta & \frac{1}{\alpha} \\ 1 & 0 \\ 0 & \frac{1}{\sigma} \end{pmatrix} \begin{pmatrix} \frac{\varepsilon}{\alpha\sigma^2} \\ \frac{\varepsilon^2 - \sigma^2}{\sigma^2} \end{pmatrix}$$

- Note that $E[\varepsilon] = 0$ and $E[\varepsilon^2 - \sigma^2] = 0$

- Thus $E[s(\theta, y)] = 0$ (our lemma is valid!)

- Information

$$I_\theta = \text{Var}(s(\theta, y)) = \begin{pmatrix} \beta & \frac{1}{\alpha} \\ 1 & 0 \\ 0 & \frac{1}{\sigma} \end{pmatrix} \begin{pmatrix} \frac{1}{\alpha^2\sigma^2} & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} \beta & 1 & 0 \\ \frac{1}{\alpha} & 0 & \frac{1}{\sigma} \end{pmatrix}$$

- I_θ is a 3 by 3 matrix and the expression above is its eigenvalue decomposition

- Only 2 eigenvectors and 2 eigenvalues

- The third eigenvalue is equal to zero!

- Models that are not identified have a singular information matrix

- Identification and information

- Studying the rank of information matrix is extremely important in applied research!

- If information of your model is singular - alarming fact: (1) Think about your data; (2) Think about your model
- The relationship between identification and singularity of information of the model is not one-to-one
- If the model is not identified, information is singular
- If information is singular, it does not necessarily means that the model is not identified
- If the model has singular information, can conclude that the model cannot be estimated at \sqrt{T} -rate
- Recent studies show that many familiar models have singular information (treatment effects with unbounded support for conditional treatment probability)
- **Lemma:** If $Y \sim F(\cdot, \theta_0)$, regularity conditions are satisfied and the information matrix is non-singular, then

$$E \left[\frac{\partial^2 \log f(Y, \theta)}{\partial \theta \partial \theta'} \right] = -I_\theta$$

- *Proof:* We already know that $E[s(\theta, Y)] = 0$. We also know that $\frac{\partial^2 \log f(y, \theta)}{\partial \theta \partial \theta'} = \frac{\partial s(\theta, y)}{\partial \theta'}$. Therefore

$$\begin{aligned} \frac{\partial}{\partial \theta'} \int s(\theta, y) f(y, \theta) dy &= \int \frac{\partial s(\theta, y)}{\partial \theta'} f(y, \theta) dy \\ + \int s(\theta, y) s(\theta, y)' dy &= 0 \end{aligned}$$

This means that

$$E \left[\frac{\partial^2 \log f(Y, \theta)}{\partial \theta \partial \theta'} \right] = -E[s(\theta, Y) s(\theta, Y)'] = -I_\theta.$$

- Remark
 - This result can be useful for maximum search
 - When sample likelihood is very sensitive to parameters, information provides a more robust estimate for the Hessian
 - Need that when search for maximum, e.g. using Newton-Raphson algorithm
 - Maximum search is based on solving FOC

$$\frac{\partial \hat{L}(\theta^*)}{\partial \theta} = 0$$

- Mean-value expansion

$$\frac{\partial \hat{L}(\tilde{\theta})}{\partial \theta} + \frac{\partial^2 \hat{L}(\tilde{\theta})}{\partial \theta \partial \theta'} (\tilde{\theta} - \theta^*) = 0$$

- Then use this formula to iterate: from starting point $\theta^{(0)}$ to point $\theta^{(k)}$:

$$\frac{\partial \hat{L}(\theta_{k-1})}{\partial \theta} + \frac{\partial^2 \hat{L}(\theta_{k-1})}{\partial \theta \partial \theta'} (\theta_k - \theta_{k-1}) = 0$$

- Move from θ_{k-1} to θ_k and iterate till the points become close
- If likelihood is very sensitive to parameters, computing the second derivative can be tricky
- Do not need evaluation of the Hessian, as we can use the information matrix as a good estimate for the Hessian!

- **Theorem:** Consider an economic model with $Y \sim f(\cdot, \theta_0)$. Suppose that $\hat{\theta}_T$ is an unbiased estimator for θ_0 ($E[\hat{\theta}_T] = \theta_0$). Under our regularity conditions we have:

$$\text{Var}(\sqrt{T}(\hat{\theta}_T - \theta_0)) \geq I_{\theta}^{-1}.$$

Here \geq denotes that matrix $\text{Var}(\sqrt{T}(\hat{\theta}_T - \theta_0)) - I_{\theta}^{-1}$ is positive semidefinite (for diagonal matrices this is an element-by-element inequality)

- Cramer-Rao lower bound
 - This inequality establishes the Cramer-Rao lower bound
 - It shows the fundamental role of information for regular models: it establishes the lowest bound for the variance of regular estimator
 - Regularity here is important
 - In case of superefficient estimators can definitely beat this lower bound (by a lot!)
 - As we will see, this also implies very nice properties of the maximum likelihood estimator
- *Proof:* We start off from the definition of unbiasedness. Provided that the estimator is unbiased, for any DGP parametrized by θ

$$E_{\theta}[\hat{\theta}_T] = \theta$$

Note that $\hat{\theta}_T$ is the function of the sample y_1, \dots, y_T .

In other words if the sample is i.i.d.

$$\int \hat{\theta}_T f(y_1, \theta) \dots f(y_T, \theta) dy_1 \dots dy_T = \theta$$

Differentiate this w.r.t. θ :

$$\sum_{t=1}^T \int \hat{\theta}_T f(y_1, \theta) \dots \frac{\partial f(y_t, \theta)}{\partial \theta} \dots f(y_T, \theta) dy_1 \dots dy_T = I,$$

where I is the identity matrix.

Next, note that

$$\sum_{t=1}^T \int \hat{\theta}_T f(y_1, \theta) \dots \frac{\partial f(y_t, \theta)}{\partial \theta} \dots f(y_T, \theta) dy_1 \dots dy_T = TE \left[\hat{\theta}_T s(\theta, y_t) \right]$$

Given that

$$\sum_{t=1}^T \int \hat{\theta}_T f(y_1, \theta) \dots \frac{\partial f(y_t, \theta)}{\partial \theta} \dots f(y_T, \theta) dy_1 \dots dy_T = TE \left[\hat{\theta}_T s(\theta, y_t) \right]$$

we find that

$$\text{cov} \left(\hat{\theta}_T, s(\theta, y_t) \right) = \frac{1}{T} I$$

Consider

$$Z = \begin{pmatrix} \sqrt{T} (\hat{\theta}_T - \theta) \\ \sum_{t=1}^T s(\theta, y_t) \end{pmatrix}$$

Note that $\text{Var}(Z)$ is positive semidefinite (as covariance matrix)

$$\text{Var}(Z) = \begin{pmatrix} \text{Var}(\sqrt{T} (\hat{\theta}_T - \theta)) & T\sqrt{T} \text{cov}(\hat{\theta}_T, s(\theta, y_t)) \\ T\sqrt{T} \text{cov}(\hat{\theta}_T, s(\theta, y_t)) & TI_\theta \end{pmatrix}$$

Pick

$$c = \begin{pmatrix} -I \\ \frac{1}{\sqrt{T}} I_\theta^{-1} \end{pmatrix}$$

Given that $\text{Var}(Z)$ is positive semidefinite

$$c' \text{Var}(Z) c \geq 0$$

Then

$$\begin{aligned}
& c' \text{Var}(Z) c \\
&= \begin{pmatrix} -I & \frac{1}{\sqrt{T}} I_{\theta}^{-1} \end{pmatrix} \begin{pmatrix} \text{Var}(\sqrt{T}(\hat{\theta}_T - \theta)) & \sqrt{T} I \\ \sqrt{T} I & T I_{\theta}^{-1} \end{pmatrix} \begin{pmatrix} -I \\ \frac{1}{\sqrt{T}} I_{\theta}^{-1} \end{pmatrix} \\
&= \text{Var}(\sqrt{T}(\hat{\theta}_T - \theta)) - I_{\theta}^{-1} \geq 0
\end{aligned}$$

This delivers the result of the theorem

- **Definition:** A consistent estimator is called (asymptotically) efficient if $\lim_{T \rightarrow \infty} \text{Var}(\hat{\theta}_T) = I_{\theta}^{-1}$
- **Theorem:** Under our regularity conditions, the maximum likelihood estimator is asymptotically efficient.