

# Future Tank Lab — Technical Math Appendix

## 1. Threatscape

Drone Density ( $\lambda$ )

Poisson process:

$$P(k; \lambda \cdot t) = ((\lambda \cdot t)^k / k!) \cdot e^{-(\lambda \cdot t)}$$

where  $\lambda$  = drones per minute,  $t$  = time window.

ATGM / Rocket Salvos ( $R$ )

Rate expressed as events/hour. Converted to per-minute:

$$R_{\min} = R / 60$$

EW Severity ( $E \in [0,1]$ )

Penalty factor on APS Pk:

$$\text{Effective Pk} = (1 - E) \cdot Pk$$

## 2. Protection

APS Layering

$n$  layers, each with probability  $p$ .

$$Pk_{\text{total}} = 1 - (1 - p)^n$$

Soft-Kill EW / Obscurants

Reduction in hit probability:

$$P_{\text{hit}} = (1 - \text{Soft\_kill}) \cdot P_{\text{inbound}}$$

## 3. Survivability Metric

Survival Probability ( $S$ )

$$S = (1 - L)^N$$

where  $L$  = leak probability per shot

$$L = 1 - (Pk_{\text{total}} + \text{Soft\_kill\_adjusted})$$

## 4. Thermal Signature

$\Delta T$  Contrast

$$\Delta T = |T_{\text{skin}} - T_{\text{ambient}}|$$

Detection Probability ( $D$ )

Logistic approximation:

$$D = 1 / (1 + e^{-(k(\Delta T - \Delta T_0))})$$

## 5. Hybrid & Silent Watch

Range (km)

$$\text{Range} = (\text{Fuel\_energy} + \text{Battery\_energy}) / \text{Power\_draw}$$

Silent Watch Time (hours)

$$T_{\text{silent}} = \text{Battery\_capacity} / P_{\text{silent}}$$

## 6. UAV Teaming

Situational Awareness (SA)

$$SA = \text{Base\_SA} + \alpha \cdot N_{\text{swarm}} + \beta \cdot \text{Tethered}$$

## 7. Composite Dashboard Scores

- Survivability Index  $\rightarrow$  APS + soft-kill + threatscape
- Detectability Index  $\rightarrow$   $\Delta T$ , range, camouflage
- Mobility Index  $\rightarrow$  hybrid range + silent watch
- SA Index  $\rightarrow$  UAV contributions

(All scaled 0–100 for presentation)

### Disclaimer

Equations are simplified abstractions.

They are designed for transparency and interactivity, not predictive accuracy.