

Nov 15

Hypothesis testing is like classification of machine learning.

Bayesian Decision Theory

$$\tilde{\theta} = \begin{cases} \theta^*, & \text{if } |\hat{\theta}_{MLE} - \theta^*| < 1/n \\ \hat{\theta}_{MLE}, & \text{if } |\hat{\theta}_{MLE} - \theta^*| > 1/n \end{cases}$$

Take any estimator

some θ

Statistical Decision Theory

Example: Classifying Bernoulli's.

• $p_0 = 1$, $p_1 = 0$, $x = 1$

Decision: p_0

• $p_0 = 0.99$, $p_1 = 0.1$, $x = \{1, 1, 1\}$

Decision: p_0

family of distⁿ composing our model
 $\mathcal{P} = \{P_\theta, \theta \in \mathcal{H}\}$ — is the space of distributions.

* H_0 is the subset of "acceptable" elements of \mathcal{P} . (the hypothesis / null hypothesis)

* H_1 is the subset of "rejectable" elements of \mathcal{P} . (alternative / alternative hypothesis).

$$\mathcal{P} = H_0 \cup H_1; \quad H_0 \cap H_1 = \emptyset$$

$$\Rightarrow \mathcal{H} = \mathcal{H}_0 \cup \mathcal{H}_1 \quad (\text{parameter space}).$$

$$H_0 = \{P_\theta, \theta \in \mathcal{H}_0\}; \quad H_1 = \{P_\theta, \theta \in \mathcal{H}_1\}$$

* Data (one single obs): x , realization of
 r.v. X w. dist $\sim P_\theta, \theta \in \mathcal{H}$

We want to construct $\delta(x) \in \{0, 1\}$, where
 $\delta(x)$ is the decision that $\theta \in H_0$ ($\delta(x)=0$)
 or not ($\delta(x)=1$) \rightarrow Binary Form.

(the general form of this would be
 a randomized distribution of decision
 rule \rightarrow this was Nash's decision.)

Objective Function (in ML: pattern recognition)

loss function $L_S(\theta)$ of decision rule \rightarrow depends on θ that generates data.
 \rightarrow Pattern recognition loss.

* Ex-ante problem: Before data is classified, we want to set the decision rule.
* Distn is fully accessible.

Misclassification Probability

Misclassification Probability:—

$$L_S(\theta) = \begin{cases} P_\theta(\delta(X) = 1), & \text{if } \theta \in \textcircled{H}_0 : \text{Type 1 error} \\ P_\theta(\delta(X) = 0), & \text{if } \theta \in \textcircled{H}_1 : \text{Type 2 error} \end{cases}$$

Going back to the Bernoulli Example:

$$H_0 = \{ \text{Bernoulli}(\underline{p_0}) \} \quad H_1 = \{ \text{Bernoulli}(p_1) \}$$
$$x \in \{0, 1\}$$

Options for decision rules:-

$$\delta^1(x) = \begin{cases} 1, & \text{if } x=1 \\ 0, & \text{otherwise if } x=0 \end{cases}$$

$$\delta^2(x) = \begin{cases} 0, & \text{if } x=1 \\ 1, & \text{if } x=0 \end{cases}$$

$$\delta^3(x) = \begin{cases} 1, & \text{if } x=1 \\ 1, & \text{if } x=0 \end{cases}$$

$$\delta^4(x) = \begin{cases} 0, & \text{if } x=1 \\ 0, & \text{if } x=0 \end{cases}$$

Example

$$L_\delta(\theta) = \begin{cases} P_0(\delta(X)=1), & \text{if } \theta \in \textcircled{+} \text{ : Type 1 error} \\ P_0(\delta(X)=0), & \text{if } \theta \in \textcircled{-} \text{ : Type 2 error} \end{cases}$$

Decision Rule	$L_\delta(\theta), P_\theta \in H_0$	$L_\delta(\theta), P_\theta \in H_1$
1	P_0	$1 - P_1$
2	$1 - P_0$	P_1
3	1	0
4	0	1

There is no global optimum decision rule in this case. (we want to min. loss)