SOEN331: Introduction to Formal Methods for Software Engineering

Assignment 4 on algebraic specifications

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Spec: Location;
Sort: Location;
Imports:String, Point
Description: A location contains a description
Operations:
   newLocation: String \times Point \rightarrow Location;
   setDescription: String \times Location \rightarrow Location;
   getDescription : Location \rightarrow String;
   setPoint : Point \times Location \rightarrow Location;
   getPoint : Location \rightarrow Point;
Variables:
   newDesc, d: String; newPoint, p: Point;
Axioms:
   [A1] getDescription(newLocation(d, p)) = d;
   [A2] getDescription(setDescription(newDesc, newLocation(d, p))) = newDesc;
   [A3] getDescription(setPoint(newPoint, newLocation(d,p))) = d;
   [A4] getPoint(newLocation(d, p)) = p;
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[A5] getPoint(setPoint(newPoint, newLocation(d,p))) = newPoint;
   [A6] getPoint(setDescription(newDesc, newLocation(d,p))) = p;
   [A7] setDescription(newDesc, newLocation(d,p)) = newLocation(newDesc, p);
   [A8] setDescription(getDescription(newLocation(d,p)), newLocation(d,p)) = newLocation(d,p)
tion(d,p);
   [A9] setPoint(newPoint, newLocation(d,p)) = newLocation(d, newPoint);
   [A10] setPoint(getPoint(newLocation(d,p)), newLocation(d,p)) = newLocation(d, p);
Spec: Map (Location);
Sort: Map;
Imports: String, Point, Boolean, Location;
Description: A map contains locations
Operations:
   newmap: \rightarrow Map;
   addlocation: Map \times Location \rightarrow Map;
   deletelocation: Map \times String \rightarrow Map;
   containsdescription : Map \times String \rightarrow Boolean;
   containspoint : Map \times Point \rightarrow Boolean;
   findlocation: Map \times String \rightarrow Point;
   isempty : Map \rightarrow Boolean;
   clear: Map \rightarrow Map;
Variables:
   d: String; p, q: Point; loc: Location; map: Map
Axioms:
   [A1] isempty(newmap) = true;
   [A2] isempty(clear(map)) = true;
   [A3] contains description (addlocation (map, loc), get Description (loc)) = true;
   [A4] contains description (map, d) \rightarrow find location (add location (map, newlocation (d,q)), d)
== q
   [A5] deletelocation(addlocation(addlocation(newmap, newLocation(d, p)),newLocation(d,q)),d)
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= newmap
[A6]
[A7] findlocation(map, getDescription(loc)) = getPoint(loc)
[A8] findlocation(newmap) = undefined;
[A9] deletelocation(newmap) = undefined;
preconditions:
    pre : deletelocation(map, d) = not isempty(map);
    pre : findlocation(map, d) = not isempty(map);
end:
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