

ANSWERS: EXERCISE SHEET NO. 4

NONLINEAR EQUATIONS PT. II.

Automatic Differentiation in python using autograd

No submission for this section. The important idea is to understand why Automatic Differentiation (AD) is useful and how it can be used.

1 Automatic Differentiation in Conjunction with a SciPy Root Solver

You should have a python file something like:

```
1 import autograd.numpy as np
2 from autograd import jacobian
3 import scipy.optimize as sp
4
5 def fun(x):
6     return np.arctan(x)
7
8 jac = jacobian(fun)
9 sol = sp.root(fun, [3.], jac=jac, method='lm')
10 print(sol)
```

LM should converge with a status of 4, i.e. there is an error message, but the algorithm did converge.

2 Flash tank

The code to answer all questions is included below:

```
1 # -*- coding: utf-8 -*-
2 """
3 Created on Jan 23
4
5 @author: E. Turan
6 """
7 import autograd.numpy as np
8 from autograd import jacobian
9 import scipy.optimize as sp
10
11 # Demonstrate Newton type methods on a flash tank problem
12 # The problem is solved using the root finding function of scipy.
13 # optimize
14
15 # Antoine parameters
16 A = np.array([3.97786, 4.00139, 3.93002], dtype=np.float64)
17 B = np.array([1064.840, 1170.875, 1182.774], dtype=np.float64)
18 C = np.array([-41.136, -48.833, -52.532], dtype=np.float64)
19 # feed composition
20 z = np.array([0.5, 0.3, 0.2], dtype=np.float64)
21 # feed flow, pressure and temperature
22 F = 100
23 p = 5
24 T = 390
```

```

24
25 # As T and P are specified can calculate K directly
26 psat = np.float64(10) ** (A - B / (T + C))
27 K = psat / p
28
29 # define the residual function
30 def fun(inp):
31     # the input is a vector of 8 elements, unpack now
32     x = inp[0:3]
33     y = inp[3:6]
34     V = inp[6]
35     L = inp[7]
36     res_MB = -F * z + V * y + L * x
37     res_EQ = -y + K * x
38     res_xy = np.array([1 - sum(y), 1 - sum(x)])
39     return np.concatenate((res_MB, res_EQ, res_xy)) # return a
        vector of residuals
40
41
42 ini_guess = np.array([0.5, 0.5, 0.5, 0.5, 0.5, 0.5, 50, 50]) #
        initial guess
43
44 jac = jacobian(fun) # autograd to calculate the jacobian
45
46 sol_flash = sp.root(fun, ini_guess, jac=jac, method="lm") # solve
        the problem
47 print(sol_flash)
48
49 # set up problem in a different formulation
50
51
52 def f_rr(psi):
53     return np.sum((z * (K - 1)) / (1 + psi * (K - 1)))
54
55
56 # psi is V/F, and from this everything else can be calculated
57
58 # Autograd
59 jac_ad = jacobian(f_rr)
60
61
62 # solve
63 sol_psi_hybr = sp.root(f_rr, np.float64(0.5), jac=jac_ad, method="
        hybr")
64 sol_psi_lm = sp.root(f_rr, np.float64(0.5), jac=jac_ad, method="lm"
        )
65
66
67 print(sol_psi_hybr)
68 print(sol_psi_lm)

```

You should find that 'hybr' sometimes has trouble converging, however when started "close enough" it should converge faster than LM. If you don't specify the derivative function then the method automatically does finite differencing. As this 1) is less accurate and 2) requires repeated evaluations of the function you should find that it requires many more function evaluations (and probably more iterations) to converge to the solution.