

Formal Verification of RDMA Failover Impossibility

We formalize and mechanically verify three impossibility theorems for transparent RDMA failover using the Rocq proof assistant (formerly Coq). All proofs are available at github.com/taooceros/shift-verification.

Theorem 1: Indistinguishability of Packet Loss and ACK Loss

Definition (Sender View). Let \mathcal{T} be an execution trace. The *sender view* $\sigma(\mathcal{T})$ is the projection containing only sender-observable events: operation sends, completions, and timeouts.

Definition (Transparent Overlay). A failover mechanism is *transparent* if its retransmission decision $D : \sigma(\mathcal{T}) \times \text{Op} \rightarrow \{0, 1\}$ depends only on the sender view.

Theorem (Impossibility of Safe Retransmission). For any transparent overlay D , there exist executions \mathcal{T}_1 (packet lost) and \mathcal{T}_2 (ACK lost, memory reused) such that:

$$\sigma(\mathcal{T}_1) = \sigma(\mathcal{T}_2) \quad (1)$$

but safety requires $D(\sigma(\mathcal{T}_1)) = 1$ (retransmit) while $D(\sigma(\mathcal{T}_2)) = 0$ (do not retransmit).

Proof. We construct two traces with identical sender views but opposite correctness requirements:

\mathcal{T}_1 : [Send(W_D), PacketLost(W_D), Timeout(W_D)]

\mathcal{T}_2 : [Send(W_D), Receive, Execute, AppConsume, AppReuse(V'), AckLost, Timeout(W_D)]

Both produce sender view [ObsSent(W_D), ObsTimeout(W_D)]. In \mathcal{T}_1 , the operation was never executed (liveness requires retry). In \mathcal{T}_2 , the operation executed and memory was reused with value $V' \neq V_1$ (safety forbids retry). Since D is a function, $D(\sigma(\mathcal{T}_1)) = D(\sigma(\mathcal{T}_2))$, contradicting the requirements. \square

Theorem 2: Non-Idempotency of Atomic Operations

Theorem (FADD Non-Idempotency). For any $\delta > 0$ and memory state m , FADD is not idempotent:

$$\text{exec}_{\text{FADD}}(\text{exec}_{\text{FADD}(m, a, \delta)}, a, \delta) \neq \text{exec}_{\text{FADD}(m, a, \delta)} \quad (2)$$

Proof. Let $m[a] = v$. After one FADD: $m'[a] = v + \delta$. After retry: $m''[a] = v + 2\delta$. Since $\delta > 0$, we have $v + \delta \neq v + 2\delta$. \square

Theorem (CAS Retry Violation). Under concurrent modification, a CAS retry can succeed twice, violating at-most-once semantics.

Proof. Consider sender S with $\text{CAS}(a, 0, 1)$ and concurrent process P with $\text{CAS}(a, 1, 0)$:

State 0: $m[a] = 0$

State 1: $S.\text{CAS}(0, 1)$ succeeds $\rightarrow m[a] = 1$

State 2: $P.\text{CAS}(1, 0)$ succeeds $\rightarrow m[a] = 0$

State 3: S retries $\text{CAS}(0, 1) \rightarrow$ succeeds again!

S 's single CAS executed twice, and P 's successful modification was silently overwritten. \square

Theorem 3: Consensus Hierarchy Barrier

We prove that failover coordination is equivalent to 2-process consensus, which read-only verification cannot solve.

Unified Observation Constraint Framework

Definition (Observation Constraint). Each synchronization primitive defines a constraint on what protocols can observe:

Primitive	Constraint
Register	$\text{valid}_{\text{rw}} : \text{obs}(\text{exec}, i)$ depends only on writes before i
FADD	$\text{valid}_{\text{fadd}} : \text{obs}(\text{exec}, i)$ depends only on $\{j : j \text{ before } i\}$ (set, not order)
CAS	$\text{valid}_{\text{cas}} : \text{obs}(\text{exec}, i) = \text{winner}(\text{exec})$ (first process)

The constraints are *derived* from primitive semantics:

- **Register**: Reads are invisible; only writes affect observable state
- **FADD**: Returns sum of prior deltas; $\delta_0 + \delta_1 = \delta_1 + \delta_0$
- **CAS**: First CAS to sentinel wins; all subsequent fail; all read same value

Consensus Number Verification

Definition (Consensus Number). $\text{CN}(X) = n$ iff X can solve n -consensus but not $(n+1)$ -consensus.

Lemma (Register CN = 1). For any observation function satisfying valid_{rw} , solo executions [0] and [1] produce identical observations (both have empty prior write history) but require decisions 0 and 1 respectively.

Lemma (FADD CN = 2). For any observation function satisfying $\text{valid}_{\text{fadd}}$, executions [0, 1, 2] and [1, 0, 2] are indistinguishable to process 2 (both see $\{0, 1\}$ ran before), but require decisions 0 and 1.

Lemma (CAS CN = ∞). Any observation function satisfying $\text{valid}_{\text{cas}}$ gives $\text{obs}(\text{exec}, i) = \text{winner}(\text{exec})$. Different winners \rightarrow different observations \rightarrow always distinguishable.

Reduction: Failover Solver \Rightarrow 2-Consensus Protocol

Following Herlihy's methodology, we prove failover requires $\text{CN} \geq 2$ by showing that a correct failover solver implies a correct 2-consensus protocol.

Definition (Failover Solver). A failover solver $F : \text{Memory} \rightarrow \{\text{Commit}, \text{Abort}\}$ correctly determines whether the CAS was executed based on memory state.

Definition (2-Consensus Protocol from Failover). Given failover solver F , construct 2-consensus protocol:

- **Encoding**: P_0 's input \mapsto "CAS executed", P_1 's input \mapsto "CAS not executed"
- **Protocol**: Both processes call $F(\text{shared_mem})$ and return the result
- **Decoding**: Commit $\mapsto P_0$ won, Abort $\mapsto P_1$ won

Theorem (Reduction Correctness). If F correctly solves failover, then $\text{consensus_from_failover}(F)$ correctly solves 2-consensus.

Proof. Let F be a correct failover solver. For any execution where P_i wins:

- Encode as history h_i : $h_0 = \text{HistExecuted}(m)$, $h_1 = \text{HistNotExecuted}(m)$
- By correctness: $F(\text{mem}(h_i)) = \text{correct_decision}(h_i) = i$
- **Agreement**: Both processes call F on same memory \rightarrow same output

- **Validity:** Output equals winner's input by correctness of F

□

Theorem (Failover Requires CN ≥ 2). No correct failover solver exists, therefore failover requires CN ≥ 2 .

Proof. Suppose F is a correct failover solver. Then:

- $F(m) = \text{true}$ for $H_1 = \text{HistExecuted}(m)$ (correctness for “executed”)
- $F(m) = \text{false}$ for $H_0 = \text{HistNotExecuted}(m)$ (correctness for “not executed”)

But $\text{mem}(H_0) = \text{mem}(H_1) = m$ (ABA problem), so $F(m)$ must be both true and false. Contradiction.

By the reduction, if failover were solvable, 2-consensus would be solvable. Since 2-consensus requires CN ≥ 2 , so does failover. □

Theorem (Transparent Failover Impossibility). Read-only verification has CN = 1 < 2, therefore transparent failover is impossible.

Theorem (Main Result). Transparent RDMA failover for atomic operations is impossible because:

1. Failover requires solving 2-consensus
2. Transparency limits verification to read-only operations
3. CN(Register) = 1 < 2
4. By Herlihy's hierarchy, CN=1 primitives cannot solve 2-consensus

Mechanization

Component	Lines	Key Theorems
Core definitions	400	Memory model, RDMA operations, traces
Theorem 1	200	<code>impossibility_safe_retransmission</code>
Theorem 2	300	<code>fadd_not_idempotent, cas_double_success</code>
Theorem 3	1200	<code>register_cn_1_verified, fadd_cn_2_verified, valid_cas_no_ambiguity, transparent_cas_failover_impossible</code>

Table 1: Rocq formalization statistics

All proofs are constructive and fully mechanized in Rocq 9.0. The consensus number framework provides a unified treatment where each primitive's limitation is derived from its operational semantics, and the failover impossibility follows as a direct consequence of Herlihy's hierarchy applied to the structural isomorphism between failover and 2-consensus.