

# **NP Completeness**

Tao Hou

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- Previously, for different problems we consider, we were trying to show how we *can* design efficient algorithms for solving them
- Now, we are going to show for certain problems, how we *cannot* design efficient algorithms

# Hard vs. Easy Problems

- “Efficient” algorithms: **polynomial-time** algorithms, i.e., ones with worst-case time complexity being  $O(n^k)$  for some constant  $k$
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  - ▶ There are also problems that can be solved in finite steps (e.g., in exponential time), but not in polynomial time
- Generally, we think of problems that are solvable by polynomial-time algorithms as being **tractable**, or “easy”, and problems that require superpolynomial time as being **intractable**, or “hard”

- The subject of this chapter, however, is an interesting class of problems called the “NP-complete” problems, whose status is unknown:
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- This so-called  $P \neq NP$  question has been one of the deepest, most perplexing open research problems in theoretical computer science since it was first posed in 1971
- Notice that NP-complete problems are still in general considered “hard” problems as most people believe you cannot find polynomial time algorithms for them

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Euler tour vs. Hamiltonian cycle:

- An **Euler tour** of an undirected graph is a cycle that traverses each edge of the graph exactly once (it is allowed to visit vertices more than once)
- A **Hamiltonian cycle** of an undirected graph is a simple cycle that traverses each vertex exactly once
- We can determine whether a graph has an Euler tour in only  $O(|E|)$  time
- Determining whether an undirected graph has a Hamiltonian cycle is NP-complete

Throughout this topic, we shall consider three classes of problems:

- **P**: Problems that are solvable in polynomial time
- **NP**: Problems that are “verifiable” in polynomial time
  - ▶ We have  $P \subseteq NP$
- **NPC**: NP-complete problems, those problems that are as hard as **any** problems in the class  $NP$  (you can also say is the hardest problem in  $NP$ )



# Why do we study it?

Understanding NP-completeness theory is critical to algorithm designers:

- If you can find that a problem is NP-complete, you would then do better to spend your time finding an approximation algorithm or solving a tractable special case
- Many natural and interesting problems that on the surface seem no harder than sorting, graph searching, or network flow are in fact NP-complete

# Why do we care polynomial time?

We focus on polynomial time algorithms for certain reasons:

- Although a polynomial running time of  $\Theta(n^{100})$  is completely disastrous in practice, the polynomial-time algorithms we actually encountered ***typically require much less time***
- Experience has shown that once the first polynomial-time algorithm for a problem has been discovered, ***more efficient algorithms often follow***

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- Most importantly, the class of polynomial-time solvable problems has nice ***closure properties***, since polynomials are closed under addition, multiplication, and composition
  - ▶ E.g., if we apply a polynomial-time algorithm for polynomially many times, we still have a polynomial-time algorithm

# Decision Problems vs. Optimization Problems

- Many problems of interest are *optimization* problems: each legal solution has an associated value, and we wish to find a legal solution with the best value
- (Example) SHORTEST-PATH-OPTMZ: given an undirected graph  $G$  and vertices  $u$  and  $v$ , we wish to find a path from  $u$  to  $v$  with the fewest edges

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- However, the theory of NP-Completeness focuses only on **decision** problems: given an input, a program should produce “yes” or “no”
- (Example) SHORTEST-PATH: given an undirected graph  $G$ , two vertices  $u$  and  $v$ , and **an integer  $k$** , is there a path from  $u$  to  $v$  with  $\leq k$  edges?

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  - ▶ E.g., given an instance  $(G, u, v, k)$  of SHORTEST-PATH, we can find the length  $\ell$  of the shortest path of  $(G, u, v)$  using an algorithm for the optimization problem, and then check if  $k \geq \ell$



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- Implication: if we show that a decision problem is “hard”, we also show that **its related optimization problem is hard**
  - ▶ If we can find a polynomial-time algorithm for the optimization problem, we can definitely find a polynomial-time algorithm for the decision problem
  - ▶ Equivalently, if we **cannot** find a polynomial-time algorithm for the decision problem, we **also cannot** find a polynomial-time algorithm for the optimization problem
- Thus, though NP-completeness theory restricts attention to decision problems, it **often has implications for optimization problems**

# Formal Definition of *Problems*

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A ***problem*** is an association of problem instances (inputs) and to their solutions

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- An instance for the problem is a triple  $(G, u, v)$
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(Example) SHORTEST-PATH:

- An instance for the problem is a triple  $(G, u, v, k)$
- Return ...

## Polynomial-time solvable problem

A problem is said to be ***polynomial-time solvable*** if there exist an algorithm such that:

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- The algorithm finishes in  $O(n^k)$  time for any instance of size  $k$



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## Complexity class $P$

The complexity class  $P$  is the set of decision problems that are polynomial-time solvable

Consider two problems:

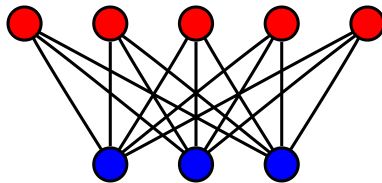
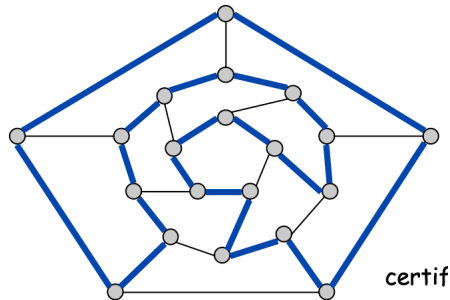
## Hamiltonian cycle problem (HAM-CYCLE)

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Left dodecahedron graph (taken from [K&T] slides) has a Hamiltonian cycle while the right bipartite graph (taken from Wikipedia) does not have one

## Satisfiability problem (SAT)

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A boolean formula is made up of the boolean variables  $x_1, \dots, x_n$ , operators including  $\wedge$  (AND),  $\vee$  (OR),  $\neg$  (NOT),  $\rightarrow$  (implication),  $\leftrightarrow$  (if and only if), and composite (combinations) of them possibly with parenthesis. E.g.,:

$$((x_1 \rightarrow x_2) \vee \neg((\neg x_1 \leftrightarrow x_3) \vee x_4)) \wedge \neg x_2.$$

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- Let's consider an easier version for such a problem by solving it “*indirectly*” (HAM-CYCLE as an example)
- Suppose that someone tells you a given graph  $G$  is Hamiltonian and offers to prove it *by giving you a sequence of vertices* which this person claims to be a Hamiltonian cycle
- It would then be easy to *verify* this: simply verify whether the sequence contain all the vertices and whether each two consecutive vertices form an edge

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- It would then be easy to **verify** this: simply verify whether the sequence contain all the vertices and whether each two consecutive vertices form an edge
- The “verification” process can definitely be done in polynomial time in terms of the size of  $G$
- Formally speaking, the algorithm used for the “verification” is termed as a **verification algorithm**, and the sequence of vertices you used for verification is called a **certificate**



## Verification algorithm

For a (decision) problem  $Q$ , a **verification algorithm** (or simply **verifier**), denoted  $C(x, y)$ , is an algorithm satisfying:

- $C(x, y)$  returns “yes”/“no”
- input  $x$  is an instance of  $Q$
- input  $y \in \{0, 1\}^*$  (a binary string) is a **certificate**
- $x$  is an “yes”-instance of  $Q \Leftrightarrow$  there exist a certificate  $y$  making  $C(x, y)$  return “yes”

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Notice:

- For a “yes”-instance  $x$ , it’s okay that  $C(x, y)$  returns “no” given some certificate  $y$
- As long as **there is one certificate**  $y$  making  $C(x, y)$  return “yes”, it is fine
- But if  $x$  is a “no”-instance, then  $C(x, y)$  should return “no” **for all certificates**

To write a verification algorithm  $C(x, y)$  for a problem:

- You first “**decode**” the certificate  $y$  (which is a binary string) into something “meaningful”
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- When you try to decode  $y$ , if you cannot decode it into something meaningful, the verifier simply returns “no”

(**Example**) A verification algorithm  $C(x, y)$  for SAT:

- Notice that here  $x$  is a boolean formula with boolean variables  $x_1, \dots, x_n$
- Given  $y$  as a bit string, decode  $y$  into a T/F assignment to  $x_1, \dots, x_n$ 
  - ▶ The simplest thing to do is to take the first  $n$  bits in  $y$  and take them as the T/F assignment to  $x_1, \dots, x_n$
  - ▶ If  $y$  has less than  $n$  bits, return “no”
- Then use the T/F assignment of  $x_1, \dots, x_n$  from the certificate  $y$  to verify whether the boolean formula evaluate to true; If true, return “yes”; otherwise, return “no”

(Example) A verification algorithm  $C(x, y)$  for HAM-CYCLE:

- Given  $y$  as a bit string, decode  $y$  into a sequence of  $n$  vertices where  $n$  is the number of vertices in the input graph  $G := x$ 
  - ▶ If  $y$  cannot be decoded into  $n$  vertices, return “no”
  - ▶ Ignore the remaining bits
- Then verify whether the  $n$  vertices form a valid Hamiltonian cycle

## The Complexity Class **NP**

The complexity class **NP** is a set of decision problems such that a problem  $Q \in \mathbf{NP}$  if and only if there is a verification algorithm  $C(x, y)$  for  $Q$  running in polynomial time in term of the size of the  $Q$ 's instance  $x$

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Example: SAT, HAM-CYCLE  $\in \mathbf{NP}$



- There is one complexity class ***NPC*** which is yet to be defined
- Roughly saying, ***NPC*** is the set of “hardest” problems in ***NP***
- But to do that, we need a way to compare the “difficulty” of problems
- For that, we introduce the notion of “***reducibility***”, which is probably the single most important notion in the topic

## Polynomial reduction

A decision problem  $Q_1$  is said to **polynomially reduces** to (or simply **reduces** to) another decision problem  $Q_2$  if there is a polynomial time ( $O(|x_1|^k)$ ) algorithm  $\mathcal{F}$  taking an instance  $x_1$  for  $Q_1$  and computing an instance  $x_2$  for  $Q_2$  such that:

- $x_1$  is a “yes”-instance for  $Q_1$  iff  $x_2$  is a “yes”-instance for  $Q_2$

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(Implications) If  $Q_1$  polynomially reduces to  $Q_2$ :

- $Q_1$  is “no harder” than  $Q_2$  in the sense that
- Any polynomial-time algorithm  $\mathcal{A}$  for  $Q_2$  can be used to solve  $Q_1$  in polynomial-time, by doing:
  - ▶ Given an instance  $x_1$  of  $Q_1$ , use  $\mathcal{F}$  to compute an instance  $x_2$  of  $Q_2$
  - ▶ Then use  $\mathcal{A}$  to decide whether  $x_2$  is a “yes”-instance for  $Q_2$
  - ▶ Return “yes” if  $\mathcal{A}$  returns “yes”, and return “no” if  $\mathcal{A}$  returns “no”,
- So if  $Q_2$  can be solved in polynomial time, then  $Q_1$  also can

So whether a problem  $Q_1$  reduces to another problem  $Q_2$  completely relies on whether you can find a “reduction algorithm”  $\mathcal{F}$

Example:

- $Q_1$ : Given a string  $x_1$ , does  $x_1$  contain the letter “a”?
- $Q_2$ : Given a string  $x_2$ , does  $x_2$  contain the letter “b”?

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- $Q_2$ : Given a string  $x_2$ , does  $x_2$  contain the letter “b”?
- $Q_1$  reduces to  $Q_2$  with the reduction algorithm: given an instance  $x_1$  of  $Q_1$ , replace each occurrence of “a” in  $x_1$  with “b” and each occurrence of “b” in  $x_1$  with “a” and produce an instance  $x_2$  of  $Q_2$

## The Complexity Class ***NPC***

- A problem  $Q \in \mathbf{NP}$  is called ***NP-Complete*** if *all* problems in ***NP*** reduce to  $Q$
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- Let  $Q$  be a problem in ***P***
- Then there is an algorithm  $\mathcal{A}$  solving  $Q$  in polynomial time
- To show that  $Q \in \mathbf{NP}$ , we only need to design a polynomial-time verifier  $C(x, y)$  for  $Q$
- To do this, in  $C$ , we only need to invoke  $\mathcal{A}$  on  $x$ , and return the answer of  $\mathcal{A}$  (certificate  $y$  is completely ignored)

- The biggest question in CS: Is  $P = NP$ ?
- This question was raised in the 1970's, and there is not an answer till this day
- The common belief is that  $P \neq NP$
- The key lies in those NP-Complete problems, because if you can find an algorithm for a single NP-Complete problem, then all problems in  $NP$ , including all the other NP-Complete problems, can be solved in polynomial time (so  $P = NP$ )
- However, there are tons of NP-Complete problems out there, and **no one** has ever found a polynomial-time algorithm **for any of them** till this day

## Proposition

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### ***proof:***

- Let  $Q$  be an NP-Complete problem and let  $\mathcal{A}$  be a polynomial-time algorithm for  $Q$
- Let  $Q'$  be an arbitrary problem in **NP**
- Since  $Q'$  reduces to  $Q$ , we have a polynomial-time reduction algorithm  $\mathcal{F}$  from  $Q'$  to  $Q$
- Then we can have a polynomial-time algorithm for  $Q'$ : given an instance  $x'$  of  $Q'$ , compute an instance  $x$  of  $Q$  using the algorithm  $\mathcal{F}$ , then you just return whatever  $\mathcal{A}$  returns on  $x$

## The complexity class *EXP*

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# The complexity class **EXP**

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## Proposition

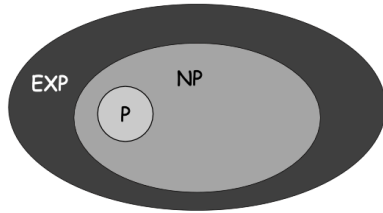
$$\mathbf{NP} \subseteq \mathbf{EXP}$$

### **proof:**

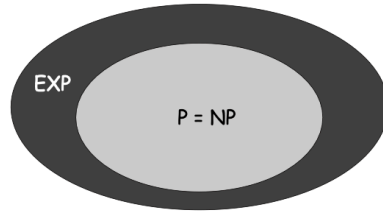
- Let  $Q$  be a problem in **NP** with a verifier  $C(x, y)$
- Given an instance  $x$  of  $Q$ , we enumerate all possible certificates for  $x$  and see whether there is one certificate  $y$  making  $C(x, y)$  return “yes”
- If there is such a certificate, we return “yes” for  $x$ , otherwise, we return “no”
- Notice that we only need to enumerate certificates of up to a size  $m = \text{poly}(|x|)$ , because any certificate beyond size  $m$  will not be helpful to us (see the “decoding” process for certificates)
- Total time would be  $2^{\text{poly}(|x|)} f(|x|)$ , where  $f(|x|)$  is the time complexity of  $C(x, y)$



# The million-dollar question



If  $P \neq NP$



If  $P = NP$

(Figure from [K&T] slides)

- The term “NP” does not stand for “non-polynomial time” (we don’t know whether these problems can or cannot be solved in polynomial time)
- It stands for “non-deterministic polynomial-time solvable” (the verification algorithm we write is indeed a “non-deterministic algorithm”)
- As mentioned, if you have shown that a problem is NP-complete, then you should do something else rather trying to find a polynomial-time algorithm for it
- But people on this planet **haven’t proved** that an NP-Complete problem does not have a polynomial-time algorithm
- Only that people believe so because there are tons of NP-Complete problems and no one has ever found a polynomial-time algorithm for **any** of them

# How to show that a problem is NP-Complete?

How to show that a problem  $Q$  is NP-Complete?

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2. Show that  $Q$  is “**NP-hard**”, i.e., all problems in **NP** reduce to  $Q$

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- To do that, you need a “first” NP-hard problem  $Q^*$
  - Then you only need to show that  $Q^*$  reduces to  $Q$ 
    - ▶ Due to the *transitivity* of reducibilities ( $Q_1$  reduces to  $Q_2$ ,  $Q_2$  reduces to  $Q_3 \Rightarrow Q_1$  reduces to  $Q_3$ )

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  - So the general strategy for showing a problem  $Q$  to be NP-hard is to first find a problem  $Q^*$  known to be NP-hard, and then reduce  $Q^*$  to  $Q$