

Compilers

Local Optimization

The simplest form of optimization

- Optimize one basic block
 - No need to analyze the whole procedure body

Some statements can be deleted

$$x := x + 0$$

$$x := x * 1$$

Some statements can be simplified

Algebraic Simplifications

$$x := x * 0 \qquad \Rightarrow x := 0$$

$$y := y * 2 \qquad \Rightarrow y := y * y$$

$$x := x * 8 \qquad \Rightarrow x := x << 3$$

$$x := x * 15 \qquad \Rightarrow t := x << 4; x := t - x$$

(on some machines << is faster than *; but not on all!)

- Operations on constants can be computed at compile time Constant?
 - If there is a statement $x := y \circ p z$
 - And y and z are constants
 - Then y op z can be computed at compile time

- Example: $x := 2 + 2 \implies x := 4$
- Example: if 2 < 0 jump L can be deleted if 270 jump L jump L

Constant folding can be dangerous.



crosscompiler

X and Y are different archs.

$$\alpha := 1.5 + 3.7$$

 $\alpha := 5.2$

- Eliminate unreachable basic blocks:
 - Code that is unreachable from the initial block
 - E.g., basic blocks that are not the target of any jump or "fall through" from a conditional

- Removing unreachable code makes the program smaller
 - And sometimes also faster
 - Due to memory cache effects
 - Increased spatial locality

Why would unreachable basic blocks occur?

libraries

result of optimizations

 Some optimizations are simplified if each register occurs only once on the left-hand side of an assignment

• Rewrite intermediate code in single assignment form

$$\begin{array}{c}
\underline{x} := z + y \\
a := \underline{x} \\
\underline{x} := 2 * \underline{x}
\end{array}$$

$$\Rightarrow \begin{array}{c}
\underline{b} = z + y \\
a = \underline{b} \\
x := 2 * \underline{b}
\end{array}$$
(b is a fresh register)

More complicated in general, due to loops

- If
 - Basic block is in single assignment form



common Subexplession elimination

- A definition x :=is the first use of xin a block
- Then
 - When two assignments have the same rhs, they compute the same value
- Example:

$$\begin{array}{c} x := y + z \\ \hline \\ w := y + z \\ \hline \end{array} \Rightarrow \qquad \begin{array}{c} x := y + z \\ \\ w := x \\ \end{array}$$

(the values of x, y, and z do not change in the ... code)

- If $\underline{w} := x$ appears in a block, replace subsequent uses of w with uses of x
 - Assumes single assignment form
- Example:

$$\begin{array}{ccc} b := z + y & & b := z + y \\ a := b & \Rightarrow & a := b \\ x := 2 * a & & x := 2 * b \end{array}$$

- Only useful for enabling other optimizations
 - Constant folding
 - Dead code elimination

• Example:

$$a := 5$$
 $x := 2 * 8$
 $\Rightarrow x := 10$
 $y := x + 6 = 16$
 $t := x * x$
 $\Rightarrow x := 10$
 $t := x * x$
 $\Rightarrow x := 10$
 $t := x * x$

lf

w := <u>rhs</u> appears in a basic blockw does not appear anywhere else in the program

Then

the statement w := rhs is dead and can be eliminated

— <u>Dead</u> = <u>does not contribute</u> to the program's result

Example: (a is not used anywhere else)

$$\begin{cases}
x := z + y & b := z + y \\
a := x \Rightarrow a := b & \Rightarrow x := 2 * b
\end{cases}$$

$$x := 2 * b \Rightarrow x := 2 * b$$

Each local optimization does little by itself

- Typically optimizations interact
 - Performing one optimization enables another

- Optimizing compilers repeat optimizations until no improvement is possible
 - The optimizer can also be stopped at any point to limit compilation time

• Initial code:

• Algebraic optimization:

$$a := x ** 2$$
 $b := 3$
 $c := x$
 $d := c * c$
 $e := b * 2$
 $f := a + d$
 $g := e * f$

• Algebraic optimization:

$$a := x * x$$
 $b := 3$
 $c := x$
 $d := c * c$
 $e := b << 1$
 $f := a + d$
 $g := e * f$

Copy propagation:

Copy propagation:

Constant folding:

Constant folding:

Common subexpression elimination:

Common subexpression elimination:

Copy propagation:

Copy propagation:

Dead code elimination:

Dead code elimination:

$$a := x * x$$

$$f:=a+a$$
 $2*\alpha$ $g:=6*f$ $g:=12*\alpha$

This is the final form

Which of the following are valid local optimizations for the given basic block? Assume that only g and x are referenced outside of this basic block.

- Copy propagation: Line 4 becomes d := a * b.
- Common subexpression elimination: Line 5 becomes e := d.
- Dead code elimination: Line 3 is removed.
- After many rounds of valid optimizations, the entire block can be reduced to g := 5.

Local Optimization

```
1 a := 1
2 b := 3
3 c := a + x
4 d := a * 3
5 e := b * 3
6 f := a + b
7 g := e - f
```