

Using the Timing Analyzer

For Quartus® Prime 21.1

1 Introduction

This tutorial provides an introduction to the Timing Analyzer. It demonstrates how to set up timing constraints and obtain timing information for a logic circuit.

The reader is expected to have a basic understanding of the Verilog hardware description language, and to be familiar with the Intel® Quartus® Prime CAD software.

Contents:

- Introduction to timing analysis
- Using the Timing Analyzer
- Setting Up Timing Constraints

2 Background

Timing analysis is a process of **analyzing delays** in a logic circuit to determine the conditions under which the circuit operates reliably. One example of a timing analysis computation is to find the maximum clock frequency for a circuit, illustrated in Figure 1.

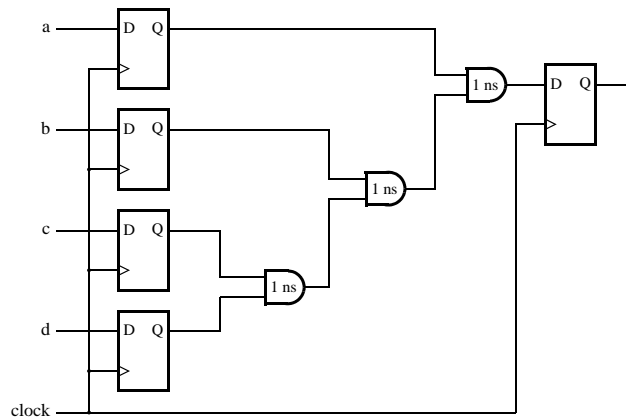


Figure 1. A example for timing analysis.

In this example, flip-flops on the left-hand side drive a combinational circuit that generates an output that is later stored in the flip-flop on the right-hand side. To operate correctly, the clock period has to be long enough to accommodate the delay on the longest path in the circuit. If we assume that the clock-to-Q and setup times for each flip-flop are 1 ns, and the delay through each gate is 1 ns, then the maximum clock frequency for this circuit is:

$$f_{max} = \frac{1}{t_{cq} + 3 \times t_{and} + t_{su}} = \frac{1}{5 \text{ ns}} = 200 \text{ MHz}$$

Computing the longest delays in a circuit and comparing these delays to the clock period is a basic function of a timing analyzer. The timing analyzer can be used to guide computer-aided design (CAD) tools in the implementation of logic circuits. For example, the circuit in Figure 1 shows an implementation of a 4-input function using 2-input AND gates. Without any timing requirements, the presented solution is acceptable. However, if a user requires the circuit to operate at a clock frequency of 250 MHz, then the above solution is inadequate. By placing timing constraints on the maximum clock frequency, it is possible to direct the CAD tools to seek an implementation that meets those constraints. As a result, the CAD tools may arrive at a solution shown in Figure 2. The new circuit has $f_{max} = 250 \text{ MHz}$ and thus meets the required timing constraints.

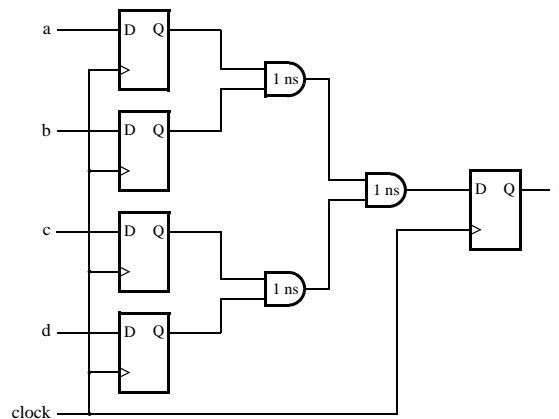


Figure 2. Functionally equivalent circuit with a different logic structure.

In this tutorial, we demonstrate how to obtain timing information and how to set timing constraints using the Timing Analyzer.

The example circuit provided with this tutorial contains only one clock signal, which is connected to all flip-flops. Performing timing analysis for circuits that have multiple clock signals is discussed in section 6.

3 Design Example

As an example we will use an adder that adds three 8-bit numbers and produces a sum output. The inputs are *A*, *B*, and *C*, which are stored in registers *reg_A*, *reg_B* and *reg_C* at the positive edge of the *clock*. The three registers provide inputs to the adder, whose result is stored in the *reg_sum* register. The output of the *reg_sum* register drives the output port *sum*. The diagram of the circuit is shown in Figure 3.

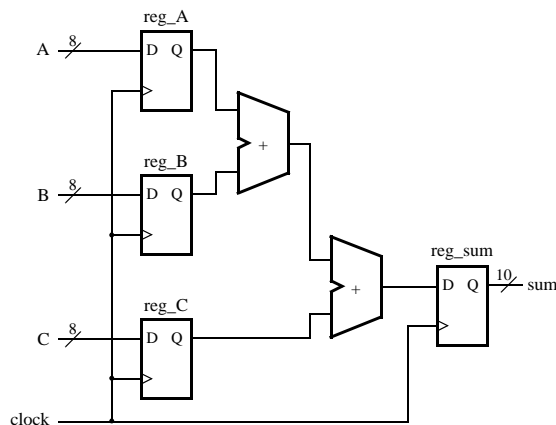


Figure 3. Diagram of the example circuit.

The Verilog source code for the design is given in Figure 4. Note that the "synthesis keep" comment is included in this code. This comment is interpreted as a directive that instructs the Quartus Prime software to retain the specified nodes in the final implementation of the circuit and keep their names as stated. This directive will allow us to refer to these nodes in the tutorial.

```
module add_three_numbers(clock, A, B, C, sum);
    input clock;
    input [7:0] A,B,C;
    output [9:0] sum;

    // Registers
    reg [7:0] reg_A, reg_B, reg_C /* synthesis keep */;
    reg [9:0] reg_sum /* synthesis keep */;

    always @(posedge clock)
    begin
        reg_A <= A;
        reg_B <= B;
        reg_C <= C;
        reg_sum <= reg_A + reg_B + reg_C;
    end
    assign sum = reg_sum;
endmodule
```

Figure 4. Verilog code for the example circuit.

To begin the tutorial create a new Quartus Prime project for the design of our example circuit. Select as the target device the EP4CE115F29C7, which is the FPGA chip on the Intel DE2-115 board. Type the Verilog code in Figure 4 into a file and add this file to the project.

You do not need to make any pin assignments for this example. Compile the project to see the results of timing analysis. These results will be available in the compilation report, once the design is compiled.

4 Using the Timing Analyzer

As illustrated in Figure 5, open the Timing Analyzer section of the Compilation Report, and click on the Clocks item to select it. In the *Clocks* display panel that opens on the right-hand side of the Quartus Prime window, notice that the *clock* signal from the example design has been given a clock period constraint of 1 ns (frequency of 1000 MHz). This is a default constraint that the Quartus Prime CAD tool places on any clock signal in a design project that does not have any user-provided timing constraints.

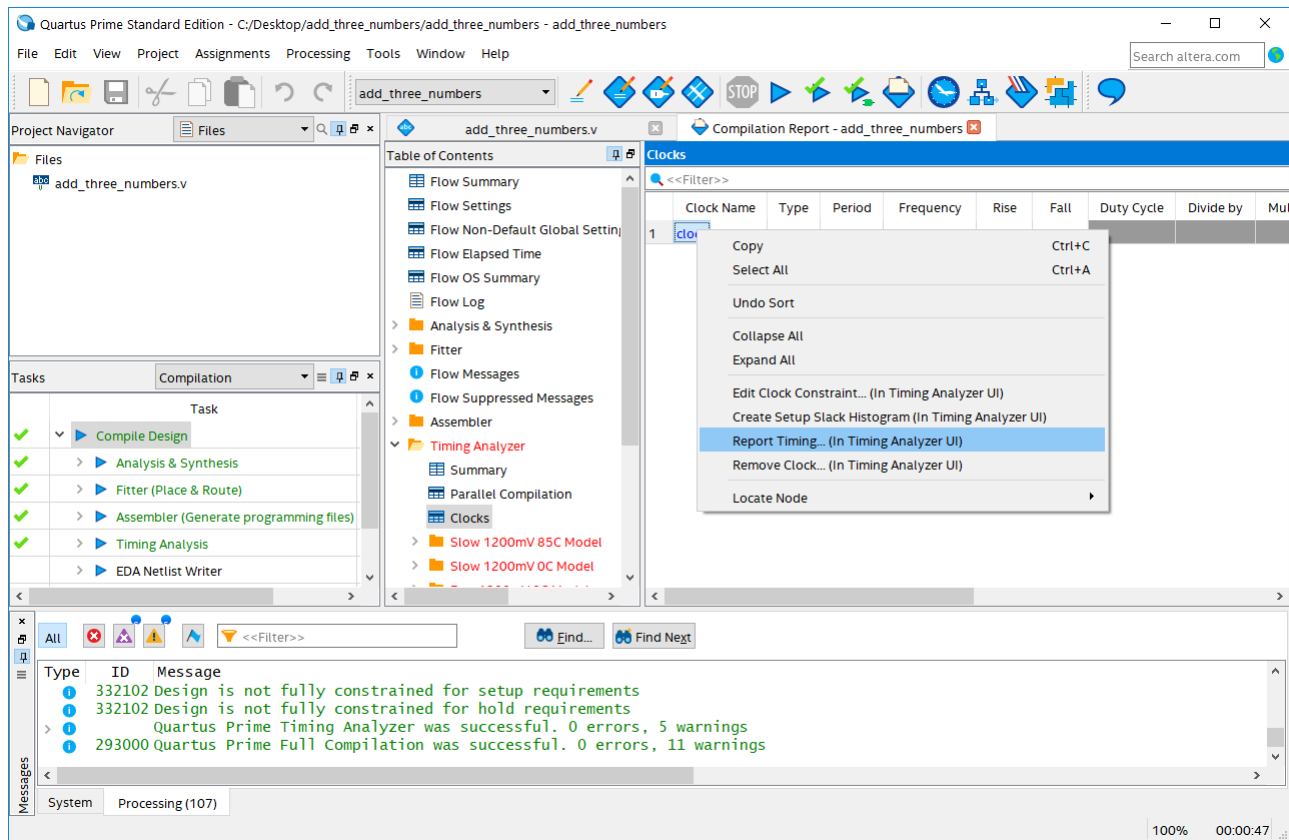
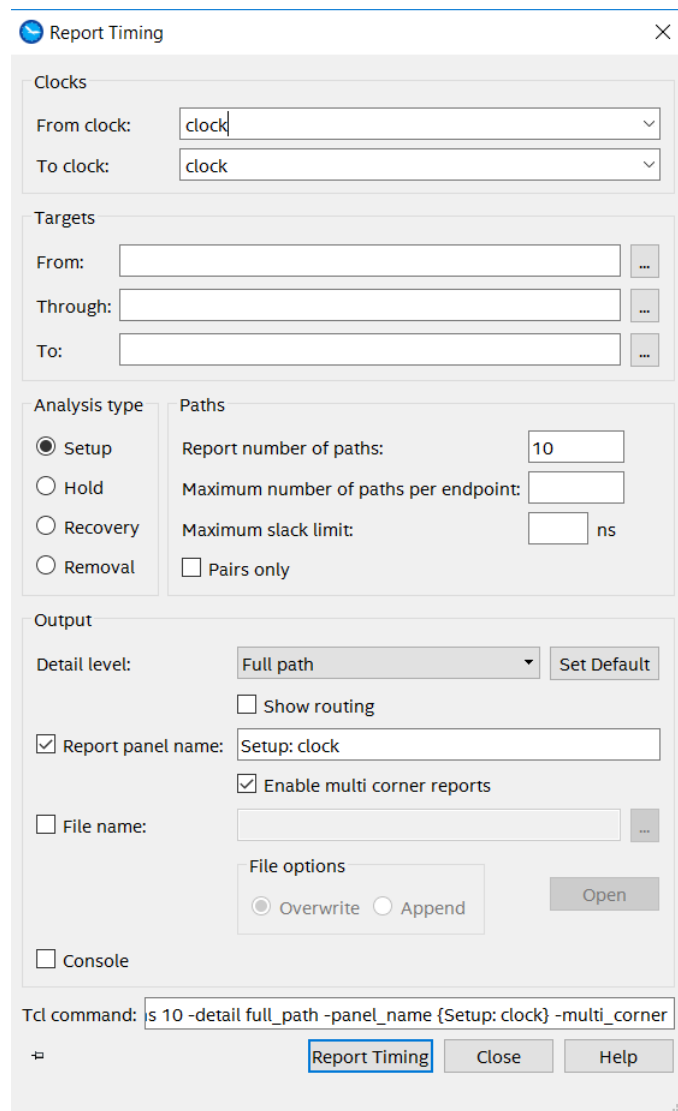


Figure 5. The Timing Analyzer section of the compilation report.

As indicated in Figure 5, right-click on the name of the *clock* signal and select the command **Report Timing ... (In Timing Analyzer UI)**. This action opens the *Report Timing* dialog shown in Figure 6. Click the drop-down arrow in the *From clock* item and select the *clock* signal. This selection is used to instruct the Timing Analyzer to analyze all paths in the example circuit that start and end at flip-flops that are clocked by the *clock* signal. The various settings displayed in Figure 6 are described in Section 5.

Accept all of the other default selections in Figure 6 and click on the **Report Timing** button. This command opens the Timing Analyzer Graphical User Interface (GUI), as depicted in Figure 7.



The Report Timing dialog box is used to configure timing analysis. It includes sections for Clocks, Targets, Analysis type, Paths, Output, and a Tcl command field.

Clocks

From clock: ▼

To clock: ▼

Targets

From: ...

Through: ...

To: ...

Analysis type

☒ Setup

☐ Hold

☐ Recovery

☐ Removal

Paths

Report number of paths:

Maximum number of paths per endpoint:

Maximum slack limit: ns

☐ Pairs only

Output

Detail level: ▼ Set Default

☐ Show routing

☒ Report panel name:

☒ Enable multi corner reports

☐ File name: ...

File options

☒ Overwrite ☐ Append Open

☐ Console

Tcl command:

Report Timing Close Help

Figure 6. The Report Timing dialog.

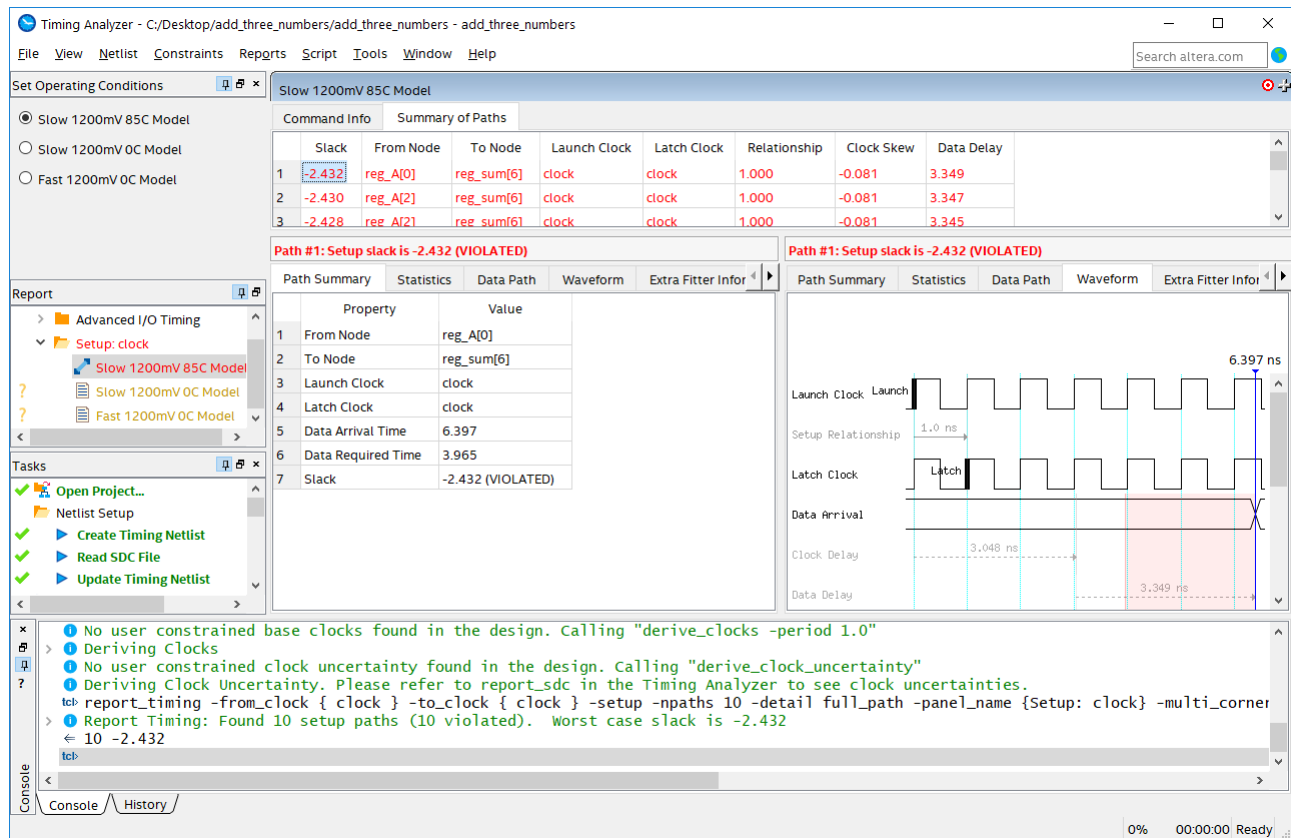


Figure 7. The Timing Analyzer GUI.

The Timing Analyzer GUI consists of several sections. They include the main menu at the top, the Report pane in the top-left corner, the Tasks pane on the left, the detailed results panes in the middle, and the Console display at the bottom of the window. The main menu is used to interact with the Timing Analyzer tool and issue commands. The Report pane contains any reports generated when using the tool, and the Tasks pane contains a sequence of actions that can be performed to obtain timing reports. The View pane hosts any windows that are opened, such as details about the timing information. The Console window at the bottom provides access to a command line for Timing Analyzer.

We will focus on the panes in the middle of the Timing Analyzer GUI, which show detailed results of the timing analysis. The **Slow 1200mV 85C Model** pane lists the analyzed paths in the circuit from source to destination flip-flops for that particular timing model. The first column in this pane shows the *Slack* of each path with respect to the (default) clock constraint of 1 ns. For each path in the circuit the slack value represents the difference between the clock period constraint and the path delay; a positive slack means that the delay is smaller than the constraint, and a negative slack represents a delay that is larger than the constraint. The slack values in the report are negative, and shown in red, because the timing results fail to meet the required constraint. The maximum negative slack value shown is -2.432 ns, which means that the worst-case delay path is $1 - (-2.432) = 3.432$ ns long. This corresponds to a maximum usable clock frequency, F_{max} , of about 291.38 MHz.

The waveforms shown for path #1 in Figure 7 illustrate the detailed timing situation. The waveforms show that the clock signal takes 3.048 ns to propagate from its input pin to the source flip-flop, and then this flip-flop produces data that takes 3.349 ns to reach the destination flip-flop. Also, the clock signal takes 2.935 ns to reach the destination flip-flop. The clock delays at the source and destination flip-flops represent a clock skew $t_{skew} = 2.935 - 3.048 = -0.113$. A value of 0.032 to account for *Clock Pessimism* is added to the clock skew, making the final clock skew value to be -0.081 ns. The difference in the required arrival time of the data on this path and the actual arrival time is shown by the negative slack value of $1 - 3.349 + t_{skew} = -2.430$ ns. Timing Analyzer adds a value of -0.002 ns to account for *Clock Uncertainty*, leading to the final slack value of -2.432 ns.

4.1 Setting Up Timing Constraints for a Design

In the Timing Analyzer GUI, select **Constraints > Create Clock**, which leads to the Create Clock window shown in Figure 8. Set the Clock name to *clock* and the Period to 4.000 ns. It is necessary to tell the Timing Analyzer which signal in our design this clock constraint applies to. To do this, click the ... button to the right of the **Targets** field, leading to the Name Finder window shown in Figure 9. Click **List** to show all of the ports in the design. In the list of ports, highlight *clock*, which is the clock signal in our circuit, press **>**, then click **OK**. Finally, click the **Run** button in the Create Clock window to apply the constraint.

In order to use this clock constraint for all future compilations and timing analysis of this project, we must save the constraint to a file of the type *sdc* which stands for Synopsys* Design Constraint. This file uses an industry-standard format for specifying timing constraints. Select **Constraints > Write SDC File...** to write all of the currently set constraints (in our case just the one clock constraint) to an SDC file. This leads to the dialog shown in Figure 10. Specify the file name *add_three_numbers.sdc* (note that this is different from the default file name) and press **OK**. Note that Quartus will by default try to locate and use the sdc file whose file name matches the project name (except for the .sdc extension).

Now, navigate back to the previous screen by going to the **Report** pane on the left hand side of the Timing Analyzer GUI and selecting **Setup: Clock > Slow 1200mV 85C Model**. You will notice that our clock timing report *Setup clock* is now out of date, as indicated by the yellow font and highlighting. Right-click the report and select **Regenerate**, as shown in Figure 11, to re-run the timing analysis using the new 4 ns clock period constraint. This analysis results in a positive slack of 0.568 ns. The corresponding waveforms are depicted in Figure 12.

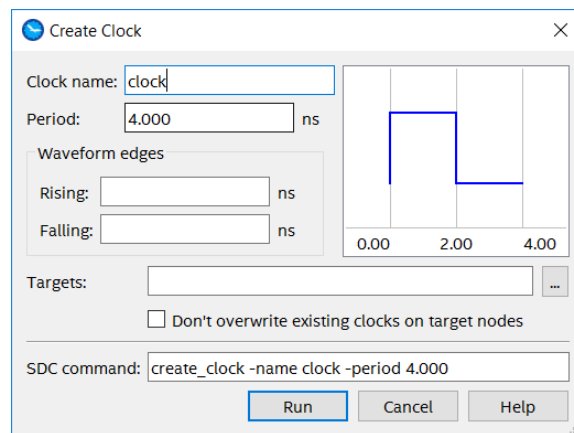


Figure 8. The Create Clock window.

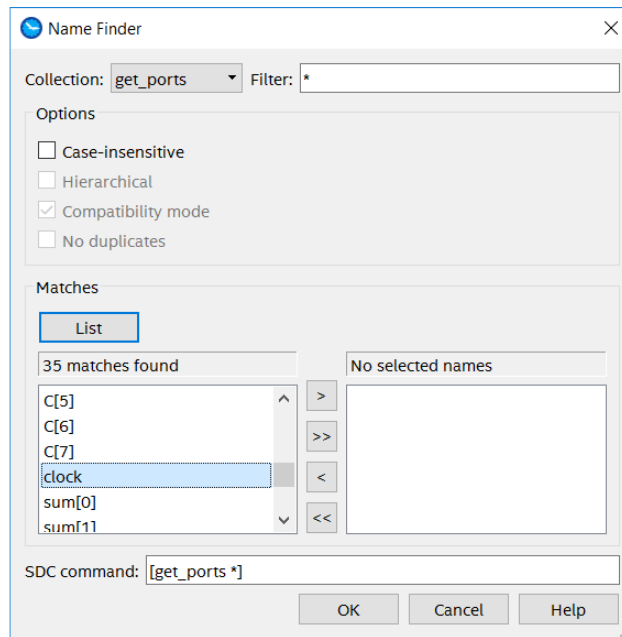


Figure 9. The Name Finder window.

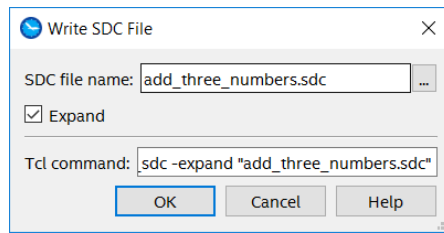


Figure 10. The Write SDC File dialog.

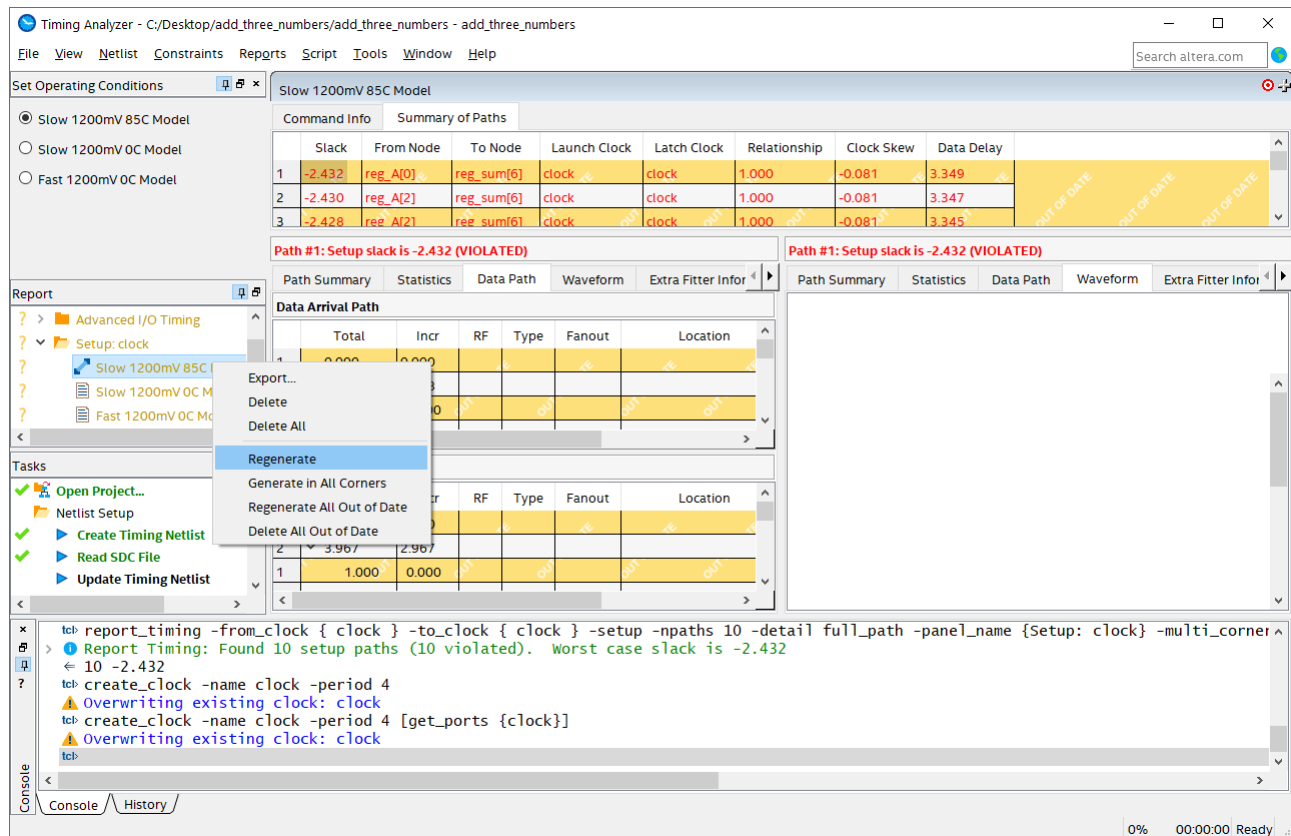


Figure 11. Regenerating the Timing Report.

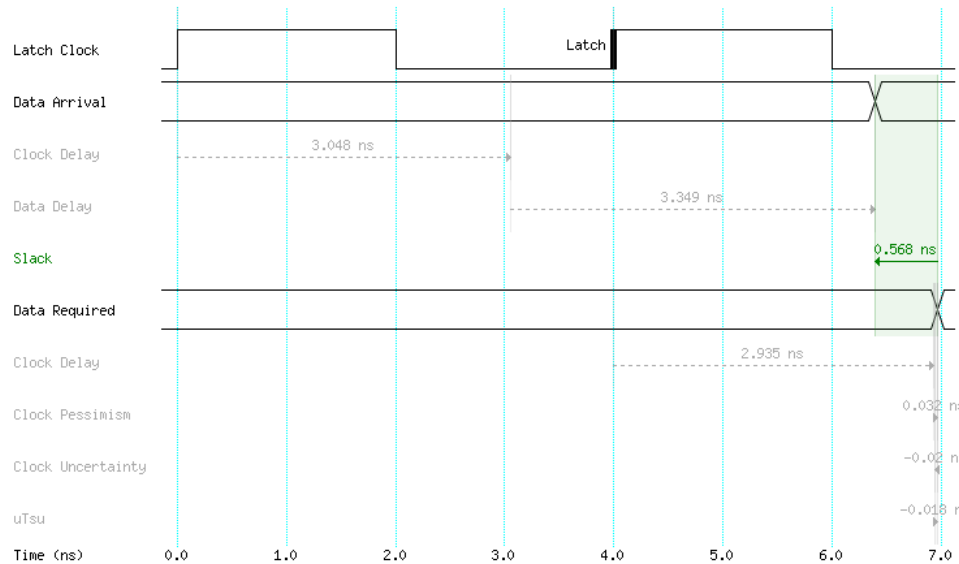


Figure 12. Timing analysis results using the 4 ns clock period constraint.

Close the Timing Analyzer GUI. A dialog will appear, asking if you want to save the SDC file. Select **No**, since we have already saved the SDC file.

Since we have not recompiled the example design after adding the 4 ns clock period constraint, the timing analysis is based of the circuit that was produced by Quartus Prime when using the (default) 1 ns clock period constraint. To see the effect of the new timing constraint on the compilation results, recompile the project. Then, follow the steps described previously to perform a new timing analysis using the Timing Analyzer. The 4 ns timing constraint will cause the Quartus Prime optimization algorithms to make different decisions from those made when the (default) 1 ns constraint was used. In particular, the optimization algorithms will likely take less time to execute, because once the generated circuit has sufficient positive slack to meet the constraint, the algorithms can terminate. Figure 13 shows the results of timing analysis, with a positive slack of 0.718 ns.

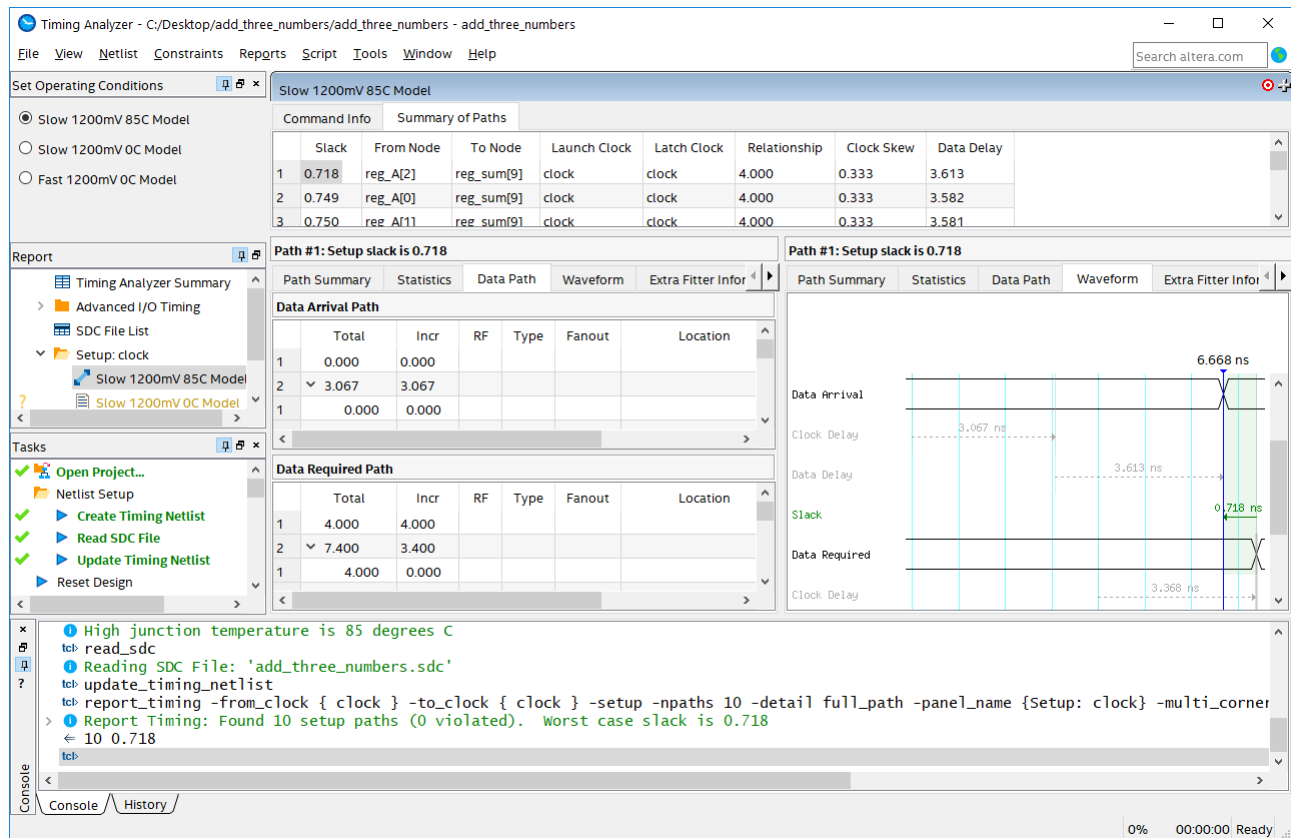


Figure 13. Updated compilation results with the 4 ns clock period constraint.

5 The Timing Analyzer Graphical User Interface

In the above sections we accessed the Timing Analyzer via the Quartus Prime Compilation Report. Another way to open the Timing Analyzer GUI is to use the command **Tools > Timing Analyzer** from the main Quartus Prime window. The Timing Analyzer window shown in Figure 14, will appear.

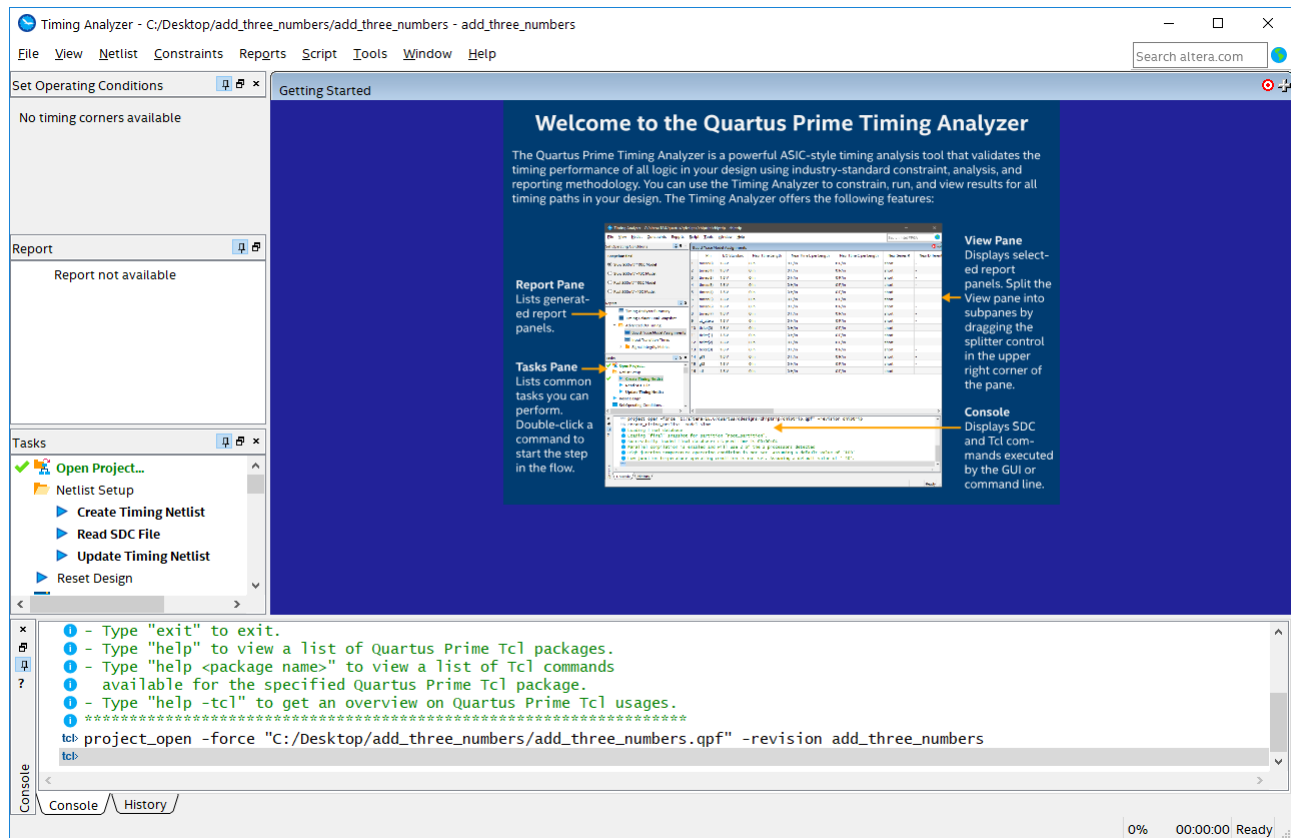


Figure 14. The Timing Analyzer window.

To demonstrate some of the commands available in the Timing Analyzer GUI, we go through a set of basic steps to obtain timing data for the example design. In the Tasks pane, begin by double-clicking the **Create Timing Netlist** command to create a timing netlist, which will be used to perform the analysis. Note that while this netlist was generated automatically when performing a timing analysis as described in the previous sections, the netlist can also be generated manually by using the Tasks pane. Next double-click **Read SDC File** to instruct the analyzer to read a Synopsys Design Constraints (SDC) file and apply the constraints during analysis. The SDC file can be edited manually (using any text editor) at any time, and the timing analysis can then be re-run using the new constraints. Finally, double-click the **Update Timing Netlist** command to use the specified constraints to determine which parts of the circuit fail to meet them. Once the timing netlist is updated, reports can be generated.

5.1 Timing Analysis Reports

To generate a report, double-click on a report name in the Tasks pane. For example, double-click on the **Report Setup Summary**. This command will bring up a window in the view pane as shown in Figure 15. Right-click on the *clock* name then click on **Report Timing...** to open the Report Timing dialog in Figure 16. Although we previously showed this dialog in Figure 6 we now describe it in more detail.

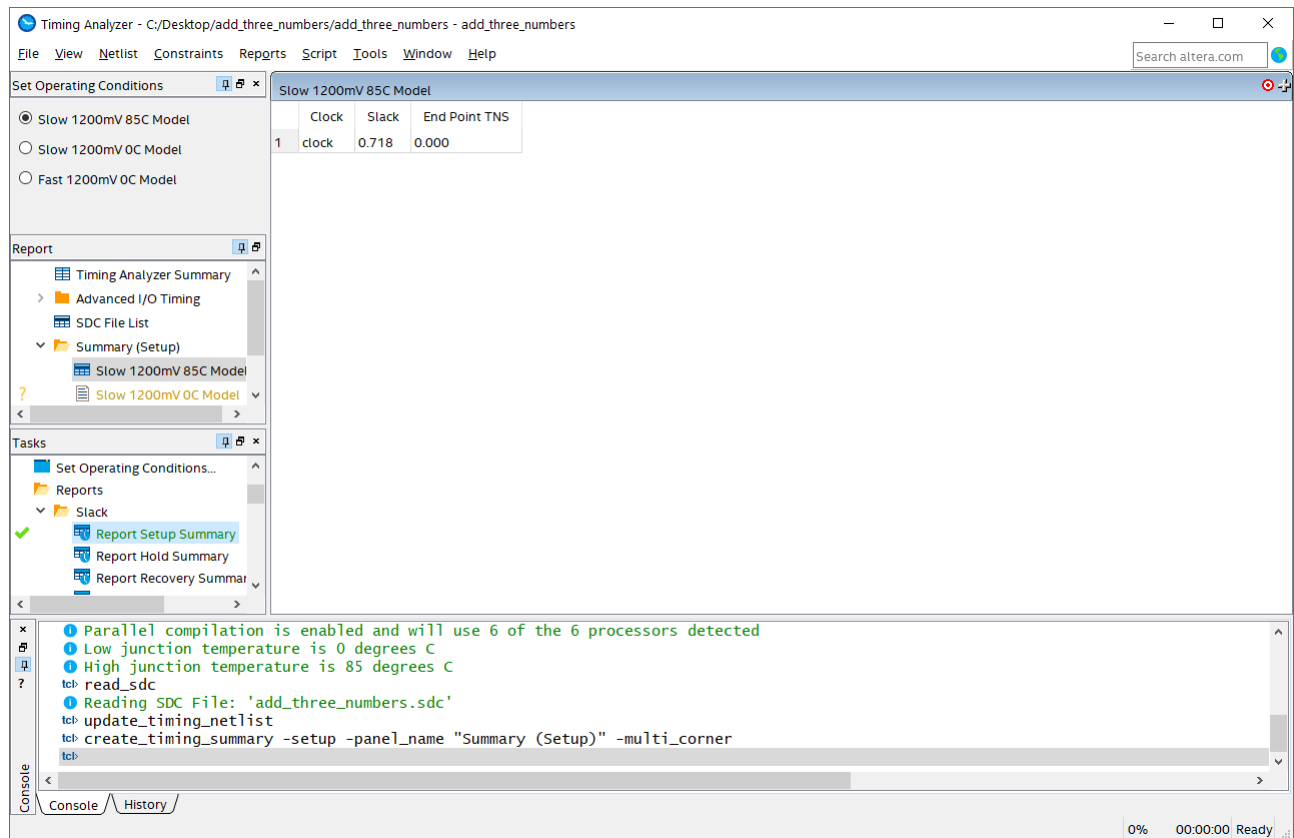
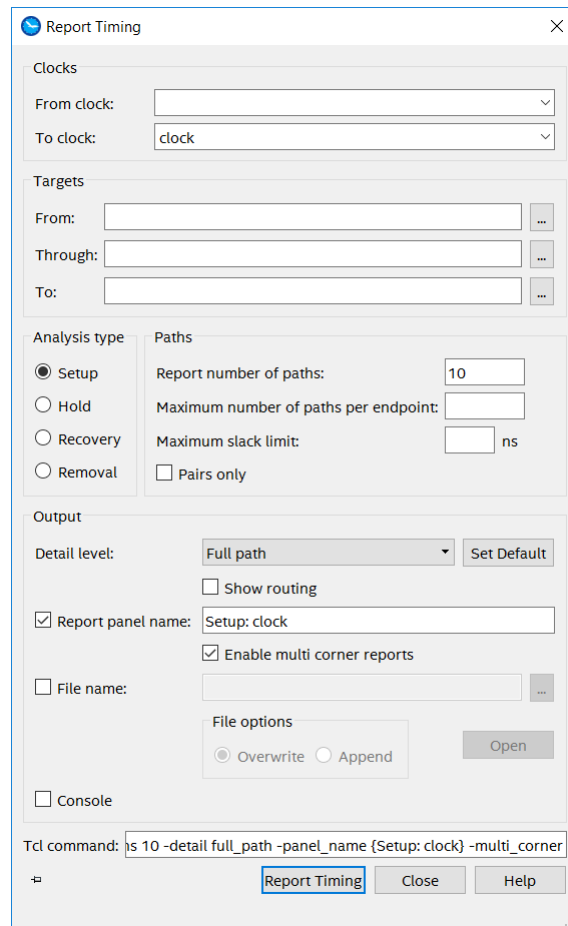


Figure 15. Setup summary.

There are several fields in Figure 16 that help specify the data to be reported. The first field is the **Clocks** field, which specifies the types of paths that will be reported. More precisely, it specifies the clock signal at the source flip-flops (From clock) and the clock signal at the destination flip-flops (To clock). For this example, choose the signal named *clock* for the To clock and From clock fields. This will limit the reporting to the register-to-register paths only.



The image shows the 'Report Timing' dialog box in Quartus Prime. It is divided into several sections: 'Clocks', 'Targets', 'Analysis type', 'Paths', 'Output', and a 'Tcl command' field at the bottom. The 'Clocks' section has 'From clock' and 'To clock' dropdowns, with 'clock' selected in 'To clock'. The 'Targets' section has 'From:', 'Through:', and 'To:' text boxes, all empty. The 'Analysis type' section has radio buttons for 'Setup' (selected), 'Hold', 'Recovery', and 'Removal'. The 'Paths' section has 'Report number of paths' set to 10, 'Maximum number of paths per endpoint' empty, 'Maximum slack limit' empty with 'ns' unit, and a 'Pairs only' checkbox. The 'Output' section has 'Detail level' set to 'Full path' with a 'Set Default' button, 'Show routing' unchecked, 'Report panel name' checked and set to 'Setup: clock', 'File name' unchecked, 'Enable multi corner reports' checked, and 'File options' with 'Overwrite' selected and 'Append' unselected. There is an 'Open' button next to the file options. At the bottom, there is a 'Console' checkbox, a 'Tcl command' field containing 'js 10 -detail full_path -panel_name {Setup: clock} -multi_corner', and three buttons: 'Report Timing' (highlighted with a blue border), 'Close', and 'Help'.

Figure 16. Timing report generation window.

The next field is the **Targets** field. It can be used to refine the report by focusing only on certain paths in the design. We can specify the starting and the ending point of the paths of interest by filling the **From** and **To** fields. In addition, we can look at only the paths that pass through certain nodes in the design. For this example, we leave these fields blank to indicate that every path should be taken into account for the report.

The next two fields are the **Analysis type** and **Paths** fields. The **Analysis type** field specifies if the report should contain setup, hold, recovery, or removal information. Each of these analyses looks for distinct timing characteristics in your design. For example, the setup analysis determines if the data arrives at a flip-flop sufficiently early for the flip-flop to store it reliably, given a clock period. On the other hand, the hold analysis determines if the data input at any given flip-flop remains stable after the positive edge of the clock long enough for the data to be stored in a flip-flop reliably. The **Paths** field specifies the maximum number of paths to be reported and the maximum slack required for a path to be included in the report. For this example, choose the type of analysis to be **Setup** and select 10 paths to be reported. This will generate a setup analysis report and show 10 paths with the least slack.

The next set of fields specify the Output format and the level of detail in the report. The output could be to a window or a file. Set the Detail level to **Path Only**, then set the output to a window by checking the **Report panel name** check box (and not the **File name** check box). The window should be named **Setup: clock** by default, and that name will identify the report in the report pane.

Finally, the last field is the Tcl command field. This field shows a command that will be executed to generate the requested report. You do not need to edit this field.

5.2 Creating Timing Constraints in the Timing Analyzer GUI

Timing constraints can be entered by using the **Constraints** menu in the Timing Analyzer GUI. To assign a clock constraint, select **Create Clock...** from the **Constraint** menu. A window shown in Figure 17 will appear.

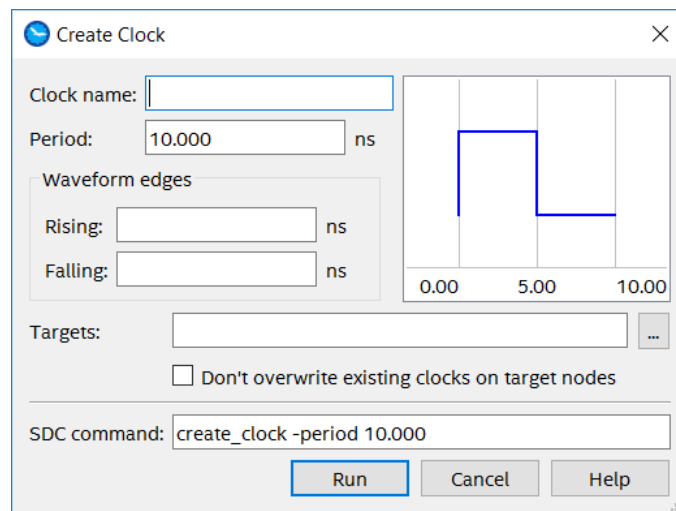


Figure 17. The Timing Analyzer window to create a clock constraint.

In the figure the clock constraint is given the name *clock* in the top field. The clock period is assigned to be 4 ns in the field below. The next two fields define the time at which the clock changes from 0 to 1 and 1 to 0. Leaving these fields empty indicates that the rising edge of the clock should appear at time 0, and the falling edge at one half of the clock period. Finally, the **Targets** field is set to the signal name *clock* as shown in the figure, to indicate that the given constraint is for the signal named *clock*. Pressing the **Run** button applies the constraint. The constraint can be saved into an SDC file by double-clicking on the **Write SDC File...** task as shown in Figure 18.

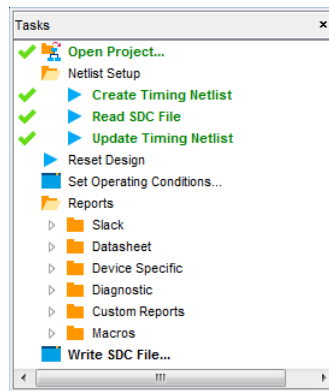


Figure 18. Saving a constraints file.

Once the constraints file is saved, it can be used by Quartus Prime when compiling a project. This is done in Quartus Prime by going into **Assignments > Settings... > Timing Analyzer**, and adding the SDC file to the Timing Analyzer settings as shown in Figure 19. The Quartus Prime project can then be recompiled to use the constraint.

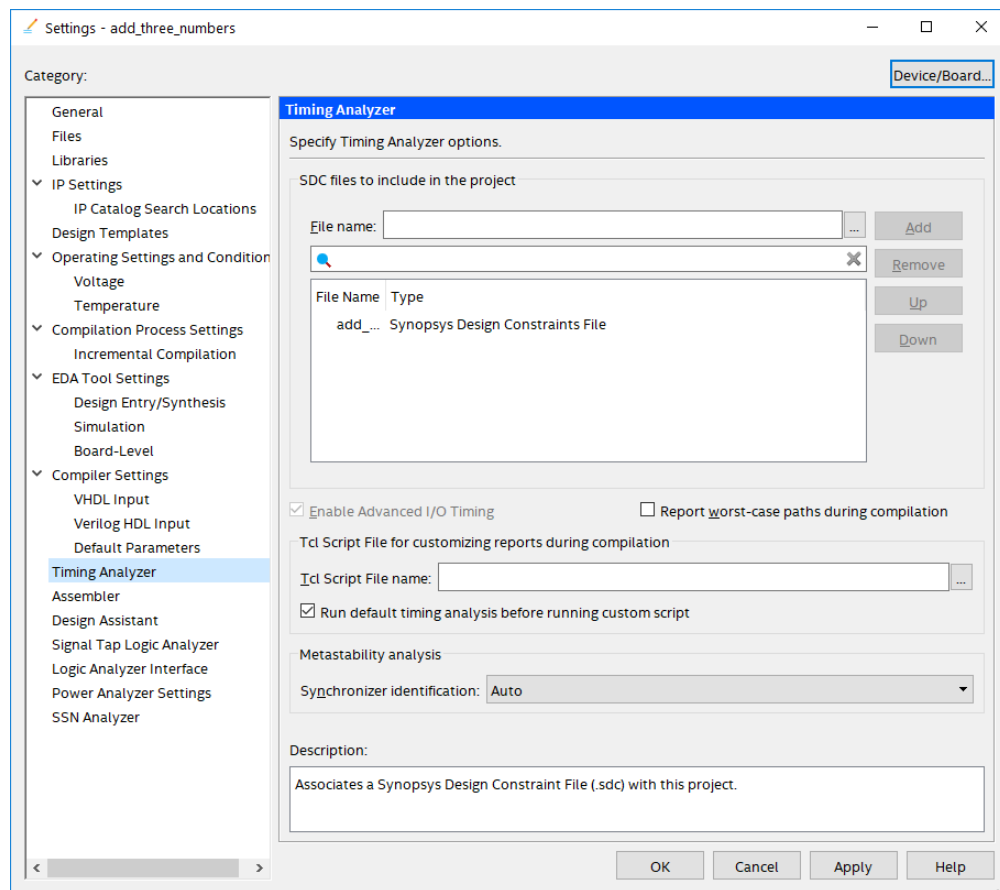


Figure 19. Including a constraints file in Quartus Prime project.

6 Circuits with Multiple Clock Signals

The Timing Analyzer is capable of analyzing circuits that contain multiple clocks. This includes cases where the designer uses several clocks, or where clock signals are generated automatically to support features such as the SignalTap Logic Analyzer or a JTAG* interface. Should the reader work with such designs, it is important to note that the experience with the Timing Analyzer may differ from that described above. In designs with multiple clocks, it is important to apply constraints to each clock before performing timing analysis. Doing so will make the analyzer provide the same reports as described in previous sections.

7 Conclusion

This tutorial demonstrated the basic use of the Timing Analyzer. While the descriptions of timing analysis and setting up timing constraints were limited to clock constraints in a simple circuit, the Timing Analyzer provides even more powerful tools to specify timing constraints for larger and more complex designs.

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