Answers: Exercise Sheet No. 6 ODE Pt. II.

1 Basic theory and manipulations

2 asod

```
# -*- coding: utf-8 -*-
3 Created on Thu Feb 17 12:23:21 2022
5 @author: P. Maxwell
9 import numpy as np
10 import matplotlib as mpl
import matplotlib.pyplot as plt
12 from scipy.integrate import solve_ivp
13
14
15
16
def f_lorenz(t, w, sigma, beta, rho):
18
      """Lorenz differential equations"""
      x = w[0]
19
     y = w[1]
20
      z = w[2]
21
     return np.array([ sigma*(y-x), x*(rho-z) - y, x*y - beta*z ],
22
      dtype=np.float64 )
23
24
# Parameters in order sigma, beta, rho.
27 param_args = (10.0, 8/3, 28)
29 # Initial point
x0 = np.array([5.0, 5.0, 5.0])
31
_{\rm 32} # Time interval to integrate over
33 tspan = [0, 60]
35 # Set tolerances
36 reltol = 1e-12
37 abstol = 1e-14
39
40
42 def do_solve(f, tspan, x0, abstol, reltol, param_args):
      """Use SciPy to solve system explicitly with 8th order RK"""
43
      sol = solve_ivp(f, tspan, x0,
44
                               args=param_args,
45
46
                               method='DOP853', dense_output=True,
                               rtol=reltol, atol=abstol)
47
     return sol
48
50
```

```
52
53
54 def plot_lorenz(sol_lorenz, t_pts):
       # Plot using a 2x2 subplot figure, with t-x, t-y, t-z, and 3d x
       -v-z.
       fig = plt.figure(figsize=(30, 30))
ax1 = fig.add_subplot(221)
57
       ax1.plot(t_pts, sol_lorenz.sol(t_pts)[0,:], 'b-', linewidth
58
       =1.0)
       ax1.tick_params(axis='both', labelsize=22)
59
60
       ax1.set_xlabel(r'$t$', fontsize=28)
       ax1.set_ylabel(r'$x$', fontsize=28)
61
62
63
       ax2 = fig.add_subplot(222)
       ax2.plot(t_pts, sol_lorenz.sol(t_pts)[1,:], 'b-', linewidth
64
       =1.0)
       ax2.tick_params(axis='both', labelsize=22)
       ax2.set_xlabel(r'$t$', fontsize=28)
ax2.set_ylabel(r'$y$', fontsize=28)
66
67
68
       ax3 = fig.add_subplot(223)
69
       ax3.plot(t_pts, sol_lorenz.sol(t_pts)[2,:], 'b-', linewidth
70
       =1.0)
       ax3.tick_params(axis='both', labelsize=22)
71
       ax3.set_xlabel(r'$t$', fontsize=28)
ax3.set_ylabel(r'$z$', fontsize=28)
72
73
74
       ax4 = fig.add_subplot(224, projection='3d')
75
       ax4.plot3D(sol_lorenz.sol(t_pts)[0,:], sol_lorenz.sol(t_pts)
76
       [1,:], sol_lorenz.sol(t_pts)[2,:], 'b-', linewidth=1.0)
       ax4.tick_params(axis='both', labelsize=22)
77
78
79
80
81
83 sol_lorenz = do_solve(f_lorenz, tspan, x0, abstol, reltol,
      param_args)
84
85 t_pts = np.linspace(tspan[0], tspan[1], 10000)
86 plot_lorenz(sol_lorenz, t_pts)
# -*- coding: utf-8 -*-
3 Created on Mon Feb 21 03:41:46 2022
5 @author: P. Maxwell
6 """
8 import autograd.numpy as np
9 from autograd import jacobian
10 from autograd import grad
import matplotlib as mpl
import matplotlib.pyplot as plt
13 from scipy.integrate import solve_ivp
14
15
16
17
# Parameters in order sigma, beta, rho.
19 param_args = ()
20
```

51

```
21 # Initial point
x0 = np.array([1.0, 0.0, 0.0])
23
# Time interval to integrate over
25 tspan = np.array([0.0, 10.0])
26
# Set tolerances
_{28} reltol = 1e-4
_{29} abstol = 1e-7
31
32
33
def f_robertson(t, w):
      """Simplified Brusselator differential equations"""
35
      y1 = w[0]
36
      y2 = w[1]
37
      y3 = w[2]
      return np.array([ -0.04*y1 + 1e4*y2*y3,
39
                             0.04*y1 - 1e4*y2*y3 - 3e7*y2**2,
40
                             3e7*y2**2], dtype=np.float64)
41
42
43
44
_{
m 45} # Jacobian (used for the Newton iteration of an implicit method
      like RADAU)
46 jac_robertson_autograd = jacobian(f_robertson, 1)
47 def jac_robertson(t, x):
      return jac_robertson_autograd(t, x)
48
49
50
51
52
53 def do_solve_explicit(f, tspan, x0, abstol, reltol, param_args):
       """Use SciPy to solve system explicitly with RK45"""
54
55
       sol = solve_ivp(f, tspan, x0,
56
                                args=param_args,
                                method='RK45', dense_output=True, rtol=reltol, atol=abstol)
57
58
      return sol
59
60
61
62
63
64 def do_solve_implicit(f, tspan, x0, abstol, reltol, param_args, jac
       """Use SciPy to solve system explicitly with Radau"""
65
       sol = solve_ivp(f, tspan, x0,
66
                                args=param_args,
67
                                method='Radau', dense_output=True,
68
                                jac=jac,
69
                                rtol=reltol, atol=abstol)
70
      return sol
71
72
73
74
75
_{76} def plot_robertson(sol_robertson_explicit, sol_robertson_implicit,
      t_pts):
      fig = plt.figure(figsize=(40, 40))
77
       ax1 = fig.add_subplot(321)
78
    ax1.semilogx(t_pts, sol_robertson_explicit.sol(t_pts)[0,:], 'b
79
```

```
-', linewidth=3)
       ax1.semilogx(sol_robertson_explicit.t, sol_robertson_explicit.y
       [0,:], 'ro', linewidth=3, markersize=15)
       ax1.grid()
81
       ax1.tick_params(axis='both', labelsize=22)
82
       ax1.set_title(r'Robertson $y_1$ (explicit)', fontsize=28)
83
       ax1.set_xlabel(r'$t$', fontsize=28)
       ax1.set_ylabel(r'$y_1$', fontsize=28)
85
86
       ax2 = fig.add_subplot(323)
88
       ax2.semilogx(t_pts, sol_robertson_explicit.sol(t_pts)[1,:], 'b
89
       -', linewidth=3)
       ax2.semilogx(sol_robertson_explicit.t, sol_robertson_explicit.y
90
       [1,:], 'ro', linewidth=3, markersize=15)
       ax2.grid()
91
       ax2.tick_params(axis='both', labelsize=22)
92
       ax2.set_title(r'Robertson $y_2$ (explicit)', fontsize=28)
       ax2.set_xlabel(r'$t$', fontsize=28)
ax2.set_ylabel(r'$y_2$', fontsize=28)
94
95
96
       ax3 = fig.add subplot(325)
97
       ax3.semilogx(t_pts, sol_robertson_explicit.sol(t_pts)[2,:], 'b
       -', linewidth=3)
       ax3.semilogx(sol_robertson_explicit.t, sol_robertson_explicit.y
99
       [2,:], 'ro', linewidth=3, markersize=15)
       ax3.grid()
100
       ax3.tick_params(axis='both', labelsize=22)
101
       ax3.set_title(r'Robertson $y_3$ (explicit)', fontsize=28)
102
       ax3.set_xlabel(r'$t$', fontsize=28)
103
       ax3.set_ylabel(r'$y_3$', fontsize=28)
104
106
       ax4 = fig.add_subplot(322)
107
       ax4.semilogx(t_pts, sol_robertson_implicit.sol(t_pts)[0,:], 'b
108
       -'. linewidth=3)
       ax4.semilogx(sol_robertson_implicit.t, sol_robertson_implicit.y
       [0,:], 'ro', linewidth=3, markersize=15)
       ax4.grid()
       ax4.tick_params(axis='both', labelsize=22)
       ax4.set_title(r'Robertson $y_1$ (implicit)', fontsize=28)
       ax4.set_xlabel(r'$t$', fontsize=28)
113
       ax4.set_ylabel(r'$y_1$', fontsize=28)
114
115
116
       ax5 = fig.add_subplot(324)
       ax5.semilogx(t_pts, sol_robertson_implicit.sol(t_pts)[1,:], 'b
117
       -', linewidth=3)
       ax5.semilogx(sol_robertson_implicit.t, sol_robertson_implicit.y
118
       [1,:], 'ro', linewidth=3, markersize=15)
       ax5.grid()
119
       ax5.tick_params(axis='both', labelsize=22)
120
       ax5.set_title(r'Robertson $y_2$ (implicit)', fontsize=28)
121
       ax5.set_xlabel(r'$t$', fontsize=28)
       ax5.set_ylabel(r'$y_2$', fontsize=28)
123
124
       ax6 = fig.add_subplot(326)
       {\tt ax6.semilogx(t\_pts, sol\_robertson\_implicit.sol(t\_pts)[2,:], 'b}
126
       -', linewidth=3)
       ax6.semilogx(sol_robertson_implicit.t, sol_robertson_implicit.y
       [2,:], 'ro', linewidth=3, markersize=15)
       ax6.grid()
       ax6.tick_params(axis='both', labelsize=22)
129
```

```
ax6.set_title(r'Robertson $y_3$ (implicit)', fontsize=28)
130
       ax6.set_xlabel(r'$t$', fontsize=28)
131
       ax6.set_ylabel(r'$y_3$', fontsize=28)
132
133
134
135
137 sol_robertson_explicit = do_solve_explicit(f_robertson, tspan, x0,
       abstol, reltol, param_args)
138 sol_robertson_implicit = do_solve_implicit(f_robertson, tspan, x0,
       abstol, reltol, param_args, jac_robertson)
139
140
# t_pts = np.linspace(tspan[0], tspan[1], 1000)
142 t_pts = 10**np.linspace(-6, np.log10(tspan[1]), 1000)
143 plot_robertson(sol_robertson_explicit, sol_robertson_implicit,
   t_pts)
# -*- coding: utf-8 -*-
3 Created on Mon Feb 21 03:19:20 2022
 5 @author: P. Maxwell
 8 import numpy as np
9 import matplotlib as mpl
{\tt 10} import matplotlib.pyplot as plt
11 from scipy.integrate import solve_ivp
13
14
15
16 # Parameters in order sigma, beta, rho.
17 param_args = (1.0, 3.0)
19 # Initial point
x0 = np.array([1.0, 3.08])
21
# Time interval to integrate over
23 \text{ tspan} = [0.0, 15.0]
24
25 # Set tolerances
_{26} reltol = 1e-6
27 abstol = 1e-9
29
30
31
def f_brusselator_simple(t, w, A, B):
"""Simplified Brusselator differential equations"""
       y1 = w[0]
34
       y2 = w[1]
35
       return np.array([ A + y2*y1**2 -(B+1)*y1, B*y1 -y2*y1**2 ],
36
       dtype=np.float64 )
37
38
39
41 def do_solve(f, tspan, x0, abstol, reltol, param_args):
42 """Use SciPy to solve system explicitly with RK45"""
       sol = solve_ivp(f, tspan, x0,
43
                                args=param_args,
44
```

```
method='RK45', dense_output=True,
45
                                 rtol=reltol, atol=abstol)
46
47
       return sol
48
49
50
61 def plot_brusselator_simple(sol_brusselator_simple, t_pts):
       fig, ax = plt.subplots(1, 1, figsize=(20, 20))
52
       ax.plot(sol_brusselator_simple.sol(t_pts)[0,:],
53
       sol_brusselator_simple.sol(t_pts)[1,:], linewidth=3)
       ax.grid()
54
       ax.tick_params(axis='both', labelsize=22)
ax.set_title(r'Brusselator Simple', fontsize=28)
55
56
       ax.set_xlabel(r'$y_1$', fontsize=28)
ax.set_ylabel(r'$y_2$', fontsize=28)
57
59
60
62 sol_brusselator_simple = do_solve(f_brusselator_simple, tspan, x0,
       abstol, reltol, param_args)
63
64
65 t_pts = np.linspace(tspan[0], tspan[1], 1000)
plot_brusselator_simple(sol_brusselator_simple, t_pts)
       # -*- coding: utf-8 -*-
3 Created on Sun Feb 20 21:23:11 2022
5 @author: P. Maxwell
9 import autograd.numpy as np
10 from autograd import jacobian
11 from autograd import grad
^{12} import matplotlib as mpl
13 import matplotlib.pyplot as plt
^{14} #import scipy.optimize as sp0
15 from scipy.integrate import solve_ivp
16
17
_{\rm 18} # Remember to note that this is a continuous reformulation of a
      discrete process
20
21
22
_{23} N = 1000000
24 Ethres = N * 0.2
25 R0 = 4.0
_{26} gamma = 1 / 5
beta_sir = R0 * gamma
28 beta_seirsd = R0 * (gamma + alpha1)
29 alpha1 = 0.015
30 \# alpha2 = 0.03
alpha2 = 0.03
32 sigma = 1/5 # Original Covid
33 \text{ omega} = 1/180
34
35
36 initial_seed = 10.0
w0_sir = np.array([N-initial_seed, initial_seed, 0.0])
```

```
38 wO_seirsd = np.array([N-initial_seed, initial_seed, 0.0, 0.0, 0.0])
40
41
42 param_args_sir = np.array([N, beta_sir, gamma])
param_args_seirsd = np.array([N, alpha1, alpha2, beta_seirsd, gamma, sigma, omega, Ethres])
44 \text{ tspan} = (0.0, 400.0)
_{45} reltol = 1e-4
46 abstol = 1e-7
47
48
49 def f_sir(t, w, N, beta, gamma):
       """Calculate derivatives in SIR model"""
50
       S = w[0]
51
       I = w[1]
52
       R = w[2]
53
       dwdt = np.zeros((3,), dtype=np.float64)
55
       # dS/dt
56
       dwdt[0] = -beta*I*S/N
57
       # dI/dt
58
59
       dwdt[1] = beta*I*S/N -gamma*I
       # dR/dt
60
       dwdt[2] = gamma*I
61
62
63
64
       if abs((S+I+R-N)) > 1.0:
            print("Consistency error! S, I, R, N, diff:", S, I, R, N,
65
       abs((S+I+R-N)))
       return dwdt
67
68
69
70
71
73
74
75 def f_seirsd(t, w, N, alpha1, alpha2, beta, gamma, sigma, omega,
       Ethres):
       """Calculate derivatives in simple SEIRSD model."""
       S = w[0]
77
       E = w[1]
78
79
       I = w[2]
       R = w[3]
80
       D = w[4]
81
       alpha1_cntr = np.max(np.array([0.0, (alpha1*N - D)/N])) * I
alpha2_cntr = np.max(np.array([0.0, (alpha2*N - D)/N])) * np.
82
83
       max(np.array([0.0, I-Ethres]))
       dwdt = np.zeros((5,), dtype=np.float64)
84
       # dS/dt
85
       dwdt[0] = -beta*I*S/N + omega*R
86
       # dE/dt
87
       dwdt[1] = beta*I*S/N -sigma*E
88
       # dI/dt
89
       dwdt[2] = sigma*E -gamma*I -alpha1_cntr -alpha2_cntr
90
91
       # dR/dt
       dwdt[3] = gamma*I - omega*R
92
       # dD/dt
93
94
       dwdt[4] = alpha1_cntr + alpha2_cntr
95
```

```
return dwdt
96
97
98
99
100
101
def do_solve_cm(f, tspan, w0, abstol, reltol, param_args):
       \ensuremath{\text{\#}} Do the integration using explicit 8th order RK
104
       sol_cm = solve_ivp(f, tspan, w0,
105
                                 args=param_args,
106
107
                                method='RK45', dense_output=True,
                                rtol=reltol, atol=abstol)
108
       return sol cm
109
110
113
114
115
116
def plot_solution_sir(sol_sir, end_day):
       t_pts = np.float64(np.arange(0, end_day+1))
118
       fig, ax = plt.subplots(1, 1, figsize=(30, 15))
119
       ax.plot(t_pts, sol_sir.sol(t_pts)[0, :], label='Susceptible',
120
       linewidth=3)
       ax.plot(t_pts, sol_sir.sol(t_pts)[1, :], label='Infectious',
       linewidth=3)
       ax.plot(t_pts, sol_sir.sol(t_pts)[2, :], label='Recovered',
       linewidth=3)
       ax.grid()
123
       ax.tick_params(axis='both', labelsize=22)
124
       ax.legend(fontsize=28)
125
       ax.set_title(r'SIR model output', fontsize=28)
       ax.set_xlabel(r'$t$ (days)', fontsize=28)
127
       ax.set_ylabel(r'Individuals (millions)', fontsize=28)
128
129
130
131
132
def plot_solution_seirsd(sol_seirsd, end_day):
       t_pts = np.float64(np.arange(0, end_day+1))
135
136
       fig, ax = plt.subplots(1, 1, figsize=(30, 15))
137
       ax.plot(t_pts, sol_seirsd.sol(t_pts)[0, :], label='Susceptible
        ', linewidth=3)
       ax.plot(t_pts, sol_seirsd.sol(t_pts)[1, :], label='Exposed',
       linewidth=3)
       ax.plot(t_pts, sol_seirsd.sol(t_pts)[2, :], label='Infectious',
139
        linewidth=3)
       ax.plot(t_pts, sol_seirsd.sol(t_pts)[3, :], label='Recovered',
140
       linewidth=3)
       ax.plot(t_pts, sol_seirsd.sol(t_pts)[4, :], label='Dead',
141
       linewidth=3)
       ax.grid()
142
       ax.tick_params(axis='both', labelsize=22)
143
       ax.legend(fontsize=28)
144
       ax.set_title(r'SEIRSD model output', fontsize=28)
145
       ax.set_xlabel(r'$t$ (days)', fontsize=28)
146
       ax.set_ylabel(r'Individuals (millions)', fontsize=28)
147
148
149
```