

2025 Yokohama National University, Faculty of Science and  
Engineering, Mathematical Science EP Graduation Research

# Magnitude Homology of Graphs and the Magnitude as its Categorification

**2264257 Kensho Yachi**

<https://taro-ken.com>

**Supervisor : Yuta Nozaki Associate  
Professor**

**(January 30th, 2025)**

Supervisor's seal	accep- tance stamp

## **Abstract**

Sample Abstract

# Contents

<b>1</b>	<b>Introduction</b>	<b>3</b>
<b>2</b>	<b>The Magnitude of Graphs</b>	<b>4</b>
2.1	The definition of the magnitude of Graphs . . . . .	4
2.2	Basic Properties and Examples . . . . .	7
2.3	The main result of magnitude of graphs . . . . .	11
<b>3</b>	<b>The Magnitude Homology of Graphs</b>	<b>15</b>
3.1	The Definition of the magnitude homology of graphs . . .	15
3.2	Magnitude Homology of Graphs is Categorification of Mag- nitude of Graphs . . . . .	16
3.3	u . . . . .	16
<b>4</b>	<b>Motivation : The Magnitude of Enriched Categories</b>	<b>17</b>

# 1 Introduction

Lamport's guide to L<sup>A</sup>T<sub>E</sub>X [1].

## 2 The Magnitude of Graphs

In this section, we define the magnitude of a graph  $G$  and the magnitude homology of a graph  $G$ , give some very basic examples and properties. By a *graph* we mean a finite undirected graph with no loops or multiple edges. The set of vertices of a graph  $G$  is denoted by  $V(G)$ , and the set of edges of  $G$  is denoted by  $E(G)$ . If  $x$  and  $y$  are vertices of a graph  $G$ , then the *distance*  $d_G(x, y)$  between  $x$  and  $y$  is defined to be the length of a shortest edge path from  $x$  to  $y$ . If  $x$  and  $y$  lie in different components of  $G$  then  $d(x, y) = \infty$ .

### 2.1 The definition of the magnitude of Graphs

Here, we define the magnitude of a graph, which can be expressed as either a rational function over  $\mathbb{Q}$  or a formal power series over  $\mathbb{Z}$ . Write  $\mathbb{Z}[q]$  for the polynomial ring over the integers in one variable  $q$  and  $\mathbb{Z}[[q]]$  for the ring of formal power series over the integers in one variable  $q$ .

**Definition 2.1.1.** Let  $G$  be a graph. We define the  $G$ -matrix  $Z_G = Z_G(q)$  over  $\mathbb{Z}[q]$  whose rows and columns are indexed by the vertices of  $G$ , and whose  $(x, y)$ -entry is given by

$$Z_G(q)(x, y) = q^{d(x, y)} \quad (x, y \in V(G))$$

where by convention  $q^\infty = 0$ .

$G$ -matrix is the square symmetric matrix.

**Proposition 2.1.2.**  $G$ -matrix is invertible.

*Proof.* By definition, the determinant of  $Z_G$  has constant term 1, which implies that  $\det Z_G \neq 0$ .  $\square$

**Definition 2.1.3.** The *magnitude* of a graph  $G$  is defined to be the rational function given by

$$\#G(q) = \sum_{x, y \in V(G)} (Z_G(q))^{-1}(x, y)$$

in the rational function field  $\mathbb{Q}(q)$ .

**Remark 2.1.4.**

$$\#G(q) = \text{sum}(Z_G(q)^{-1}) = \frac{\text{sum}(\text{adj}(Z_G(q)))}{\det(Z_G(q))}$$

where  $\text{adj}$  is the adjugate matrix and  $\text{sum}$  is the sum of all entries of a matrix.

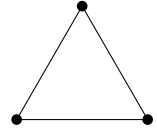
**Proposition 2.1.5.**  $\#G(q)$  takes values in  $\mathbb{Z}[[q]]$ .

*Proof.* Let  $\det Z_G(q) = 1 - qf(q)$  for some  $f(q) \in \mathbb{Z}[q]$  by theorem 2.1.2. Then we have

$$\#G(q) = \frac{\text{sum}(\text{adj}(Z_G))}{\det(Z_G)} = \text{sum}(\text{adj}(Z_G)) \sum_{n=0}^{\infty} q^n f(q)^n$$

Note that  $qf(q)$  has no constant term and then  $\sum_{n=0}^{\infty} q^n f(q)^n$  takes values in  $\mathbb{Z}[[q]]$ . □

**Example 2.1.6.** Let  $G = K_3$  (complete graph with three vertices).



Then, you can calculate the magnitude of  $K_3$  as follows:

$$Z_{K_3}(q) = \begin{pmatrix} 1 & q & q \\ q & 1 & q \\ q & q & 1 \end{pmatrix}, \quad Z_{K_3}(q)^{-1} = \frac{1}{1 - 3q^2 + 2q^3} \begin{pmatrix} 1 - q^2 & -q + q^2 & -q + q^2 \\ -q + q^2 & 1 - q^2 & -q + q^2 \\ -q + q^2 & -q + q^2 & 1 - q^2 \end{pmatrix},$$

$$\#K_3(q) = \frac{3}{1+2q}$$

**Definition 2.1.7.** Let  $G$  be a graph and  $x \in V(G)$ . The *weight* of  $x$  in  $G$  is defined

$$w_G(x)(q) = \sum_{y \in V(G)} (Z_G(q))^{-1}(x, y)$$

The function  $w_G : V(G) \rightarrow \mathbb{Q}(q)$  is called the *weighting* on  $G$ .

The magnitude can be expressed using the weighting as follows:

$$\#G(q) = \sum_{x \in V(G)} w_G(x)$$

**Lemma 2.1.8.** *For any graph  $G$ , the weighting  $w_G$  satisfies*

$$\sum_{y \in V(G)} q^{d(x,y)} w_G(y) = 1 \quad (x \in V(G))$$

*Proof.* For any vertex  $x \in V(G)$ , we have

$$\begin{aligned} \sum_{y \in V(G)} q^{d(x,y)} w_G(y) &= \sum_{y,z \in V(G)} q^{d(x,y)} Z_G^{-1}(y, z) \\ &= \sum_{y,z \in V(G)} Z_G(x, y) Z_G^{-1}(y, z) \\ &= \sum_{z \in V(G)} \sum_{y \in V(G)} Z_G(x, y) Z_G^{-1}(y, z) \\ &= \sum_{z \in V(G)} (Z_G Z_G^{-1})(x, z) \\ &= \sum_{z \in V(G)} I(x, z) \\ &= 1. \end{aligned}$$

□

This equation is called the *weighting equation*.

**Lemma 2.1.9.** *Let  $G$  be a graph and  $\tilde{w}_G : V(G) \rightarrow \mathbb{Q}$  be a function satisfying a weighting equation. Then,  $\tilde{w}_G = w_G$ . Now,  $w_G$  is the weighting on  $G$ .*

*Proof.* Let  $\mathbf{b} = (1, 1, \dots, 1)^T$  where the length of  $\mathbf{b}$  is  $|V(G)|$  and  $\mathbf{w}_G = (w_G(x))_{x \in V(G)}^T$ . If  $\tilde{w}_G$  satisfies the weighting equation, then we have

$$Z_G \tilde{\mathbf{w}}_G = \mathbf{b}$$

Since  $Z_G$  is invertible by theorem 2.1.2, we have  $\tilde{w}_G = w_G$

□

This lemma shows that the weighting on a graph is unique and we use this frequently to compute the magnitude of graphs.

## 2.2 Basic Properties and Examples

Here we give the most basic facts about magnitude. We focus on transitive graphs, disjoint unions, cartesian products, and how the magnitude behaves within  $\mathbb{Z}[[q]]$ .

**Definition 2.2.1.** Let  $G = (V(G), E(G))$ ,  $H = (V(H), E(H))$  be a graph. An *graph homomorphism* from  $G$  to  $H$  is a map  $f : V(G) \rightarrow V(H)$  such that if  $\{x, y\} \in E(G)$  then  $\{f(x), f(y)\} \in E(H)$ .

We can define a *graph automorphism* using the definition above. We denote the group of all graph automorphisms of a graph  $G$  by  $\text{Aut}(G)$ .  $\text{Aut}(G)$  includes  $\text{id}_G$  and for  $g, h \in \text{Aut}(G)$  and  $x \in V(G)$ ,  $g(h(x)) = (gh)(x)$ , which means  $\text{Aut}(G)$  acts on  $V(G)$ .

**Definition 2.2.2.** A graph  $G$  is *vertex-transitive* if  $\text{Aut}(G)$  acts transitively on  $V(G)$ . It says that for any vertices  $x$  and  $y$  of  $G$ , there exists an automorphism  $g : G \rightarrow G$  such that  $y = g(x)$ .

**Lemma 2.2.3.** *Let  $G$  be a vertex-transitive graph. Then,*

$$\#G(q) = \frac{|V(G)|}{\sum_{y \in V(G)} q^{d(x,y)}}$$

*for any vertex  $x \in V(G)$ .*

*Proof.* Let  $S(x) = \sum_{y \in V(G)} q^{d(x,y)}$  for a vertex  $x \in V(G)$ . We show that  $S(x)$  does not depend on the choice of  $x$ . Take any vertices  $a, b \in V(G)$ . Since  $G$  is vertex-transitive, there exists  $g \in \text{Aut}(G)$  such that  $b = g(a)$ . Then,

$$\begin{aligned} S(b) &= \sum_{y \in V(G)} q^{d(b,y)} \\ &= \sum_{y \in V(G)} q^{d(g(a),y)} \\ &= \sum_{y \in V(G)} q^{d(g(a),g(y))} \quad (\text{since } g \text{ is bijective}) \\ &= \sum_{y \in V(G)} q^{d(a,y)} \quad (\text{since } g \text{ is an isomorphism}) \\ &= S(a) \end{aligned}$$



Thus,  $S(x)$  does not depend on the choice of  $x$ , denoting it by  $S$ . Now, we define a function  $\tilde{w}_G : V(G) \rightarrow \mathbb{Q}(q)$  by  $\tilde{w}_G(x) = \frac{1}{S}$  for any vertex  $x \in V(G)$ . Then  $\tilde{w}_G$  satisfies the weighting equation and by theorem 2.1.9, we have  $\#G = \frac{|V(G)|}{S}$ .

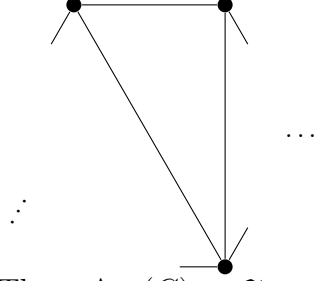
□

**Example 2.2.4.** (i)  $G = V_n$  (edgeless graph with  $n$  vertices).



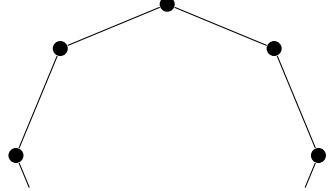
Then,  $\text{Aut}(G) \approx \mathfrak{S}_n$  and  $G$  is vertex-transitive.  $S = 1$  and we have  $\#V_n = n$ .

(ii)  $G = K_n$  (complete graph with  $n$  vertices).



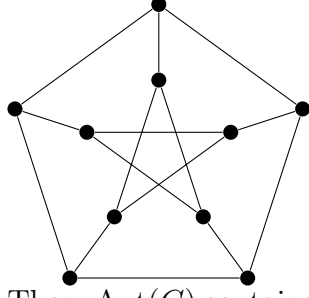
Then,  $\text{Aut}(G) \approx \mathfrak{S}_n$  and  $G$  is vertex-transitive.  $S = 1 + (n - 1)q$  and we have  $\#K_n = \frac{n}{1 + (n - 1)q}$ .

(iii)  $G = C_n$  (cycle graph with  $n$  vertices).



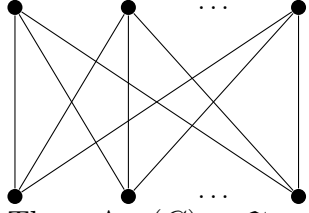
Then,  $\text{Aut}(G) \approx D_{2n}$  and  $G$  is vertex-transitive. If  $n = 2m$ (even), then  $S = 1 + 2(q + q^2 + \dots + q^{m-1}) + q^m = \frac{1+q-q^m-q^{m+1}}{1-q}$ . Thus, we have  $\#C_{2m} = \frac{2m(1-q)}{(1+q)(1-q^m)} = \frac{n(1-q)}{(1+q)(1-q^m)}$ . If  $n = 2m - 1$ (odd), then similarly  $\#C_{2m-1} = \frac{n(1-q)}{1+q-2q^m}$ .

(iv)  $G$  is a Petersen graph.



Then,  $\text{Aut}(G)$  contains  $D_{10}$  as its subgroup and  $G$  is vertex-transitive.  
 $S = 1 + 3q + 6q^2$  and we have  $\#G = \frac{10}{1+3q+6q^2}$ .

(v)  $G = K_{m,n}$  (complete bipartite graph).



Then,  $\text{Aut}(G) \approx \mathfrak{S}_m \times \mathfrak{S}_n$  if  $m \neq n$  and  $G$  is not vertex-transitive.  
 You can calculate the magnitude with other methods. Let  $a, b$  be the weight of vertices on each part of  $K_{m,n}$ . Then, the weighting equation is written by two equations as follows:

$$\begin{cases} \{q^0 + (m-1)q^2\}a + nqb = 1 \\ \{q^0 + (n-1)q^2\}b + mqa = 1 \end{cases}$$

You can solve this and we have

$$\#K_{m,n} = ma + nb = \frac{(m+n) - (2mn - m - n)q}{(1+q)(1 - (m-1)(n-1)q^2)}$$

**Lemma 2.2.5.** *Let  $G$  and  $H$  be graphs. Then,*

$$\#(G \sqcup H) = \#G + \#H$$

where  $G \sqcup H$  is the disjoint union of  $G$  and  $H$ .

*Proof.*  $Z_{G \sqcup H} = \begin{pmatrix} Z_G & O \\ O & Z_H \end{pmatrix},$

$$Z_{G \sqcup H}^{-1} = \begin{pmatrix} Z_G^{-1} & O \\ O & Z_H^{-1} \end{pmatrix}.$$

Thus,

$$\#(G \sqcup H) = \text{sum}(Z_{G \sqcup H}^{-1}) = \text{sum}(Z_G^{-1}) + \text{sum}(Z_H^{-1}) = \#G + \#H$$

□

**Definition 2.2.6.** Let  $G$  and  $H$  be graphs. The *cartesian product*  $G \square H$  of  $G$  and  $H$  is the graph defined as follows;

- $V(G \square H) = V(G) \times V(H)$
- $E(G \square H) = \{(x, y), (x', y')\} | x = x' \text{ and } \{y, y'\} \in E(H) \text{ or } y = y' \text{ and } \{x, x'\} \in E(G)\}.$

**Lemma 2.2.7.**  $\#G \square H = \#G \cdot \#H$

*Proof.* For  $x, x' \in V(G)$  and  $y, y' \in V(H)$ ,  
 $d_{G \square H}((x, y), (x', y')) = d_G(x, x') + d_H(y, y')$   
 $\Rightarrow Z_{G \square H}((x, y), (x', y')) = q^{d_{G \square H}((x, y), (x', y'))} = q^{d_G(x, x')} q^{d_H(y, y')} = Z_G(x, x') Z_H(y, y')$   
 $\Rightarrow Z_{G \square H} = Z_G \otimes Z_H$  and then  $Z_{G \square H}^{-1} = Z_G^{-1} \otimes Z_H^{-1}$   
 $\Rightarrow \#G \square H = \text{sum}(Z_{G \square H}^{-1}) = \text{sum}(Z_G^{-1} \otimes Z_H^{-1}) = \text{sum}(Z_G^{-1}) \cdot \text{sum}(Z_H^{-1}) = \#G \cdot \#H$

We used the fact that  $(P \otimes Q)(R \otimes S) = (PR) \otimes (QS)$  for proper matrices  $P, Q, R, S$ . □

**Example 2.2.8.** See  $G = K_2 \square K_3$ .

$$\#K_2 \square K_3 = \#K_2 \cdot \#K_3 = \frac{2}{1+q} \cdot \frac{3}{1+2q} = \frac{6}{(1+q)(1+2q)} = \#K_{3,3}.$$

**Remark 2.2.9.** Here we use the cartesian product for graph product, but there are other graph products such as the tensor product and strong product. However, there is a reason that we use the cartesian product. This will be clear in Section 4.

**Proposition 2.2.10.** *Let  $G$  be a graph. Then,*

$$\begin{aligned} \#G(q) &= \sum_{k=0}^{\infty} (-1)^k \sum_{x_0 \neq x_1 \neq \dots \neq x_k} q^{d(x_0, x_1) + d(x_1, x_2) + \dots + d(x_{k-1}, x_k)} \\ &= \sum_{n=0}^{\infty} c_n q^n \end{aligned}$$

where  $c_n = \sum_{k=0}^n (-1)^k |\{(x_0, \dots, x_k) | x_0 \neq x_1 \neq \dots \neq x_k, d(x_0, x_1) + \dots + d(x_{k-1}, x_k) = n\}|$

*Proof.* aaa □

**Corollary 2.2.11.** *Let  $G$  be a graph.  $|V(G)| = \#G(0)$ ,  $|E(G)| = -\frac{1}{2} \frac{d}{dq} \#G(q) \Big|_{q=0}$ . Here, the derivative is taken in  $\mathbb{Z}[[q]]$ .*

*Proof.* From the previous proposition, we have

$$\begin{aligned} c_0 &= \sum_{k=0}^0 (-1)^k |\{(x_0, \dots, x_k) | x_0 \neq x_1 \neq \dots \neq x_k, d(x_0, x_1) + \dots + d(x_{k-1}, x_k) = n\}| \\ &= |\{(x_0) | x_0 \in V(G)\}| \\ &= |V(G)| \end{aligned}$$

and

$$\begin{aligned} c_1 &= |\{(x_0) | d(x_0, x_0) = 1\}| - |\{(x_0, x_1) | x_0 \neq x_1, d(x_0, x_1) = 1\}| \\ &= 0 - 2|E(G)| \\ &= -2|E(G)| \end{aligned}$$

This corollary immediately follows from these equations. □

**Remark 2.2.12.**  $c_0 \geq 0$ ,  $c_1 \leq 0$ , and  $c_2 \geq 0$ .  $c_2 = 0$  if and only if

## 2.3 The main result of magnitude of graphs

This section states the inclusion-exclusion principle of magnitude of graphs under some conditions. First, we see that the magnitude does not satisfy the inclusion-exclusion principle in general. Then, we introduce the sufficient condition for the inclusion-exclusion principle to hold.

**Definition 2.3.1.** Let  $R$  be a ring. A function  $\Phi$  is an  $R$ -valued graph invariant if

- $\Phi(G) \in R$  for any graph  $G$
- If  $G \approx H$  as a graph then  $\Phi(G) = \Phi(H)$

**Definition 2.3.2.** Let  $\Phi$  be an  $R$ -valued graph invariant.

1.  $\Phi$  is said to be multiplicative if

- $\Phi(K_1) = 1$

- $\Phi(G \square H) = \Phi(G) \cdot \Phi(H)$  for any graphs  $G$  and  $H$
- 2.  $\Phi$  is said to satisfy the inclusion-exclusion principle if
  - $\Phi(\emptyset) = 0$
  - $\Phi(G \cup H) = \Phi(G) + \Phi(H) - \Phi(G \cap H)$  for any graphs  $G$  and  $H$

**Lemma 2.3.3.** *Let  $R$  be a ring containing no nonzero nilpotents and  $\Phi$  be a multiplicative  $R$ -valued graph invariant satisfying the inclusion-exclusion principle. Then,  $\Phi(G) = |V(G)|$  for any graph  $G$ .*

*Proof.* aaa □

**Corollary 2.3.4.** *The magnitude does not satisfy the inclusion-exclusion principle in general.*

**Example 2.3.5.** labelWillerton

**Definition 2.3.6.** Let  $X$  be a graph and  $U$  be a subgraph of  $X$ .  $U$  is said to be *convex* in  $X$  if for any vertices  $x, y \in V(U)$ ,  $d_U(x, y) = d_X(x, y)$ .

**Lemma 2.3.7.** *Let  $X$  be a graph and  $G, H$  be subgraphs of  $X$  such that  $X = G \cup H$ . In this document, we mean  $G \cup H$  as a graph  $(V(G) \cup V(H), E(G) \cup E(H))$ . Let  $g \in V(G)$  and  $h \in V(H)$  such that there is a path  $(g = x_0 \rightarrow x_1 \rightarrow \cdots \rightarrow x_n = h)$  in  $X$ . Then, there exists a vertex  $x_i \in V(G) \cap V(H)$ .*

*Proof.* aaa □

**Lemma 2.3.8.** *Let  $X$  be a graph and  $G, H$  be subgraphs of  $X$  such that  $X = G \cup H$ . If  $G \cap H$  is convex in  $X$ , then  $G$  and  $H$  are also convex in  $X$ .*

*Proof.* aaa □

**Definition 2.3.9.** Let  $X$  be a graph and  $U$  be a subgraph of  $X$  such that  $U$  is convex in  $X$ . Write  $V_U(X) = \{v \in V(X) \mid d_X(v, u) < \infty \text{ for some } u \in V(U)\}$ . Then, we say that  $X$  projects to  $U$  if for any  $x \in V_U(X)$ , there exists  $\pi(x) \in V(U)$  such that for any  $u \in V(U)$ ,  $d_X(x, u) = d_X(x, \pi(x)) + d_X(\pi(x), u)$ .

**Lemma 2.3.10.** *If  $X$  projects to  $U$ , then  $\pi(x)$  is uniquely determined for any  $x \in V_U(X)$ .*

*Proof.* aaa □

**Example 2.3.11.** aaa

**Lemma 2.3.12.** *Let  $X$  be a graph and  $U \subset X$  be a convex subgraph of  $X$  such that  $X$  projects to  $U$ . Then, for any  $u \in V(U)$ ,*

$$w_U(u) = \sum_{x \in \pi^{-1}(u)} q^{d_X(u,x)} w_X(x)$$

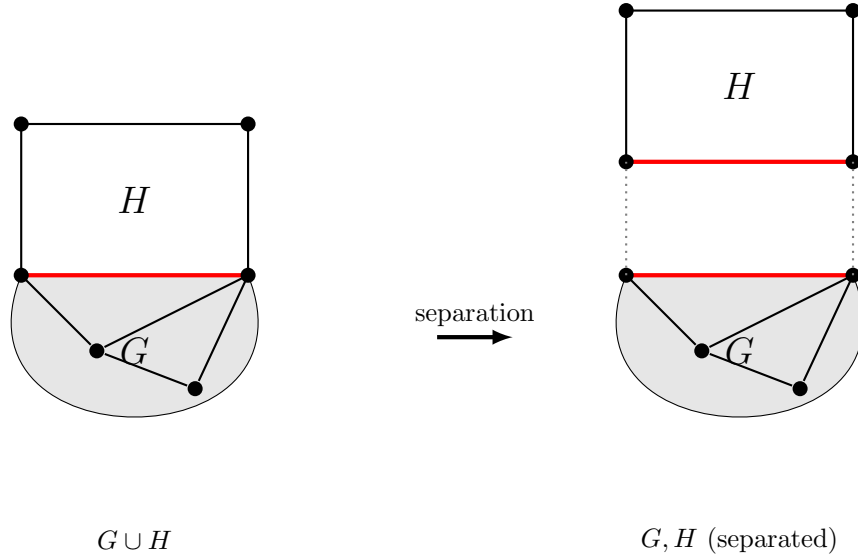
*Proof.* aaa □

**Theorem 2.3.13.** *(main theorem I) Let  $X$  be a graph and  $G, H$  be subgraphs of  $X$  such that  $X = G \cup H$ . If  $G \cap H$  is convex in  $X$  and  $H$  projects to  $G \cap H$ , then*

$$\#X = \#G + \#H - \#(G \cap H)$$

Before proving this theorem, we give the example of graphs for which we can apply this theorem.

**Example 2.3.14.** Let  $G$  be a graph and consider the graph  $H$  formed by identifying one of the edges of a cycle graph  $C_n$  with an edge of  $G$ . Now, let  $n \geq 4$ .



Then, we can apply the main theorem I to  $X = G \cup H$  as follows:

$$\#X = \#G + \#C_n - \#K_2$$

Similarly, if  $G$  and  $H$  are graphs and  $G \vee H$  is the graph formed by identifying one vertex of  $G$  with one vertex of  $H$ , then we have

$$\#(G \vee H) = \#G + \#H - 1$$

*Proof.* (of main theorem I) aaa □

**Example 2.3.15.** The three graphs below are divided into a graph  $C_3$ , and two graphs  $C_2$ , so they all have the same magnitude and can be calculated as follows:

$$\#G = \#C_3 + 2\#C_2 - 2$$

**Example 2.3.16.** If  $G$  is a forest, then we can calculate the magnitude of  $G$  as follows:

$$\#G = |V(G)| - 2|E(G)| \frac{q}{1+q}$$

If  $G$  is a tree, then

$$\#G = |V(G)| - 2(|V(G)| - 1) \frac{q}{1+q}$$

Furthermore examples.

### 3 The Magnitude Homology of Graphs

In this section, we define the magnitude homology of a graph  $G$ , give some very

#### 3.1 The Definition of the magnitude homology of graphs

**Definition 3.1.1.** Let  $G$  be a graph. For positive integers  $k$ , the *length* of a tuple  $(x_0, \dots, x_k)$  of  $V(G)$  is defined to be

$$\begin{aligned} l(x_0, \dots, x_k) &= d(x_0, x_1) + d(x_1, x_2) + \dots + d(x_{k-1}, x_k) \\ &= \sum_{i=1}^k d(x_{i-1}, x_i) \end{aligned}$$

Now, let  $l(x_0) = 0$ .

**Lemma 3.1.2.** (*Triangle inequality*)

$$l(x_0, \dots, x_k) \geq l(x_0, \dots, \hat{x}_i, \dots, x_k)$$

**Definition 3.1.3.** (magnitude chain complex) Let  $G$  be a graph.  $MC_{*,*}(G)$  is the *magnitude complex* defined as follows:

$$MC_{*,*}(G) = \bigoplus_{l=0} MC_{*,l}(G)$$

For non-negative integers  $k$  and  $l$ ,  $MC_{k,l}(G)$  is freely generated by tuples  $(x_0, \dots, x_k)$  of  $V(G)$  satisfying  $x_0 \neq x_1 \neq \dots \neq x_k$  and  $l(x_0, \dots, x_k) = l$ . The coefficient ring is  $\mathbb{Z}$ . The differential  $\partial : MC_{k,l}(G) \rightarrow MC_{k-1,l}(G)$  is defined by

$$\partial = \sum_{i=1}^{k-1} (-1)^{i-1} \partial_i$$

where  $\partial_i(x_0, \dots, x_k) = (x_0, \dots, \hat{x}_i, \dots, x_k)$  if  $l(x_0, \dots, \hat{x}_i, \dots, x_k) = l(x_0, \dots, x_k)$  and 0 otherwise.

**Remark 3.1.4.**

$$\partial_i(x_0, \dots, x_k) \neq 0 \iff d(x_{i-1}, x_i) + d(x_i, x_{i+1}) = d(x_{i-1}, x_{i+1})$$

**Lemma 3.1.5.**  $\partial \circ \partial = 0$

*Proof.* aaa. □



### **3.2 Magnitude Homology of Graphs is Categorification of Magnitude of Graphs**

### **3.3 u**

## 4 Motivation : The Magnitude of Enriched Categories

## References

- [1] Leslie Lamport. *LaTeX: A Document Preparation System*. Addison-Wesley, 2nd edition, 1994.
- [2] Donald E. Knuth. *The TeXbook*. Addison-Wesley, 1984.

**Proposition .0.1.** *Let  $G = K_{n,n}$ . Then,  $\text{Aut}(G) \approx (\mathfrak{S}_n \times \mathfrak{S}_n) \rtimes_s \mathbb{Z}_2$ , where  $s : \mathbb{Z}_2 \rightarrow \text{Aut}(G); 0 \mapsto \text{id}_G, 1 \mapsto \tau$  and  $\tau$  is the automorphism which interchanges the two parts of  $K_{n,n}$ .*

*Proof.* Now,

$$0 \rightarrow \mathfrak{S}_n \times \mathfrak{S}_n \xrightarrow{\text{incl}} \text{Aut}(G) \xrightarrow{s} \mathbb{Z}_2 \rightarrow 0$$

is exact and this sequence splits. Thus, we have  $\text{Aut}(G) \approx (\mathfrak{S}_n \times \mathfrak{S}_n) \rtimes_s \mathbb{Z}_2$ .  $\square$