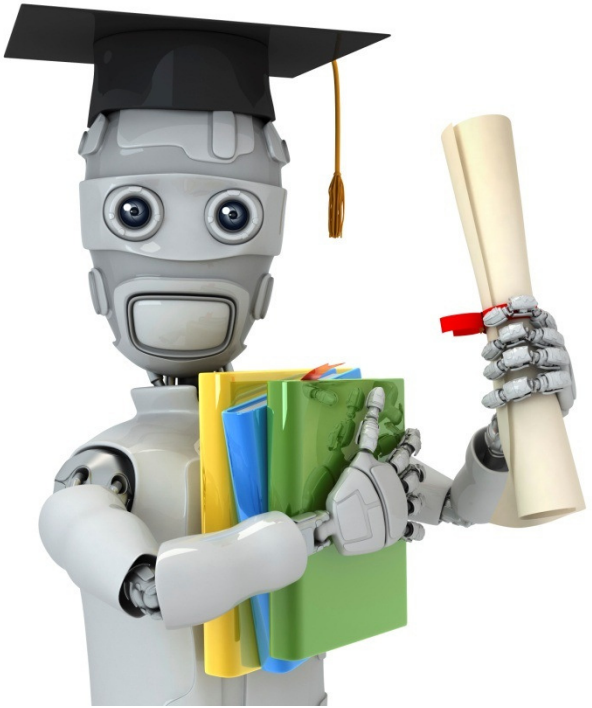


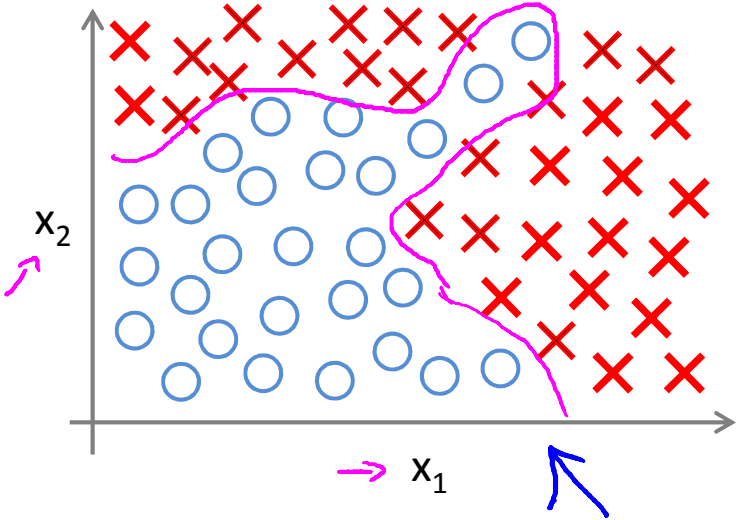
Machine Learning

Neural Networks: Representation

Non-linear hypotheses

Non-linear Classification

If you want to apply logistic regression to this problem, one thing you could do is apply logistic regression with a lot of nonlinear features like that.



$$g(\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1 x_2 + \theta_4 x_1^2 x_2 + \theta_5 x_1^3 x_2 + \theta_6 x_1 x_2^2 + \dots)$$

$x_1^2, x_1x_2, x_1x_3, x_1x_4 \dots x_1x_{100}$

$x_2^2, x_2x_3 \dots$

≈ 5000 feature $O(n^2)$

$\approx \frac{n^2}{2}$

$x_1^2, x_2^2, x_3^2, \dots, x_{100}^2$

$x_1x_2x_3, x_1^2x_2, x_{10}x_{11}x_{17}, \dots$

$O(n^3)$

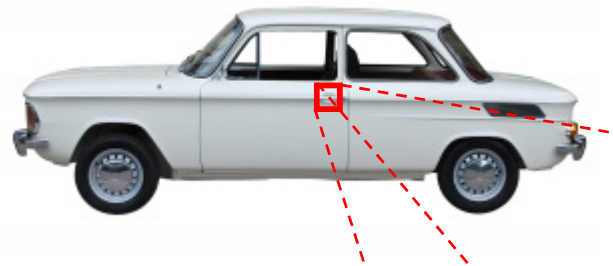
$170{,}000$

x_1 = size
x_2 = # bedrooms
x_3 = # floors
x_4 = age
$\dots$
x_{100}

$n = 100$

What is this?

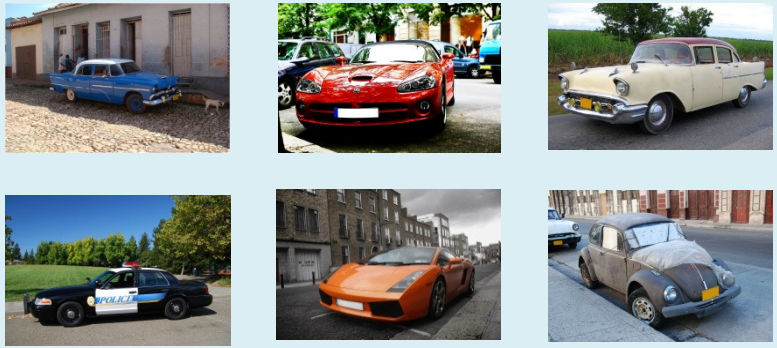
You see this:



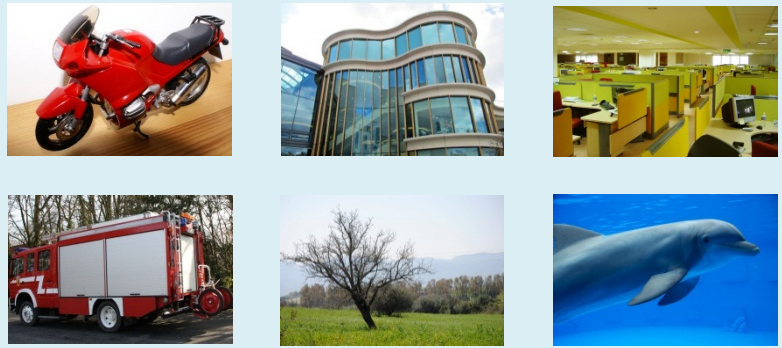
But the camera sees this:

194	210	201	212	199	213	215	195	178	158	182	209
180	189	190	221	209	205	191	167	147	115	129	163
114	126	140	188	176	165	152	140	170	106	78	88
87	103	115	154	143	142	149	153	173	101	57	57
102	112	106	131	122	138	152	147	128	84	58	66
94	95	79	104	105	124	129	113	107	87	69	67
68	71	69	98	89	92	98	95	89	88	76	67
41	56	68	99	63	45	60	82	58	76	75	65
20	43	69	75	56	41	51	73	55	70	63	44
50	50	57	69	75	75	73	74	53	68	59	37
72	59	53	66	84	92	84	74	57	72	63	42
67	61	58	65	75	78	76	73	59	75	69	50

Computer Vision: Car detection



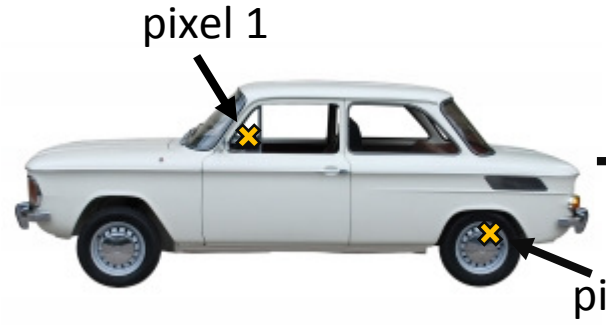
Cars



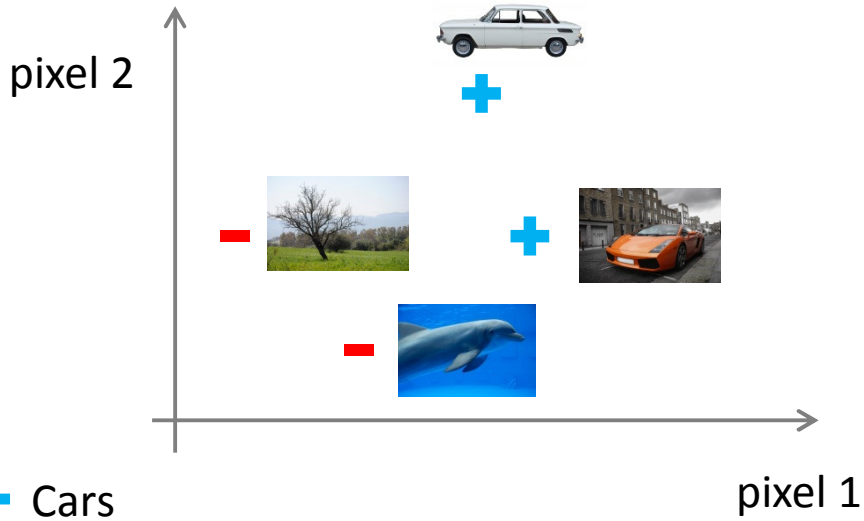
Not a car

Testing:

What is this?

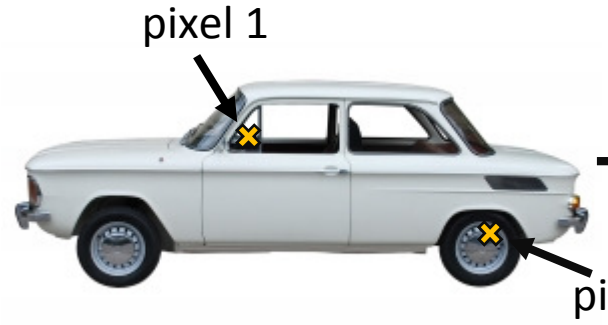


Learning Algorithm

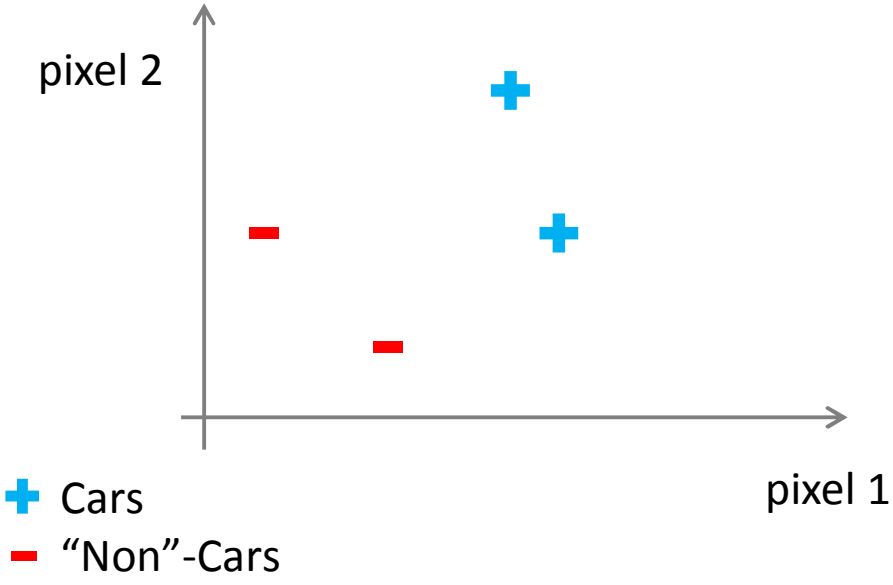


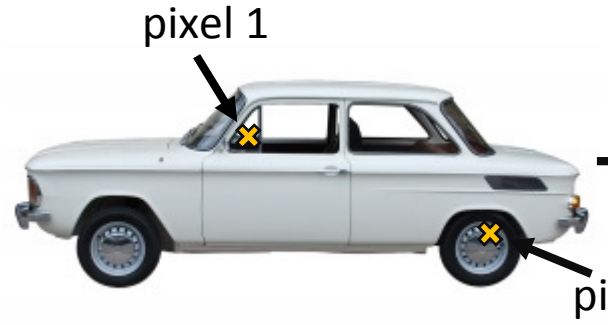
+ Cars

- “Non”-Cars

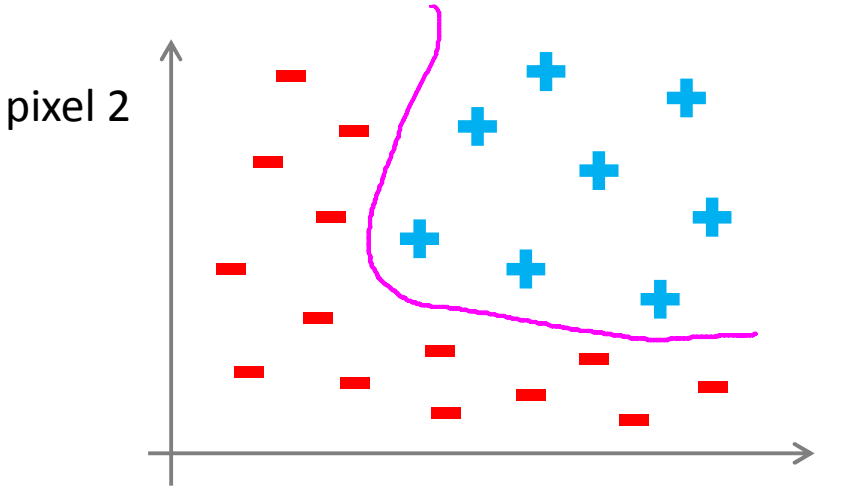


Learning Algorithm





Learning Algorithm



Cars

"Non"-Cars

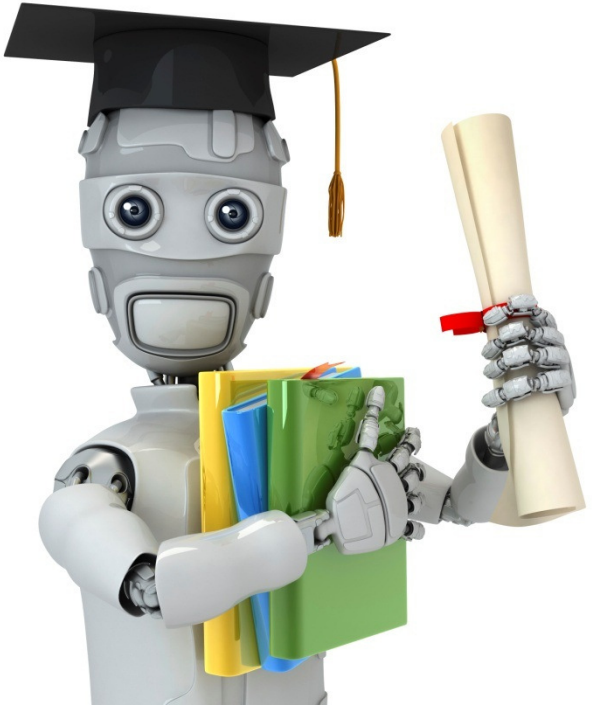
50 x 50 pixel images→ 2500 pixels

$n = 2500$ (7500 if RGB)

$$x = \begin{bmatrix} \text{pixel 1 intensity} \\ \text{pixel 2 intensity} \\ \vdots \\ \text{pixel 2500 intensity} \end{bmatrix}$$

0-255

Quadratic features ($x_i \times x_j$): ≈3 million features



Machine Learning

Neural Networks: Representation

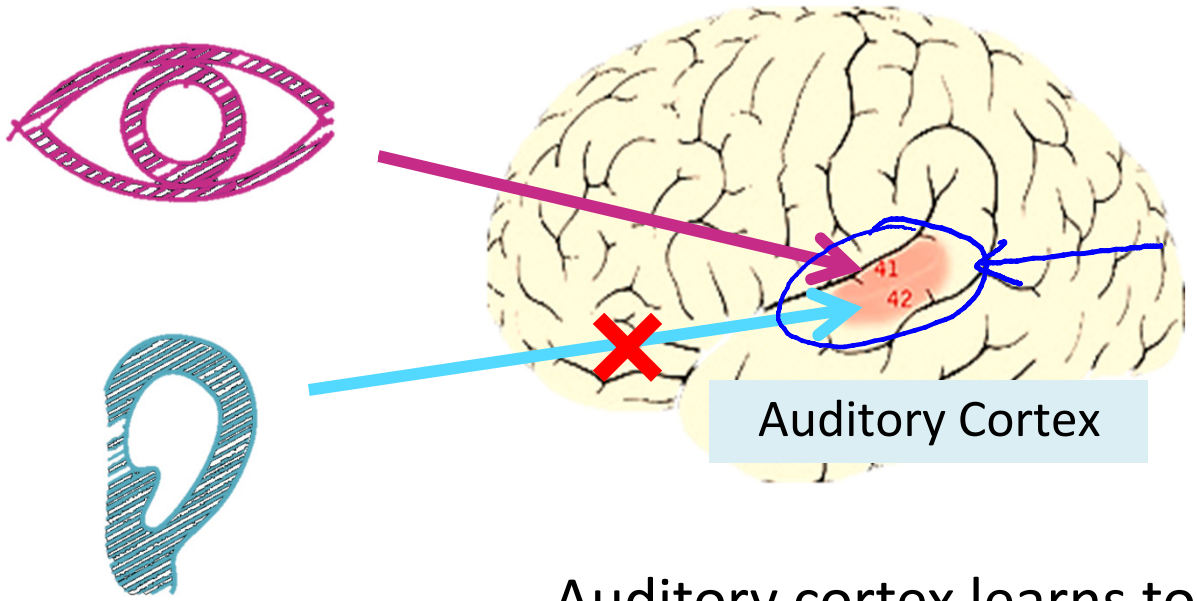
Neurons and the brain

Neural Networks

- Origins: Algorithms that try to mimic the brain.
- Was very widely used in 80s and early 90s; popularity diminished in late 90s.
- Recent resurgence: State-of-the-art technique for many applications

One of the reasons for this resurgence is that Neural Networks are computationally some what more expensive algorithm and so, it was only, you know, maybe somewhat more recently that computers became fast enough to really run large scale Neural Networks and because of that as well as a few other technical reasons

The “one learning algorithm” hypothesis

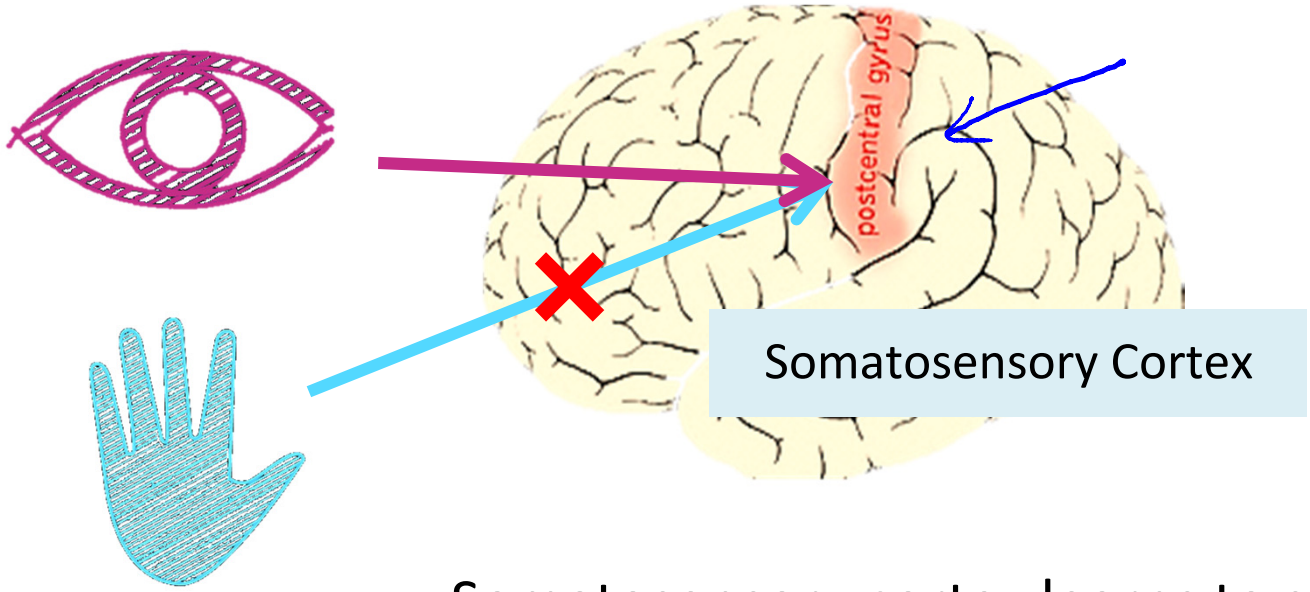


Auditory cortex learns to see

There's this sense that if the same piece of physical brain tissue can process sight or sound or touch then maybe there is one learning algorithm that can process sight or sound or touch.

[Roe et al., 1992]

The “one learning algorithm” hypothesis

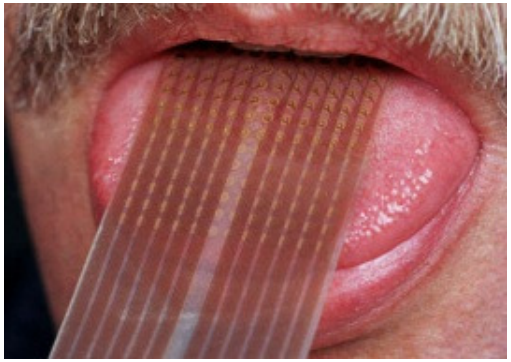


Somatosensory cortex learns to see

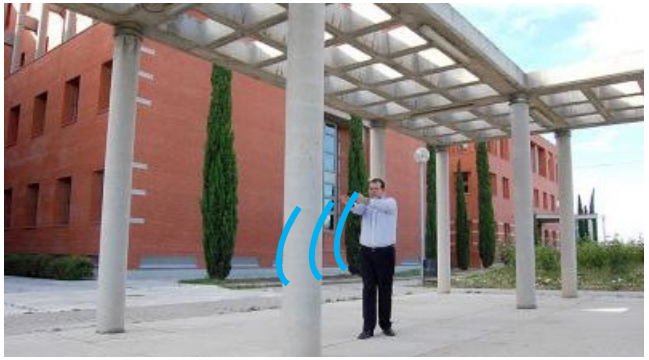
[Metin & Frost, 1989]

(看下頁解說)

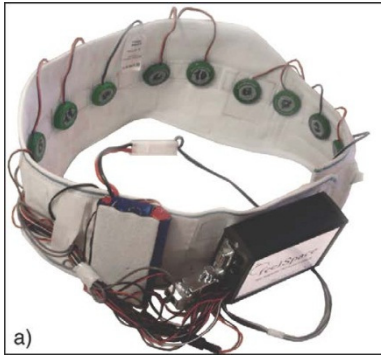
Sensor representations in the brain



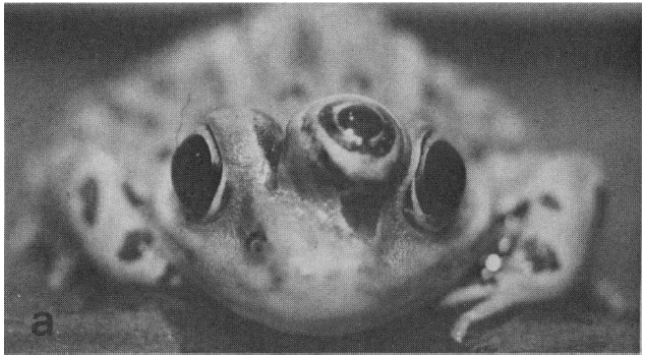
Seeing with your tongue



Human echolocation (sonar)



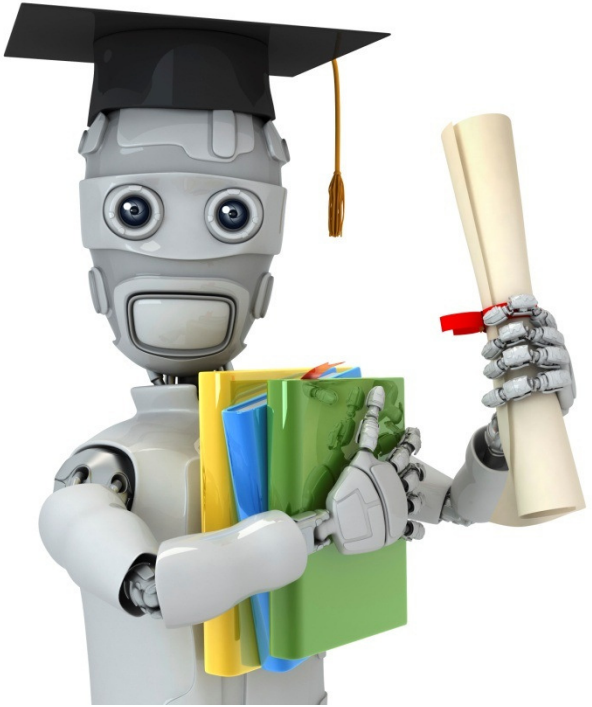
Haptic belt: Direction sense



Implanting a 3rd eye

[BrainPort; Welsh & Blasch, 1997; Nagel et al., 2005; Constantine-Paton & Law, 2009]

上頁:
Here are a few more examples. On the upper left is an example of learning to see with your tongue. The way it works is--this is actually a system called BrainPort undergoing FDA trials now to help blind people see--but the way it works is, you strap a grayscale camera to your forehead, facing forward, that takes the low resolution grayscale image of what's in front of you and you then run a wire to an array of electrodes that you place on your tongue so that each pixel gets mapped to a location on your tongue where maybe a high voltage corresponds to a dark pixel and a low voltage corresponds to a bright pixel and, even as it does today, with this sort of system you and I will be able to learn to see, you know, in tens of minutes with our tongues.

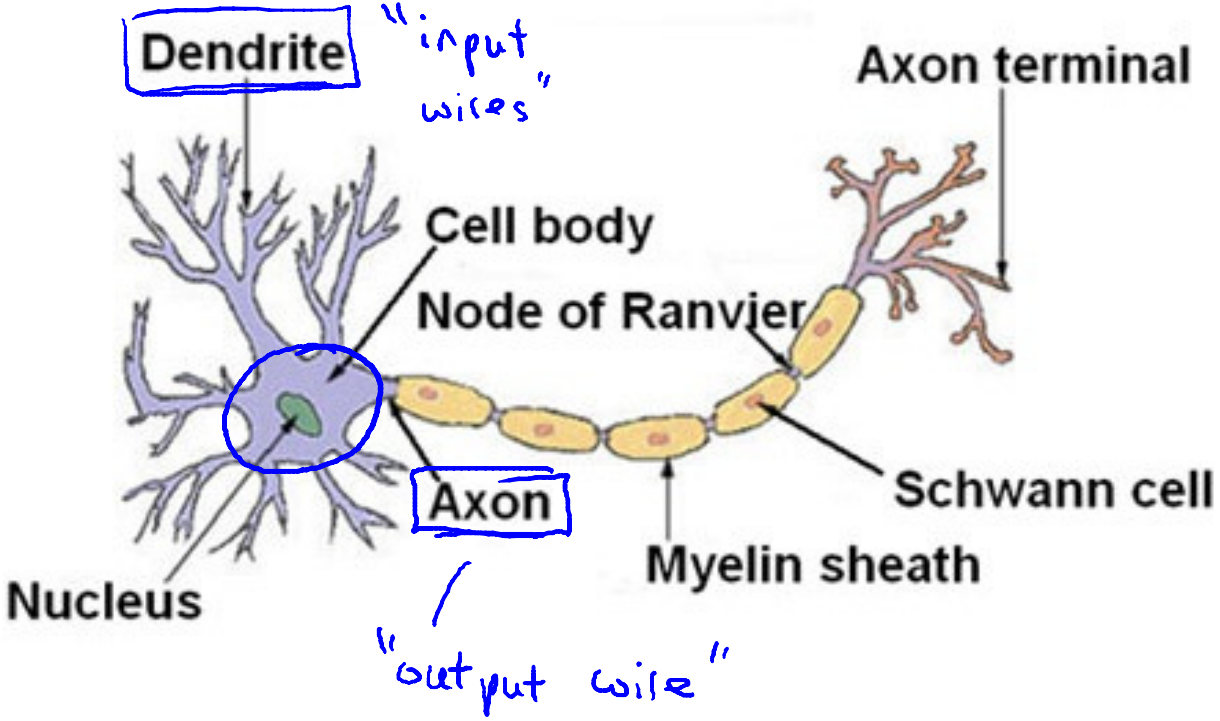


Machine Learning

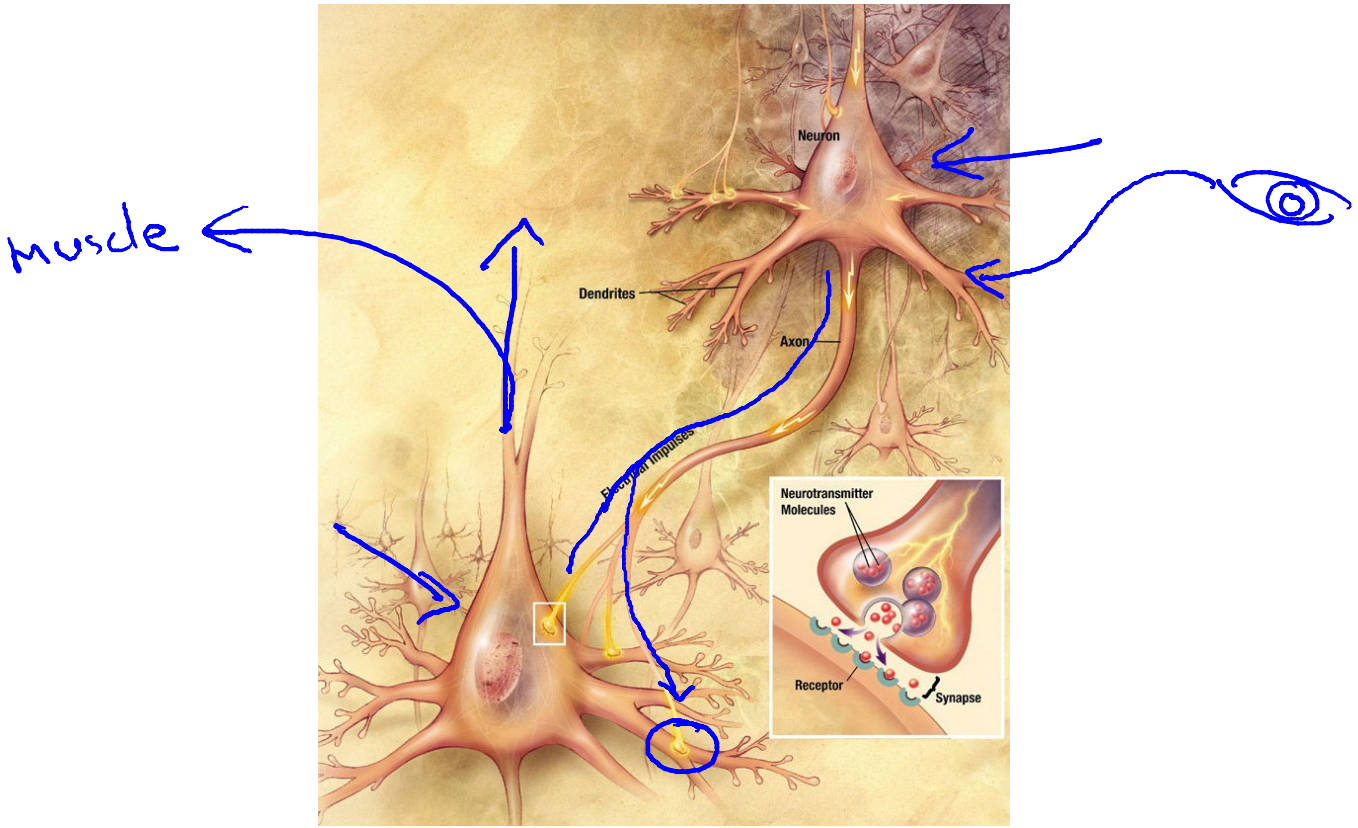
Neural Networks: Representation

Model representation I

Neuron in the brain

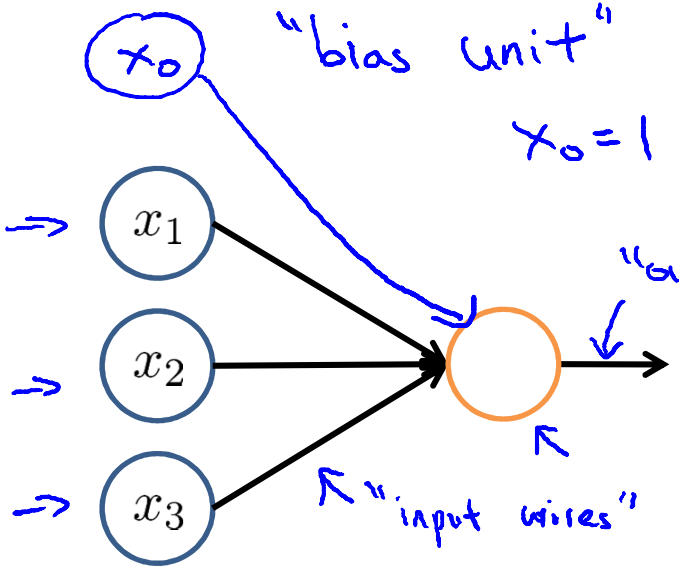


Neurons in the brain



[Credit: US National Institutes of Health, National Institute on Aging]

Neuron model: Logistic unit



$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \qquad \theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \\ \theta_3 \end{bmatrix}$$

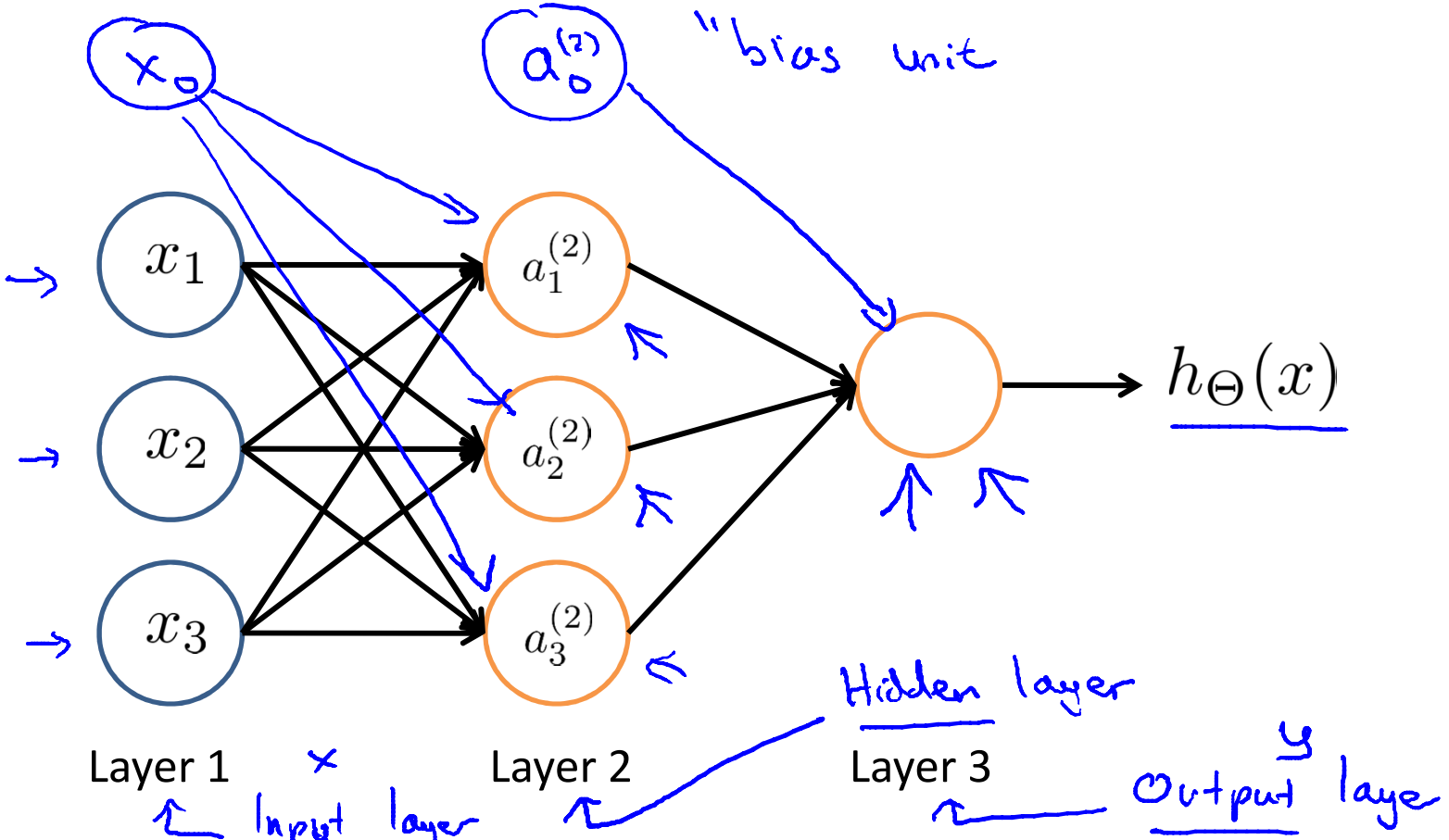
"weights" ("parameters")

$$h_\theta(x) = \frac{1}{1 + e^{-\theta^T x}}$$

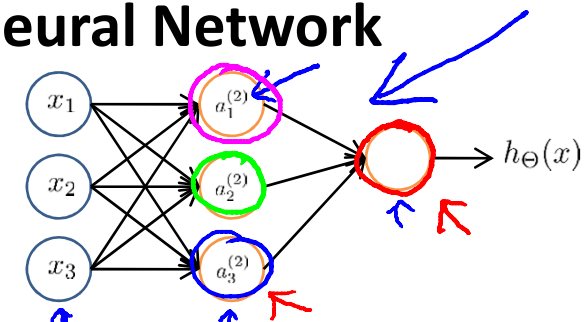
Sigmoid (logistic) activation function.

$$g(z) = \frac{1}{1 + e^{-z}}$$

Neural Network



Neural Network



→ $a_i^{(j)}$ = "activation" of unit i in layer j

→ $\Theta^{(j)}$ = matrix of weights controlling function mapping from layer j to layer $j+1$

$\Theta^{(1)} \in \mathbb{R}^{3\times 4}$

$h_\Theta(x)$

→ $a_1^{(2)} = g(\Theta_{10}^{(1)}x_0 + \Theta_{11}^{(1)}x_1 + \Theta_{12}^{(1)}x_2 + \Theta_{13}^{(1)}x_3)$

→ $a_2^{(2)} = g(\Theta_{20}^{(1)}x_0 + \Theta_{21}^{(1)}x_1 + \Theta_{22}^{(1)}x_2 + \Theta_{23}^{(1)}x_3)$

→ $a_3^{(2)} = g(\Theta_{30}^{(1)}x_0 + \Theta_{31}^{(1)}x_1 + \Theta_{32}^{(1)}x_2 + \Theta_{33}^{(1)}x_3)$

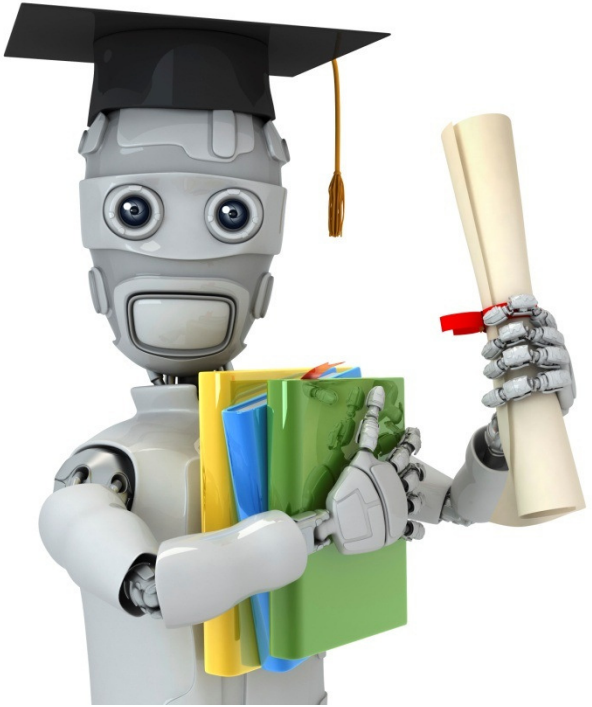
$\Theta^{(2)}$

易知a^(3)_1已經是output了，沒必要再算h(a^(3)_1)

→ $h_\Theta(x) = a_1^{(3)} = g(\Theta_{10}^{(2)}a_0^{(2)} + \Theta_{11}^{(2)}a_1^{(2)} + \Theta_{12}^{(2)}a_2^{(2)} + \Theta_{13}^{(2)}a_3^{(2)})$

→ If network has s_j units in layer j, s_{j+1} units in layer $j+1$, then $\Theta^{(j)}$ will be of dimension $s_{j+1} \times (s_j + 1)$.

$s_{j+1} \times (s_j + 1)$

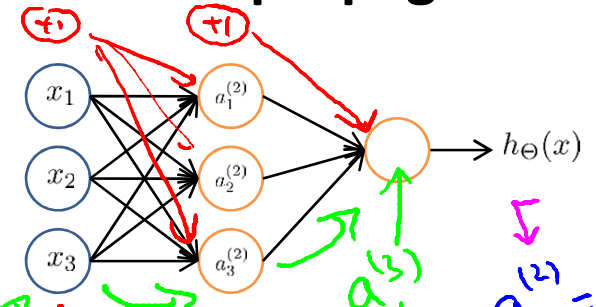


Machine Learning

Neural Networks: Representation

Model representation II

Forward propagation: Vectorized implementation



$a^{(1)} = x$

$a_1^{(2)} = g(z_1^{(2)})$

$$a_1^{(2)} = g(\Theta_{10}^{(1)} x_0 + \Theta_{11}^{(1)} x_1 + \Theta_{12}^{(1)} x_2 + \Theta_{13}^{(1)} x_3)$$
$$a_2^{(2)} = g(\Theta_{20}^{(1)} x_0 + \Theta_{21}^{(1)} x_1 + \Theta_{22}^{(1)} x_2 + \Theta_{23}^{(1)} x_3)$$
$$a_3^{(2)} = g(\Theta_{30}^{(1)} x_0 + \Theta_{31}^{(1)} x_1 + \Theta_{32}^{(1)} x_2 + \Theta_{33}^{(1)} x_3)$$
$$h_\Theta(x) = g(\Theta_{10}^{(2)} a_0^{(2)} + \Theta_{11}^{(2)} a_1^{(2)} + \Theta_{12}^{(2)} a_2^{(2)} + \Theta_{13}^{(2)} a_3^{(2)})$$

$a_3^{(2)} = g(z_3^{(2)})$ $\quad z^{(3)}$

$$x = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \qquad z^{(2)} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \\ z_3^{(2)} \end{bmatrix}$$

$z^{(2)} = \Theta^{(1)} a^{(1)}$

$a^{(2)} = g(z^{(2)})$ $\quad \mathbb{R}^3 \quad \mathbb{R}^3$

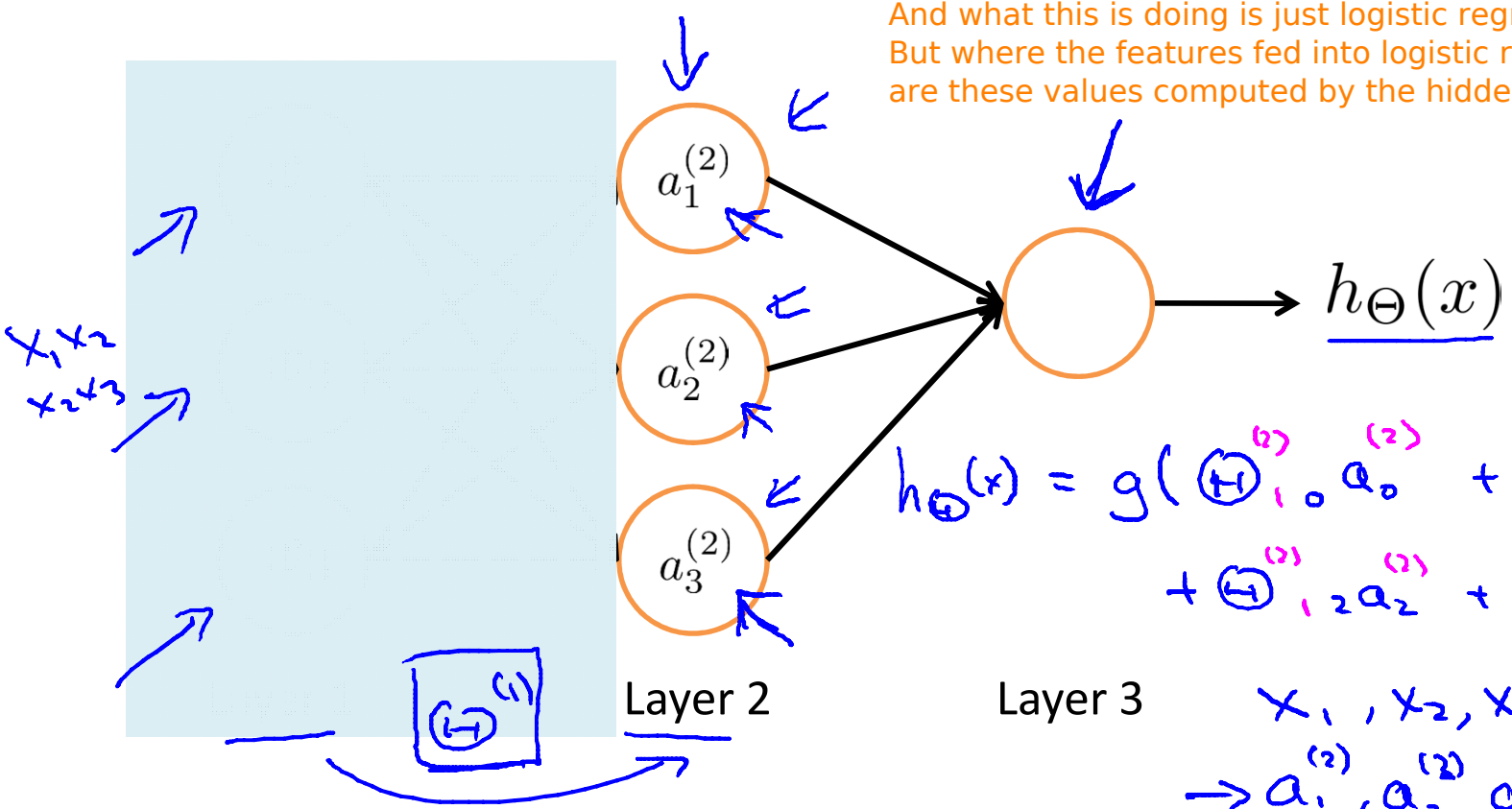
Add $a_0^{(2)} = 1.$ $\quad a^{(2)} \in \mathbb{R}^4$

$z^{(3)} = \Theta^{(2)} a^{(2)}$

$h_\Theta(x) = a^{(3)} = g(z^{(3)})$

Neural Network learning its own features

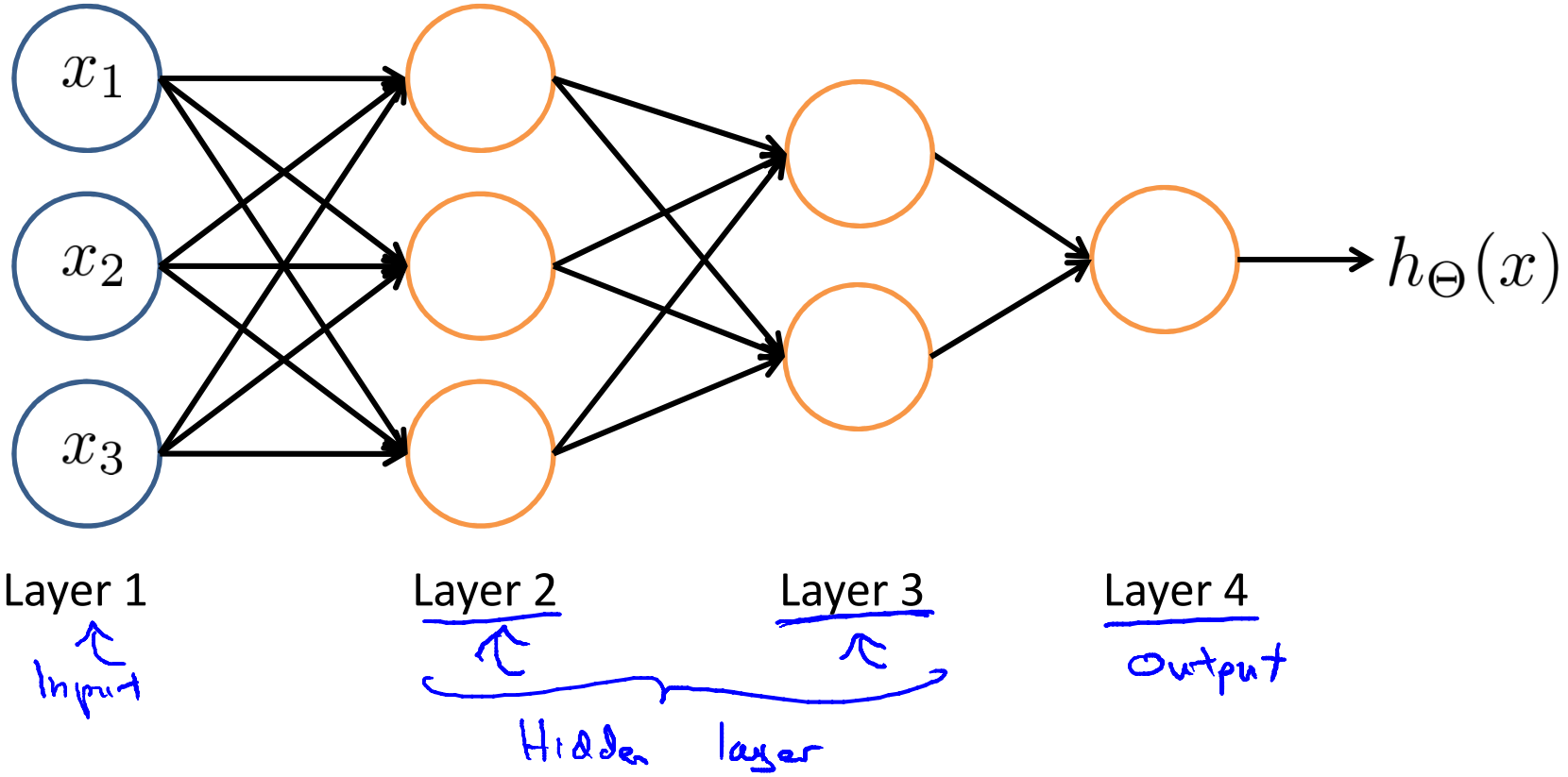
And what this is doing is just logistic regression.
But where the features fed into logistic regression are these values computed by the hidden layer.

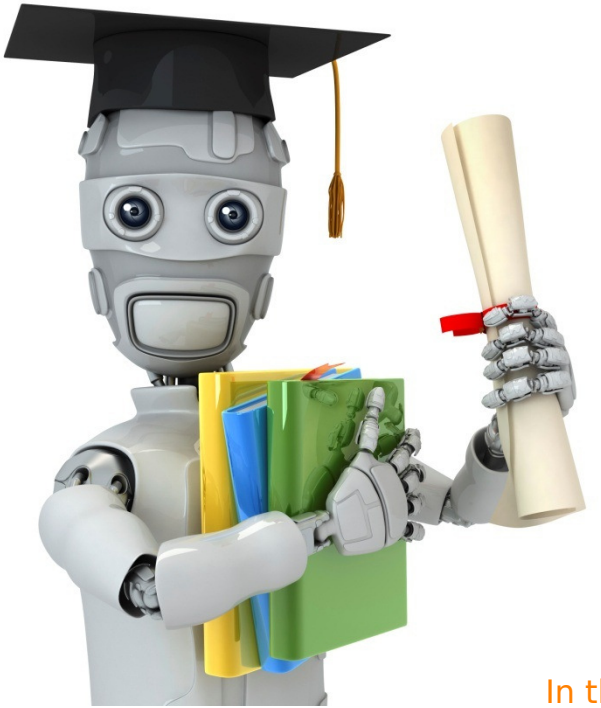


$$h_\Theta(x) = g(\Theta_{1,0}^{(2)} a_0^{(2)} + \Theta_{1,1}^{(1)} a_1^{(2)} + \Theta_{1,2}^{(2)} a_2^{(2)} + \Theta_{1,3}^{(2)} a_3^{(2)})$$

x_1, x_2, x_3
$\rightarrow a_1^{(2)}, a_2^{(2)}, a_3^{(2)}$

Other network architectures





Machine Learning

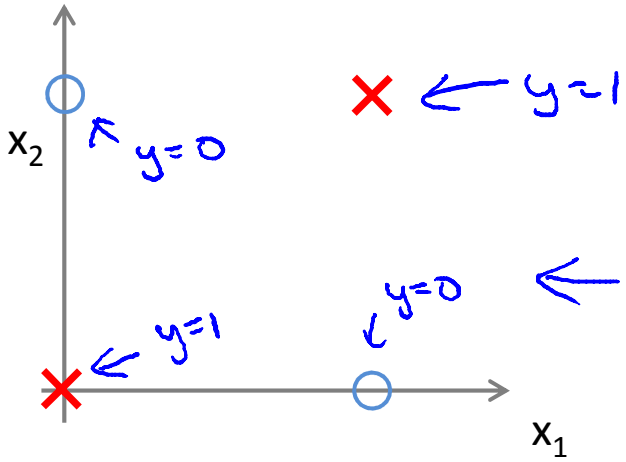
Neural Networks: Representation

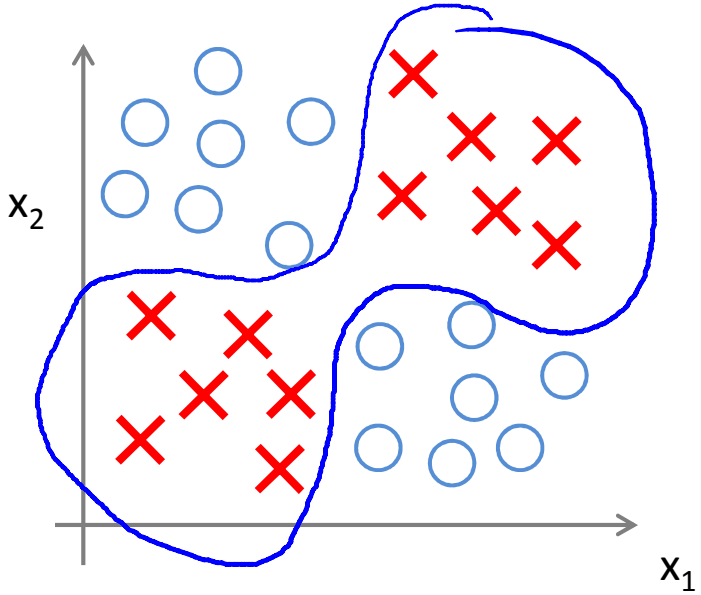
Examples and intuitions I

In this and the next video I want to work through a detailed example showing how a neural network can compute a complex non linear function of the input. And hopefully this will give you a good sense of why neural networks can be used to learn complex non linear hypotheses.

Non-linear classification example: XOR/XNOR

x_1, x_2 are binary (0 or 1).





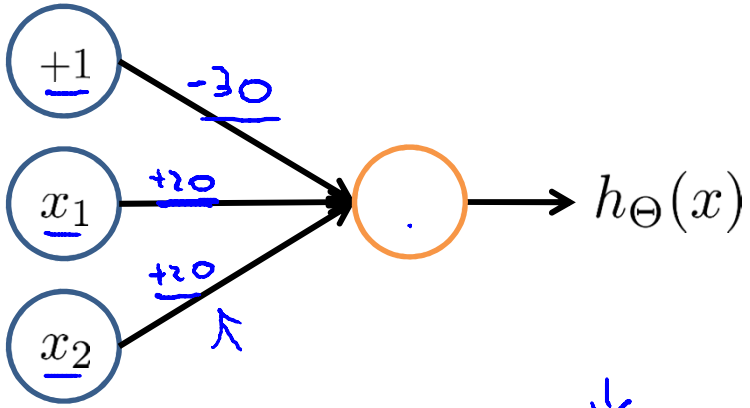
$y = x_1 \text{ XOR } x_2$

$x_1 \text{ XNOR } x_2$

$\text{NOT } (x_1 \text{ XOR } x_2)$

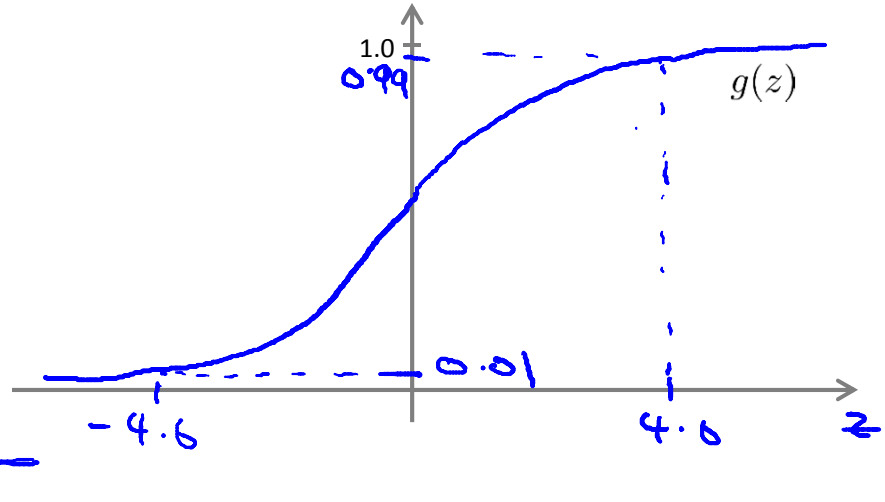
Simple example: AND

- $x_1, x_2 \in \{0, 1\}$
- $y = x_1$ AND x_2



$h_\Theta(x) = g(-30 + 20x_1 + 20x_2)$

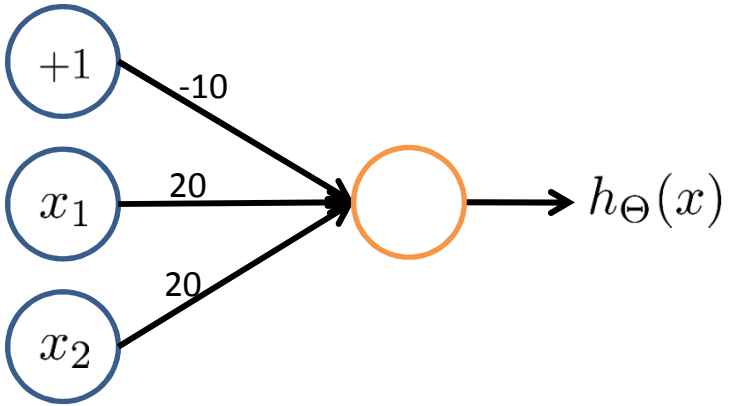
$\Theta^{(1)}_{10}$ $\Theta^{(1)}_{11}$ $\Theta^{(1)}_{12}$



x_1	x_2	$h_\Theta(x)$
0	0	$g(-30) \approx 0$
0	1	$g(-10) \approx 0$
1	0	$g(-10) \approx 0$
1	1	$g(10) \approx 1$

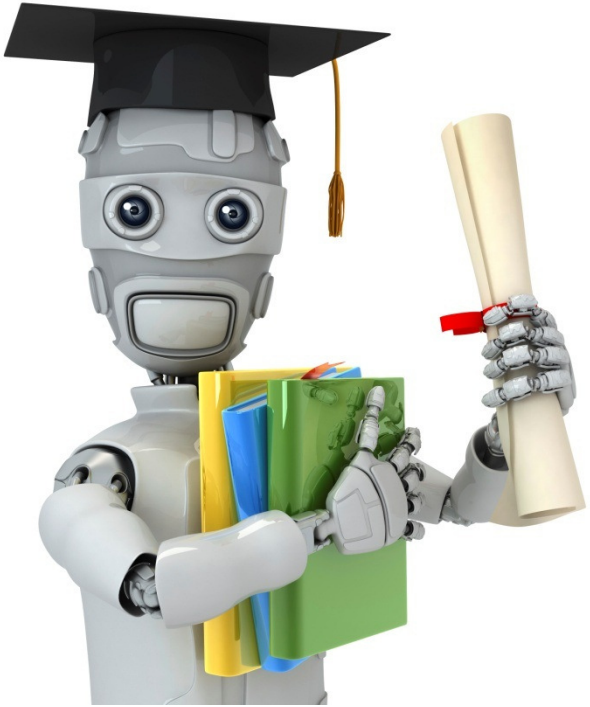
$h_\Theta(x) \approx x_1$ AND x_2

Example: OR function



$g(-10 + 20x_1 + 20x_2)$

x_1	x_2	$h_\Theta(x)$
0	0	$g(-10) \approx 0$
0	1	$g(10) \approx 1$
1	0	≈ 1
1	1	≈ 1



Machine Learning

Neural Networks: Representation

Examples and intuitions II

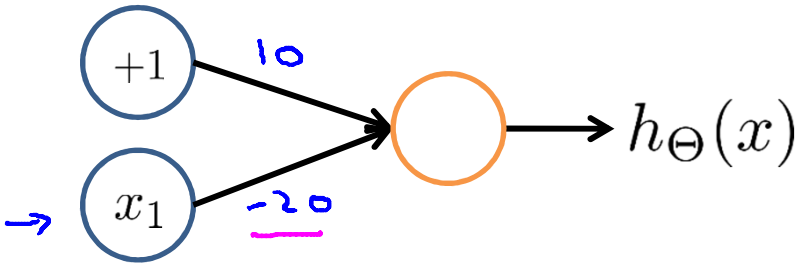
→ x_1 AND x_2

→ x_1 OR x_2

{0,1}.

Negation:

NOT x_1



x_1	$h_\Theta(x)$
0	$g(10) \approx 1$
1	$g(-10) \approx 0$

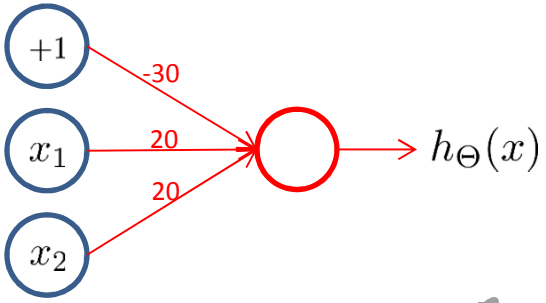
$h_\Theta(x) = g(10 - 20x_1)$

→ (NOT x_1) AND (NOT x_2)

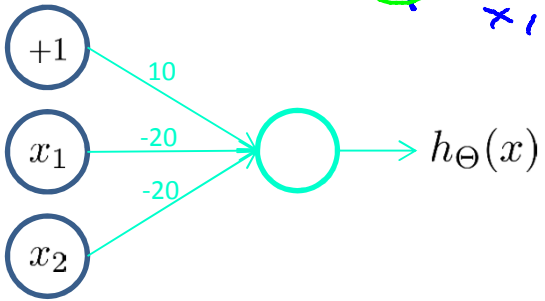
(=1 if and only if

→ $x_1 = x_2 = 0$

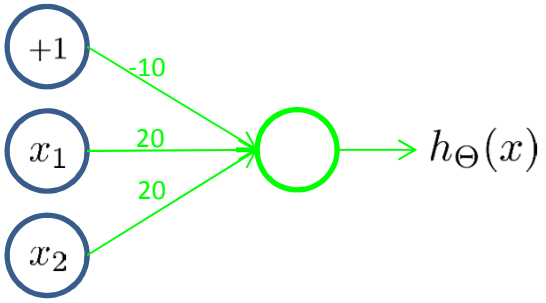
Putting it together: x_1 XNOR x_2



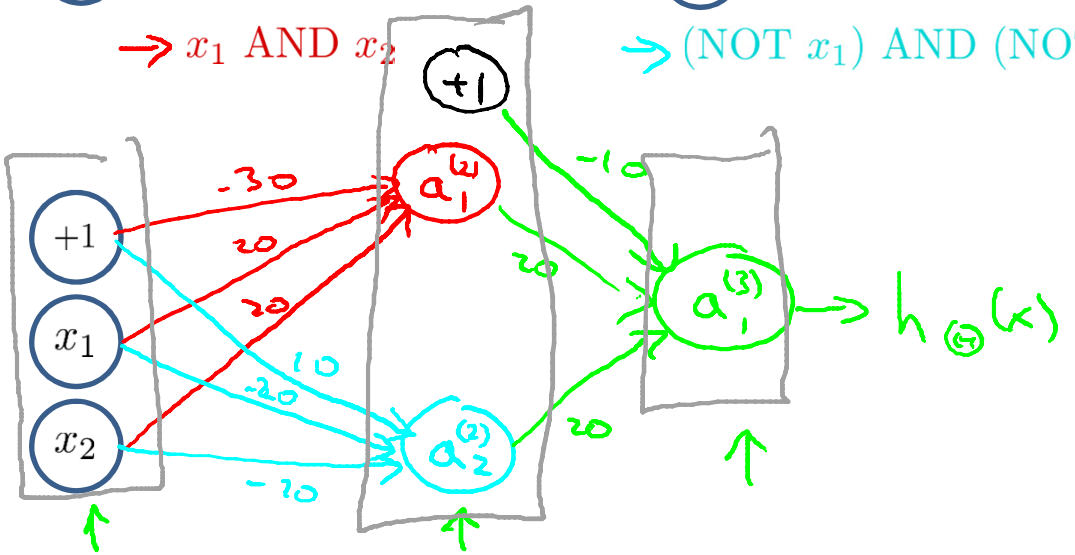
$\rightarrow x_1$ AND x_2



$\rightarrow$ (NOT x_1) AND (NOT x_2)

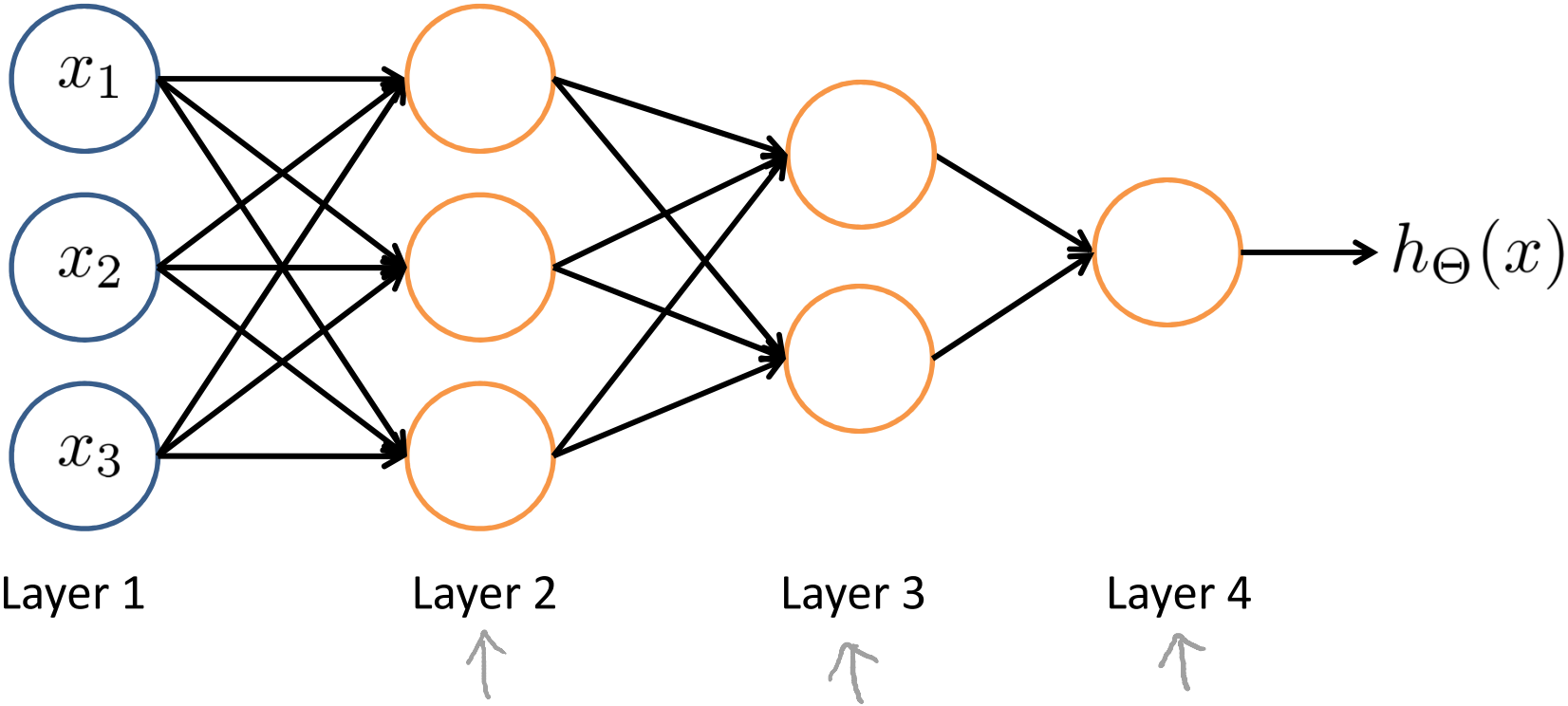


$\rightarrow x_1$ OR x_2



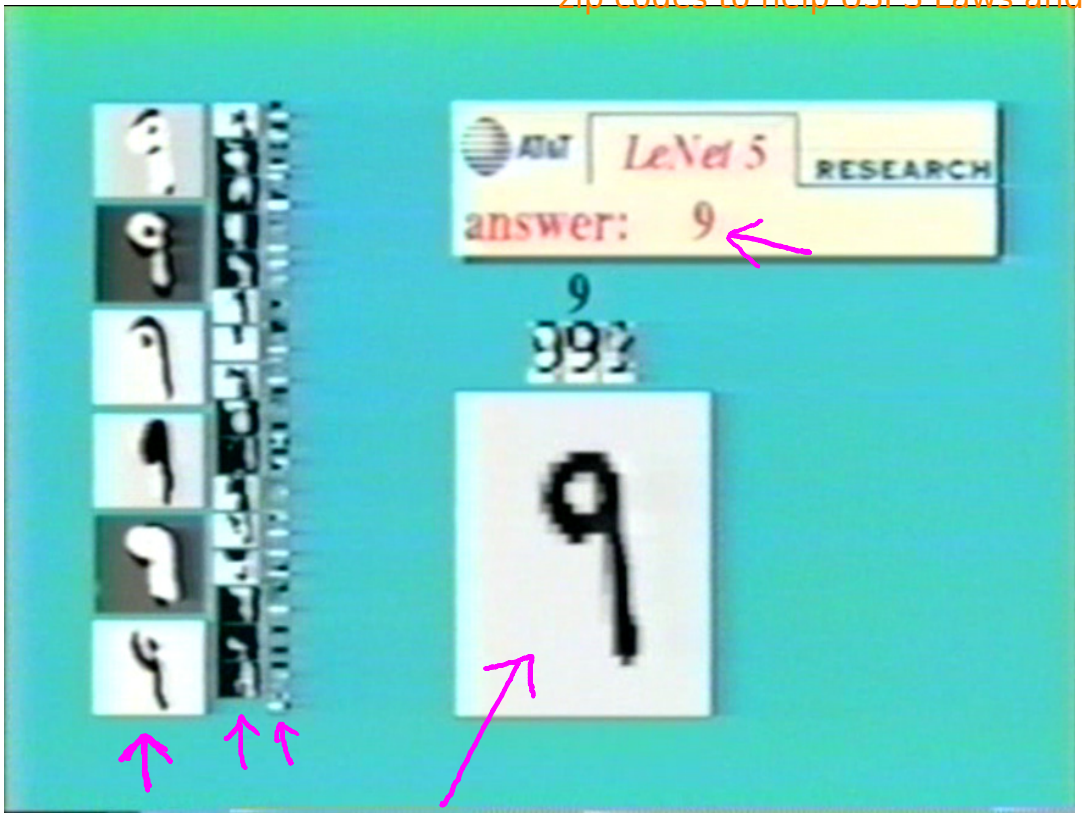
x_1	x_2	$a_1^{(2)}$	$a_2^{(2)}$	$h_\Theta(x)$
0	0	0	1	1
0	1	0	0	0
1	0	0	0	0
1	1	1	0	1

Neural Network intuition



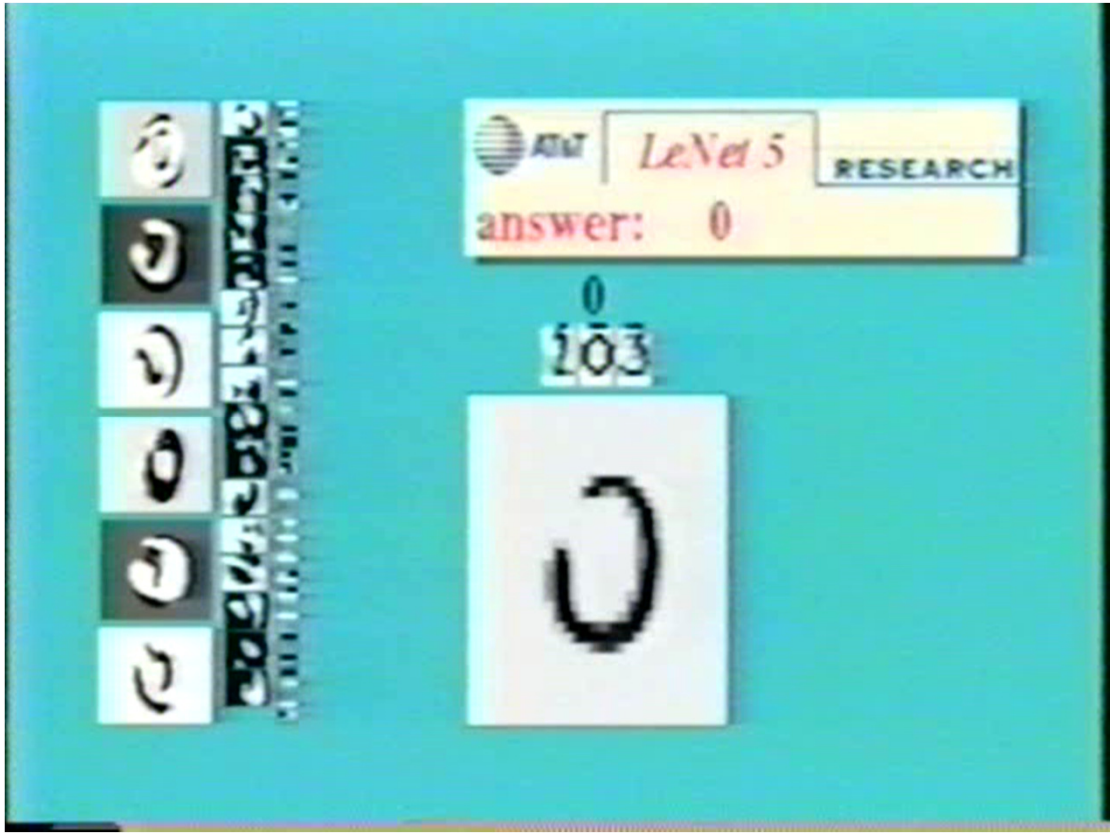
Handwritten digit classification

at the start of this class I said that one of the earliest successes of neural networks was trying to use it to read zip codes to help USPS Laws and read postal codes.

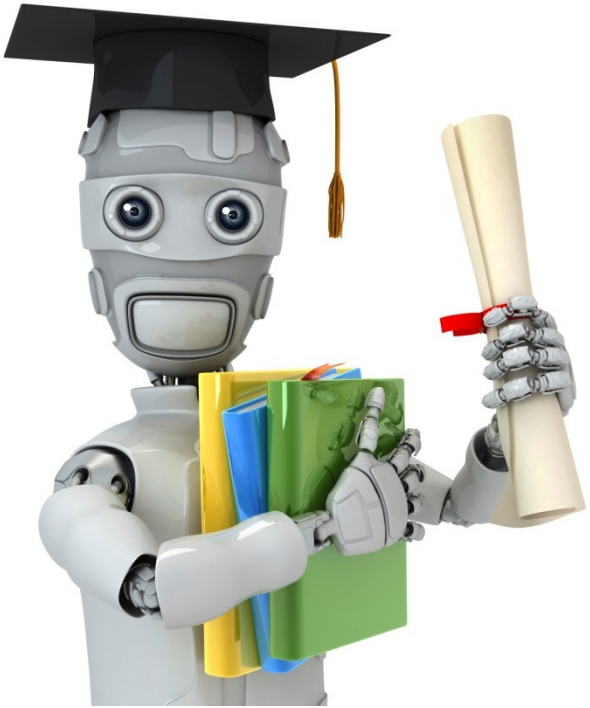


[Courtesy of Yann LeCun]

Handwritten digit classification



[Courtesy of Yann LeCun]



Machine Learning

Neural Networks: Representation

Multi-class classification

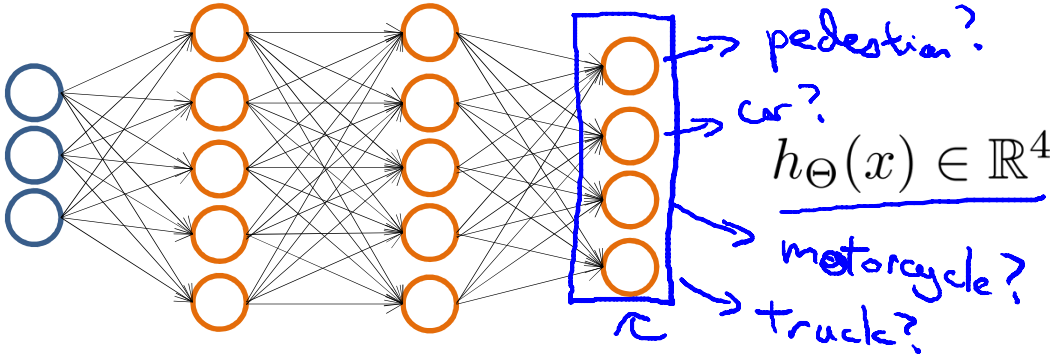
Multiple output units: One-vs-all.

Pedestrian

Car

Motorcycle

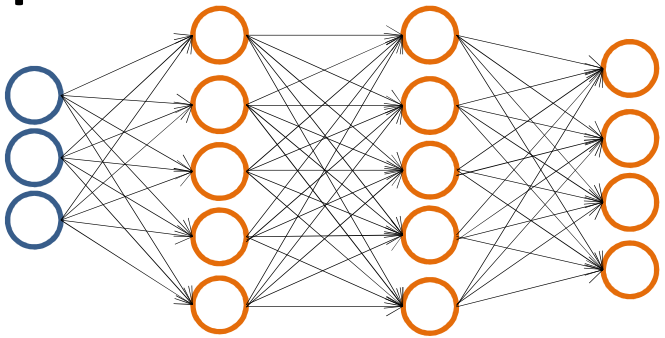
Truck



Want $h_\Theta(x) \approx \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$, $h_\Theta(x) \approx \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$, $h_\Theta(x) \approx \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$, etc.

when pedestrian when car when motorcycle

Multiple output units: One-vs-all.



$h_\Theta(x) \in \mathbb{R}^4$

Want $h_\Theta(x) \approx \begin{bmatrix}1\\0\\0\\0\end{bmatrix}$, $h_\Theta(x) \approx \begin{bmatrix}0\\1\\0\\0\end{bmatrix}$, $h_\Theta(x) \approx \begin{bmatrix}0\\0\\1\\0\end{bmatrix}$, etc.

when pedestrian when car when motorcycle

Training set: $(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \ldots, (x^{(m)}, y^{(m)})$

$y^{(i)}$ one of $\begin{bmatrix}1\\0\\0\\0\end{bmatrix}, \begin{bmatrix}0\\1\\0\\0\end{bmatrix}, \begin{bmatrix}0\\0\\1\\0\end{bmatrix}, \begin{bmatrix}0\\0\\0\\1\end{bmatrix}$

pedestrian car motorcycle truck

$(x^{(i)}, y^{(i)})$

Previously $y \in \{1, 2, 3, 4\}$

$h_\Theta(x^{(i)}) \approx y^{(i)}$

$\in \mathbb{R}^4$