# EM Algorithm: an informal tutorial

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#### Abstract

## 1 Introduction

The expectation-maximization (EM) algorithm introduced by Dempster et al [1] in 1977 is a very general method to solve maximum likelihood estimation with hidden state problems. In this informal report, we review the theory behind EM.

## 2 Problem setting

Let Y a random variable with probability density function (pdf)  $p(y|\theta)$ , where  $\theta$  is an unknown parameters vector. Let  $y=y_{1..N}$  be N observations of Y, we aim at maximizing the likelihood function  $p(y|\theta)$  or  $\arg\min_{\theta} p(y|\theta)$ . We can solve this by stochastic gradient descent (SGD) optimization. However if Y depends on both hidden variables Z and parameters  $\theta$  such as in Gaussian mixture distribution, it becomes intractable to directly calculate  $p(y|\theta) = \int_x p(y,x|\theta)dx$  because  $x=x_{1..N}$ , where N could be millions of samples. The EM algorithm iteratively solves the problem by assuming one of x and  $\theta$  are known.

## 3 EM algorithm

## 3.1 Intuition

Since  $\arg\min_{\theta} p(y|\theta) = \arg\min_{\theta} \ln p(y|\theta)$ , we can maximize  $\ln p(y|\theta)$  instead. For any distribution with pdf q(z), the equation 1 is alway true.

$$\ln(p(y)) = \int_z q(z) \ln p(y) dz \qquad p(y) \text{ is constant given } z$$

$$= \int_z q(z) \ln \frac{p(y,z)}{p(z|y)} dz \qquad p(y) = p(y,z)/p(z|y)$$

$$= \int_z q(z) \ln \frac{p(y,z)/q(z)}{p(z|y)/q(z)} dz \qquad \text{both are divided by } q(z)$$

$$= \int_z q(z) \ln \frac{p(y,z)}{q(z)} dz - \int_z q(z) \ln \frac{p(z|y)}{q(z)} dz \qquad (1)$$

Let evidence of low bound (ELBO) as

$$\mathcal{L}(q, p(y, z)) = \int_{z} q(z) \ln \frac{p(y, z)}{q(z)} dz$$
 (2)

Since KL divergence  $\mathcal{KL}(q \parallel p(z|y)) = -\int_z q(z) \ln(\frac{p(z|y)}{q(z)}) dz$ , so equation 1 can be written as

$$\ln p(y) = \mathcal{L}(q, p(y, z)) + \mathcal{K}\mathcal{L}(q \parallel p(z|y))$$
(3)

From equation 3, we have two conclusions. First, since y are observations and  $\ln p(y)$  is constant, minimizing KL divergence (alway positive) between any distribution q(z) and posterior distribution p(z|y) is equal to maximize ELBO. Second, the best distribution q(z) approximating p(z|y) is the posterior itself, where KL divergence is 0 and ELBO  $\mathcal{L}$  has the maximum value  $\ln p(y)$ .

Introducing parameters  $\theta$ , from equation 3, we have

$$\ln p(y|\theta) = \mathcal{L}(q(z), p(y, z|\theta)) + \mathcal{K}\mathcal{L}(q \parallel p(z|y, \theta)) \tag{4}$$

If parameters  $\theta$  are fixed, the best q(z) is  $p(z|y,\theta)$ . This is the key idea in the E-step of EM algorithm.

If q(z) is close enough to the true posterior  $p(z|y,\theta)$ , then KL divergence is close to 0. To find  $\arg\min_{\theta} \ln p(y|\theta)$ , we can approximately find the best  $\theta$  to maximize  $\mathcal{L}$  instead. In ideal case, if q(z) is true posterior  $p(z|y,\theta)$ , then  $\mathcal{L}$  is the same as  $\ln p(y|\theta)$ . This is the key idea in the M-step of EM algorithm.

If we combine those two steps iteratively, we get the EM algorithm.

- 1. E-Step: given  $\theta^t$  at time t, let  $q^t(z)$  equal to  $p(z|y,\theta^t)$
- 2. M-Step: given  $q^t(z)$  at E-Step, find  $\theta^{t+1} = \arg \max_{\theta} \mathcal{L}(q^t(z), p(y, z | \theta))$

#### 3.2 Proof

To prove the EM algorithm will converge to the local minimum, we need to show  $\ln p(y|\theta^{t+1})$  is no less than  $\ln p(y|\theta^t)$ .

**Lemma 3.1.** 
$$\ln p(y|\theta^{t+1}) > = \ln p(y|\theta^t)$$

Proof.

$$\begin{split} & \ln p(y|\theta^{t+1}) = \mathcal{L}(q^t(z), p(y, z|\theta^{t+1})) + \mathcal{KL}(q^t(z) \parallel p(z|y, \theta^{t+1})) & \text{according to 4} \\ & \geq \mathcal{L}(q^t(z), p(y, z|\theta^{t+1})) & \text{since } \mathcal{KL}(q^t \parallel p(z|y, \theta^{t+1})) \geq 0 \\ & \geq \mathcal{L}(q^t(z), p(y, z|\theta^t)) & \text{in M-step, } \theta^{t+1} \text{ is the best} \\ & = \mathcal{L}(q^t(z), p(y, z|\theta^t)) + \mathcal{KL}(q^t(z) \parallel p(z|y, \theta^t)) & \text{in E-Step, } q^t(z) = p(z|y, \theta^t) \\ & = \ln p(y|\theta^t) & \text{according to 4} \end{split}$$

## 3.3 Improve

Notice in M-step, to maximize  $\mathcal{L}$ , we don't need to calculate its own entropy. We can further simplify it.

Let  $Q(\theta^t, \theta) = \int_z q^t(z) \ln p(y, z|\theta) dz$ , and  $H(q(z)) = -\int_z q(z) \ln q(z)$ . We have

$$\mathcal{L}(q^t(z), p(y, z | \theta)) = \int_z q^t(z) \ln p(y, z | \theta) dz + - \int_z q^t(z) \ln q^t(z) dz$$

$$= Q(\theta^t, \theta) + H(q^t(z))$$
(5)

Since entropy  $H(q^t(z))$  doesn't depend on  $\theta$ , we have  $\arg\min_{\theta} \mathcal{L}(q^t(z), p(y, z|\theta)) = \arg\min_{\theta} Q(\theta^t, \theta)$ . We can maximize  $Q(\theta^t, \theta)$  instead of ELBO  $\mathcal{L}$  in M-step.

## 3.4 Practical assumptions

For large N samples, where  $y = y_{1..N}$  and  $z = z_{1..N}$ , without any constraint on joint distribution  $p(y_{1..N}, z_{1..N}|\theta)$ , it is not easy to calculate  $p(z_{1..N}|y_{1..N}|\theta)$  and  $Q(\theta^t, \theta)$ . Such restrictions on the joint distribution are generally presented by probabilistic graphical models. One of common restriction is assuming each  $y_i$  is identical independent distribution (iid) conditional on its corresponding latent variable  $z_i$ .

With conditional idd assumption, we can simplify E-step as the following

$$p(z_{1..N}|y_{1..N},\theta) = p(y_{1..N}, z_{1..N}|\theta)/p(y_{1..N}|\theta)$$

$$\propto \prod_{i=1}^{N} p(z_i, y_i|\theta)$$

$$= \prod_{i=1}^{N} p(z_i|y_i|\theta) * p(y_i|\theta)$$

$$\propto \prod_{i=1}^{N} p(z_i|y_i,\theta)$$
(6)

In equation 6, we know normalizer must be 1 when integrating both sides over  $z_{1...N}$ . Thus, we have  $p(z_{1...N}|y_{1...N},\theta) = \prod_{i=1}^N p(z_i|y_i,\theta)$ . So in E-step, we just need to calculate each observation marginal distribution  $p(z_i|y_i,\theta)$ , which dramatically simplify the calculation.

The equation 7 says instead of calculating expectation by join distribution, we can use marginal distribution to calculate expectation under decomposition.

$$\int_{z_{1}} \int_{z_{2}} q(z_{1}, z_{2}) * (f_{1}(z_{1}) + f_{2}(z_{2})) dz_{1} dz_{2} = \int_{z_{1}} \int_{z_{2}} q(z_{1}, z_{2}) * f(z_{1}) dz_{1} dz_{2} + \int_{z_{1}} \int_{z_{2}} q(z_{1}, z_{2}) * f_{2}(z_{2}) dz_{1} dz_{2}$$

$$= \int_{z_{1}} f(z_{1}) (\int_{z_{2}} q(z_{1}, z_{2}) dz_{2}) dz_{1} + \int_{z_{2}} f_{2}(z_{2}) (\int_{z_{1}} q(z_{1}, z_{2}) dz_{1}) dz_{2}$$

$$= \int_{z_{1}} q(z_{1}) * f_{1}(z_{1}) dz_{1} + \int_{z_{2}} q(z_{2}) * f_{2}(z_{2}) dz_{2}$$

$$(7)$$

With equation 7, we can see how to simplify in calculation  $Q(\theta^t, \theta)$ .

$$Q(\theta^{t}, \theta) = \int_{z} q^{t}(z) \ln p(y, z|\theta) dz$$

$$= \int_{z} q^{t}(z) \ln \left( \prod_{i=1}^{N} p(y_{i}, z_{i}|\theta) \right) dz$$

$$= \int_{z} q^{t}(z) \sum_{i=1}^{N} \ln p(y_{i}, z_{i}|\theta) dz$$

$$= \int_{z_{1}} \dots \int_{z_{N}} q^{t}(z_{1..N}) \sum_{i=1}^{N} \ln p(y_{i}, z_{i}|\theta) dz_{1} \dots dz_{N}$$

$$= \sum_{i=1}^{N} \int_{z_{i}} q^{t}(z_{i}) \ln p(y_{i}, z_{i}|\theta) dz$$

$$(8)$$

The last step is by repeatedly applying equation 7. We also notice  $q^t(z) = p(z_i|y_i, \theta^t)$ . By assuming each observation (with its corresponding latent variables) is idd, we can dramatically simplifying computation.

# 4 Gaussian mixture example

## References

[1] A. P. Dempster, N. M. Laird, and D. B. Rubin. "Maximum Likelihood from Incomplete Data via the EM Algorithm". In: *Journal of the Royal Statistical Society. Series B (Methodological)* 39.1 (1977), pp. 1–38. ISSN: 00359246. URL: http://www.jstor.org/stable/2984875.