EEE424 Homework 2

(Clearly justify all answers.)

(Due 16 March 2023)

- 1- It is given that V is an N-dimensional inner product space (standard inner product), and S_2 be a subspace in V. $Q = \{\mathbf{p_1}, \mathbf{p_2}, \cdots \mathbf{p_M}\}$, M < N, is a basis for S_2 . The problem is to find a solution to $\underset{\hat{\mathbf{v}}}{\operatorname{argmin}} ||\mathbf{v} \hat{\mathbf{v}}||^2$, where $||\cdot||$ is the inner product induced norm, $\mathbf{v} \in V$ and $\hat{\mathbf{v}} \in S_2$.
 - a) Prove that the solution to the above problem must satisfy,

i-
$$(y - \hat{y}) \perp S_2$$

ii-
$$(y - \hat{y}) \perp \hat{y}$$

iii-
$$(y - \hat{y}) \perp \mathbf{p_i}, \quad j = 1, \dots, M$$

- b) Derive the normal equations in terms of inner products $\langle p_i, p_j \rangle$ and $\langle y, p_j \rangle$ to solve for coefficients, c_i 's where $\hat{\mathbf{y}} = \sum_{i=1}^{M} c_i \mathbf{p}_i$ using the facts given in (a).
- c) \mathbf{x} is a vector in S_1 which is an M-dimensional inner product space (standard inner product), and \mathbf{A} is an $N \times M$ matrix, N > M, whose columns are linearly independent, representing a linear transform. Derive the left pseudoinverse \mathbf{A}_{ps} of \mathbf{A} which would yield $\hat{\mathbf{x}} = \mathbf{A}_{ps}\mathbf{y}$ such that $\hat{\mathbf{x}}$ is the solution to $\hat{\mathbf{x}} = \underset{\mathbf{x}}{\operatorname{argmin}} ||\mathbf{y} \mathbf{A}\mathbf{x}||^2$
- d) Let

$$A = \begin{bmatrix} 1 & -1 \\ 2 & 1 \\ -1 & 1 \end{bmatrix} \qquad \mathbf{y} = \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$$

Find
$$\hat{\mathbf{x}} = \underset{\mathbf{x}}{\operatorname{argmin}} ||\mathbf{y} - \mathbf{A}\mathbf{x}||^2$$
.

- e) Find $\hat{\mathbf{y}} = \mathbf{A}\hat{\mathbf{x}}$ and show that $(\mathbf{y} \hat{\mathbf{y}})$ is orthogonal to $\hat{\mathbf{y}}$.
- 2- Functions $\phi_i(t)$, i = 1, 2, 3 are given as,

$$\phi_1(t) = \begin{cases} t & \text{if } t \in [0, 1] \\ 0 & \text{else} \end{cases}$$

$$\phi_2(t) = \begin{cases} -1 & \text{if } t \in [0, 2] \\ 0 & \text{else} \end{cases}$$

$$\phi_3(t) = \begin{cases} -t+1 & \text{if } t \in [1,2] \\ 0 & \text{else} \end{cases}$$

- a) Plot these functions. Are these functions orthogonal to each other?
- b) Find the range space of $\{\phi_1(t), \phi_2(t), \phi_3(t)\}$. Select an arbitrary (c_1, c_2, c_3) (indicate you selection). Plot a typical function in that range space using your selected coefficients, i.e., plot $c_1\phi_1(t) + c_2\phi_2(t) + c_3\phi_3(t)$ for your c_i 's.
- c) Find the parameters, c_i 's to minimize $\left| \left| y(t) \sum_{i=1}^{3} c_i \phi_i(t) \right| \right|^2$, where

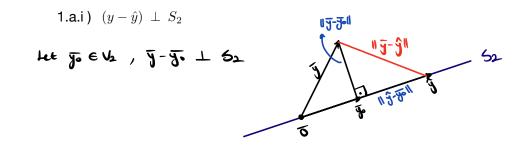
$$y(t) = \begin{cases} -1 & \text{if} \quad t \in [-1, 1] \\ 2 & \text{if} \quad t \in [2, 3] \\ 0 & \text{else} \end{cases}$$

Plot (y(t)) and $\hat{y}(t) = c_1\phi_1(t) + c_2\phi_2(t) + c_3\phi_3(t)$ using the optimum c_i 's you found on the same graph.

- d) Find and plot the error function $e(t) = y(t) \hat{y}(t)$, and show that e(t) is orthogonal to $\hat{y}(t)$.
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EEE424 Digital Signal Processing Homework 2

- It is given that V is an N-dimensional inner product space (standard inner product), and S_2 be a subspace in V. $Q = \{\mathbf{p_1}, \mathbf{p_2}, \cdots \mathbf{p_M}\}$, M < N, is a basis for S_2 . The problem is to find a solution to $\underset{\hat{\mathbf{x}}}{\operatorname{argmin}} ||\mathbf{y} \hat{\mathbf{y}}||^2$, where $||\cdot||$ is the inner product induced norm, $\mathbf{y} \in V$ and $\hat{\mathbf{y}} \in S_2$.
 - a) Prove that the solution to the above problem must satisfy,



again
$$\|\bar{y} - \hat{y}\|^2 = \operatorname{again} \left[\|\hat{y} - \bar{y}_0\|^2 + \|\bar{y} - \bar{y}_0\|^2\right] = \operatorname{again} \|\hat{y} - \bar{y}_0\| = \bar{y}_0$$
Constant

=) Therefore
$$\hat{y} = \overline{y_0}$$
 and since $\overline{y} - \overline{y_0} \perp 52$

The proof is complete.

1.a.ii)
$$(y - \hat{y}) \perp \hat{y}$$

Since $\hat{y} \in \delta_2$ and $(\bar{y} - \hat{y}) \perp \delta_2$. $(\bar{y} - \hat{y}) \perp \hat{y}$ is also connecte and proposed \blacksquare

1.a.iii)
$$(y-\hat{y})\perp \mathbf{p_j}, \quad j=1,\cdots,M$$

Since
$$\bar{p}_j \in S_2$$
 for $j = 0, 1, ..., M$
and $(\bar{y} - \hat{y}) \perp S_2$
Hen, $(\bar{y} - \hat{y}) \perp p_j$ is also connect and proposed

1.b) Derive the normal equations in terms of inner products $\langle p_i, p_j \rangle$ and $\langle y, p_j \rangle$ to solve for coefficients, c_i 's where $\hat{\mathbf{y}} = \sum_{j=1}^M c_i \mathbf{p}_i$ using the facts given in (a).

$$\overline{J} - \hat{J} = \overline{J} - \sum_{i=1}^{M} c_{i} \cdot \overline{p_{i}} \quad B_{J} \text{ using the equation } \int_{nem} Lo.iii)$$

$$\Rightarrow \left(\left(\overline{J} - \sum_{i=1}^{M} c_{i} \overline{p_{i}} \right) \perp \overline{p_{j}} \text{ for } \overline{J} = 1, \dots, M$$

$$\Rightarrow \left(\left(\widehat{J} - \sum_{i=1}^{M} c_{i} \overline{p_{i}} \right), \overline{p_{j}} \right) = 0 \text{ for } \overline{J} = 1, \dots, M$$

$$\langle \widehat{J}, \overline{p_{j}} \rangle = \sum_{i=1}^{M} c_{i} \langle \overline{p_{i}}, \overline{p_{j}} \rangle = 0 \text{ for } \overline{J} = 1, \dots, M$$

$$\langle \widehat{J}, \overline{p_{j}} \rangle = \overline{J} \quad C_{i} \langle \overline{p_{i}}, \overline{p_{j}} \rangle = \overline{L} \quad C_{i} \quad$$

1.C) \mathbf{x} is a vector in S_1 which is an M-dimensional inner product space (standard inner product), and \mathbf{A} is an $N \times M$ matrix, N > M, whose columns are linearly independent, representing a linear transform. Derive the left pseudoinverse \mathbf{A}_{ps} of \mathbf{A} which would yield $\hat{\mathbf{x}} = \mathbf{A}_{ps}\mathbf{y}$ such that $\hat{\mathbf{x}}$ is the solution to $\hat{\mathbf{x}} = \operatorname{argmin} ||\mathbf{y} - \mathbf{A}\mathbf{x}||^2$

Let
$$\overline{A} = [\overline{a_1} \ \overline{a_2} \ \cdots \overline{a_M}]$$
,

$$\Rightarrow \hat{x} = \operatorname{conjuin}^{n} \| \overline{y} - \overline{A_{\overline{v}}} \|^2, \quad \hat{y} = \overline{A_{\overline{v}}} \hat{x} \quad \text{Then the initialization}$$

becomes $\operatorname{conjuin}^{n} \| \overline{y} - \overline{A_{\overline{v}}} \|^2$ where $\hat{y} \in \mathbb{P}(\overline{A})$. By using the relations proposed in previous parts:

$$\Rightarrow (\overline{y} - \widehat{y}) \perp \mathbb{P}(\overline{A}) \quad \hat{y} = \sum_{l=1}^{M} \hat{x_l} \cdot \overline{a_l} \Rightarrow \langle \overline{y} - \sum_{l=1}^{M} \hat{x_l} \cdot \overline{a_l}, \quad \overline{a_j} \rangle = 0 \text{ for } j = 1, 2, ..., M$$

$$\Rightarrow \langle \overline{y}, \overline{a_j} \rangle = \sum_{l=1}^{M} \hat{x_l} \cdot \langle \overline{a_l}, \overline{a_j} \rangle \quad \text{for } j = 1, 2, ..., M \quad \Rightarrow \underline{\text{The Normal Eqn}}$$

$$\vec{A}_{a_{i_1}} \cdot \vec{y} = \vec{A}_{a_{i_2}} \cdot \vec{A} \cdot \hat{x} \Rightarrow \hat{x} = (\vec{A}_{a_{i_2}} \cdot \vec{A})^{-1} \cdot \vec{A}_{a_{i_2}} \cdot \vec{y}$$

$$\vec{A}_{p_2} = (\vec{A}_{a_{i_2}} \cdot \vec{A})^{-1} \cdot \vec{A}_{a_{i_2}} \cdot \vec{y}$$

$$\vec{A}_{p_3} = (\vec{A}_{a_{i_3}} \cdot \vec{A})^{-1} \cdot \vec{A}_{a_{i_2}} \cdot \vec{y}$$

$$\vec{A}_{p_3} = (\vec{A}_{a_{i_3}} \cdot \vec{A})^{-1} \cdot \vec{A}_{a_{i_3}} \cdot \vec{y}$$

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$$\vec{A}_{p_3} = (\vec{A}_{a_{i_3}} \cdot \vec{A})^{-1} \cdot \vec{A}_{a_{i_3}} \cdot \vec{y}$$

$$A = \begin{bmatrix} 1 & -1 \\ 2 & 1 \\ -1 & 1 \end{bmatrix} \qquad \mathbf{y} = \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$$

By using the equation derived in part $\underline{L.c.}$ argumen $\|\bar{y}-\bar{A}\bar{x}\|^2 = (\bar{A}_{ab},\bar{A})^{-1},\bar{A},\bar{y}$

$$\hat{\mathbf{X}} = (\bar{\mathbf{A}}_{odj} \cdot \bar{\mathbf{A}})^{-1} \cdot \bar{\mathbf{A}}_{odj} \cdot \bar{\mathbf{J}}$$

$$\bar{\mathbf{A}}_{odj} \cdot \bar{\mathbf{A}} = \begin{bmatrix} 1 & 2 & -1 \\ -1 & 1 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & -1 \\ 2 & 1 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 6 & 0 \\ 0 & 3 \end{bmatrix}$$

$$(\bar{\mathbf{A}}_{odj} \cdot \bar{\mathbf{A}})^{-1} = \begin{bmatrix} 1/6 & 0 \\ 0 & 1/3 \end{bmatrix}$$

$$\hat{X} = \begin{bmatrix} 1/6 & 0 \\ 0 & 1/3 \end{bmatrix} \cdot \begin{bmatrix} 1 & 2 & -1 \\ -1 & L & L \end{bmatrix} \begin{bmatrix} 3 \\ -1 \\ L \end{bmatrix}$$

$$\begin{bmatrix} 1/6 & 1/3 & 1/6 \\ -1/3 & 1/3 & 1/6 \end{bmatrix} \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$\mathbf{x} = \begin{bmatrix} -\mathbf{r} \\ \mathbf{o} \end{bmatrix}$$

 $\hat{\mathbf{x}} = \begin{bmatrix} \mathbf{0} \\ -\mathbf{L} \end{bmatrix} \quad \text{which is again} \| \bar{\mathbf{y}} - \bar{\mathbf{A}} \bar{\mathbf{x}} \|^2$

1.e) e) Find $\hat{\mathbf{y}} = \mathbf{A}\hat{\mathbf{x}}$ and show that $(\mathbf{y} - \hat{\mathbf{y}})$ is orthogonal to $\hat{\mathbf{y}}$.

$$\hat{x} = \begin{bmatrix} 0 \\ -1 \end{bmatrix} , \hat{A} = \begin{bmatrix} 1 & -1 \\ 2 & 1 \\ -1 & 1 \end{bmatrix} , \hat{g} = \begin{bmatrix} 1 & -1 \\ 2 & 1 \\ -1 & 1 \end{bmatrix} , \hat{g} = \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix} , \hat{g} = \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$$

$$\bar{y} - \hat{y} = \begin{bmatrix} 2 \\ 0 \\ 2 \end{bmatrix} , \hat{y} = \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix} , \langle \bar{y} - \hat{y}, \hat{y} \rangle = 2.1 + 0.(-1) + 2.(-1) = \underline{0}$$

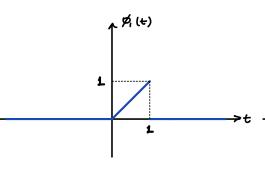
$$(\bar{y}-\hat{y})\perp\hat{y}$$
 so expected.

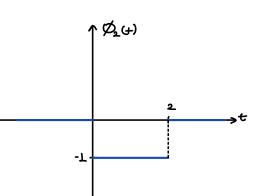
2.a) Plot these functions. Are these functions orthogonal to each other?

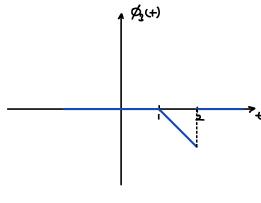
$$\phi_1(t) = \begin{cases} t & \text{if } t \in [0, 1] \\ 0 & \text{else} \end{cases}$$

$$\phi_2(t) = \begin{cases} -1 & \text{if } t \in [0, 2] \\ 0 & \text{else} \end{cases}$$

$$\phi_3(t) = \begin{cases} -t+1 & \text{if } t \in [1,2] \\ 0 & \text{else} \end{cases}$$







•
$$\langle \phi_{1}(+), \phi_{2}(+) \rangle = \int_{0}^{1-t} -t \, dt = -\frac{1}{2}$$

•
$$\langle \%_2(+), \%_3(+) \rangle = \int_{1}^{2} t^{-1} dt = \frac{t^2}{2} - t \int_{1}^{2} = \frac{L}{2}$$

$$\langle p_1(+), p_2(+) \rangle = \underline{0}$$

 \emptyset_2 (+) is onthogonal neither \emptyset_1 (+) non \emptyset_3 (+).

Find the range space of $\{\phi_1(t), \phi_2(t), \phi_3(t)\}$. Select an arbitrary (c_1, c_2, c_3) (indicate you selection). 2.b) Plot a typical function in that range space using your selected coefficients, i.e., plot $c_1\phi_1(t)$ + $c_2\phi_2(t) + c_3\phi_3(t)$ for your c_i 's.

 $\emptyset(+) = e_1 \cdot \emptyset_1(+) + c_2 \cdot \emptyset_2(+) + c_3 \cdot \emptyset_3(+) \in \mathcal{R}(\{\emptyset_1(+), \emptyset_2(+), \emptyset_3(+)\}) \quad \forall \quad c_1, c_2, c_3 \in \mathcal{R}$

$$\emptyset(+) = \begin{cases}
c_{1} \cdot \epsilon - c_{2} & \epsilon \in [0, 1] \\
-c_{3} \cdot \epsilon - c_{2} + c_{3} & \epsilon \in [1, 2]
\end{cases}$$

$$0 \qquad e'se$$

$$\forall C_{1}, C_{2}, C_{3} \in \mathbb{R}$$

$$\emptyset(+) \in \mathbb{R}(\S \emptyset_{1}(+), \emptyset_{2}(+), \emptyset_{3}(+)\S)$$

$$\forall C_1, C_2, C_3 \in \mathbb{R}$$

$$\emptyset(+) \in \mathbb{R}(\S \emptyset(+), \emptyset_2(+), \emptyset_3(+)^2)$$

Let say
$$\bar{c} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$
, then $\phi(+) = \begin{cases} +2 \\ 3-t \\ t \in [1,2] \end{cases}$

O else

2.C) c) Find the parameters,
$$c_i$$
's to minimize $\left\|y(t) - \sum_{i=1}^3 c_i \phi_i(t)\right\|^2$, where
$$y(t) = \begin{cases} -1 & \text{if } t \in [-1,1]\\ 2 & \text{if } t \in [2,3]\\ 0 & \text{else} \end{cases}$$

Plot (y(t)) and $\hat{y}(t) = c_1\phi_1(t) + c_2\phi_2(t) + c_3\phi_3(t)$ using the optimum c_i 's you found on the same graph.

Ci's those minimize
$$\|y(+) - \sum_{\ell=1}^{3} \operatorname{Ci} |y_{\ell}(+)\|^{2}$$
 can be found by using the pneurous results.

$$\overline{\overline{\Phi}} = \left[\phi_1(t) \ \phi_2(t) \ \phi_3(t) \right] \quad . \quad \text{Then}, \quad \overline{\overline{\Phi}}_{ody} \cdot \overline{\overline{\Phi}} \cdot \overline{c} = \overline{\overline{\Phi}}_{ody} \cdot y \cup$$

$$\overline{c} = (\overline{\underline{\Phi}}_{\alpha j} \cdot \overline{\underline{\Phi}})^{-1} \cdot \overline{\underline{\Phi}} \cdot y(4)$$

•
$$\overline{\underline{\Phi}}_{cdj}$$
 . $\overline{\underline{\Phi}} = \begin{bmatrix} \varphi_1(t) \\ \varphi_2(t) \\ \varphi_3(t) \end{bmatrix}$. $\begin{bmatrix} \varphi_1(t) \\ \varphi_2(t) \end{bmatrix}$. $\begin{bmatrix} \varphi_1(t) \\ \varphi_2(t) \end{bmatrix}$

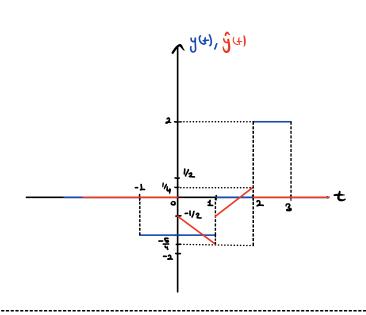
$$=\begin{bmatrix} \langle \phi_{1}(+), \phi_{1}(+) \rangle & \langle \phi_{2}(+), \phi_{1}(+) \rangle & \langle \phi_{3}(+), \phi_{1}(+) \rangle \\ \langle \phi_{1}(+), \phi_{2}(+) \rangle & \langle \phi_{2}(+), \phi_{2}(+) \rangle & \langle \phi_{3}(+), \phi_{2}(+) \rangle \\ \langle \phi_{1}(+), \phi_{3}(+) \rangle & \langle \phi_{2}(+), \phi_{3}(+) \rangle & \langle \phi_{3}(+), \phi_{3}(+) \rangle \end{bmatrix} = \begin{bmatrix} \frac{1}{3} & -\frac{1}{2} & 0 \\ -\frac{1}{2} & 2 & -\frac{1}{2} \\ 0 & -\frac{1}{2} & \frac{1}{3} \end{bmatrix}$$

$$\left(\frac{\overline{\underline{d}}}{\underline{d}} \underbrace{\underline{d}}_{0}^{-1} \underbrace{\underline{\underline{d}}}_{0}^{-1/2} \underbrace{\underline{\underline{d}}}_{0}^{-1/2} \underbrace{\underline{\underline{d}}}_{0}^{-1/2} \underbrace{\underline{\underline{d}}}_{0}^{-1/2} \underbrace{\underline{\underline{d}}}_{0}^{-1/2} \underbrace{\underline{\underline{d}}}_{0}^{-1/2} \underbrace{\underline{\underline{d}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{d}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{\underline{d}}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{d}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{d}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{d}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{d}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{\underline{d}}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{d}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{d}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{d}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{\underline{d}}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{d}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{\underline{d}}}}}_{0}^{-1/2} \underbrace{\underline{\underline{\underline{\underline{d}}}}$$

$$\bullet \ \ \overline{C} \ = \ \left(\ \ \overline{\underline{\Phi}}_{\alpha k_{1}^{\prime}} \cdot \ \overline{\underline{\Phi}}_{\beta k_{2}^{\prime}} \cdot \ \overline{\underline{\Phi}}_{\beta k_{1}^{\prime}} \cdot \ \overline{\underline{\Psi}}_{\beta k_{2}^{\prime}} \cdot \ \overline{\underline{\Psi}}_{\beta k_{2}^{$$

$$\hat{y}(+) = \begin{cases} -\frac{3}{4} \ell - \frac{1}{2} & \ell \in [0, 1] \\ \frac{3}{4} \ell - \frac{5}{4} & \ell \in [1, 2] \end{cases}$$

$$0 \quad \text{else}$$



2.d) Find and plot the error function $e(t) = y(t) - \hat{y}(t)$, and show that e(t) is orthogonal to $\hat{y}(t)$.

$$e(t) = y(t) - \hat{y}(t) = \begin{cases} -1 & \text{if } t \in [-1, 0] \\ \frac{3}{4}t - \frac{1}{4} & \text{if } t \in [0, 1] \\ \frac{5}{4}t - \frac{3t}{4} & \text{if } t \in [1, 2] \\ 2 & \text{if } t \in [2, 3] \end{cases}$$

$$= (-\frac{3t^3}{16} + \frac{t}{4}) \Big|_{1}^{1} + \left(-\frac{3t^3}{16} + \frac{55t^3}{16} + \frac{15t}{16} + \frac{25}{16} + \frac{15}{16} + \frac{25}{16} + \frac{15}{16} + \frac{25}{16} + \frac{15}{16} + \frac{25}{16} + \frac{15}{16} + \frac{25}{16} + \frac{25}{16}$$