Notation

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Contents

1	Fon	t notation			
2	Sign	nals and functions			
	2.1	Time indexing			
	2.2	Common signals			
	2.3	Common functions			
	2.4	Operations and symbols			
	2.5	Transformations			
3	Probability, statistics, and stochastic processes				
	3.1	Operators and symbols			
	3.2	Stochastic processes			
	3.3	Functions			
	3.4	Distributions			
4	Machine learning, optimization theory, and				
	stat	sistical signal processing			
	4.1	Derivative terms			
	4.2	Estimated terms			
	4.3	Signals, (hyper)parameters, system performance, and criteria			
5	Lin	ear Algebra			
	5.1	Common matrices and vectors			
	5.2	Indexing			
	5.3	General operations			
	5.4	Operations with matrices and tensors			
	5.5	Operations with vectors			
	5.6	Decompositions			
	5.7	Spaces and sets			

		Set operations	
6	6.1	Amunication systems Symbols	
7	7.1 7.2	Propositional Logic	
8	Calo	culus	
9	Elec	etromagnetic waves	
10	10 Generic mathematical symbols		
11	1 Abbreviations		

1 Font notation

$a, b, c, \ldots, A, B, C, \ldots$	Scalars
a, b, c, \dots	Vectors
$\overline{\mathbf{A}, \mathbf{B}, \mathbf{C}, \dots}$	Matrices
$\mathcal{A}, \mathcal{B}, \mathcal{C}, \dots$	Tensors
ABC ABC ABC	Sets

2 Signals and functions

2.1 Time indexing

x(t)	Continuous-time t
$x[n],x[k],x[m],x[i],\ldots$	Discrete-time n, k, m, i, \ldots (parenthe-
$x_n, x_k, x_m, x_i, \dots$	sis should be adopted only if there
$x(n), x(k), x(m), x(i), \dots$	are no continuous-time signals in the
	context to avoid ambiguity)
$x\left[\left((n-m)\right)_{N}\right],x\left((n-m)\right)_{N}$	Circular shift in m samples within a
	N-samples window [13, 19]

2.2 Common signals

$\delta(t)$	Delta function
$\delta[n], \delta_{i,j}$	Kronecker function $(n = i - j)$
h(t), h[n]	Impulse response (continuous and
	discrete time)
$\tilde{x}[n], \tilde{x}(t)$	Periodic discrete- or continuous-time
	signal
$\hat{x}[n], \hat{x}(t)$	Estimate of $x[n]$ or $x(t)$
$\dot{x}[m]$	Interpolation of $x[n]$

2.3 Common functions

$\mathcal{O}(\cdot), O(\cdot)$	Big-O notation
$\Gamma(\cdot)$	Gamma function
$Q(\cdot)$	Quantization function
$I_{lpha}(\cdot)$	Modified Bessel function of the first
	kind and order α
$\binom{n}{k}$	Binomial coefficient

2.4 Operations and symbols

$f:A\to B$	A function f whose domain is A and
	codomain is B
$\mathbf{f}:A\to\mathbb{R}^n$	A vector-valued function \mathbf{f} , i.e., $n \geq 2$
$f^n, x^n(t), x^n[k]$	<i>n</i> th power of the function f , $x[n]$ or
	x(t)
$f^{(n)}, x^{(n)}(t)$	nth derivative of the function f or
	x(t)
$f', f^{(1)}, x'(t)$	1th derivative of the function f or
	x(t)
$f'', f^{(2)}, x''(t)$	2th derivative of the function f or
	x(t)
$ \operatorname{argmax}_{x \in A} f(x) $	Value of x that minimizes x
$ \frac{x \in \mathcal{A}}{\arg\min_{x \in \mathcal{A}} f(x)} $	Value of x that minimizes x
$f(\mathbf{x}) = \inf_{\mathbf{y} \in \mathcal{A}} g(\mathbf{x}, \mathbf{y})$	Infimum, i.e., $f(\mathbf{x}) =$
$\mathbf{y} \in \mathcal{A}$	$\min \{ g(\mathbf{x}, \mathbf{y}) \mid \mathbf{y} \in \mathcal{A} \land (\mathbf{x}, \mathbf{y}) \in \text{dom}(g) \},\$
	which is the greatest lower bound of
	this set [3]
$f(\mathbf{x}) = \sup g(\mathbf{x}, \mathbf{y})$	Supremum, i.e., $f(\mathbf{x}) =$
$\mathbf{y} \in \mathcal{A}$	$\max \{g(\mathbf{x}, \mathbf{y}) \mid \mathbf{y} \in \mathcal{A} \land (\mathbf{x}, \mathbf{y}) \in \text{dom}(g)\}\$
	which is the least upper bound of
	this set [3]
$f \circ g$	Composition of the functions f and
	g
*	Convolution (discrete or continuous)
*, N	Circular convolution [7, 19]

2.5 Transformations

W_N	Twiddle factor, $e^{-j\frac{2\pi}{N}}$ [13]
$\mathcal{F}\left\{\cdot\right\}$	Fourier transform
$\mathcal{L}\left\{ \cdot \right\}$	Laplace transform
$\overline{\mathcal{Z}\left\{ \cdot \right\}}$	z-transform
$\hat{x}(t), \hat{x}[n]$	Hilbert transform of $x(t)$ or $x[n]$
X(s)	Laplace transform of $x(t)$
X(f)	Fourier transform (FT) (in linear fre-
	quency, Hz) of $x(t)$
$X(j\omega)$	Fourier transform (FT) (in angular
	frequency, rad/sec) of $x(t)$
$X(e^{j\omega})$	Discrete-time Fourier transform
	(DTFT) of $x[n]$

$X[k], X(k), X_k$	Discrete Fourier transform (DFT) or
	fast Fourier transform (FFT) of $x[n]$,
	or even the Fourier series (FS) of the
	periodic signal $x(t)$
$\tilde{X}[k], \tilde{X}(k), \tilde{X}_k$	Discrete Fourier series (DFS) of $\tilde{x}[n]$
X(z)	z-transform of $x[n]$

3 Probability, statistics, and stochastic processes

3.1 Operators and symbols

$\mathrm{E}\left[\cdot ight],\mathbf{E}\left[\cdot ight],E\left[\cdot ight]$	Statistical expectation operator [6,
	18]
$E_{u}\left[\cdot\right], \mathbf{E}_{u}\left[\cdot\right], E_{u}\left[\cdot\right], \mathbb{E}_{u}\left[\cdot\right]$	Statistical expectation operator with
	respect to u
$\langle \cdot \rangle$	Ensemble average
$\operatorname{var}\left[\cdot\right], \operatorname{VAR}\left[\cdot\right]$	Variance operator [2, 12, 17, 21]
$\operatorname{var}_{u}\left[\cdot\right]\left[\cdot\right], \operatorname{VAR}_{u}\left[\cdot\right]$	Variance operator with respect to u
$cov[\cdot], COV[\cdot]$	Covariance operator [2]
$cov_u[\cdot], COV_u[\cdot]$	Covariance operator with respect to
	и
μ_x	Mean of the random variable x
μ_{x}, m_{x}	Mean vector of the random variable
	x [4]
μ_n	nth-order moment of a random vari-
	able
σ_x^2, κ_2	Variance of the random variable x
\mathcal{K}_x, μ_4	Kurtosis (4th-order moment) of the
	random variable x
Kn	nth-order cumulant of a random vari-
	able
$ ho_{x,y}$	Pearson correlation coefficient be-
	tween x and y
$a \sim P$	Random variable a with distribution
	P
$\overline{\mathcal{R}}$	Rayleigh's quotient

3.2 Stochastic processes

$r_{x}(au), R_{x}(au)$	Autocorrelation function of the signal
	x(t) or $x[n]$ [18]

$S_x(f), S_x(j\omega)$	Power spectral density (PSD) of $x(t)$
	in linear (f) or angular (ω) frequency
$S_{x,y}(f), S_{x,y}(j\omega)$	Cross PSD of $x(t)$ and $y(t)$ in linear
	or angular (ω) frequency
R_{x}	(Auto)correlation matrix of $\mathbf{x}(n)$
$r_{x,d}(\tau), R_{x,d}(\tau)$	Cross-correlation between $x[n]$ and
	d[n] or $x(t)$ and $d(t)$ [18]
R_{xy}	Cross-correlation matrix of $\mathbf{x}(n)$ and
	$\mathbf{y}(n)$
$\mathbf{p}_{\mathbf{x}d}$	Cross-correlation vector
	between $\mathbf{x}(n)$ and $d(n)$
	$[{\bf diniz Adaptive Filtering 1997}]$
$c_x(\tau), C_x(\tau)$	Autocovariance function of the signal
	x(t) or x[n] [18]
$C_x, K_x, \Sigma_x, \text{cov}[x]$	(Auto)covariance matrix of x [12, 17,
	[21, 27]
$c_{xy}(\tau), C_{xy}(\tau)$	Cross-covariance function of the sig-
	$\operatorname{nal} x(t) \text{ or } x[n] [18]$
$C_{xy}, K_{xy}, \Sigma_{xy}$	Cross-covariance matrix of \mathbf{x} and \mathbf{y}

3.3 Functions

$Q(\cdot)$	Q-function, i.e., $P[\mathcal{N}(0,1) > x]$ [21]
$\operatorname{erf}(\cdot)$	Error function [21]
$\operatorname{erfc}(\cdot)$	Complementary error function i.e.,
	$\operatorname{erfc}(x) = 2Q(\sqrt{2}x) - \operatorname{erf}(x)$ [21]
P[A]	Probability of the event or set A [17]
$p(\cdot), f(\cdot)$	Probability density function (PDF)
	or probability mass function (PMF)
	[17]
$p(x \mid A)$	Conditional PDF or PMF [17]
$F(\cdot)$	Cumulative distribution function
	(CDF)
$\Phi_{x}(\omega), M_{x}(j\omega), E\left[e^{j\omega x}\right]$	First characteristic function (CF) of
	x [21, 26]
$M_X(t), \Phi_X(-jt), E[e^{tX}]$	Moment-generating function (MGF)
	of x [21, 26]
$\Psi_{x}(\omega), \ln \Phi_{x}(\omega), \ln E\left[e^{j\omega x}\right]$	Second characteristic function
$K_x(t)$, $\ln E\left[e^{tx}\right]$, $\ln M_x(t)$	Cumulant-generating function
	(CGF) of x [12]

3.4 Distributions

$\mathcal{N}(\mu,\sigma^2)$	Gaussian distribution of a random variable with mean μ and variance σ^2
$\mathcal{CN}(\mu, \sigma^2)$	Complex Gaussian distribution of a random variable with mean μ and variance σ^2
$\mathcal{N}(\pmb{\mu},\pmb{\Sigma})$	Gaussian distribution of a vector random variable with mean μ and covariance matrix Σ
$\mathcal{CN}(oldsymbol{\mu}, oldsymbol{\Sigma})$	Complex Gaussian distribution of a vector random variable with mean μ and covariance matrix Σ
$\frac{\mathcal{U}(a,b)}{\chi^2(n),\chi_n^2}$	Uniform distribution from a to b
$\chi^2(n), \chi_n^2$	Chi-square distribution with n degree of freedom (assuming that the Gaussians are $\mathcal{N}(0,1)$)
$\operatorname{Exp}(\lambda)$	Exponential distribution with rate parameter λ
$\Gamma(\alpha, \beta)$	Gamma distribution with shape parameter α and rate parameter β
$\Gamma(\alpha, \theta)$	Gamma distribution with shape parameter α and scale parameter $\theta = 1/\beta$
$\operatorname{Nakagami}(m,\Omega)$	Nakagami-m distribution with shape parameter or fading figure m and spread, scale, or shape parameter Ω
Rayleigh(σ)	Rayleigh distribution with scale parameter σ
$\operatorname{Rayleigh}(\Omega)$	Rayleigh distribution with the second moment $\Omega = E[x^2] = 2\sigma^2$
$\mathrm{Rice}(s,\sigma)$	Rice distribution with noncentrality parameter s and σ . s^2 represent the specular component power
$\overline{\mathrm{Rice}(A,K)}$	Rice distribution with Rice factor $K = s^2/2\sigma^2$ and scale parameter $A = s^2 + 2\sigma^2$

4 Machine learning, optimization theory, and statistical signal processing

4.1 Derivative terms

$\mathbf{\nabla} f, \mathbf{g}$	Gradient descent vector

$\nabla_x f, \mathbf{g}_x$	Gradient descent vector with respect x [2]
J	Jacobian matrix
H	Hessian matrix

4.2 Estimated terms

\mathbf{g} (or $\hat{\mathbf{g}}$ if the gradient vector is $\mathbf{g})$	Stochastic gradient descent (SGD), i.e., instantaneous approximation of
	gradient descent vector
$\hat{x}(t)$ or $\hat{x}[n]$	Estimate of $x(t)$ or $x[n]$
$\hat{\mathbf{\mu}}_{x},\hat{\mathbf{m}}_{x}$	Sample mean of $x[n]$ or $x(t)$
$\frac{\hat{\boldsymbol{\mu}}_{\mathbf{x}}, \hat{\mathbf{m}}_{\mathbf{x}}}{\hat{r}_{x}(\tau), \hat{R}_{x}(\tau)}$	Sample mean vector of $\mathbf{x}[n]$ or $\mathbf{x}(t)$
$\hat{r}_{x}(au), \hat{R}_{x}(au)$	Estimated autocorrelation function
	of the signal $x(t)$ or $x[n]$ [18]
$\hat{S}_x(f), \hat{S}_x(j\omega)$	Estimated power spectral density (PSD) of $x(t)$ in linear (f) or angular (ω) frequency
$\hat{\mathbf{R}}_{\mathbf{x}}$	Sample (auto)correlation matrix
$\frac{\hat{\mathbf{R}}_{\mathbf{x}}}{\hat{r}_{x,d}(\tau),\hat{R}_{x,d}(\tau)}$	Estimated cross-correlation between
	x[n] and $d[n]$ or $x(t)$ and $d(t)$
$\hat{S}_{x,y}(f), \hat{S}_{x,y}(j\omega)$	Estimated cross PSD of $x(t)$ and $y(t)$
	in linear or angular (ω) frequency
$\hat{\mathbf{R}}_{\mathbf{x}\mathbf{y}}$	Sample cross-correlation matrix of
•	$\mathbf{R}_{\mathbf{x}\mathbf{y}}$
$\hat{c}_x(\tau), \hat{C}_x(\tau)$	Estimated autocovariance function of
	the signal $x(t)$ or $x[n]$
$\frac{\hat{\mathbf{C}}_{\mathbf{x}}, \hat{\mathbf{K}}_{\mathbf{x}}, \hat{\mathbf{\Sigma}}_{\mathbf{x}}}{\hat{c}_{xy}(\tau), \hat{C}_{xy}(\tau)}$	Sample (auto)covariance matrix
$\hat{c}_{xy}(\tau), \hat{C}_{xy}(\tau)$	Estimated cross-covariance function
	of the signal $x(t)$ or $x[n]$
$\frac{\hat{\mathbf{C}}_{\mathrm{xy}},\hat{\mathbf{K}}_{\mathrm{xy}},\hat{\mathbf{\Sigma}}_{\mathrm{xy}}}{\hat{\mathbf{H}}}$	Sample cross-covariance matrix
Ĥ	Estimate of the Hessian matrix

4.3 Signals, (hyper)parameters, system performance, and criteria

$\mathbf{x}(n), \mathbf{x}_n$	Input signal
$\mathbf{y}(n), \mathbf{y}_n$	Output signal
$\hat{\mathbf{y}}(n), \hat{\mathbf{y}}_n$	Alternative output signal
$d(n), d_n$	Desired label (in case of supervised
	learning)

$\hat{\mathbf{y}}(n), \hat{\mathbf{y}}_n$	Alternative desired signal if the out-
	put is $\mathbf{y}(n), \mathbf{y}_n$
$\mathbf{w}(n), \mathbf{w}_n, \mathbf{\theta}(n), \mathbf{\theta}_n$	Parameters, coefficients, or weights
	vector
$\mathbf{w}_o, \mathbf{w}^{\star}, \mathbf{\theta}_o, \mathbf{\theta}^{\star}$	Optimum value of the parameters,
	coefficients, or weights vector
W	Matrix of the weights
η	Learning rate hyperparameter
$J(\cdot), \mathcal{E}(\cdot)$	Cost-function or objective function
$\Lambda(\cdot)$	Likelihood function
$\Lambda_l(\cdot)$	Log-likelihood function
$\hat{ ho}_{x,y}$	Estimated Pearson correlation coeffi-
•	cient between x and y
ρ	Distance of the margin of separation
	between two classes (Support Vector
	Machine, SVM)
$g(\cdot)$	Discriminant function, i.e., $g(\mathbf{w}^*) = 0$

5 Linear Algebra

5.1 Common matrices and vectors

\mathbf{W}, \mathbf{D}	Diagonal matrix
P	Projection matrix; Permutation ma-
	trix
J	Jordan matrix
L	Lower matrix
U	Upper matrix
$\overline{\mathbf{C}}$	Cofactor matrix
$\mathbf{C}_{\mathbf{A}}, \operatorname{cof}\left(\mathbf{A}\right)$	Cofactor matrix of A
S	Symmetric matrix
Q	Orthogonal matrix
$\overline{\mathbf{I}_N}$	$N \times N$ -dimensional identity matrix
$0_{M imes N}$	$M \times N$ -dimensional null matrix
0_N	N-dimensional null vector
$1_{M imes N}$	$M \times N$ -dimensional ones matrix
$\overline{1_N}$	N-dimensional ones vector
0	Null matrix, vector, or tensor (di-
	mensionality understood by context)
1	Ones matrix, vector, or tensor (di-
	mensionality understood by context)

5.2 Indexing

$x_{i_1,i_2,,i_N}, [\mathcal{X}]_{i_1,i_2,,i_N}$	Element in the position
2,2, ,1,	(i_1, i_2, \ldots, i_N) of the tensor \mathcal{X}
$\mathcal{X}^{(n)}$	nth tensor of a nontemporal sequence
$\mathbf{x}_n, \mathbf{x}_{:n}$	nth column of the matrix X
X_{n} :	nth row of the matrix X
$\mathbf{x}_{i_1,\ldots,i_{n-1},:,i_{n+1},\ldots,i_N}$	Mode- n fiber of the tensor \mathcal{X}
$\mathbf{x}_{:,i_2,i_3}$	Column fiber (mode-1 fiber) of the
	thrid-order tensor \mathcal{X}
$\mathbf{x}_{i_1,:,i_3}$	Row fiber (mode-2 fiber) of the thrid-
	order tensor \mathcal{X}
$X_{i_1,i_2,:}$	Tube fiber (mode-3 fiber) of the
	thrid-order tensor \mathcal{X}
$X_{i_1,:,:}$	Horizontal slice of the thrid-order
	tensor \mathcal{X}
$X_{:,i_2,:}$	Lateral slices slice of the thrid-order
	tensor \mathcal{X}
$X_{i_3}, X_{:,:,i_3}$	Frontal slices slice of the thrid-order
	tensor \mathcal{X}

5.3 General operations

$\langle \mathbf{a}, \mathbf{b} angle$, $\mathbf{a}^{T} \mathbf{b}$, $\mathbf{a} \cdot \mathbf{b}$	Inner or dot product
$\mathbf{a} \circ \mathbf{b}, \mathbf{a} \mathbf{b}^{ op}$	Outer product
⊗	Kronecker product
· ·	Hadamard (or Schur) (elementwise)
	product
.⊙n	nth-order Hadamard power
$0.00 \frac{1}{n}$	nth-order Hadamard root
Ø	Hadamard (or Schur) (elementwise)
	division
♦	Khatri-Rao product
8	Kronecker Product
\times_n	<i>n</i> -mode product

5.4 Operations with matrices and tensors

\mathbf{A}^{-1}	Inverse matrix
$\mathbf{A}^{+},\mathbf{A}^{\dagger}$	Moore-Penrose left pseudoinverse
$\mathbf{A}^{ op}$	Transpose

$\mathbf{A}^{-\top}$	Transpose of the inverse, i.e.,
	$(\mathbf{A}^{-1})^{T} = (\mathbf{A}^{T})^{-1} [10, 20]$
\mathbf{A}^*	Complex conjugate
\mathbf{A}^H	Hermitian
$\ \mathbf{A}\ _{\mathrm{F}}$	Frobenius norm
A	Matrix norm
$ \mathbf{A} , \det{(\mathbf{A})}$	Determinant
$\operatorname{diag}\left(\mathbf{A}\right)$	The elements in the diagonal of A
E [A]	Vectorization: stacks the columns of
	the matrix \mathbf{A} into a long column vec-
	tor
$\mathbf{E}_d\left[\mathbf{A}\right]$	Extracts the diagonal elements of a
	square matrix and returns them in a
	column vector
$\mathbf{E}_{l}\left[\mathbf{A} ight]$	Extracts the elements strictly below
	the main diagonal of a square matrix
	in a column-wise manner and returns
	them into a column vector
$\mathbf{E}_{u}\left[\mathbf{A}\right]$	Extracts the elements strictly above
	the main diagonal of a square matrix
	in a column-wise manner and returns
	them into a column vector
$\mathbf{E}_b\left[\mathbf{A} ight]$	Block vectorization operator: stacks
	square block matrices of the input
	into a long block column matrix
$\operatorname{unvec}\left(\mathbf{A}\right)$	Reshapes a column vector into a ma-
	trix
tr{ A }	trace
$X_{(n)}$	n -mode matricization of the tensor $\mathcal X$

5.5 Operations with vectors

$\ \mathbf{a}\ $	l_1 norm, 1-norm, or Manhattan norm
$\ \mathbf{a}\ , \ \mathbf{a}\ _2$	l_2 norm, 2-norm, or Euclidean norm
$\ \mathbf{a}\ _p$	l_p norm, p -norm, or Minkowski norm
$\ \mathbf{a}\ _{\infty}$	l_{∞} norm, ∞ -norm, or Chebyshev
	norm
$\overline{\mathrm{diag}\left(\mathbf{a}\right)}$	Diagonalization: a square, diagonal
	matrix with entries given by the vec-
	tor a

5.6 Decompositions

Λ	Eigenvalue matrix [25]
Q	Eigenvectors matrix; Orthogonal ma-
	trix of the QR decomposition[25]
R	Upper triangular matrix of the QR
	decomposition[25]
U	Left singular vectors[25]
$\overline{\mathrm{U}_r}$	Left singular nondegenerated vectors
$rac{\mathrm{U}_r}{\Sigma}$	Singular value matrix
Σ_r	Singular value matrix with nonzero
	singular values in the main diagonal
Σ^+	Singular value matrix of the pseu-
	doinverse [25]
Σ_r^+	Singular value matrix of the pseu-
	doinverse with nonzero singular val-
	ues in the main diagonal
V	Right singular vectors [25]
$\overline{\mathbf{V}_r}$	Right singular nondegenerated vec-
	tors
$eig(\mathbf{A})$	Set of the eigenvalues of A [5, 17, 20]
$\llbracket A, \overline{B}, \overline{C}, \ldots bracket$	CANDECOMP/PARAFAC (CP) de-
	composition of the tensor $\mathcal X$ from the
	outer product of column vectors of A ,
	B, C,
$\boxed{ \llbracket \boldsymbol{\lambda}; \mathbf{A}, \mathbf{B}, \mathbf{C}, \ldots \rrbracket }$	Normalized CANDE-
	COMP/PARAFAC (CP) decom-
	position of the tensor \mathcal{X} from the
	outer product of column vectors of
	A, B, C, \dots

5.7 Spaces and sets

$\mathrm{span}\left\{\mathbf{a}_{1},\mathbf{a}_{2},\ldots,\mathbf{a}_{n}\right\}$	Vector space spanned by the argument vectors [10]
$C(\mathbf{A})$, columnspace(\mathbf{A}), range(\mathbf{A}),	Columnspace, range or image, i.e.,
$\operatorname{span} \{\mathbf{A}\}, \operatorname{image}(\mathbf{A})$	the space span $\{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_n\}$, where
	\mathbf{a}_i is the ith column vector of the ma-
	trix A [18, 25]
$C(\mathbf{A}^{H})$	Row space (also called left
	columnspace) [18, 25]
$N(\mathbf{A})$, nullspace(\mathbf{A}), null(\mathbf{A}), kernel(\mathbf{A})	Nullspace (or kernel space) [18, 25,
	26]
$N(\mathbf{A}^{H})$	Left nullspace
rank A	Rank, that is, $\dim(\operatorname{span}\{A\}) =$
	$\dim \left(\mathrm{C} \left(\mathbf{A} \right) \right) \left[18 \right]$

nullity (A)	Nullity of \mathbf{A} , i.e., dim $(N(\mathbf{A}))$
$\{1,2,\ldots,n\}$	Discrete set containing the integer el-
	ements $1, 2, \ldots, n$
U	Universe
2^A	Power set of A
\mathbb{R}	Set of real numbers
C	Set of complex numbers
\mathbb{Z}	Set of integer number
$\mathbb{B} = \{0, 1\}$	Boolean set
Ø	Empty set
N	Set of natural numbers
$\mathbb{K} \in \{\mathbb{R}, \mathbb{C}\}$	Real or complex space (field)
$\mathbb{K}^{I_1 \times I_2 \times \cdots \times I_N}$	$I_1 \times I_2 \times \cdots \times I_N$ -dimensional real (or
	complex) space
K +	Nonnegative real (or complex) space
	[3]
K++	Positive real (or complex) space, i.e.,
	$\mathbb{K}_{++} = \mathbb{K}_+ \setminus \{0\} [3]$
$\mathbb{S}^n, \mathcal{S}^n$	Conic set of the symmetric matrices
	in $\mathbb{R}^{n \times n}$ [3]
$\mathbb{S}^n_+, \mathcal{S}^n_+$	Conic set of the symmetric positive
	semidefinite matrices in $\mathbb{R}^{n \times n}$ [3]
$\mathbb{S}^n_{++}, \mathcal{S}^n_{++}$	Conic set of the symmetric positive
	definite matrices in $\mathbb{R}^{n\times n}$, i.e., \mathbb{S}^n_{++} =
	$\mathbb{S}^n_+ \setminus \{0\} \ [3]$
\mathbb{H}^n	Set of all hermitian matrices in $\mathbb{C}^{n\times n}$
[a,b]	Closed interval of a real set from a to
	b
(a,b)	Opened interval of a real set from a
	to b
[a,b),(a,b]	Half-opened intervals of a real set
	from a to b
$\operatorname{conv} C$	Convex hull
$\operatorname{aff} C$	Affune hull
\mathcal{R}	Ray
\mathcal{H}	Hyperplane
$\mathcal{H}_+, \mathcal{H}$	Positive/negative halfspace
$B(\mathbf{x}_c, r)$	Euclidean ball with radium r and
	centered at \mathbf{x}_c
\mathcal{E}	Ellipsoid
С	Norm cone
K	Proper cone
<i>K</i> *	Dual cone

\mathcal{P}	Polyhedra
S	Simplex
C_{α}	α -sublevel set
epi f	Epigraph of the function f
hypo f	Hypograph of the function f

5.8 Set operations

A + B	Set addition (Minkowski sum), i.e.,
	$\{\mathbf{v} \in \mathbb{R}^n \mid \mathbf{v} = \mathbf{x} + \mathbf{y}, \ \forall \ \mathbf{x} \in \mathcal{X} \land \mathbf{y} \in \mathcal{Y}\}$ [15]
A - B	Minkowski difference, i.e.,
	$\{\mathbf{v} \in \mathbb{R}^n \mid \mathbf{v} = \mathbf{x} - \mathbf{y}, \ \forall \ \mathbf{x} \in \mathcal{X} \land \mathbf{y} \in \mathcal{Y}\}$
$A\ominus B$	Pontryagin difference, i.e.,
	$\{\mathbf{v} \in \mathbb{R}^n \mid \mathbf{v} + \mathbf{y} \in \mathcal{X}, \ \forall \ \mathbf{y} \in \mathcal{Y}\} $ [15]
$A \setminus B, A - B$	Set difference or set subtraction, i.e.,
	$A \setminus B = \{x x \in A \land x \notin B\}$ the set con-
	taining the elements of A that are not
	in B [23]
$A \cup B$	Set of union
$A \cap B$	Set of intersection
$A \times B$	Cartesian product
A^n	$A \times A \times \cdots \times A$
	n times
A^{\perp}	Orthogonal complement of A , e.g.,
	$N(\mathbf{A}) = C(\mathbf{A}^{T})^{\perp} [3]$
$\mathbf{a}\perp\mathbf{b}$	a is orthogonal to b
a ⊥ b	${f a}$ is not orthogonal to ${f b}$
$A \oplus B$	Direct sum, i.e., each $\mathbf{v} \in$
	$\{\sum \mathbf{a}_i \mid \mathbf{a}_i \in S_i, i = 1, \dots, k\}$ has a
	unique representation of $\sum \mathbf{a}_i$ with
	$\mathbf{a}_i \in S_i$. That is, they expand to a
	space. Note that $\{S_i\}$ might not be
	orthogonal each other [10]
$A \stackrel{=}{\oplus} B$	Direct sum of two spaces that are or-
	thogonal and span a <i>n</i> -dimensional
	space, e.g., $C(\mathbf{A}^{T}) \stackrel{\perp}{\oplus} C(\mathbf{A}^{T})^{\perp} =$
	\mathbb{R}^n (this decomposition of \mathbb{R}^n is
	called the orthogonal decomposition
	induced by \mathbf{A}) [3]
\bar{A}, A^c	Complement set (given U)
#A, A	Cardinality

$a \in A$	a is element of A
$a \notin A$	a is not element of A

5.9 Inequalities

$\mathcal{X} \leq 0$	Nonnegative tensor
$\mathbf{a} \leq_K \mathbf{b}$	Generalized inequality meaning that
	$\mathbf{b} - \mathbf{a}$ belongs to the conic subset K in
	the space $\mathbb{R}^n[3]$
$\mathbf{a} \prec_K \mathbf{b}$	Strict generalized inequality meaning
	that $\mathbf{b} - \mathbf{a}$ belongs to the interior of
	the conic subset K in the space $\mathbb{R}^n[3]$
$a \le b$	Generalized inequality meaning that
	$\mathbf{b} - \mathbf{a}$ belongs to the nonnegative or-
	thant conic subset, \mathbb{R}^n_+ , in the space
	\mathbb{R}^n .[3]
a < b	Strict generalized inequality meaning
	that $\mathbf{b} - \mathbf{a}$ belongs to the positive or-
	thant conic subset, \mathbb{R}_{++}^n , in the space
	$\mathbb{R}^n[3]$
$\mathbf{A} \leq_K \mathbf{B}$	Generalized inequality meaning that
	${\bf B}-{\bf A}$ belongs to the conic subset K
	in the space $\mathbb{S}^n[3]$
$A \prec_K B$	Strict generalized inequality meaning
	that $\mathbf{B} - \mathbf{A}$ belongs to the interior of
	the conic subset K in the space $\mathbb{S}^n[3]$
$A \leq B$	Generalized inequality meaning that
	$\mathbf{B} - \mathbf{A}$ belongs to the positive semidef-
	inite conic subset, \mathbb{S}_{+}^{n} , in the space
	$\mathbb{S}^n[3]$
A < B	Strict generalized inequality meaning
	that $\mathbf{B} - \mathbf{A}$ belongs to the positive or-
	thant conic subset, \mathbb{S}_{++}^n , in the space
	$\mathbb{S}^n[3]$

6 Communication systems

6.1 Symbols

B	One-sided bandwidth of the trans-
	mitted signal, in Hz

$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	\overline{W}	One-sided bandwidth of the trans-
$ \begin{array}{c} x_i \\ x_q \\ \\ f_c, f_{RF} \\ \\ C_c, f_{$		
$ \begin{array}{c} x_q \\ f_c, f_{RF} \\ f_c \\ f_{FF} \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ $	x_i	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	-	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$, 2	- v
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	f_{IF}	· · · · · · · · · · · · · · · · · · ·
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	f_s	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		(in Hertz)
R Bit rate T Bit interval/duration/period T_c Chip interval/duration/period T_{sy}, T_{sym} Symbol/signaling[21] interval/duration/period S_{RF} Transmitted signal in RF S_{FI} Transmitted signal in FI s_{SI} Lowpass (or baseband) equivalent signal or envelope complex of transmitted signal r_{RF} Received signal in RF r_{FI} Received signal in FI r_{r_I} Lowpass (or baseband) equivalent signal or envelope complex of received signal ϕ Signal phase ϕ_0 Initial phase η_{RF}, w_{RF} Noise in RF η_{FI}, w_{FI} Noise in FI η, w Noise in baseband τ Timing delay $\Delta \tau$ Timing error (delay - estimated) ϕ Phase offset $\Delta \varphi$ Phase error (offset - estimated) f_d Linear Doppler frequency - estimated) ν Angular Doppler frequency - estimated) ν Angular Doppler frequency - estimated)	T_s	Sampling time interval/duration/pe-
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$, , , , , , , , , , , , , , , , , , ,
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	R	Bit rate
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	T	Bit interval/duration/period
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	T_c	Chip interval/duration/period
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	T_{sy}, T_{sym}	Symbol/signaling[21] interval/dura-
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	2	tion/period
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	SRF	Transmitted signal in RF
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	SFI	Transmitted signal in FI
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	S, S_l	Lowpass (or baseband) equivalent
r_{RF} Received signal in RF r_{FI} Received signal in FI r, r_{I} Lowpass (or baseband) equivalent signal or envelope complex of received signal ϕ Signal phase ϕ_{0} Initial phase η_{RF}, w_{RF} Noise in RF η_{FI}, w_{FI} Noise in FI η, w Noise in baseband τ Timing delay $\Delta \tau$ Timing error (delay - estimated) φ Phase offset $\Delta \varphi$ Phase error (offset - estimated) f_d Linear Doppler frequency Δf_d Frequency error (Doppler frequency - estimated) ν Angular Doppler frequency $\Delta \nu$ Frequency error (Doppler frequency - estimated)		signal or envelope complex of trans-
r_{FI} Received signal in FI r, r_{I} Lowpass (or baseband) equivalent signal or envelope complex of received signal ϕ Signal phase ϕ_{0} Initial phase η_{RF}, w_{RF} Noise in RF η_{FI}, w_{FI} Noise in baseband τ Timing delay $\Delta \tau$ Timing error (delay - estimated) φ Phase offset $\Delta \varphi$ Phase error (offset - estimated) f_d Linear Doppler frequency Δf_d Frequency error (Doppler frequency - estimated) ν Angular Doppler frequency $\Delta \nu$ Frequency error (Doppler frequency - estimated)		
$ r, r_l $ Lowpass (or baseband) equivalent signal or envelope complex of received signal $ \phi $ Signal phase $ \phi_0 $ Initial phase $ \eta_{RF}, w_{RF} $ Noise in RF $ \eta_{FI}, w_{FI} $ Noise in FI $ \eta, w $ Noise in baseband $ \tau $ Timing delay $ \Delta \tau $ Timing error (delay - estimated) $ \varphi $ Phase offset $ \Delta \varphi $ Phase error (offset - estimated) $ f_d $ Linear Doppler frequency $ \Delta f_d $ Frequency error (Doppler frequency - estimated) $ v $ Angular Doppler frequency - estimated) $ v $ Frequency error (Doppler frequency - estimated)	r_{RF}	<u> </u>
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	r_{FI}	<u> </u>
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	r, r_l	- \ / -
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		
$\begin{array}{cccc} \phi_0 & & & & & & & \\ \eta_{RF}, w_{RF} & & & & & & \\ Noise in RF & & & & & \\ \eta_{FI}, w_{FI} & & & & & \\ Noise in FI & & & & \\ \eta, w & & & & & \\ \Delta \tau & & & & & \\ Timing delay & & \\ \Delta \tau & & & & & \\ Timing error (delay - estimated) & \\ \varphi & & & & & \\ Phase offset & \\ \Delta \varphi & & & & & \\ Phase error (offset - estimated) & \\ f_d & & & & & \\ Linear Doppler frequency & \\ \Delta f_d & & & & \\ Frequency error (Doppler frequency - estimated) & \\ \nu & & & & & \\ \Delta v & & & & \\ Frequency error (Doppler frequency - estimated) & \\ \end{array}$		<u> </u>
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	ϕ	
	ϕ_0	
η, w Noise in baseband τ Timing delay $\Delta \tau$ Timing error (delay - estimated) φ Phase offset $\Delta \varphi$ Phase error (offset - estimated) f_d Linear Doppler frequency Δf_d Frequency error (Doppler frequency - estimated) ν Angular Doppler frequency $\Delta \nu$ Frequency error (Doppler frequency - estimated)	η_{RF}, w_{RF}	
$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	η_{FI}, w_{FI}	
$\begin{array}{cccc} \Delta \tau & & & & & & & \\ \hline \varphi & & & & & & \\ \hline \varphi & & & & & \\ \hline \Delta \varphi & & & & & \\ \hline \Delta \varphi & & & & & \\ \hline \Delta hase error (offset - estimated) \\ \hline f_d & & & & \\ \hline \Delta f_d & & & \\ \hline \Delta f_d & & & \\ \hline \Delta f_d & & & \\ \hline Frequency error (Doppler frequency - estimated) \\ \hline \nu & & & & \\ \hline \Delta v & & & \\ \hline \Delta v & & & \\ \hline Errequency error (Doppler frequency - estimated) \\ \hline \end{array}$	η, w	
$\begin{array}{cccc} \varphi & & \text{Phase offset} \\ \Delta \varphi & & \text{Phase error (offset - estimated)} \\ f_d & & \text{Linear Doppler frequency} \\ \Delta f_d & & \text{Frequency error (Doppler frequency - estimated)} \\ \nu & & \text{Angular Doppler frequency} \\ \Delta \nu & & \text{Frequency error (Doppler frequency - estimated)} \end{array}$		
$ \begin{array}{cccc} \Delta \varphi & & \text{Phase error (offset - estimated)} \\ f_d & & \text{Linear Doppler frequency} \\ \Delta f_d & & \text{Frequency error (Doppler frequency - estimated)} \\ \nu & & \text{Angular Doppler frequency} \\ \Delta \nu & & \text{Frequency error (Doppler frequency - estimated)} \\ \end{array} $	Δau	
$ \begin{array}{ccc} f_d & & \text{Linear Doppler frequency} \\ \Delta f_d & & \text{Frequency error (Doppler frequency -} \\ & & \text{estimated)} \\ \nu & & \text{Angular Doppler frequency} \\ \Delta \nu & & \text{Frequency error (Doppler frequency -} \\ & & \text{estimated)} \\ \end{array} $		
	$\Delta \varphi$	
$\begin{array}{ccc} & & & \text{estimated}) \\ \nu & & & \text{Angular Doppler frequency} \\ \Delta\nu & & & \text{Frequency error (Doppler frequency -} \\ & & & & \text{estimated}) \end{array}$		
$ \nu $ Angular Doppler frequency Frequency error (Doppler frequency - estimated)	Δf_d	
$\Delta \nu$ Frequency error (Doppler frequency - estimated)		
estimated)		
,	$\Delta \nu$	
γ, A Transmitted signal amplitude		,
	γ, A	Transmitted signal amplitude

γ_0, A_0	Combined effect of the path loss and
	antenna gain

6.2 Fading multipath channels

$t \stackrel{\mathcal{F}}{\leftrightarrow} \lambda$	Support temporal of the signal. λ is obtained after taking the Fourier transform on t .
$\tau \overset{\mathcal{F}}{\leftrightarrow} f$	Second support temporal of the signal $(c(t))$ varies with with the input at the time τ). f is obtained after taking the Fourier transform on τ .
c(t, au)	Complex envelope of the channel response at the time t due to an impulse applied at the $t-\tau$
C(f,t)	Transfer function of $c(t,\tau)$ in τ
$\alpha(t,\tau)$	Attenuation of $c(t,\tau)$, i.e., $c(t,\tau) = \alpha(t,\tau)e^{e\pi f_c\tau}$
$R_c(au_1, au_2,\Delta t)$	Autocorrelation function of
	$c(t,\tau)$, i.e., $R_c(\tau_1,\tau_2,\Delta t) = $ $\mathbb{E}\left[c^*(t,\tau_1),c^*(t+\Delta t,\tau_2)\right]$
$R_c(\tau, \Delta t)$	Autocorrelation function of $c(t, \tau)$ as-
	suming uncorrelated scattering
$R_c(\tau), R_c(\tau, \Delta t)\Big _{\Delta t=0}$	Multipath intensity profile or delay
	power spectrum
$R_C(\Delta f, \Delta t), R_C(f_1, f_2; \Delta t),$	Spaced-frequency, spaced-time corre-
$\mathrm{E}\left[C(f_1,t),C(f_2,t+\Delta t)\right],$	lation function $(\Delta f = f_2 - f_1)$
$\mathcal{F}_{\tau}\left\{R_{c}\left(au,\Delta t\right)\right\}$	
$\frac{\mathcal{F}_{\tau}\left\{R_{c}(\tau, \Delta t)\right\}}{R_{C}(\Delta f), R_{C}(\Delta f, \Delta t)\Big _{\Delta t=0}, \mathcal{F}\left\{R_{c}(\tau)\right\}}$	Spaced-frequency correlation function
$-(\Delta f)_c$	Coherence bandwidth of $c(t)$, that
	is, the frequency interval in which
	$R_C(\Delta f)$ is nonzero
T_m	Multipath spread of the channel, that
	is, the time interval in which $R_c(\tau)$ is
	nonzero $(T_m \approx 1/(\Delta f)_c)$
$R_C(\Delta t), R_C(\Delta f, \Delta t)\Big _{\Delta f=0}$	Spaced-time correlation function
$S_C(\lambda), \mathcal{F}\left\{R_C(\Delta t)\right\}$	Doppler power spectrum
$(\Delta t)_c$	Coherence time of $c(t)$, that is, the
	time interval in which $R_C(\Delta t)$ is
	nonzero

B_m	Multipath spread of the channel, that
	is, the frequency interval in which
	$S_c(\lambda)$ is nonzero $(B_d \approx 1/(\Delta t)_c)$
$S_C(\tau,\lambda), \mathcal{F}_{\Delta f,\Delta t} \left\{ R_C(\Delta f,\Delta t) \right\}$	Scattering function

7 Discrete mathematics

7.1 Quantifiers, inferences

A	For all (universal quantifier) [11]
3	There exists (existential quantifier)
	[11]
<u></u> ∄ ∃!	There does not exist [11]
	There exist an unique [11]
€	Belongs to [11]
∉	Does not belong to [11]
::	Because [11]
 ,:	Such that, sometimes that parenthe-
	ses is used [11]
$\overline{}$,,(·)	Used to separate the quantifier with
	restricted domain from its scope, e.g.,
	$\forall x < 0 (x^2 > 0) \text{ or } \forall x < 0, x^2 > 0$
	[11]
:.	Therefore [11]

7.2 Propositional Logic

$\neg a$	Logical negation of a [23]
$a \wedge b$	Conjunction (logical AND) operator
	between a and $b[23]$
$a \lor b$	Disjunction (logical OR) operator be-
	tween a and $b[23]$
$a \oplus b$	Exclusive OR (logical XOR) operator
	between a and $b[23]$
$a \rightarrow b$	Implication (or conditional) state-
	ment[23]
$a \leftrightarrow b$	Bi-implication (or biconditional)
	statement, i.e., $(a \rightarrow b) \land (b \rightarrow a)$
	[23]
$a \equiv b, a \iff b, a \Leftrightarrow b$	Logical equivalence, i.e., $a \leftrightarrow b$ is a
	tautology[23]

7.3 Operations

a	Absolute value of a
log	Base-10 logarithm or decimal loga-
	rithm
ln	Natual logarithm
$\operatorname{Re}\left\{ x\right\}$	Real part of x
$\operatorname{Im}\left\{ x\right\}$	Imaginary part of x
۲٠	Phase (complex argument)
$x \mod y$	Remainder, i.e., $x - y \lfloor x/y \rfloor$, for $y \neq 0$
x div y	Quotient [23]
$x \equiv y \pmod{m}$	Congruent, i.e., $m \setminus (x - y)$ [23]
frac(x)	Fractional part, i.e., $x \mod 1$ [11]
$a \setminus b, a \mid b$	b is a positive integer multiple of a ,
	i.e., $\exists \ n \in \mathbb{Z}_{++} \mid b = na \ [11, \ 23]$
$a \not\setminus b, a \not\mid b$	b is not a positive integer multiple of
	$a, \text{ i.e., } \nexists n \in \mathbb{Z}_{++} \mid b = na \ [11, \ 23]$
[·]	Ceiling operation [11]
[·]	Floor operation [11]

8 Calculus

abla	Vector differential operator (Nabla symbol), i.e., ∇f is the gradient of the scalar-valued function f , i.e., f :
	$\mathbb{R}^n o \mathbb{R}$
t,(u,v)	Parametric variables commonly used,
	t for one variable, (u, v) for two vari-
	ables[24]
dl, dr	Vector position, i.e., (x, y, z) . Stewart
	[24] utilizes the letter \mathbf{r} to denote it,
	but it appears in many electromag-
	netics books as dl
$\overline{1(t)}$	Vector position parametrized by t ,
	i.e., $(x(t), y(t), z(t))$ [22, 24]
$\mathbf{l}'(t), \mathrm{d}\mathbf{l}/\mathrm{d}t$	First derivative of $\mathbf{l}(t)$, i.e., the
	tangent vector of the curve
	(x(t), y(t), z(t)) [24]
$\mathbf{T}(t), \mathbf{u}(t)$	Tangent unit vector of $\mathbf{l}(t)$, i.e.,
	$\mathbf{u}(t) = \mathbf{l}'(t)/ \mathbf{l}'(t) [16, 24]$
$\mathbf{n}(t), \left(\frac{y'(t)}{ Y(t) }, -\frac{x'(t)}{ Y(t) }\right)$	Normal vector of $\mathbf{l}(t)$, i.e.,
$\langle \cdot \cdot \cdot \langle \mathbf{r} (t) \cdot \cdot \mathbf{r} (t) \rangle$	$\mathbf{n}(t) \perp \mathbf{T}(t)[24]$

\overline{C}	Contour that traveled by $l(t)$, for $a \le 1$
	$t \leq b$ [24]
L, L(C)	Total length of the contour C
	(which can be defined the vector
	l, parametrized by t), i.e., $L_C =$
	$\int_a^b \mathbf{l}'(t) \mathrm{d}t[24]$
s(t)	Length of the arc, which can be de-
``	fined by the vector \mathbf{l} and t , that is,
	$s(t) = \int_{a}^{t} \mathbf{l}'(u) \mathrm{d}u \ (s(b) = L)[24]$
-ds	Differential operator of the length of
	the contour C , i.e., $ds = \mathbf{l'}(t) dt$ [24]
$\int_C f(\mathbf{l}) \mathrm{d}s , \int_a^b f(\mathbf{l}(t)) \mathbf{l}'(t) \mathrm{d}t$	Line integral of the function $f: \mathbb{R}^n \to$
$\int_C f(\mathbf{l}) \mathrm{d}s , \int_a f(\mathbf{l}(t)) \mathbf{l}(t) \mathrm{d}t$	
	\mathbb{R} along the contour C [1, 24]
$\int_C \mathbf{F} \cdot d\mathbf{l} , \int_a^b \mathbf{F}(\mathbf{l}(t)) \cdot \mathbf{l}'(t) dt , \int_C \mathbf{F} \cdot \mathbf{T} ds$	Line integral of vector field F along
ah ah	the contour C [1, 24]
$\int_{\mathbf{a}}^{\mathbf{b}} \mathbf{F}, \int_{\mathbf{a}}^{\mathbf{b}} \mathbf{F} \cdot d\mathbf{l}$	Alternative notation to the line inte-
	gral, where the parametric variable t
	goes from a to b , making r goes from
	$\mathbf{l}(a) = \mathbf{a} \text{ to } \mathbf{l}(b) = \mathbf{b} \ [1]$
\oint_C, \oint_C	Line integral along the closed contour
	C (the arrow indicates the contour in-
	tegral orientation, which is counter-
	clockwise, by default)
$ \oint_S $	Surface integral over the closed sur-
	face S
1(u,v)	Vector position
	(x(u, v), y(u, v), z(u, v)) parametrized
	$\frac{\text{by }(u,v)}{(u,v)}$
$\frac{\mathbf{l}_{u}}{\mathbf{l}_{u}}$	$(\partial x/\partial u, \partial y/\partial u, \partial z/\partial u)$
1,	$(\partial x/\partial v, \partial y/\partial v, \partial z/\partial v)$
$\mathrm{d}A$	Differential operator of a 2D area
	(denoted by D or R) in the \mathbb{R}^2 do-
	main. This differential operator can
	be solved in different ways (rectangu-
D B	lar, polar, cylindric, etc) [24]
D,R	Integration domain in which dA is in-
C	tegrated, i.e., $\iint_D f dA$ [24]
S	Smooth surface S, i.e., a 2D area in a
	3D space (\mathbb{R}^3 domain)

dS , $ \mathbf{l}_u \times \mathbf{l}_v dA$	Differential operator of a 2D area in
	a 3D domain (an surface). Note that
	$dS = \mathbf{l}_u \times \mathbf{l}_v dA$ should be accompa-
	nied with the change of the integra-
	tion interval (from S to D)
$A(S)$, $\iint_S dS$, $\iint_D \mathbf{l}_u \times \mathbf{l}_v dA$	Area of the surface S parametrized by
JJS = JJD	(u, v), in which dA is the area defined
	in the D domain (which is form by
	the u -by- v graph)
$-\mathrm{d}V$	Differential operator of a shape vol-
	ume (denoted by E) in \mathbb{R}^3 domain,
	i.e., $\iiint_E dV = V$
E	Integration domain in which dV is in-
	tegrated, i.e., $\iiint_E f dV$ [24]
$V, \iint_D f \mathrm{d}A, \iiint_F f \mathrm{d}V$	Volume of the function f over the re-
33 D · 333 E ·	gions D (in the case of double inte-
	grals) or E (in the case of triple inte-
	grals)
$\frac{\iint_{S} f \mathrm{d}S, \iint_{D} f \mathbf{l}_{u} \times \mathbf{l}_{v} \mathrm{d}A}{\mathbf{n}(u, v), \frac{\mathbf{l}_{u}(u, v) \times \mathbf{l}_{v}(u, v)}{ \mathbf{l}_{u}(u, v) \times \mathbf{l}_{v}(u, v) }}$	Surface integral over S
$\mathbf{n}(u,v), \frac{\mathbf{l}_u(u,v)\times\mathbf{l}_v(u,v)}{\mathbf{l}_v(u,v)\times\mathbf{l}_v(u,v)}$	Normal vector of of the smooth sur-
$ \mathbf{I}_{\mathcal{U}}(u,v)\wedge\mathbf{I}_{\mathcal{V}}(u,v) $	face S
$\iint_{\mathbf{S}} \mathbf{F} \cdot \mathbf{n} \mathrm{d}S$, $\iint_{\mathbf{S}} \mathbf{F} \cdot \mathrm{d}\mathbf{S}$,	Flux integral of vector field F through
33.5	the smooth surface S ($\mathbf{n} dS \triangleq d\mathbf{S}$)
$ \frac{\iint_D \mathbf{F} \cdot (\mathbf{l}_u \times \mathbf{l}_v) \mathrm{d}A}{\oiint_S \mathbf{F} \cdot \mathbf{n} \mathrm{d}S, \oiint_S \mathbf{F} \cdot \mathbf{d}S,} $	Flux integral of vector field F through
$\iint_D \mathbf{F} \cdot (\mathbf{l}_u \times \mathbf{l}_v) \mathrm{d}A$	the smooth and closed surface S
JJD^{2} (2 $u \times 2v$) and	$(\mathbf{n} dS \triangleq d\mathbf{S})$
$\nabla \times \mathbf{F}$, curl \mathbf{F}	Curl (rotacional) of the vector field F
$\nabla \cdot \mathbf{F}, \operatorname{div} \mathbf{F}$	Divercence of the vector field F
$\nabla^2 f, \nabla \cdot (\nabla f), \Delta f,$	Scalar Laplacian operator (per-
$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$	formed on a scalar-valued function
	$\frac{f: \mathbb{R}^n \to \mathbb{R}}{\text{Vector Laplacian operator (per-}}$
$\nabla^2 \mathbf{F}, \nabla \times \nabla \times \mathbf{F} - \nabla (\nabla \cdot \mathbf{F}), \Delta \mathbf{F},$	Vector Laplacian operator (per-
$(\partial^2 \mathbf{F}/\partial x^2, \partial^2 \mathbf{F}/\partial y^2, \partial^2 \mathbf{F}/\partial z^2)$	formed on a vector field, i.e., a vector-
· · · · · · · · · · · · · · · · · · ·	valued function, $\mathbf{F} : \mathbb{R}^n \to \mathbb{R}^n$).
	∇^2 denotes the scalar (vector) Lapla-
	cian if the function is scalar-valued
	(vector-valued)
	()

9 Electromagnetic waves

J	Electric current density vector (in
	A/m^2)
<u>H</u>	Magnetic field vector (in A/m)
В	Magnetic flux density vector (in
	$Wb/m^2 = T$)
$q_{ m free}$	Free electric charge (in C)
qbound	Bound electric charge (in C)
$q, q_{\mathrm{free}} + q_{\mathrm{bound}}$	Electric charge (in C)
$ ho_{ m free}$	Free electric charge density
$ ho_{ m bound}$	Electric charge density
$\rho, \rho_{\text{free}} + \rho_{\text{bound}}$	Electric charge density (it can be
	in C/m^3 , C/m^2 or C/m depending
	whether it is a volume, surface, or
	line shapes)
f	Electrostatic force (Coulomb force),
	(in kg m/s^2)
ε	Electric permittivity(in F/m) [22]
$\overline{\varepsilon_r}$	Relative electric permittivity or di-
	electric constant (in F/m) [22]
$-\varepsilon_0$	Electric permittivity in vacuum,
	$8.854 \times 10^{-12} \mathrm{F/m}$ [22]
E	Electric field vector (in V/m)
D	Electric flux density, electric dis-
	placement, or electric induction vec-
	$tor (in C/m^2)$
$\Phi_D, \Psi, \oiint_{\mathbf{S}} \mathbf{D} \mathrm{d}\mathbf{S}$	Electric flux (D -filed flux) [8]
$\Phi_E, \oiint_S \mathbf{E} \mathrm{d}\mathbf{S}$	Electric flux (E -filed flux) [9]
P	Electric polarization of the material
	(in C/m^2)
Xe	Electric susceptibility (for linear and
7 · ·	isotropic materials)
μ	Magnetic permeability
$\frac{\dot{\mu}_0}{\mu_0}$	Magnetic permeability in vacuum

10 Generic mathematical symbols

	Q.E.D.
	Equal by definition
:=, ←	Assignment [23]
	Not equal
∞	Infinity
j	$\sqrt{-1}$

11 Abbreviations

PS: Only names of techniques and algorithms or usual abbreviations are considered.

wrt.	With respect to
st.	Subject to
iff.	If and only if
EVD	Eigenvalue decomposition, or eigen-
	decomposition [18]
SVD	Singular value decomposition
CP	CANDECOMP/PARAFAC
SGD	Stochastic gradient descent
SVM	Support vector machine
BPNN	Backpropagation neural network [14]
RBF	Radial basis function

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