## **All-Pairs Shortest Paths**

Tao Hou

#### Why study it?

We can solve an all-pairs shortest-paths problem by running a single-source shortest-paths algorithm *for each vertex*:

- Use Dijkstra's algorithm:  $O(|V||E|\log(|V|))$ 
  - ▶ For sparse graph,  $|E| = \Theta(|V|)$ :  $O(|V|^2 \log(|V|))$  (not too bad)
  - ► For dense graph,  $|E| = \Theta(|V|^2)$ :  $O(|V|^3 \log(|V|))$  (can do better)
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  - ► Time complexity:  $O(|V|^2|E|)$
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#### We introduce *Floyd-Warshall* algorithm:

■ Run in  $O(|V|^3)$  time and allow negative weights

## Floyd-Warshall: Setting

- Assume that the vertices are numbered 1, 2, ..., n where n = |V|
- The input is an  $n \times n$  matrix  $W = (w_{i,j})$  representing the edge weights (an *augmentation* of adjacency matrix):

$$w_{i,j} = \begin{cases} 0 & \text{if } i = j \\ \text{weight of edge } (i,j) & \text{if } i \neq j \text{ and } (i,j) \in E \\ \infty & \text{if } i \neq j \text{ and } (i,j) \notin E \end{cases}$$

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- Allow negative-weight edges, but assume that the input graph contains no negative-weight cycles
- Returns an  $n \times n$  matrix  $D = (d_{i,j})$ , where  $d_{i,j} = \delta(i,j)$
- lacktriangle Also returns a **predecessor matrix**  $\Pi = (\pi_{i,j})$

$$\pi_{i,j} = \begin{cases} \text{Nil} & i = j \text{ or no path from } i \text{ to } j \\ \text{Predecessor of } j \text{ on a shortest path from } i \text{ to } j \end{cases}$$

• *i*-th row of  $\Pi$  defines a shortest-paths tree rooted at *i* (the procedure to print a shortest path from *i* should be evident from previous contents)

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- A dynamic-programming approach utilizing the *optimal substructure property* of shortest paths
- As can be imagined, the parameter of the *OPT* function contains: *i* and *j*, the start and end vertices
- However, if your *OPT* contains only *i*, *j*, then:

$$d(i,j) = \min\{d(i,\ell) + d(\ell,j) \mid \ell \in V\}$$

- It would be nearly *impossible* to find a valid *evaluation order* 
  - ► There is no natural definition of 'size' for the problems d(i,j): they are all 'equal'; no one is a natural 'subproblem' of another
  - Also no natural base cases

- The solution is that, we introduce **another parameter** k, and consider all paths from i to j whose **intermediate vertices** are  $\leq k$ 
  - ► E.g., path  $p = \langle v_1 = i, v_2, ..., v_{q-1}, v_q = j \rangle$  where  $v_2, ..., v_{q-1} \le k$

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- *OPT function*: Let  $d_{i,j}^{(k)} := d(i,j,k)$  be the minimum weight of all paths from i to j with intermediate vertices  $\leq k$
- We have the following immediate evidence why this definition makes sense:
  - (1) We could easily identify the **base case**:  $d_{i,j}^{(0)} = w_{i,j}$
  - (2) There is a natural notion of "size": k

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- Now consider defining  $d_{i,j}^{(k)}$  for general k.

Paths from *i* to *j* with intermediate vertices  $\leq k$  fall in two sets:

- ▶ Does not contain *k*:
- Contains k:

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- Now consider defining  $d_{i,j}^{(k)}$  for general k.
  - Paths from *i* to *j* with intermediate vertices  $\leq k$  fall in two sets:
    - ▶ Does not contain k: intermediate vertices are  $\leq k-1$ ; the shortest one is  $d_{i,i}^{(k-1)}$
    - ► Contains k: the shortest one is  $d_{i,k}^{(k-1)} + d_{k,j}^{(k-1)}$

- The solution is that, we introduce **another parameter** k, and consider all paths from i to j whose **intermediate vertices** are  $\leq k$ 
  - ► E.g., path  $p = \langle v_1 = i, v_2, ..., v_{q-1}, v_q = j \rangle$  where  $v_2, ..., v_{q-1} \le k$
- **OPT function**: Let  $d_{i,j}^{(k)} := d(i,j,k)$  be the minimum weight of all paths from i to j with intermediate vertices < k
- We have the following immediate evidence why this definition makes sense:
  - (1) We could easily identify the **base case**:  $d_{i,j}^{(0)} = w_{i,j}$
  - (2) There is a natural notion of "size": k
- Now consider defining  $d_{i,j}^{(k)}$  for general k. Paths from i to j with intermediate vertices  $\leq k$  fall in two sets:
  - ▶ Does not contain k: intermediate vertices are  $\leq k-1$ ; the shortest one is  $d_{i,i}^{(k-1)}$
  - Contains k: the shortest one is  $d_{ik}^{(k-1)} + d_{ki}^{(k-1)}$
- So,

$$d_{i,j}^{(k)} = \begin{cases} w_{i,j} & k = 0\\ \min\left\{d_{i,j}^{(k-1)}, d_{i,k}^{(k-1)} + d_{k,j}^{(k-1)}\right\} & k > 0 \end{cases}$$

### Floyd-Warshall: Algorithm

```
FLOYD-WARSHALL(W)

1 D^{(0)} = W

2 \text{for } k = 1, \dots, n

3 D^{(k)} := \left(d_{i,j}^{(k)}\right) be a new n \times n matrix

4 \text{for } i = 1, \dots, n

5 \text{for } j = 1, \dots, n

6 d_{i,j}^{(k)} = \min\left\{d_{i,j}^{(k-1)}, d_{i,k}^{(k-1)} + d_{k,j}^{(k-1)}\right\}
```

Time complexity:  $\Theta(|V|^3)$ , or  $\Theta(n^3)$ 

 $\blacksquare$  Recall that we also need to compute a **predecessor matrix**  $\Pi = (\pi_{i,j})$ 

```
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ight.
```

• *i*-th row of  $\Pi$  defines a shortest-paths tree rooted at *i* 

 $\blacksquare$  Recall that we also need to compute a **predecessor matrix**  $\Pi = (\pi_{i,i})$ 

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- i-th row of  $\Pi$  defines a shortest-paths tree rooted at i
- lacksquare We have  $\Pi^{(k)} = \left(\pi_{i,j}^{(k)}\right)$  corresponding to each  $D^{(k)}$

$$\pi_{i,j}^{(k)} = \begin{cases} & \text{Nil} & i = j \text{ or no path from } i \text{ to } j \\ & \text{with intermediate vertices } \leq k \end{cases}$$

$$\text{Predecessor of } j \text{ on a shortest path from } i \text{ to } j \\ & \text{with intermediate vertices } \leq k \end{cases}$$
otherwise

■ We simply let  $\Pi = \Pi^{(n)}$ 

Base case

$$\pi_{i,j}^{(0)} = \begin{cases} \text{Nil} & \text{if } i = j \text{ or } (i,j) \notin E \\ i & \text{if } i \neq j \text{ and } (i,j) \in E \end{cases}$$

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General case

$$\pi_{i,j}^{(k)} = \left\{ \begin{array}{c} \text{ if } d_{i,j}^{(k-1)} \leq d_{i,k}^{(k-1)} + d_{k,j}^{(k-1)} \\ \text{ if } d_{i,j}^{(k-1)} > d_{i,k}^{(k-1)} + d_{k,j}^{(k-1)} \end{array} \right.$$

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#### Floyd-Warshall: With $\Pi$ matrix update

```
FLOYD-WARSHALL(W)
     Initialize D^{(0)} and \Pi^{(0)}
     for k = 1, \ldots, n
           for i = 1, \ldots, n
                 for j = 1, ..., n
                       else
10
```