

# Autonomous UAV Networks – Digital Green v2.3

## User Guide

### Overview

This guide introduces the Autonomous UAV Networks simulator — a research and educational tool that models real world UAV networking behavior under aerospace accurate conditions. It integrates International Standard Atmosphere (ISA) physics, aerodynamic power equations, RF propagation (Two Ray + Rician), and LTE MCS throughput estimation to simulate resilient airborne networks.

### Quick Start

- 1. Launch the app: ``streamlit run app.py``.
- 2. Adjust parameters in the sidebar — area, UAV count, frequency, and MAC scheme.
- 3. Click **\*\* Run Simulation \*\*** to start.
- 4. Monitor the progress bar and live metrics.
- 5. Review visualizations (2D, 3D Orbit, or Animation).
- 6. Export results via the **\*\* Download \*\*** buttons for CSV, JSON, or ZIP bundles.

### Key Features

- ISA based atmosphere model for air density and temperature realism.
- Aerodynamic power computation combining induced, parasite, and climb loads.
- Two Ray + Rician RF propagation for multi path ground reflection modeling.
- LTE MCS PHY model or Shannon ideal channel for link throughput estimation.
- TDMA, NOMA, and RSMA MAC presets for multi access performance testing.
- Integrated jammer and eavesdropper modules for security analysis.
- Dynamic 3D orbit visualization (LEO/MEO/GEO reference rings).
- Expanded export suite: metrics, trajectory, fleet, and configuration data.

### Simulation Workflow

Each simulation step evaluates aerodynamic power, link quality, and throughput for every UAV. Kinematic updates incorporate wind vectors, climb rates, and heading changes. Signal to Interference plus Noise Ratio (SINR) is recalculated dynamically per link. A directed capacity graph determines end to end throughput using a “ widest path ” flow heuristic for network efficiency analysis.

### Data Export and Analysis

Upon completion, exportable datasets include metrics (throughput, SoC, energy), trajectory, fleet specifications, and final UAV positions. A ZIP bundle consolidates all exports along with the session settings JSON, ensuring reproducibility and compatibility with Python, MATLAB, or Excel workflows.

### Troubleshooting & Best Practices

- Ensure Python 3.10 and Streamlit 1.30.
- For large fleets (>25 UAVs), reduce simulation steps or disable animations.
- If simulation halts, use `** Reset Fleet & Reseed**` to restart.
- Use consistent random seeds for repeatable studies.
- Keep the terminal open to monitor progress and runtime logs.

## Appendix: Mathematical Foundations

Core algorithms employ ISA atmosphere equations, aerodynamic power balance, Two Ray ground reflection, Rician fading statistics, and LTE Modulation and Coding Schemes. A detailed technical reference is available in the *\*Aerospace Math Appendix – UAV Networks v2.3\** document.