Adaptive gPC Convergence Criteria Norms

Paul Talbot*

1 Notation

- ξ The vector of input variables $\xi = (\xi_1, \xi_2, \cdots, \xi_N)$
- Ω The input space spanned by the input variable distributions
- ullet ϵ The error between an iteration Λ_2 and Λ_1
- k A combination of polynomial orders, given as a tuple
- ullet Λ_1 The set of all desired polynomial combinations k for the current iteration
- \bullet Λ_2 The set of all desired polynomial combinations k for the next iteration
- ullet $c_{i,k}$ The scalar coefficient for polynomial combination with orders k in index set Λ_i
- $\bullet~\Phi_k$ The multidimensional orthonormal polynomial basis with degrees k.

2 L2 of Difference Space

$$\epsilon = \sqrt{\int_{\Omega} d\xi \left[\sum_{k \in \Lambda_2} c_{2,k} \Phi_k(\xi) - \sum_{k \in \Lambda_1} c_{1,k} \Phi_k(\xi) \right]^2}.$$
 (1)

Let $c_{1,k} = 0 \forall k \notin \Lambda_1$, and noting

$$\int_{\Omega} \Phi_j(\xi) \Phi_k(\xi) P(\xi) d\xi = \delta_{jk}, \tag{2}$$

$$\epsilon = \sqrt{\int_{\Omega} d\xi \left[\sum_{m=1}^{2} \sum_{n=1}^{2} \sum_{j \in \Lambda_2} \sum_{k \in \Lambda_2} c_{m,k} c_{n,j} \Phi_k(\xi) \Phi_j(\xi) \right]},$$
(3)

$$= \sqrt{\sum_{k \in \Lambda_2} c_{2,k}^2 - 2\sum_{k \in \Lambda_2} c_{2,k} c_{1,k} + \sum_{k \in \Lambda_2} c_{1,k}^2},$$
(4)

$$= \sqrt{\sum_{k \in \Lambda_2} (c_{2,k} - c_{1,k})^2}.$$
 (5)

^{*}talbotp@unm.edu