

# Formal Verification of RDMA Failover Impossibility

We formalize and mechanically verify three impossibility theorems for transparent RDMA failover using the Rocq proof assistant (formerly Coq). All proofs are available at [github.com/taooceros/shift-verification](https://github.com/taooceros/shift-verification).

## Theorem 1: Indistinguishability of Packet Loss and ACK Loss

**Definition** (Sender View). Let  $\mathcal{T}$  be an execution trace. The *sender view*  $\sigma(\mathcal{T})$  is the projection containing only sender-observable events: operation sends, completions, and timeouts.

**Definition** (Transparent Overlay). A failover mechanism is *transparent* if its retransmission decision  $D : \sigma(\mathcal{T}) \times \text{Op} \rightarrow \{0, 1\}$  depends only on the sender view.

**Theorem** (Impossibility of Safe Retransmission). For any transparent overlay  $D$ , there exist executions  $\mathcal{T}_1$  (packet lost) and  $\mathcal{T}_2$  (ACK lost, memory reused) such that:

$$\sigma(\mathcal{T}_1) = \sigma(\mathcal{T}_2) \quad (1)$$

but safety requires  $D(\sigma(\mathcal{T}_1)) = 1$  (retransmit) while  $D(\sigma(\mathcal{T}_2)) = 0$  (do not retransmit).

*Proof.* We construct two traces with identical sender views but opposite correctness requirements:

$\mathcal{T}_1$ : [Send( $W_D$ ), PacketLost( $W_D$ ), Timeout( $W_D$ )]

$\mathcal{T}_2$ : [Send( $W_D$ ), Receive, Execute, AppConsume, AppReuse( $V'$ ), AckLost, Timeout( $W_D$ )]

Both produce sender view [ObsSent( $W_D$ ), ObsTimeout( $W_D$ )]. In  $\mathcal{T}_1$ , the operation was never executed (liveness requires retry). In  $\mathcal{T}_2$ , the operation executed and memory was reused with value  $V' \neq V_1$  (safety forbids retry). Since  $D$  is a function,  $D(\sigma(\mathcal{T}_1)) = D(\sigma(\mathcal{T}_2))$ , contradicting the requirements.  $\square$

## Theorem 2: Non-Idempotency of Atomic Operations

**Theorem** (FADD Non-Idempotency). For any  $\delta > 0$  and memory state  $m$ , FADD is not idempotent:

$$\text{exec}_{\text{FADD}}(\text{exec}_{\text{FADD}}(m, a, \delta), a, \delta) \neq \text{exec}_{\text{FADD}}(m, a, \delta) \quad (2)$$

*Proof.* Let  $m[a] = v$ . After one FADD:  $m'[a] = v + \delta$ . After retry:  $m''[a] = v + 2\delta$ . Since  $\delta > 0$ , we have  $v + \delta \neq v + 2\delta$ .  $\square$

**Theorem** (CAS Retry Violation). Under concurrent modification, a CAS retry can succeed twice, violating at-most-once semantics.

*Proof.* Consider sender  $S$  with CAS( $a, 0, 1$ ) and concurrent process  $P$  with CAS( $a, 1, 0$ ):

State 0:  $m[a] = 0$

State 1:  $S.\text{CAS}(0, 1)$  succeeds  $\rightarrow m[a] = 1$

State 2:  $P.\text{CAS}(1, 0)$  succeeds  $\rightarrow m[a] = 0$

State 3:  $S$  retries CAS( $0, 1$ )  $\rightarrow$  succeeds again!

$S$ 's single CAS executed twice, and  $P$ 's successful modification was silently overwritten.  $\square$

## Theorem 3: Consensus Hierarchy Barrier

We prove that failover coordination is equivalent to 2-process consensus, which read-only verification cannot solve.

## Unified Observation Constraint Framework

**Definition** (Observation Constraint). Each synchronization primitive defines a constraint on what protocols can observe:

Primitive	Constraint
Register	$\text{valid}_{\text{rw}} : \text{obs}(\text{exec}, i)$ depends only on writes before $i$
FADD	$\text{valid}_{\text{fadd}} : \text{obs}(\text{exec}, i)$ depends only on $\{j : j \text{ before } i\}$ (set, not order)
CAS	$\text{valid}_{\text{cas}} : \text{obs}(\text{exec}, i) = \text{winner}(\text{exec})$ (first process)

The constraints are *derived* from primitive semantics:

- **Register:** Reads are invisible; only writes affect observable state
- **FADD:** Returns sum of prior deltas;  $\delta_0 + \delta_1 = \delta_1 + \delta_0$
- **CAS:** First CAS to sentinel wins; all subsequent fail; all read same value

## Consensus Number Verification

**Definition** (Consensus Number).  $\text{CN}(X) = n$  iff  $X$  can solve  $n$ -consensus but not  $(n + 1)$ -consensus.

**Lemma** (Register  $\text{CN} = 1$ ). For any observation function satisfying  $\text{valid}_{\text{rw}}$ , solo executions  $[0]$  and  $[1]$  produce identical observations (both have empty prior write history) but require decisions 0 and 1 respectively.

**Lemma** (FADD  $\text{CN} = 2$ ). For any observation function satisfying  $\text{valid}_{\text{fadd}}$ , executions  $[0, 1, 2]$  and  $[1, 0, 2]$  are indistinguishable to process 2 (both see  $\{0, 1\}$  ran before), but require decisions 0 and 1.

**Lemma** (CAS  $\text{CN} = \infty$ ). Any observation function satisfying  $\text{valid}_{\text{cas}}$  gives  $\text{obs}(\text{exec}, i) = \text{winner}(\text{exec})$ . Different winners  $\rightarrow$  different observations  $\rightarrow$  always distinguishable.

## Reduction: Failover Solver $\Rightarrow$ 2-Consensus Protocol

Following Herlihy's methodology, we prove failover requires  $\text{CN} \geq 2$  by showing that a correct failover solver implies a correct 2-consensus protocol.

**Definition** (Failover Solver). A failover solver  $F : \text{Memory} \rightarrow \{\text{Commit}, \text{Abort}\}$  correctly determines whether the CAS was executed based on memory state.

**Definition** (2-Consensus Protocol from Failover). Given failover solver  $F$ , construct 2-consensus protocol:

- **Encoding:**  $P_0$ 's input  $\mapsto$  "CAS executed",  $P_1$ 's input  $\mapsto$  "CAS not executed"
- **Protocol:** Both processes call  $F(\text{shared\_mem})$  and return the result
- **Decoding:** Commit  $\mapsto P_0$  won, Abort  $\mapsto P_1$  won

**Theorem** (Reduction Correctness). If  $F$  correctly solves failover, then  $\text{consensus\_from\_failover}(F)$  correctly solves 2-consensus.

*Proof.* Let  $F$  be a correct failover solver. For any execution where  $P_i$  wins:

- Encode as history  $h_i$ :  $h_0 = \text{HistExecuted}(m)$ ,  $h_1 = \text{HistNotExecuted}(m)$
- By correctness:  $F(\text{mem}(h_i)) = \text{correct\_decision}(h_i) = i$
- **Agreement:** Both processes call  $F$  on same memory  $\rightarrow$  same output

- **Validity:** Output equals winner’s input by correctness of  $F$

□

**Theorem** (Failover Requires  $\text{CN} \geq 2$ ). No correct failover solver exists, therefore failover requires  $\text{CN} \geq 2$ .

*Proof.* Suppose  $F$  is a correct failover solver. Then:

- $F(m) = \text{true}$  for  $H_1 = \text{HistExecuted}(m)$  (correctness for “executed”)
- $F(m) = \text{false}$  for  $H_0 = \text{HistNotExecuted}(m)$  (correctness for “not executed”)

But  $\text{mem}(H_0) = \text{mem}(H_1) = m$  (ABA problem), so  $F(m)$  must be both true and false. Contradiction.

By the reduction, if failover were solvable, 2-consensus would be solvable. Since 2-consensus requires  $\text{CN} \geq 2$ , so does failover. □

**Theorem** (Transparent Failover Impossibility). Read-only verification has  $\text{CN} = 1 < 2$ , therefore transparent failover is impossible.

**Theorem** (Main Result). Transparent RDMA failover for atomic operations is impossible because:

1. Failover requires solving 2-consensus
2. Transparency limits verification to read-only operations
3.  $\text{CN}(\text{Register}) = 1 < 2$
4. By Herlihy’s hierarchy,  $\text{CN}=1$  primitives cannot solve 2-consensus

## Mechanization

Component	Lines	Key Theorems
Core definitions	400	Memory model, RDMA operations, traces
Theorem 1	200	<code>impossibility_safe_retransmission</code>
Theorem 2	300	<code>fadd_not_idempotent</code> , <code>cas_double_success</code>
Theorem 3	1200	<code>register_cn_1_verified</code> , <code>fadd_cn_2_verified</code> , <code>valid_cas_no_ambiguity</code> , <code>transparent_cas_failover_impossible</code>

Table 1: Rocq formalization statistics

All proofs are constructive and fully mechanized in Rocq 9.0. The consensus number framework provides a unified treatment where each primitive’s limitation is derived from its operational semantics, and the failover impossibility follows as a direct consequence of Herlihy’s hierarchy applied to the structural isomorphism between failover and 2-consensus.