

Exploring the Robustness of the Frank-Wolfe method and the Effectiveness of Linear Minimization Oracle

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1 Introduction

Let $Q \subset \mathbb{R}^d$ be a compact convex set and $f : Q \rightarrow \mathbb{R}$ be the objective function. Denote $\|\cdot\|$ to be the l^2 norm. Our main purpose here is to consider the minimization problem here:

$$\begin{aligned} \min_{\lambda} \quad & f(\lambda) \\ \text{s.t.} \quad & \lambda \in Q. \end{aligned} \tag{1}$$

The Frank-Wolfe method is an effective way to address this problem which computes at $\lambda_k \in Q$ the point for linear minimization

$$\tilde{\lambda}_k \in \arg \min_{\lambda \in Q} \{f(\lambda_k) + \nabla f(\lambda_k)^\top (\lambda - \lambda_k)\} \tag{2}$$

and updates with $\lambda_{k+1} = (1 - \bar{\alpha}_k)\lambda_k + \bar{\alpha}_k\tilde{\lambda}_k$ where $\bar{\alpha}_k \in [0, 1)$. Assuming that ∇f is L -Lipschitz on Q , and Q is of diameter D , then Frank-Wolfe achieves the classical $\mathcal{O}(LD^2/k)$ convergence rate for convex functions [6, 4], and $\mathcal{O}(LD^2/\sqrt{k})$ convergence rate for nonconvex functions [7].

It is worth noticing that in the convergence analysis, those auxiliary sequences are frequently used and will also be used in our proof:

$$\beta_k = \frac{1}{\prod_{j=1}^{k-1} (1 - \bar{\alpha}_j)}, \quad \alpha_k = \frac{\beta_k \bar{\alpha}_k}{1 - \bar{\alpha}_k}, \quad k \geq 1. \tag{3}$$

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Here $\{\bar{\alpha}_k\}_{k=1}^{+\infty}$ is sequence of stepsizes in our algorithm. We follow the conventions: $\prod_{j=1}^0 \cdot = 1$ and $\sum_{i=1}^0 \cdot = 0$.

Besides the convergence guarantee, robustness and the efficiency of the Linear Minimization Oracle (LMO) are also important aspects of the Frank-Wolfe method.

To start with, the robustness of Frank-Wolfe, that is, how Frank-Wolfe performs under inexact gradient, is a very interesting problem. With unbiased gradients and bounded variance (or sub-Gaussian tails), Stochastic Frank-Wolfe variants achieve a Frank-Wolfe gap of $\mathcal{O}(\varepsilon)$ with $\mathcal{O}(1/\varepsilon^4)$ gradient evaluations, and variance reduction accelerates finite-sum problems and can achieve the same Frank-Wolfe gap with $\mathcal{O}(1/\varepsilon^3)$ gradient evaluations [11, 5, 9, 8, 16, 12]. For heavy-tailed noise, Stochastic Frank-Wolfe with clipping or robust estimation achieves high-probability guarantees [14, 13].

In the deterministic setting, the situation that the noise is bounded by δ but can be arbitrarily chosen along the training trajectory is often referred to as obtaining a δ -oracle:

$$|(g_\delta(x) - \nabla f(x))^T(x - y)| \leq \delta, \forall y \in Q. \quad (4)$$

Freund and Grigas proves an $\mathcal{O}(1/k + \delta)$ convergence [4], and we shows an $\mathcal{O}(1/\sqrt{k} + \delta)$ convergence for nonconvex functions in this paper.

Another interesting problem occurs when considering objective functions that are convex but non-smooth. Those functions may not obtain a gradient, but they can be equipped with a (δ, L) oracle [3]:

$$0 \leq f(x) - (f_{\delta,L}(y) + g_{\delta,L}(y)^T(x - y)) \leq \frac{L}{2} \|x - y\|^2 + \delta, \forall x, y \in Q.$$

Unlike inexact gradient, this (δ, L) oracle allows the error to interact with the local quadratic model and leads to error accumulation, which shows that the Frank-Wolfe method is only guaranteed to reach a Frank-Wolfe gap of $\mathcal{O}(\sqrt{\delta})$. However, it remains an open problem whether the final guarantee of Frank-Wolfe gap is optimal theoretically. In this paper, we show that

While Frank-Wolfe does not have the same guarantee on the (δ, L) oracle as proximal gradient descent. The ease of computing the Linear Minimization Oracle (LMO) is widely considered a major advantage of the Frank-Wolfe method. However, this belief is currently limited to intuition and set-specific comparisons [1, 10]. Beyond such instances, Woodstock showed that exact projection is never easier than obtaining an ε -accurate LMO, uniformly over compact convex sets [15]. We extend this to *approximate* projections: a single K -projection at a scaled point yields an ε -accurate LMO.

Our contributions.

- (i) **Frank-Wolfe with a δ -oracle (nonconvex).** We show that for L -smooth nonconvex f over a compact convex set, Frank-Wolfe with a directional δ -oracle achieves

$$\min_{0 \leq k \leq K} g(x^k) \leq \sqrt{\frac{2C(f(x^0) - f_{\inf})}{K+1}} + 2\delta,$$

where

$$g(x) = \sup_{y \in Q} \nabla f(y)^T (x - y)$$

- (ii) **Frank-Wolfe with a (δ, L) -oracle.** We show that Frank-Wolfe method is theoretically guaranteed to reach a Frank-Wolfe gap of $\mathcal{O}(\sqrt{\delta})$. We also show that this final Frank-Wolfe gap can be reduced to $\mathcal{O}(\delta)$ when f is convex.
- (iii) **Projection vs. LMO.** We show that a K -approximate projection at $-\lambda x$ produces an ε -accurate LMO at x with $\varepsilon = \mathcal{O}((K + D_C^2)/\lambda)$, reinforcing that coarse projections are not cheaper than accurate LMOs.

2 Frank-Wolfe with a δ -oracle: main result and a tight example

We assume $Q \subset \mathbb{R}^d$ is compact and convex with diameter D , and $f : Q \rightarrow \mathbb{R}$ is convex with L -Lipschitz gradient on Q . We run Frank-Wolfe using the δ -oracle g_δ in Algorithm 1.

Algorithm 1 Frank-Wolfe with a gradient δ -oracle (maximization)

```

1: Initialize  $\lambda_0 \in Q$ .
2: for  $k = 0, 1, 2, \dots$  do
3:   Query  $g_\delta(\lambda_k)$ .
4:   Compute  $\tilde{\lambda}_k \in \arg \min_{\lambda \in Q} \{f(\lambda_k) + g_\delta(\lambda_k)^\top (\lambda - \lambda_k)\}$ .
5:   Update  $\lambda_{k+1} = \lambda_k + \bar{\alpha}_k(\tilde{\lambda}_k - \lambda_k)$  with  $\bar{\alpha}_k \in [0, 1)$ .
6: end for
```

Lemma 1 Under (4), for any $\lambda_k \in Q$,

$$f^* \geq f(\lambda_k) + \min_{\lambda \in Q} g_\delta(\lambda_k)^\top (\lambda - \lambda_k) - \delta.$$

Proof By convexity, $f(\lambda) \geq f(\lambda_k) + \nabla f(\lambda_k)^\top (\lambda - \lambda_k)$ for any $\lambda \in Q$. From (4), $\nabla f(\lambda_k)^\top (\lambda - \lambda_k) \geq g_\delta(\lambda_k)^\top (\lambda - \lambda_k) - \delta$. Therefore,

$$f(\lambda) \geq f(\lambda_k) + g_\delta(\lambda_k)^\top (\lambda - \lambda_k) - \delta.$$

Taking $\min_{\lambda \in Q}$ on both sides yields the claim.

We also recall a subproblem-level accuracy transfer.

Proposition 2 ([4, Prop. 5.1]) Fix $\bar{\lambda} \in Q$ and $\delta \geq 0$. If $\tilde{\lambda} \in \arg \min_{\lambda \in Q} g_\delta(\bar{\lambda})^\top \lambda$, then

$$\nabla f(\bar{\lambda})^\top \tilde{\lambda} \leq \min_{\lambda \in Q} \nabla f(\bar{\lambda})^\top \lambda + 2\delta.$$

Theorem 3 (Nonaccumulation under a δ -oracle[4]) *Let Q be compact convex with diameter D , and f be convex with L -Lipschitz gradient on Q . Let g_δ satisfy (4). For the Frank-Wolfe iterates of Algorithm 1 with stepsizes satisfying $\sum_{k=0}^{+\infty} \bar{\alpha}_k = \infty$ and $\bar{\alpha}_k \downarrow 0$, then*

$$f(\lambda_{k+1}) - f^* \leq (1 - \bar{\alpha}_k)(f(\lambda_k) - f^*) + 2\bar{\alpha}_k\delta + \frac{1}{2}LD^2\bar{\alpha}_k^2, \quad (5)$$

and hence $\limsup_{k \rightarrow \infty} (f(\lambda_k) - f^*) \leq 2\delta$.

Example 4 (Tightness up to constants) *Let $Q = [-1, 1]$, $f(\lambda) = \frac{1}{2}\lambda^2$ (convex, $L = 1$, $D = 2$). Define a δ -oracle by $g_\delta(\lambda) = \nabla f(\lambda) + \frac{\delta}{D} \text{sign}(\lambda)$. Frank-Wolfe with $\bar{\alpha}_k = 2/(k+2)$ converges to a neighborhood whose size is proportional to δ .*

3 Nonconvex objectives with a directional δ -oracle

We now consider *nonconvex* minimization over a compact convex set $S \subset \mathbb{R}^d$:

$$\min_{x \in S} f(x),$$

where f is differentiable and has L -Lipschitz gradient on S . Denote $D := \text{Diam}(S)$ and set

$$C \triangleq \max\{LD^2, GD\} \quad \text{with} \quad G := \sup_{x \in S} \|\nabla f(x)\| < \infty.$$

The Frank-Wolfe (FW) gap at x is

$$g(x) \triangleq \max_{s \in S} \langle \nabla f(x), x - s \rangle.$$

We assume access to a *directional δ -oracle* for the gradient, i.e., for every $x \in S$ there exists $g_\delta(x)$ such that

$$|\langle \nabla f(x) - g_\delta(x), s - x \rangle| \leq \delta \quad \forall s \in S. \quad (6)$$

Define the *approximate Frank-Wolfe gap*

$$\tilde{g}(x) \triangleq \max_{s \in S} \langle g_\delta(x), x - s \rangle.$$

From (6) it follows that

$$|g(x) - \tilde{g}(x)| \leq \delta, \quad (7)$$

where $s_\delta(x) \in \arg \max_{s \in S} \langle g_\delta(x), x - s \rangle$.

Algorithm 2 Nonconvex Frank-Wolfe with a directional δ -oracle

- 1: **Input:** $x^0 \in S$, curvature constant $C \geq \max\{LD^2, GD\}$, error level $\delta \geq 0$.
 - 2: **for** $k = 0, 1, 2, \dots$ **do**
 - 3: Obtain $g_\delta(x^k)$ that satisfies (6); set $s^k \in \arg \max_{s \in S} \langle g_\delta(x^k), x^k - s \rangle$ and $\tilde{g}_k := \langle g_\delta(x^k), x^k - s^k \rangle = \tilde{g}(x_k)$.
 - 4: Stepsize: $\bar{\alpha}_k := \min \left\{ \frac{(\tilde{g}_k - \delta)_+}{C}, 1 \right\}$, where $(u)_+ := \max\{u, 0\}$.
 - 5: Update: $x^{k+1} \leftarrow x^k + \bar{\alpha}_k(s^k - x^k)$.
 - 6: **end for**
-

Lemma 5 (One-step decrease) *The iterates of Algorithm 2 satisfy*

$$f(x^{k+1}) \leq f(x^k) - \frac{(\tilde{g}_k - \delta)_+^2}{2C}. \quad (8)$$

Proof L -smoothness gives

$$\begin{aligned} f(x^{k+1}) &\leq f(x^k) + \bar{\alpha}_k \langle \nabla f(x^k), s^k - x^k \rangle + \frac{L}{2} \bar{\alpha}_k^2 \|s^k - x^k\|^2 \\ &\leq f(x^k) + \bar{\alpha}_k \langle g_\delta(x^k), s^k - x^k \rangle + \bar{\alpha}_k \delta + \frac{C}{2} \bar{\alpha}_k^2 \\ &= f(x^k) - \bar{\alpha}_k \tilde{g}(x^k) + \bar{\alpha}_k \delta + \frac{C}{2} \bar{\alpha}_k^2 \\ &= f(x^k) - \bar{\alpha}_k (\tilde{g}_k - \delta) + \frac{C}{2} \bar{\alpha}_k^2 \end{aligned}$$

using (7) and $\|s^k - x^k\| \leq D$.

With $\bar{\alpha}_k = (\tilde{g}_k - \delta)_+ / C$,

$$f(x^{k+1}) \leq f(x^k) - \frac{1}{2C} (\tilde{g}_k - \delta)_+^2,$$

since $\bar{\alpha}_k = 0$ if $\tilde{g}_k - \delta \leq 0$.

Theorem 6 (Nonconvex Frank-Wolfe with directional δ -oracle) *Let f be L -smooth on a compact convex set S of diameter D and let $C \geq \max\{LD^2, GD\}$. Suppose the directional δ -oracle (6) is available. Then the iterates of Algorithm 2 satisfy, for all $K \geq 0$,*

$$\min_{0 \leq k \leq K} g(x^k) \leq \sqrt{\frac{2C(f(x^0) - f_{\inf})}{K+1}} + 2\delta, \quad (9)$$

where $f_{\inf} := \inf_{x \in S} f(x)$. In particular, to reach a Frank-Wolfe gap at most $\varepsilon > 2\delta$, it suffices to take

$$K+1 \geq \frac{2C(f(x^0) - f_{\inf})}{(\varepsilon - 2\delta)^2}.$$

Remark 7 (Discussion and special cases) (i) When $\delta = 0$ the bound reduces to the classical nonconvex Frank-Wolfe rate. (ii) For $\delta > 0$, the method converges to an $O(\delta)$ neighborhood in the Frank-Wolfe gap; the error does not accumulate across iterations. (iii) The stepsize uses \tilde{g}_k (computed “for free” while solving the LMO with g_δ), exactly mirroring the steepest-feasible steps in standard Frank-Wolfe. (iv) Any $C \geq LD^2$ works for (8); taking $C \geq \max\{LD^2, GD\}$ ensures $\alpha_k \leq 1$ without extra capping.

4 Frank-Wolfe with a (δ, L) -oracle: error does not accumulate for convex functions

Algorithm 3 Frank-Wolfe with a (δ, L) -oracle (maximization)

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1: Initialize  $\lambda_0 \in Q$ .
2: for  $k = 0, 1, 2, \dots$  do
3:   Query  $(f_{\delta,L}(\lambda_k), g_{\delta,L}(\lambda_k))$ .
4:   Compute  $\tilde{\lambda}_k \in \arg \min_{\lambda \in Q} \langle g_{\delta,L}(\lambda_k), \lambda - \lambda_k \rangle$ . Denote  $g(\lambda_k) = \nabla f(\lambda_k)^T (\lambda_k - \tilde{\lambda}_k)$ .
5:   Update  $\lambda_{k+1} = \lambda_k + \bar{\alpha}_k (\tilde{\lambda}_k - \lambda_k)$  with  $\bar{\alpha}_k \in [0, 1)$ .
6: end for

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We adopt the Devolder–Glineur–Nesterov (δ, L) -oracle for the function f [2]: for any $\bar{\lambda} \in Q$, the oracle returns $(f_{\delta,L}(\bar{\lambda}), g_{\delta,L}(\bar{\lambda}))$ such that for any $\lambda \in Q$

$$\begin{aligned} \text{(upper)} \quad f(\lambda) &\leq f_{\delta,L}(\bar{\lambda}) + \langle g_{\delta,L}(\bar{\lambda}), \lambda - \bar{\lambda} \rangle + \frac{L}{2} \|\lambda - \bar{\lambda}\|^2 + \delta, \\ \text{(lower)} \quad f(\lambda) &\geq f_{\delta,L}(\bar{\lambda}) + \langle g_{\delta,L}(\bar{\lambda}), \lambda - \bar{\lambda} \rangle. \end{aligned} \quad (10)$$

Theorem 8 ([4] **Theorem 5.3**) *If the step-size sequence $\{\bar{\alpha}_k\}$ is used in the iterate sequences of the Frank-Wolfe method with the (δ, L) -oracle (Algorithm 3),*

$$f(\lambda_{k+1}) - f^* \leq \frac{f(\lambda_0) - f^*}{\beta_{k+1}} + \frac{\frac{1}{2}C \sum_{i=1}^k \bar{\alpha}_i^2 \beta_{i+1}}{\beta_{k+1}} + \frac{2\delta \sum_{i=1}^k \beta_{i+1}}{\beta_{k+1}}, \quad \forall k \geq 0, \quad (11)$$

where $C = LD^2$.

Remark 9 Consider the right hand side of Equation (11), we have that

$$\begin{aligned} &\frac{f_0 - f^*}{\beta_{k+1}} + \frac{\frac{1}{2}C \sum_{i=1}^k \frac{\alpha_i^2}{\beta_{i+1}}}{\beta_{k+1}} + \frac{\sum_{i=1}^k \beta_{i+1} \delta}{\beta_{k+1}} \\ &= \frac{f_0 - f^*}{\beta_{k+1}} + \frac{\sum_{i=1}^k (\frac{1}{2}C_{h,Q} \frac{\alpha_i^2}{\beta_{i+1}} + \beta_{i+1} \delta)}{\beta_{k+1}} \\ &\geq \frac{f_0 - f^*}{\beta_{k+1}} + \frac{\sum_{i=1}^k \alpha_i \sqrt{2C_{h,Q} \delta}}{\beta_{k+1}} \\ &= \frac{f_0 - f^*}{\beta_{k+1}} + \sqrt{2C_{h,Q} \delta} \frac{\beta_{k+1} - 1}{\beta_{k+1}}. \end{aligned}$$

For k sufficiently large, we have that

$$0 < \frac{\beta_2 - 1}{\beta_2} \leq \frac{\beta_{k+1} - 1}{\beta_{k+1}} \leq 1.$$

Therefore, error accumulation means that, in order to achieve a first-order accurate solution, we need a second-order accurate gradient.

Example 10 When we are using a constant step size $\bar{\alpha}_k = \bar{\alpha}$, and we take $\delta_i = \delta$, then we have that

$$\beta_k = (1 - \bar{\alpha})^{-k+1}, \alpha_k = \bar{\alpha}(1 - \bar{\alpha})^{-k}.$$

We will show in the appendix that, if we take $\bar{\alpha} = 1 - (k-1)^{-1/(k-2)}$, then

$$\bar{\alpha} = 1 - (k-1)^{-1/(k-2)} = 1 - e^{-\frac{\log(k-1)}{k-2}} \in \left[\frac{1}{e} \frac{\log(k-1)}{k-2}, \frac{\log(k-1)}{k-2} \right].$$

$$\begin{aligned} & f(\lambda_{k+1}) - f^* \\ & \leq \frac{1}{2} C ((1 - \bar{\alpha})^{k-1} + \bar{\alpha}) + \frac{\delta}{\bar{\alpha}} \\ & \leq \frac{1}{2} C ((1 - \bar{\alpha})^{k-2} + \bar{\alpha}) + \frac{\delta}{\bar{\alpha}} \\ & = \frac{1}{2} C \left(\frac{1}{k-1} + 1 - (k-1)^{-\frac{1}{k-2}} \right) + \frac{\delta}{\bar{\alpha}} \\ & = \frac{1}{2} C \left(\frac{1}{k-1} + 1 - e^{-\frac{\log(k-1)}{k-2}} \right) + \frac{\delta}{\bar{\alpha}} \\ & \leq \frac{1}{2} C \left(\frac{1}{k-1} + \frac{\log(k-1)}{k-2} \right) + \frac{\delta}{\bar{\alpha}} \end{aligned}$$

Therefore, in order to achieve a convergence rate of $\tilde{O}(\frac{1}{k})$, it suffices to let

$$\delta \sim O\left(\frac{\bar{\alpha}}{k}\right) = O\left(\frac{\log(k)}{k^2}\right).$$

However, if we assume that f is convex(not necessarily smooth), we can show that no error accumulates.

Theorem 11 (Nonaccumulation under convex functions[4]) Let Q be compact convex with diameter D , and f be convex with (δ, L) -oracle on Q . Let $(f_{\delta,L}, g_{\delta,L})$ satisfy (10). For the Frank-Wolfe iterates of Algorithm 1 with stepsizes satisfying $\sum_{k=0}^{+\infty} \bar{\alpha}_k = \infty$ and $\bar{\alpha}_k \downarrow 0$, then

$$f(\lambda_{k+1}) - f^* \leq (1 - \bar{\alpha}_k)(f(\lambda_k) - f^*) + 2\bar{\alpha}_k\delta + \frac{1}{2}LD^2\bar{\alpha}_k^2, \quad (12)$$

and hence $\limsup_{k \rightarrow \infty} (f(\lambda_k) - f^*) \leq 2\delta$.

5 Projection vs. LMO: accurate linear minimization beats coarse projection

Let (\cdot, \cdot) denote the Euclidean inner product and $\|\cdot\|$ its norm. For a nonempty compact convex $C \subset \mathbb{R}^d$, define the projection $\text{Proj}_C(x) = \arg \min_{c \in C} \frac{1}{2}\|c - x\|^2$ and the linear minimization oracle $\text{LMO}_C(z) = \arg \min_{c \in C} (c, z)$. We consider a K -approximate projection $p' \in C$ at x such that

$$\frac{1}{2}\|p' - x\|^2 \leq \min_{c \in C} \frac{1}{2}\|c - x\|^2 + K.$$

Proposition 12 *If $p' \in C$ is a K -approximate projection of x onto C , then for all $c \in C$,*

$$(c - p', x - p') \leq K + \frac{1}{2}\|c - p'\|^2.$$

Proof From the definition of p' , $\frac{1}{2}\|p' - x\|^2 \leq \frac{1}{2}\|c - x\|^2 + K$ for all $c \in C$. Expanding the squares and simplifying gives $(c - p', x - p') \leq K + \frac{1}{2}\|c - p'\|^2$.

Theorem 13 (From K -projection to accurate LMO) *Let $x \in \mathbb{R}^d$ and nonempty compact convex $C \subset \mathbb{R}^d$ with diameter $\delta_C := \sup_{c_1, c_2 \in C} \|c_1 - c_2\|$ and radius $\mu_C := \sup_{c \in C} \|c\|$. Let $v \in \text{LMO}_C(x)$ and $p' \in C$ be a K -approximate projection of $-\lambda x$ for some $\lambda > 0$. Then*

$$0 \leq (p', x) - (v, x) \leq \frac{K + \frac{1}{2}\delta_C^2 + \min\{\mu_C\delta_C, \mu_C^2\}}{\lambda}.$$

In particular, choosing $\lambda \geq (K + \frac{1}{2}\delta_C^2 + \min\{\mu_C\delta_C, \mu_C^2\})/\varepsilon$ ensures $(p', x) \leq \min_{c \in C} (c, x) + \varepsilon$, i.e., $p' \in \varepsilon\text{-LMO}_C(x)$.

Discussion. This extends the exact-projection implication of [15] to *inexact* projections: one K -projection at a scaled point yields an ε -accurate LMO. In particular, accurate linear minimization is *no slower* than coarse projection, uniformly over compact convex sets.

Appendix A. Proof of Theorem 3

Let $D = \text{Diam}(Q)$. Lipschitz smoothness of f and (4) yield, for the Frank-Wolfe step $\lambda_{k+1} = \lambda_k + \bar{\alpha}_k(\tilde{\lambda}_k - \lambda_k)$,

$$\begin{aligned} f(\lambda_{k+1}) &\leq f(\lambda_k) + \nabla f(\lambda_k)^\top (\lambda_{k+1} - \lambda_k) + \frac{L}{2}\|\lambda_{k+1} - \lambda_k\|^2 \\ &= f(\lambda_k) + \bar{\alpha}_k \nabla f(\lambda_k)^\top (\tilde{\lambda}_k - \lambda_k) + \frac{L}{2}\bar{\alpha}_k^2 \|\tilde{\lambda}_k - \lambda_k\|^2 \\ &\leq f(\lambda_k) + \bar{\alpha}_k g_\delta(\lambda_k)^\top (\tilde{\lambda}_k - \lambda_k) + \bar{\alpha}_k \delta + \frac{L}{2}\bar{\alpha}_k^2 \|\tilde{\lambda}_k - \lambda_k\|^2 \\ &\leq (1 - \bar{\alpha}_k)f(\lambda_k) + \bar{\alpha}_k (f(\lambda_k) + g_\delta(\lambda_k)^\top (\tilde{\lambda}_k - \lambda_k) - \delta) + 2\bar{\alpha}_k \delta + \frac{L}{2}D^2\bar{\alpha}_k^2 \\ &\leq (1 - \bar{\alpha}_k)f(\lambda_k) + \bar{\alpha}_k f^* + 2\bar{\alpha}_k \delta + \frac{L}{2}D^2\bar{\alpha}_k^2, \end{aligned}$$

where the third line uses $\|\tilde{\lambda}_k - \lambda_k\| \leq D$ and the last line uses Lemma 1. Subtracting both sides from f^* gives (12).

In order to continue, we multiply β_k by both sides of Equation (12); we get that

$$\beta_{k+1}(f(\lambda_{k+1}) - f^*) \leq \beta_k(f(\lambda_k) - f^*) + 2\bar{\alpha}_k\beta_{k+1}\delta + \frac{L}{2}D^2\bar{\alpha}_k^2\beta_{k+1}.$$

By taking summation, we get that

$$\begin{aligned} \beta_{k+1}(f(\lambda_{k+1}) - f^*) &\leq (f(\lambda_0) - f^*) + 2\delta \sum_{j=0}^k \bar{\alpha}_j \beta_{j+1} + \frac{L}{2}D^2 \sum_{j=0}^k \bar{\alpha}_j^2 \beta_{j+1} \\ &\leq (f(\lambda_0) - f^*) + 2\delta \sum_{j=0}^k (\beta_{j+1} - \beta_j) + \frac{L}{2}D^2 \sum_{j=0}^k \bar{\alpha}_j^2 \beta_{j+1} \end{aligned}$$

Since $\beta_{k+1} - \beta_k = \bar{\alpha}_k \beta_{k+1}$, the summation term telescopes as

$$\sum_{j=0}^k (\beta_{j+1} - \beta_j) = \beta_{k+1} - 1.$$

Substituting this back, we obtain

$$\beta_{k+1}(f(\lambda_{k+1}) - f^*) \leq (f(\lambda_0) - f^*) + 2\delta(\beta_{k+1} - 1) + \frac{L}{2}D^2 \sum_{j=0}^k \bar{\alpha}_j^2 \beta_{j+1}.$$

Dividing both sides by β_{k+1} yields

$$f(\lambda_{k+1}) - f^* \leq \frac{f(\lambda_0) - f^*}{\beta_{k+1}} + 2\delta\left(1 - \frac{1}{\beta_{k+1}}\right) + \frac{L}{2}D^2 \frac{\sum_{j=0}^k \bar{\alpha}_j^2 \beta_{j+1}}{\beta_{k+1}}.$$

Take any $1 < J < k$,

$$\begin{aligned} \frac{\sum_{j=0}^k \bar{\alpha}_j^2 \beta_{j+1}}{\beta_{k+1}} &= \sum_{j=0}^J \bar{\alpha}_j^2 \prod_{t=J+1}^k (1 - \bar{\alpha}_t) + \sum_{j=J+1}^k \bar{\alpha}_j^2 \prod_{t=J+1}^k (1 - \bar{\alpha}_t) \\ &\leq \sum_{j=0}^J \bar{\alpha}_j^2 \prod_{t=J+1}^k (1 - \bar{\alpha}_t) + \sum_{j=J+1}^k \bar{\alpha}_j^2. \end{aligned}$$

Therefore,

$$\limsup_{k \rightarrow +\infty} \frac{\sum_{j=0}^k \bar{\alpha}_j^2 \beta_{j+1}}{\beta_{k+1}} \leq \sum_{j=J+1}^{+\infty} \bar{\alpha}_j^2, \forall J > 1.$$

Hence,

$$\limsup_{k \rightarrow +\infty} \frac{\sum_{j=0}^k \bar{\alpha}_j^2 \beta_{j+1}}{\beta_{k+1}} = 0.$$

Hence

$$\limsup_{k \rightarrow \infty} (f(\lambda_k) - f^*) \leq 2\delta.$$

This completes the proof.

Appendix B. Proof of Theorem 6

By Lemma 5 we have

$$f(x^{k+1}) \leq f(x^k) - \frac{(\tilde{g}_k - \delta)_+^2}{2C}.$$

Summing from $k = 0$ to K yields

$$\sum_{k=0}^K (\tilde{g}_k - \delta)_+^2 \leq 2C(f(x^0) - f(x^{K+1})) \leq 2C(f(x^0) - f_{\inf}).$$

Therefore

$$\min_{0 \leq k \leq K} (g(x^k) - 2\delta)_+ \leq \min_{0 \leq k \leq K} (\tilde{g}_k - \delta)_+ \leq \sqrt{2C(f(x^0) - f_{\inf})/(K+1)}.$$

□

Appendix C. Proof of Theorem 8

$$\begin{aligned}
f(\lambda_{k+1}) &\leq f(\lambda_k) + g_{\delta,L}(\lambda_k)^T(\lambda_{k+1} - \lambda_k) + 2\delta + \frac{1}{2}L\|\lambda_{k+1} - \lambda_k\|^2 \\
&= f(\lambda_k) + \bar{\alpha}_k g_{\delta,L}(\lambda_k)^T(\tilde{\lambda}_k - \lambda_k) + 2\delta + \frac{1}{2}\bar{\alpha}_k^2 L_{h,Q}\|\tilde{\lambda}_k - \lambda_k\|^2 \\
&\leq (1 - \bar{\alpha}_k)f(\lambda_k) + \bar{\alpha}_k(f(\lambda_k) + g_{\delta,L}(\lambda_k)^T(\tilde{\lambda}_k - \lambda_k) - \delta) + (2 + \bar{\alpha}_k)\delta + \frac{1}{2}C\bar{\alpha}_k^2 \\
&\leq (1 - \bar{\alpha}_k)h(\lambda_k) + \bar{\alpha}_k f^* + 3\delta + \frac{1}{2}C\bar{\alpha}_k^2 \\
&\leq (1 - \bar{\alpha}_k)h(\lambda_k) + \bar{\alpha}_k f^* + 3\delta + \frac{1}{2}C\bar{\alpha}_k^2
\end{aligned}$$

Hence,

$$f(\lambda_{k+1}) - f^* \leq (1 - \bar{\alpha}_k)(f(\lambda_k) - f^*) + 3\delta + \frac{1}{2}C\bar{\alpha}_k^2.$$

Therefore,

$$\beta_k(f(\lambda_{k+1}) - f^*) \leq \beta_{k-1}(f(\lambda_k) - f^*) + 3\delta\beta_k + \frac{1}{2}C\bar{\alpha}_k^2\beta_k.$$

By taking summation, we get that

$$\beta_k(f(\lambda_{k+1}) - f^*) \leq (f(\lambda_0) - f^*) + 3\delta \sum_{j=1}^k \beta_j + \frac{1}{2}C \sum_{j=1}^k \bar{\alpha}_j^2 \beta_j.$$

Dividing both side by β_k yields the result. \square

Appendix D. Proof of Theorem 11

Since $\lambda_{k+1} = (1 - \bar{\alpha}_k)\lambda_k + \bar{\alpha}_k\tilde{\lambda}_k$.

$$f(\tilde{\lambda}_k) \leq f(\lambda_k) + g_{\delta,L}(\lambda_k)^T(\tilde{\lambda}_k - \lambda_k) + 2\delta + \frac{1}{2}L\|\lambda_{k+1} - \lambda_k\|^2.$$

Since $f(\lambda_{k+1}) \leq (1 - \bar{\alpha}_k)f(\lambda_k) + \bar{\alpha}_k f(\tilde{\lambda}_k)$,

$$f(\lambda_{k+1}) \leq f(\lambda_k) + \bar{\alpha}_k g_{\delta,L}(\lambda_k)^T(\tilde{\lambda}_k - \lambda_k) + 2\bar{\alpha}_k\delta + \frac{1}{2}\bar{\alpha}_k^2 L\|\tilde{\lambda}_k - \lambda_k\|^2.$$

The rest parts are the same as the proof of theorem 3.

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