

Lie Algebra is developed by **Marius Sophus Lie**

He was a Norwegian guy who was not as notable as Abel and mainly spent his life in Germany, which is disliked by our teacher Futorny.

**Definition 1.** An Algebra  $A$  is a system with a non-empty set  $S$  with  $k$  operations  $\sigma_1, \sigma_2, \dots, \sigma_k$  s.t. all elements under operation are still in the set  $S$ .

**Definition 2.** A Lie Algebra  $\mathcal{L}$  is a  $K$ -Vector Space with an operation  $[-, -]$ . Here,  $[-, -]$  is a bilinear operation s.t.  $[x, x] = 0$  and  $[x, [y, z]] + [y, [x, z]] + [z, [x, y]] = 0, \forall x, y, z \in \mathcal{L}$

**Warning.** a)  $[x, x] = 0 \quad \forall x \in \mathcal{L}$

$\leftrightarrow$  b)  $[x, y] + [y, x] = 0 \quad \forall x, y \in \mathcal{L} \quad \text{if and only if } \chi(K) \neq 2$ .

Reason:  $[x+y, x+y] = 0 \leftrightarrow [x, x] + [y, y] + [x, y] + [y, x] = 0$ .

**Example 1.** We Let  $[x, y] = 0, \forall x, y \in \mathcal{L}$ . A trivial one.

**Example 2.** For vector space  $E^3$ , we let the cross-product be the bracket notion.

**Example 3.** We Let  $[x, y] = x \cdot y - y \cdot x$ . It is easy to verify that the Jacobi identity is satisfied. Here  $x, y \in A$ .  $A$  is an associative Algebra. In this case, we denote by  $A^{\text{lie}}$ . Often(Maybe sometimes),  $A = M_n(K)$ , We denote  $\text{End}(V)^{\text{lie}} := \mathfrak{gl}_n(K)$ .

**Definition 3.** Given a subspace  $\mathcal{H} \subset \mathcal{L}$ , if the bracket operation  $[-, -]$  is closed under  $\mathcal{H}$ , Then  $\mathcal{H}$  is a Lie Subalgebra.

**Example 4.**  $\mathfrak{sl}_n(K) := \{x \in \mathfrak{gl}_n(k) : \text{Trace}(x) = 0\}$

**Definition 4.** A linear map  $d : A \rightarrow A$  is called a derivation if  $d(ab) = ad(b) + bd(a)$  for all  $a, b \in A$ . We denote the set of all derivations by  $\text{Der}(A)$ .

**Exercise 1.** Show that for vector space  $K[x]$ ,  $\text{Der}(A) = \{h(x) \cdot \frac{d}{dx} \mid h(x) \in K[x]\}$

**Solution.** By the definition,  $d(1) = d(1 \times 1) = 2d(1)$ . Hence  $d(1) = 0$ .

Let  $d(x) = h(x)$ .

By mathematics induction, we can say for  $\deg(f) \leq n$ , this holds.

Without loss of generality, we can assume  $f(x) = a_{n+1}x^{n+1} + a_nx^n + \dots + a_1x$ .

$$d(f(x)) = d(x(a_{n+1}x^n + a_nx^{n-1} + \dots + a_1)) = h(x)((n+1)a_{n+1}x^{n-1} + (n-1)a_nx^{n-2} + \dots + a_1) + h(x)f(x) = h(x)\frac{df(x)}{dx}.$$

**Note 1.** Let  $A$  be a commutative, associative algebra,  $\text{Der}(A)$  is closed under the bracket operation which can be noted as  $[d_1, d_2] = d_1d_2 - d_2d_1$ .

**Definition 5.** Definition (Lie Ideal).  $I \subset \mathfrak{g}$  is a Lie ideal if for all  $x \in \mathfrak{g}$  and  $a \in I$ ,  $[x, a] \in I$ .

**Example 5.** For vector space  $M_n(K)^{\text{lie}}$ ,  $tI_n$  is an ideal, for you got an zero.