# Magi Language Compiler

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# The Gift of the Magi

The Gift of the Magi is a short story, written by O. Henry, about a young married couple and how they deal with the challenge of buying secret Christmas gifts for each other with very little money. As a sentimental story with a moral lesson about gift-giving, it has been a popular one for adaptation, especially for presentation at Christmas time. The plot and its "twist ending" are well-known, and the ending is generally considered an example of comic irony.

### Project Overview

Time period: from Mar 22 to May 13

• Git commits: 172 commits

• Java code length: 13485 lines

# Highlights

- Use a well-organized framework with good extensibility
- Feed back a user-friendly compilation error message
- Support most features of OOP including member function, private modifier, class inheritance, member initialization and constructor function
- Achieve an outstanding compilation quality
- Implement the SSA form and do some optimizations on it including the useless code elimination and dominator-based value numbering technique
- Do not use any peephole and data-oriented optimizations
- Use the global register allocation and improve the algorithm
- Make good use of the version control system



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### Demonstration: Compilation Error Message

- 1:31: the function "angry" cannot have two parameters named "haha"!
- 2:4: "haha" is not a symbol name!
- 6:10: the number of parameters in the function-call expression is wrong!
- 7:12: two int/string-type expressions are expected in the addition expression!

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# Demonstration: Object Oriented Programming

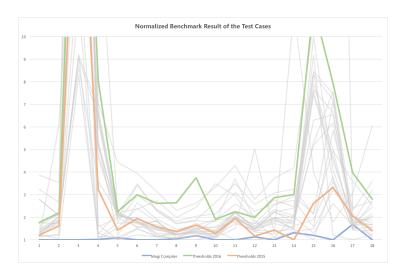
```
class Pair -
    public int first = 0:
    public int second = 0;
    public bool equal = true;
    public Pair() {
        this.first = this.second = 0:
        this.equal = true;
    public Pair(int first, int second) {
        this.first = first:
        this.second = second;
        this.equal = (first == second):
    public void print() {
       println(toString(this.first) + " " + toString(this.second));
class Triple extends Pair {
    public int third = 0:
    public bool equal = true:
    public Triple() {
        this.first = this.second = this.third = 0;
        this.equal = true:
    public Triple(int first, int second, int third) {
        this.first = first;
        this.second = second:
        this.third = third;
        this equal = (first == second && second == third);
    public void print() {
       println(toString(this.first) + " " + toString(this.second) + " " + toString(this.third));
int main() -
    Pair pair = new Pair(1, 2);
    pair.print():
    Triple triple = new Triple(1, 2, 3);
    triple.print():
    return 0;
```

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### Demonstration: Normalized Benchmark Result



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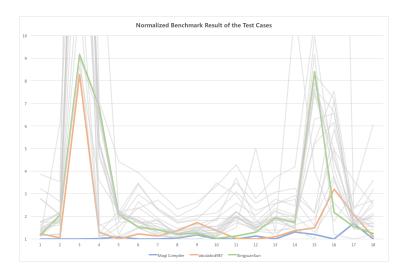
### Demonstration: Single Static Assignment

```
func min $p0 $p1 {
    %min.0.enter:
        $t4 = move $p1
        $t5 = move $p0
        jump %min.1.entry
    %min.1.entry:
        $t3 = slt $t5 $t4
        br $t3 %min.2.if_true %min.3.if_false
    %min.2.if_true:
        $t2 = move $t5
        jump %min.4.if_merge
    %min.4.if_merge:
        ret $t2
        jump %min.5.exit
    %min.3.if_false:
        $t2 = move $t4
        jump %min.4.if_merge
    %min.5.exit:
        p1 = move $t4
        p0 = move $t5
```

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    %min.1.entrv:
        $t3.0 = slt $t5.0 $t4.0
        br $t3.0 %min.2.if_true %min.3.if_false
    %min.2.if_true:
        $t2.0 = move $t5.0
        jump %min.4.if merge
    %min.4.if_merge:
        $t2.1 = phi %min.2.if true $t2.0 %min.3.if false $t2.2
        ret $t2.1
        iump %min.5.exit
    %min.3.if_false:
        $t2.2 = move $t4.0
        jump %min.4.if merge
    %min.5.exit:
        p1.1 = move $t4.0
        p0.1 = move $t5.0
}
```

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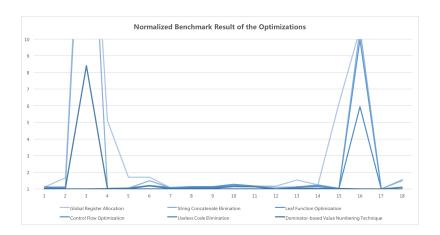


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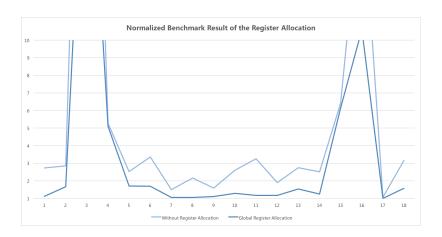


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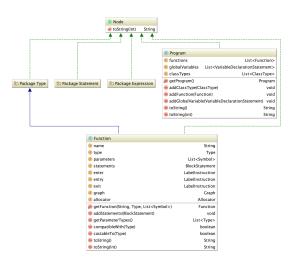
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### Front End

- Use ANother Tool for Language Recognition to generate the lexer and parser
- Convert the Concrete Syntax Tree to the Abstract Syntax Tree by the listener mode of ANTLR

# Abstract Syntax Tree Framework



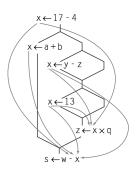
### Back End

- Convert the Abstract Syntax Tree to the linear Intermediate Representation
- 2 Build the Control Flow Graph by scanning the linear Intermediate Representation

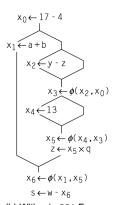
### Intermediate Representation Framework



### Single Static Assignment



(a) Original Code Fragment



(b) With x in SSA Form

# Single Static Assignment

- Compute the immediate dominator and the dominance frontier
- **2** Insert  $\phi$ -functions
- 3 Rename the variables and the temporaries
- O Do some optimizations based on SSA form
- Translate out of SSA form

# Single Static Assignment: Analyze the Dominance

#### Definition

In a flow graph with entry node s, node u dominates node v iff u lies on every path from s to v

### Data flow equation

$$dom_{v} = \{v\} \cup \left(\bigcap_{p \in pred_{v}} dom_{p}\right)$$

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# Single Static Assignment: Analyze the Dominance

#### **Definitions**

- A node u strictly dominates a node v if u dominates v and u
  does not equal v.
- The immediate dominator of a node u is the unique node that strictly dominates u but does not strictly dominate any other node that strictly dominates u.
- The dominance frontier of a node u is the set of all nodes v such that u dominates an immediate predecessor of v, but u does not strictly dominate v. It is the set of nodes where u's dominance stops.

# Single Static Assignment: Immediate Dominator

```
for all nodes, b // initialize the dominators array
    IDoms[b] ← Undefined
IDoms[b_0] \leftarrow b_0
Changed ← true
while (Changed)
   Changed ← false
   for all nodes, b, in reverse postorder (except root)
       NewIDom ← first (processed) predecessor of b // pick one
       for all other predecessors, p, of b
           if IDoms[p] \( \psi \) Undefined \( // i.e., \) Doms[p] already calculated
               then NewIdom ← Intersect(p, NewIdom)
       if IDoms[b] ≠ NewIdom then
           IDoms[b] ← NewIdom
           Changed ← true
Intersect(i, i)
   finger1 ← i
   finger2 ← i
   while (finger1 ≠ finger2)
       while (RPO(finger1) > RPO(finger2))
          finger1 = IDoms[finger1]
       while (RPO(finger2) > RPO(finger1))
          finger2 = IDoms[finger2]
   return finger1
```

# Single Static Assignment: Insert $\phi$ -functions

(a) Finding Global Names

```
Globals ← Ø
Initialize all the Blocks sets to Ø
for each block b
                                                   for each name x \in Globals
    VARKILL ← Ø
                                                        Worklist \leftarrow Blocks(x)
    for each operation i in b. in order
                                                        for each block b e Worklist
         assume that op; is "x \leftarrow y op z"
                                                             for each block d in pr(b)
         if y ∉ VARKILL then
                                                                 if d has no \phi-function for x then
             Globals ← Globals U {v}
                                                                    insert a \phi-function for x in d
         if z ∉ VARKILL then
                                                                    WorkList \leftarrow WorkList \cup \{d\}
             Globals ← Globals ∪ {z}
         VarKill \leftarrow VarKill \cup \{x\}
         Blocks(x) \leftarrow Blocks(x) \cup \{b\}
```

(b) Rewriting the Code

### Single Static Assignment: Rename the Variables

```
for each global name i
                                          Rename(b)
  counter[i] \leftarrow 0
                                             for each \phi-function in b, "x \leftarrow \phi(\cdots)"
  stack[i] \leftarrow \emptyset
                                                 rewrite x as NewName(x)
Rename(no)
                                             for each operation "x \leftarrow y op z" in b
                                                 rewrite y with subscript top(stack[y])
                                                 rewrite z with subscript top(stack[z])
                                                 rewrite x as NewName(x)
                                             for each successor of b in the CEG
NewName(n)
                                                 fill in \phi-function parameters
 i \leftarrow counter[n]
                                             for each successor s of b in the dominator tree
 counter[n] \leftarrow counter[n] + 1
                                                 Rename(s)
 push i onto stack[n]
                                             for each operation "x \leftarrow y op z" in b
 return "n;"
                                                 and each \phi-function "x \leftarrow \phi(\cdots)"
                                                 pop(stack[x])
```

### **Optimizations**

### Regular optimizations

- Leaf function optimization
- Control flow optimization

#### Optimizations based on SSA form

- Useless code elimination
- Ominator-based value numbering technique

# Optimization: Control Flow Optimization

```
Clean()
 while the CFG keeps changing
    compute postorder
    OnePass()
OnePass()
  for each block i, in postorder
    if i ends in a conditional branch then
        if both targets are identical then
             replace the branch with a jump
    if i ends in a jump to j then
        if i is empty then
             replace transfers to i with transfers to i
        if j has only one predecessor then
            combine i and j
        if j is empty and ends in a conditional branch then
            overwrite i's jump with a copy of j's branch
```

### Optimization: Useless Code Elimination

```
Mark()
 WorkList ← Ø
 for each operation i
     clear i's mark
     if i is critical then
        mark i
        WorkList ← WorkList ∪ {i}
 while (WorkList \neq \emptyset)
     remove i from WorkList
        (assume i is x \leftarrow y op z)
     if def(v) is not marked then
        mark def(y)
        WorkList ← WorkList ∪ {def(v)}
     if def(z) is not marked then
        mark def(z)
        WorkList \leftarrow WorkList \cup \{def(z)\}\
     for each block b \in RDF(block(i))
        let j be the branch that ends b
        if i is unmarked then
            mark i
            Worklist ← Worklist U (i)
               (a) The Mark Routine
```

```
Sweep()

for each operation i

if i is unmarked then

if i is a branch then

rewrite i with a jump

to i's nearest marked

postdominator

if i is not a jump then

delete i
```

(b) The Sweep Routine

# Optimization: Dominator-based Value Numbering

```
procedure DVNT(B)
   allocate a new scope for B
   for each \phi-function of the form "n \leftarrow \phi(...)" in B
      if p is meaningless or redundant then
         VN[n] ← the value number for p
         remove p
      else
         VN[n] \leftarrow n
         Add p to the hash table
   for each assignment a of the form "x \leftarrow y op z" in B
      overwrite y with VN[y]
      overwrite z with VN[z]
      let expr ← "v op z"
      if expr can be simplified to expr' then
         replace a with "x \leftarrow expr'
         expr \leftarrow expr'
      if expr has a value number v in the hash table then
         VN[x] \leftarrow v
         remove statement a
      PISP
         VN\Gamma x1 \leftarrow x
         add expr to the hash table with value number x
   for each successor s of R
      adjust the ø-function inputs in s
   for each child c of B in the dominator tree
      DVNT(c)
   deallocate the scope for B
```

### Global Register Allocation

- Analyze the liveliness
- 2 Build the interference graph
- Use the bottom-up coloring

### Global Register Allocation: Liveliness Analysis

#### **Definitions**

- v live at e iff there is a path p from e to i such that
  - instruction i uses v
  - no instructions defining v on the path p
- v live-in at i iff v live at e, where  $e \in in\text{-}edge_i$
- v live-out at i iff v live at e, where e ∈ out-edge;

#### Data flow equation

$$live-in_i = use_i \cup (live-out_i \setminus def_i)$$
  
 $live-out_i = \bigcup_{s \in succ_i} live-in_s$ 

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# Global Register Allocation: Liveliness Analysis

- Calculate the def and use for each basic block
- Oo the liveliness analysis on each basic block by using the fix-point algorithm
- Calculate the liveliness information for each instruction in each basic block by the one-pass backward calculation

# Global Register Allocation: Interference Graph

- For a move instruction i,
   add forbidden edges between def<sub>i</sub> and live-out<sub>i</sub> \ use<sub>i</sub>
   add recommend edges between def<sub>i</sub> and use<sub>i</sub>
- For a non-move instruction i,
   add forbidden edges between def<sub>i</sub> and live-out<sub>i</sub>

# Global Register Allocation: Bottom-up Coloring

### **Algorithm 1** Computing the coloring order for G = (V, E)

- 1: initialize stack to empty
- 2: while V is not empty do
- 3: **if**  $\exists v \in V$  with  $deg_v < k$  **then**
- 4:  $candidate \leftarrow v$
- 5: else
- 6: candidate  $\leftarrow v$  picked from V
- 7: end if
- 8: remove *candidate* and its edges in the graph *G*
- 9: push candidate onto stack
- 10: end while

# Global Register Allocation: Bottom-up Coloring

### **Algorithm 2** Coloring bottom-up for G = (V, E)

- 1: while stack is not empty do
- 2:  $v \leftarrow pop(stack)$
- 3: insert v and its edges into the graph G
- 4: **color** *v*
- 5: end while

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- Provide some IR test data for my classmates
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### Summary

- I am ashamed to do only a little bit of the work
- Thank all of you, my TAs and my classmates