

# Structure of Verification Integration

This document maps the formal theorems to specific sections of the SHIFT paper, providing detailed content outlines for each.

## 1. Introduction (Page 1)

**Goal:** Frame SHIFT's design choices (supporting Writes/Simple, rejecting Atomics) as theoretical necessities, not implementation gaps.

- **Content Block 1: The Core Question**

- **Insert Location:** Replace paragraph starting “However, we identify a fundamental constraint...”
- **Draft Text:** “However, a fundamental question arises: what are the theoretical limits of transparent cross-NIC failover? We prove that SHIFT achieves precisely what is possible under the transparency constraint...”
- **Key Concepts:** Mention the three barriers: Indistinguishability (ACK vs Packet loss), Non-idempotency (Atomics/Queue effects), and the Consensus Barrier (CN=1).

- **Content Block 2: Contribution List**

- **Insert Location:** New Item (2) in the contribution list.
- **Draft Text:** “We formally prove that SHIFT’s coverage is optimal: transparent failover for atomic and uncoordinated two-sided operations is impossible due to the consensus hierarchy barrier. Supporting these requires receiver-side coordination (SHIFT’s handshake) or persistent metadata. All proofs are mechanically verified in Rocq 9.0.”

## 2. Section 3.1: Insight: Boundary of Cross-NIC Fault Tolerance (Page 4)

**Goal:** Provide the “Sender’s Dilemma” intuition, formalized by the Indistinguishability Theorem, leading to the classification of operations.

- **Subsection 3.1.1: The Transparency Barrier**

- **Context (Why Transparency?):** For One-Sided RDMA (WRITE/READ), the receiver CPU is bypassed (“silent”). Thus, any failover logic **must** be transparent—residing entirely on the sender—because we cannot execute code on the receiver to track state or send application-level ACKs.
- **Paragraph 1: Intuition (The Dilemma).**
  - Start with: “When a network anomaly causes a timeout, the sender faces two indistinguishable scenarios...”
  - Explain: Scenario A (Packet Loss -> Retry Needed) vs. Scenario B (ACK Loss -> Retry Dangerous).

- **Paragraph 2: Formalization (Theorem 1).**

- State: “**Theorem 1 (Indistinguishability).** For any transparent overlay, there exist executions with identical sender observations but opposite correctness requirements.”
- Detail: Construct traces  $T_1$  (Packet Loss) and  $T_2$  (ACK Loss) where  $\text{SenderView}(T_1) = \text{SenderView}(T_2)$ .

- **Paragraph 3: Implication (The Consensus Barrier).**

- State: “Resolving this ambiguity is equivalent to solving Consensus.”
- Argument: Since transparent mechanisms can only **read** remote state (CN=1), they cannot solve the 2-Consensus problem required to agree on “Did it commit?”. Thus, ambiguity is inherent.

- **Subsection 3.1.2: The Optimality of SHIFT**

- **Table:** Insert the “Class Partition” table (Idempotent Writes | Atomics | Two-Sided).
- **Analysis:**
  - **Writes:** Supported. Safe by definition/protocol (idempotent overwrite).
  - **Atomics:** Rejected. Unsafe because FADD/CAS are non-idempotent (Thm 2). Retry corrupts state.
  - **Two-Sided:** Handshake Required. Since Two-Sided RDMA involves the receiver CPU, we can relax the transparency constraint **internally**. The handshake synchronizes queue state, mitigating the “Queue Sliding” impossibility (Thm 2b).

### 3. Section 3.2: Design Challenges (Page 5)

**Goal:** justify specific SHIFT mechanisms using the theorems proved in 3.1.

- **Challenge 1: Passive Switching (Writes & Atomics)**

- **Mechanism:** “Best-Effort Retry” for Writes.
  - **Justification:** Since we proved we **cannot** know if the packet failed (Thm 1), we must pick a default. Retry is the only choice that preserves liveness. For Writes, this is safe (idempotent).
  - **Mechanism:** “Error/Abort” for Atomics.
  - **Justification:** Since we cannot know if it failed, and retry is provably unsafe (Thm 2), the **only** correct transparent action is to abort and notify the application.

- **Challenge 2: Active Switching (Two-Sided Ops)**

- **Mechanism:** The 3-Way Handshake.
- **Problem (Queue Sliding):** Explain that blind retry of SEND/RECV causes queue misalignment. Even if the data is safe, the **consumption** of the Receive Queue element is non-idempotent.
- **Theorem Reference: Theorem 2 (Queue Sliding Case):** “Retrying a SEND operation consumes an additional Receive WQE, desynchronizing the message-to-buffer mapping.”
- **Solution:** The handshake explicitly resynchronizes sequence numbers and queue indices between sender/receiver SHIFTLib instances. This breaks transparency **internally** to preserve it for the application.

### 4. Appendix C: Formal Verification (New Section)

**Goal:** The rigorous “Territory” behind the “Map” in Section 3.

- **C.1 System Model**

- Define  $\text{State} = (\text{Memory}, \text{ReceiveQueue})$ .
- Define Transparency as a function of local history only.

- **C.2 Indistinguishability (Proof of Thm 1)**

- Present the formal trace construction:
  - $T_1$ : [Send(W), PacketLost, Timeout]
  - $T_2$ : [Send(W), Execute(W), AckLost, Timeout]
- Show  $\text{SenderView}(T_1) = \text{SenderView}(T_2)$ .

- **C.3 Non-Idempotency (Proof of Thm 2)**

- **Case A: Atomics.** Show FADD double-count and CAS ABA problem.
- **Case B: Queue Sliding.** Formalize the queue consumption.
  - Lemma:  $\text{length}(Q_{\text{after\_retry}}) = \text{length}(Q_{\text{initial}}) - 2$ .
  - Result: Message  $M_2$  lands in buffer  $B_3$  instead of  $B_2$ .

- **C.4 Consensus Barrier (Proof of Thm 3)**

- Reduce “Failover Decision” to “2-Process Consensus”.
- Cite Herlihy: Read-Only ops (transparency) have CN=1.
- Conclusion: Transparency implies impossibility of perfect failover for non-idempotent ops.

### Summary of Dependencies

- `paper_section_proof.typ` provides the exact text for Section 1 and 3.1.
- `theory_appendix.typ` provides the definitions and proof sketches for Appendix C.