

State Estimation for Robotics Solution

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My personal solution of exercises in "State Estimation for Robotics", D. Barfoot.

Post on https://github.com/taohu1994/State_Estimation_for_Robotics_solution

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1 Chapter 2. Primer on Probability Theory

1.1 2.5.1

Let $\mathbf{u} = [u_1, \dots, u_n]^T$, $\mathbf{v} = [v_1, \dots, v_n]^T$, we have

$$\mathbf{u}^T \mathbf{v} = u_1 v_1 + u_2 v_2 + \dots + u_n v_n$$

and

$$\mathbf{v}^T \mathbf{u} = \begin{bmatrix} v_1 u_1 & \dots & \dots & v_1 u_n \\ \vdots & v_2 u_2 & & \vdots \\ \vdots & & \ddots & \vdots \\ v_n u_1 & \dots & \dots & v_n u_n \end{bmatrix}.$$

It is clear that $\mathbf{u}^T \mathbf{v} = \text{tr}(\mathbf{v}^T \mathbf{u})$.

1.2 2.5.2

Recapping the equation (2.29),

$$I(\mathbf{x}, \mathbf{y}) = H(\mathbf{x}) + H(\mathbf{y}) - H(\mathbf{x}, \mathbf{y}).$$

For two independent variables \mathbf{x}, \mathbf{y} , we have

$$I(\mathbf{x}, \mathbf{y}) = 0.$$

Then, it is clear that

$$H(\mathbf{x}) + H(\mathbf{y}) = H(\mathbf{x}, \mathbf{y}).$$

1.3 2.5.3

For a Gaussian random variable, $\mathbf{x} \sim \mathcal{N}(\boldsymbol{\mu}, \boldsymbol{\Sigma})$, Its covariance matrix could be presented

$$\begin{aligned} \boldsymbol{\Sigma} &= E\{(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T\} \\ &= E\{\mathbf{x}\mathbf{x}^T\} - 2E\{\mathbf{x}\boldsymbol{\mu}^T\} + \boldsymbol{\mu}\boldsymbol{\mu}^T \\ &= E\{\mathbf{x}\mathbf{x}^T\} - \boldsymbol{\mu}\boldsymbol{\mu}^T. \end{aligned}$$

We rewrite it as

$$E\{\mathbf{x}\mathbf{x}^T\} = \boldsymbol{\Sigma} + \boldsymbol{\mu}\boldsymbol{\mu}^T.$$

1.4 2.5.4

We have

$$\begin{aligned}
E[\mathbf{x}] &= \int_{-\infty}^{+\infty} \mathbf{x} (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right) d\mathbf{x} \\
&= \int_{-\infty}^{+\infty} (\mathbf{y} + \boldsymbol{\mu}) (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1}\mathbf{y}\right) d\mathbf{y} \\
&= \int_{-\infty}^{+\infty} \mathbf{y} (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1}\mathbf{y}\right) d\mathbf{y} + \int_{-\infty}^{+\infty} \boldsymbol{\mu} (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1}\mathbf{y}\right) d\mathbf{y},
\end{aligned}$$

where we use the substitution $\mathbf{y} = \mathbf{x} - \boldsymbol{\mu}$. The first integral part could be rewritten

$$\begin{aligned}
&\int_{-\infty}^{+\infty} \mathbf{y} (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1}\mathbf{y}\right) d\mathbf{y} \\
&= \int_{-\infty}^0 \mathbf{y} (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1}\mathbf{y}\right) d\mathbf{y} + \int_0^{+\infty} \mathbf{y} (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1}\mathbf{y}\right) d\mathbf{y} \\
&= -\int_0^{+\infty} -\mathbf{y} (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1}\mathbf{y}\right) d(-\mathbf{y}) + \int_0^{+\infty} \mathbf{y} (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1}\mathbf{y}\right) d\mathbf{y} \\
&= 0.
\end{aligned}$$

Therefore, considering the substitution $\mathbf{z} = \sqrt{\frac{1}{2}} \Sigma^{-\frac{1}{2}} \mathbf{x}$, the mean became

$$\begin{aligned}
E[\mathbf{x}] &= \boldsymbol{\mu} (2\pi)^{-\frac{N}{2}} 2^{\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} |\Sigma|^{\frac{1}{2}} \int_{-\infty}^{+\infty} \exp(-\mathbf{z}^T \mathbf{z}) d\mathbf{z} \\
&= \boldsymbol{\mu} \pi^{-\frac{N}{2}} \int_{-\infty}^{+\infty} \exp(-\mathbf{z}^T \mathbf{z}) d\mathbf{z} \\
&= \boldsymbol{\mu}.
\end{aligned}$$

Note that $\int_{-\infty}^{+\infty} \exp(-x^2) dx = \sqrt{\pi}$.

1.5 2.5.5

We present the variance as follow:

$$\begin{aligned}
Var[\mathbf{x}] &= (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} \int_{-\infty}^{+\infty} (\mathbf{x} - \boldsymbol{\mu})^T (\mathbf{x} - \boldsymbol{\mu}) \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right) d\mathbf{x} \\
&= (2\pi)^{-\frac{N}{2}} |\Sigma|^{-\frac{1}{2}} |\Sigma|^{\frac{1}{2}} 2^{\frac{N}{2}} 2^N \Sigma \int_{-\infty}^{+\infty} \mathbf{y}^T \mathbf{y} \exp(-\mathbf{y}^T \mathbf{y}) d\mathbf{y} \\
&= (\pi)^{-\frac{N}{2}} \Sigma 2^N 2 \int_0^{+\infty} \frac{1}{2} \mathbf{t}^{\frac{1}{2}} \exp(-\mathbf{t}) d\mathbf{t} \\
&= \pi^{-\frac{N}{2}} \Gamma\left(\frac{3}{2}\right) 2^N \Sigma \\
&= \pi^{-\frac{N}{2}} \left(\frac{\sqrt{\pi}}{2}\right)^N 2^N \Sigma \\
&= \Sigma.
\end{aligned}$$

Here we use the substitutions $\mathbf{y} = \sqrt{\frac{1}{2}}\Sigma^{-\frac{1}{2}}(\mathbf{x} - \boldsymbol{\mu})$ and $\mathbf{t} = \mathbf{y}^T \mathbf{y}$. Note that

$$\int_0^{+\infty} \frac{1}{2} \mathbf{t}^{\frac{1}{2}} \exp(-\mathbf{t}) d\mathbf{t} = \Gamma(\frac{3}{2}),$$

where $\Gamma(\cdot)$ is the Gamma function.

1.6 2.5.6

Product of K Gaussian PDFs could be written

$$\begin{aligned} & \eta \prod_{k=1}^K \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu}_k)^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu}_k)\right) \\ &= \eta \exp\left(-\frac{1}{2} \sum_{k=1}^K (\mathbf{x} - \boldsymbol{\mu}_k)^T \Sigma_k^{-1}(\mathbf{x} - \boldsymbol{\mu}_k)\right) \\ &= \eta \exp\left(-\frac{1}{2} \left(\mathbf{x}^T \sum_{k=1}^K \Sigma_k^{-1} \mathbf{x} - \mathbf{x}^T \sum_{k=1}^K \Sigma_k^{-1} \boldsymbol{\mu}_k - \left(\sum_{k=1}^K \boldsymbol{\mu}_k^T \Sigma_k^{-1} \right) \mathbf{x} + \sum_{k=1}^K \boldsymbol{\mu}_k^T \Sigma_k^{-1} \boldsymbol{\mu}_k \right)\right) \\ &= \eta \exp\left(-\frac{1}{2} \left(\mathbf{x}^T \Sigma^{-1} \mathbf{x} - \mathbf{x}^T \Sigma^{-1} \boldsymbol{\mu} - \boldsymbol{\mu}^T \Sigma^{-1} \mathbf{x} + \boldsymbol{\mu}^T \Sigma^{-1} \boldsymbol{\mu} \right)\right) \exp\left(-\frac{1}{2} \left(\sum_{k=1}^K \boldsymbol{\mu}_k^T \Sigma_k^{-1} \boldsymbol{\mu}_k - \boldsymbol{\mu}^T \Sigma^{-1} \boldsymbol{\mu} \right)\right) \\ &= \eta' \exp\left(-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right), \end{aligned}$$

where η' is a normalization constant to enforce the axiom of the total probability, $\Sigma^{-1} = \sum_{k=1}^K \Sigma_k^{-1}$ and $\Sigma^{-1} \boldsymbol{\mu} = \sum_{k=1}^K \Sigma_k^{-1} \boldsymbol{\mu}_k$.

1.7 2.5.7

Let $\boldsymbol{\mu}_i, \Sigma_i$ denote the mean and variance of variable \mathbf{x}_i . As $\forall i, j \in [1, K], i \neq j, \mathbf{x}_i, \mathbf{x}_j$ are statistically independent. We have $E[(\mathbf{x}_i - \boldsymbol{\mu}_i)(\mathbf{x}_i - \boldsymbol{\mu}_i)^T] = \Sigma_i$ and $E[(\mathbf{x}_i - \boldsymbol{\mu}_i)(\mathbf{x}_j - \boldsymbol{\mu}_j)^T] = \mathbf{0}$. The mean of \mathbf{x} could be presented

$$E[\mathbf{x}] = \sum_{(i=1)}^K \omega_i E[\mathbf{x}_i] = \sum_{(i=1)}^K \omega_i \boldsymbol{\mu}_i = \boldsymbol{\mu}$$

The variance of \mathbf{x} could be presented

$$\begin{aligned} Var(\mathbf{x}) &= E[(\omega_1(\mathbf{x}_1 - \boldsymbol{\mu}_1) + \cdots + \omega_K(\mathbf{x}_K - \boldsymbol{\mu}_K))(\omega_1(\mathbf{x}_1 - \boldsymbol{\mu}_1) + \cdots + \omega_K(\mathbf{x}_K - \boldsymbol{\mu}_K))^T] \\ &= \sum_{i=1}^K \omega_i^2 E\{(\mathbf{x}_i - \boldsymbol{\mu}_i)(\mathbf{x}_i - \boldsymbol{\mu}_i)^T\} + \sum_{\forall i, j \in [1, K], i \neq j} \omega_i \omega_j E\{(\mathbf{x}_i - \boldsymbol{\mu}_i)(\mathbf{x}_j - \boldsymbol{\mu}_j)^T\} \\ &= \sum_{i=1}^K \omega_i^2 E\{(\mathbf{x}_i - \boldsymbol{\mu}_i)(\mathbf{x}_i - \boldsymbol{\mu}_i)^T\} \\ &= \sum_{i=1}^K \omega_i^2 \Sigma_i. \end{aligned}$$

1.8 2.5.8

Note $\mathbf{x} = [x_1, x_2, \dots, x_K]^T$. For scalar $x_i \in \mathbf{x}$, we have $x_i \sim \mathcal{N}(0, 1)$. And $\forall i, j \in [1, K], i \neq j, E\{x_i x_i\} = 1, E\{x_i x_j\} = 0$. We write the mean of \mathbf{y} as

$$\begin{aligned} E\{\mathbf{x}^T \mathbf{x}\} &= E\{x_1 x_1 + \dots + x_K x_K\} \\ &= E\{x_1 x_1\} + \dots + E\{x_K x_K\} \\ &= \sum_{i=1}^K E\{x_i x_i\} \\ &= K. \end{aligned}$$

The variance of \mathbf{y} ,

$$\begin{aligned} \text{Var}(\mathbf{y}) &= E\{(\mathbf{x}^T \mathbf{x} - K)(\mathbf{x}^T \mathbf{x} - K)^T\} \\ &= E\{\mathbf{x}^T \mathbf{x} \mathbf{x}^T \mathbf{x}\} - 2E\{\mathbf{x} \mathbf{x}^T\}K + K^2 \\ &= E\{(x_1 x_1 + \dots + x_K x_K)(x_1 x_1 + \dots + x_K x_K)\} - K^2 \\ &= E\left\{\sum_{i=1}^K x_i x_i x_i x_i\right\} + E\left\{\sum_{\forall i, j \in [1, K], i \neq j} x_i x_i x_j x_j\right\} - K^2 \\ &= KE\{x_i x_i x_i x_i\} + (K^2 - K)E\{x_i x_i x_j x_j\} - K^2 \\ &= 2K. \end{aligned}$$

Note that here we use the Isserlis' Theorem and equation (2.40), that

$$E\{x_i x_i x_i x_i\} = 3E\{x_i x_i\}E\{x_i x_i\} = 3.$$

and

$$E\{x_i x_i x_j x_j\} = E\{x_i x_i\}E\{x_j x_j\} + 2E\{x_i x_j\}E\{x_i x_j\} = 1.$$

1.9 ex 2.4

The integrate of an odd function is zero in the symmetric interval.

$$\begin{aligned}
E(\mathbf{x}) &= \int_{-\infty}^{+\infty} \mathbf{x} p(\mathbf{x}) d\mathbf{x} \\
&= \int_{-\infty}^{+\infty} \frac{\mathbf{x}}{\sqrt{(2\pi)^N \det \Sigma}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right) d\mathbf{x} \\
&= \int_{-\infty}^{+\infty} \frac{\mathbf{y} + \boldsymbol{\mu}}{\sqrt{(2\pi)^N \det \Sigma}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1} \mathbf{y}\right) d\mathbf{y} \\
&= \underbrace{\int_{-\infty}^{+\infty} \frac{\mathbf{y}}{\sqrt{(2\pi)^N \det \Sigma}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1} \mathbf{y}\right) d\mathbf{y}}_0 + \int_{-\infty}^{+\infty} \frac{\boldsymbol{\mu}}{\sqrt{(2\pi)^N \det \Sigma}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1} \mathbf{y}\right) d\mathbf{y} \\
&= \boldsymbol{\mu} \underbrace{\int_{-\infty}^{+\infty} \frac{1}{\sqrt{(2\pi)^N \det \Sigma}} \exp\left(-\frac{1}{2}\mathbf{y}^T \Sigma^{-1} \mathbf{y}\right) d\mathbf{y}}_{\mathbf{y} \sim \mathcal{N}(0, \Sigma)} \\
&= \boldsymbol{\mu} \underbrace{\int_{-\infty}^{+\infty} p(\mathbf{y}) d\mathbf{y}}_1 \\
&= \boldsymbol{\mu}
\end{aligned} \tag{1}$$

1.10 ex 2.5

$$\begin{aligned}
E\left((\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T\right) &= \int_{-\infty}^{\infty} (\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T \frac{1}{\sqrt{(2\pi)^N \det \Sigma}} \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right) d\mathbf{x} \\
&= \frac{1}{\sqrt{(2\pi)^N \det \Sigma}} \int_{-\infty}^{\infty} \underbrace{d\left(-\Sigma(\mathbf{x} - \boldsymbol{\mu}) \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)\right)}_{\text{odd,}=0} \\
&\quad + \frac{1}{\sqrt{(2\pi)^N \det \Sigma}} \int_{-\infty}^{\infty} \Sigma \exp\left(-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1}(\mathbf{x} - \boldsymbol{\mu})\right) d\mathbf{x} \\
&= \mathbf{0} + \Sigma = \Sigma
\end{aligned} \tag{2}$$

$$\begin{aligned}
\text{Cov}(\mathbf{x}) &= E((\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T) \\
&= E\left(\sum_{k=1}^K (w_k \mathbf{x}_k - w_k \boldsymbol{\mu}_k) \sum_{k=1}^K (w_k \mathbf{x}_k - w_k \boldsymbol{\mu}_k)^T\right) \\
&= E\left(\sum_{k=1}^K w_k^2 (\mathbf{x}_k - \boldsymbol{\mu}_k) (\mathbf{x}_k - \boldsymbol{\mu}_k)^T + \sum_{m=1, n=1, m \neq n}^K w_m w_n (\mathbf{x}_m - \boldsymbol{\mu}_m) (\mathbf{x}_n - \boldsymbol{\mu}_n)^T\right) \\
&= \sum_{k=1}^K w_k^2 \text{Cov}(\mathbf{x}_k) + \underbrace{E\left(\sum_{m=1, n=1, m \neq n}^K w_m w_n (\mathbf{x}_m - \boldsymbol{\mu}_m) (\mathbf{x}_n - \boldsymbol{\mu}_n)^T\right)}_{\text{independent,}=0} \\
&= \sum_{k=1}^K w_k^2 \text{Cov}(\mathbf{x}_k)
\end{aligned} \tag{3}$$

References