

# Riemann Surfaces

## An introduction

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# Overview

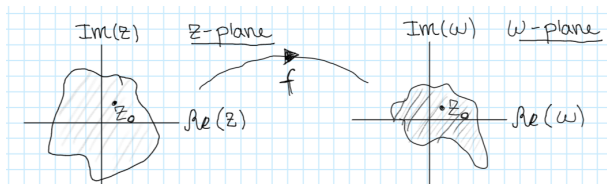
- 1 Idea of Riemann Surfaces
- 2 Riemann surface definition and examples
- 3 Applications
- 4 Conclusion



# Recap of complex analysis so far

## Functions of one complex variable

Take some open set  $U$  in the complex plane and a function  $f$  which takes complex variables  $z$  and maps them to  $w = f(z)$  in the open domain  $V$



# Recap of complex analysis so far

## Functions of one complex variable

Requiring  $f$  to be holomorphic in a neighborhood around  $z_0$  put great constraints on our functions, i.e. Cauchy Riemann conditions (among others) with  $\omega = u + iv$ ,  $z = x + iy$

$$\partial_x u = \partial_y v, \quad \partial_x v = -\partial_y u \quad (1)$$



# Some definitions

## Some definitions

- **Isomorphism:** Structure-preserving mapping between two structures of the same type that can be reversed by an inverse mapping.
- **Homeomorphism:** Isomorphism in the category of topological spaces. I.e. they are the mappings that preserve all the topological properties of a given space
- Injective holomorphic map is a holomorphic isomorphism

Given a holomorphic injective map from an open set  $U$  to  $\mathbb{C}$

$$f : U \rightarrow \mathbb{C} \quad (2)$$

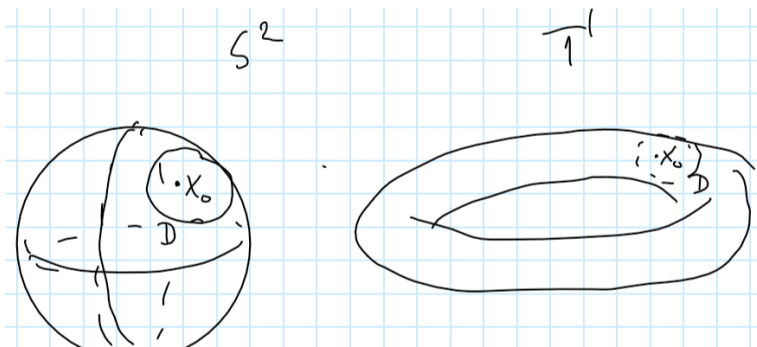
then  $f(U)$  is open, and the inverse map is also holomorphic.



# Complex analysis on surfaces

## Complex analysis on surface

- Take a known surface that we can visualize.
- Pick some point  $x_0$  on the surface on some disc-like domain  $\mathcal{D}$ .
- Introduce function  $f : \mathcal{D} \rightarrow \mathbb{C}$  that takes on complex values on  $\mathcal{D}$ .
- Extend definition of holomorphic function at  $x_0$  so that we can use tools of complex analysis on the surface.



# Pick a simple surface

## Pick a simple surface

Do this by identifying  $\mathcal{D}$  with an open subset, say

$$\Delta = \{z \in \mathbb{C} \mid |z| = 1\} \quad (3)$$

by choosing a homeomorphism

$$\phi : \mathcal{D} \rightarrow \Delta \subset \mathbb{C} \quad (4)$$

Hence we now have a map from the unit disc on the surface to the complex plane

$$\begin{array}{ccc} \Delta & \xleftarrow{\phi} \mathcal{D} & \xrightarrow{f} \mathbb{C} \\ & \searrow f \circ \phi^{-1} & \nearrow \end{array}$$

and require that  $f \circ \phi^{-1}$  is holomorphic at the point.



# Holomorphic requirement

## Holomorphic requirement

So: we get a function from the disc in the complex plane to the complex numbers.

Here it is it is easy to see when it is holomorphic at  $x_0$ .

$f$  is holomorphic on all of  $\mathcal{D}$  if  $f \circ \phi^{-1}$  is holomorphic on  $\Delta$ .





# Complex coordinate chart

## Complex coordinate chart

The pair  $(\mathcal{D}, \phi)$  is called a *complex coordinate chart*

It allows us to do complex analysis on the disc

In this example  $z = \phi(x)$ ,  $x \in X$  provides us with a new symbol in a continuously isomorphic way.

The resulting function is a function of one complex variable on an open subset on the complex plane, where we can do complex analysis.



# Extending to other surfaces

## Extending to other surfaces

We could have taken any open set, not just a disc-like neighborhood.

Would have to choose a different homeomorphism to an open set on the complex plane.



# Extending to other surfaces

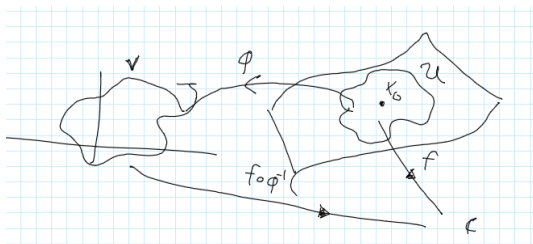
## Extending to other surfaces

More generally: a complex coordinate chart is a pair

$$(\mathcal{U}, \phi) \quad (5)$$

where  $\mathcal{U}$  is an open subset of  $X$  and  $\phi : \mathcal{U} \rightarrow \mathcal{V}$  is a homeomorphism onto an open subset  $\mathcal{V}$  of  $\mathbb{C}$ .

If we have a function  $f$  on  $\mathcal{D}$  that takes complex values,  $f$  is holomorphic if  $f \circ \phi^{-1}$  is holomorphic.



# Naïve preliminary definition of Riemann Surface

## Riemann surface

A surface  $X$  covered by a collection of charts that span of all of  $X$

$$\{(\mathcal{U}_\alpha, \phi_\alpha) \mid \alpha \in I\} \quad (6)$$



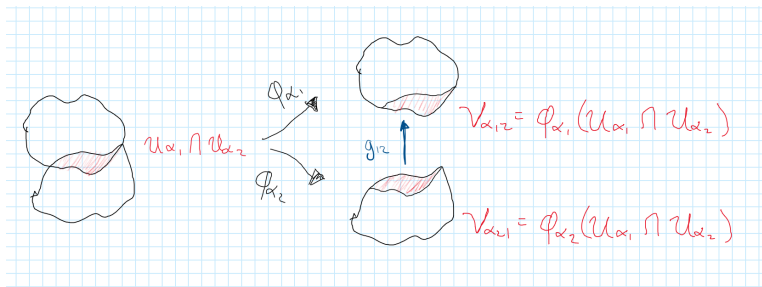
# Naïve preliminary definition of Riemann Surface

Problem since charts can in principle intersect

Consider e.g.

$$f : \mathcal{U}_{\alpha_1} \cap \mathcal{U}_{\alpha_2} \rightarrow \mathbb{C} \quad (7)$$

so we have two charts  $(\mathcal{U}_{\alpha_1}, \phi_{\alpha_1})$  and  $(\mathcal{U}_{\alpha_2}, \phi_{\alpha_2})$ . To be a Riemann surface, both charts should be holomorphic in the domain.



# Naïve preliminary definition of Riemann Surface

Problem since charts can in principle intersect

We then require the transition function  $g_{12}$  between  $\mathcal{V}_{\alpha_{12}}$  and  $\mathcal{V}_{\alpha_{21}}$  to be holomorphic

$$g_{12} = \phi_{\alpha_1}|_{\mathcal{U}_{\alpha_1} \cap \mathcal{U}_{\alpha_2}} \circ \phi_{\alpha_2}^{-1}|_{\mathcal{U}_{\alpha_1} \cap \mathcal{U}_{\alpha_2}} \quad (8)$$

since this condition leads to (ignoring subscripts)

$$f \circ \phi_{\alpha_1}^{-1} \circ g_{12} = f \circ \phi_{\alpha_2}^{-1} \quad (9)$$

$g_{12}$  is holomorphic isomorphism from the holomorphic requirement (i.e. it has an inverse  $g_{21}$ )

This implies that  $\phi_{\alpha_1}^{-1}$  and  $\phi_{\alpha_2}^{-1}$  have to both be holomorphic. It is exactly what we wanted!



# Definition of Riemann Surface

## Summary

- We require that transition functions are holomorphic for  $\mathcal{U}_{\alpha_1} \cap \mathcal{U}_{\alpha_2} \neq \emptyset$
- This gives us a collection of charts that are *compatible*
- Such a collection that covers all of  $X$  is known as a complex *Atlas*
- A surface  $X$  is a Riemann surface if there exists such an atlas.



# Examples of Riemann Surfaces

## Example I: $X = \mathbb{R}^2$

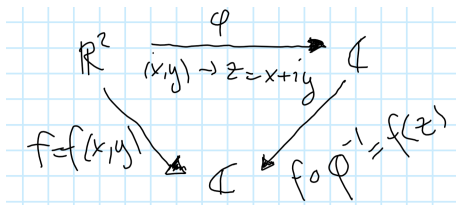
We only need one chart

$$X = \{(\mathbb{R}^2, \phi)\} \quad (10)$$

with

$$\phi : \mathbb{R}^2 \rightarrow \mathbb{C} \quad (11)$$

I.e.  $(x, y) \rightarrow x + iy$ . The holomorphic functions on  $X$  are the holomorphic functions on  $\mathbb{C}$ .





# Examples of Riemann Surfaces

## Example I: $X = \mathbb{R}^2$

We could also have taken a difference chart  $\phi : \mathbb{R}^2 \rightarrow \mathbb{C}$  with

$$\begin{aligned}\phi : (x, y) &\mapsto \frac{z}{1 + |z|} = \frac{x}{1 + \sqrt{x^2 + y^2}} + i \frac{y}{1 + \sqrt{x^2 + y^2}} \\ \phi^{-1} : z &\mapsto \frac{z}{1 - |z|} = \left( \frac{x}{1 - \sqrt{x^2 + y^2}}, \frac{y}{1 - \sqrt{x^2 + y^2}} \right)\end{aligned}\tag{12}$$

(l.e.) mapping  $\mathbb{C}$  onto  $\Delta$ . This is a homeomorphism. This is not the same Riemann surface!



# Examples of Riemann Surfaces

## Example I: $X = \mathbb{R}^2$

For  $f$  to be holomorphic,  $f \circ \phi^{-1}$  has to also be.

$$f \circ \phi^{-1}(z) = f\left(\frac{z}{1-|z|}\right) = f\left(\frac{x}{1-\sqrt{x^2+y^2}}, \frac{y}{1-\sqrt{x^2+y^2}}\right) \quad (13)$$

Not holomorphic for the natural identification  $f(x, y) \rightarrow x + iy = z$

$$f\left(\frac{z}{1-|z|}\right) = \frac{z}{1-|z|} \quad (14)$$

Completely different structure! It is the Riemann surface structure on the unit disc.

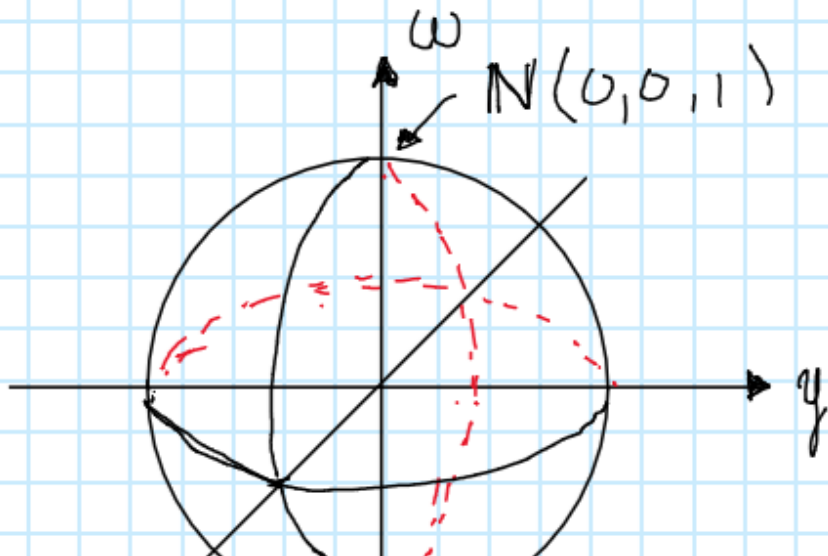
Riemann mapping theorem: unit disc is not equal to complex plane.



# Examples of Riemann Surfaces

Example:  $X = S^2$

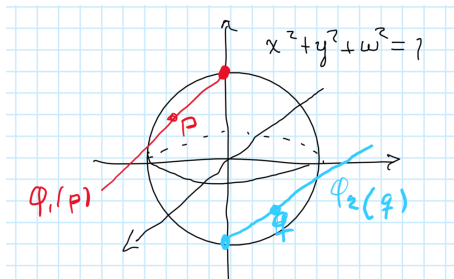
Take the two-dimensional sphere.



# Examples of Riemann Surfaces

Example:  $X = S^2$

Stereographic projection works in the following way



$\phi_1(p)$  = point of intersection of north pole with  $xy$ -plane

$\phi_2(p)$  = point of intersection of south pole with  $xy$ -plane



# Examples of Riemann Surfaces

Check for compatibility

$$\begin{aligned}\mathcal{U}_1 \cap \mathcal{U}_2 &= S^2 \setminus \{N, S\} \\ \phi_1(\mathcal{U}_1 \cap \mathcal{U}_2) &= \mathbb{C} \setminus \{0\} \\ \phi_2(\mathcal{U}_1 \cap \mathcal{U}_2) &= \mathbb{C} \setminus \{0\}\end{aligned}\tag{15}$$

The transition function from  $\mathbb{C} \setminus \{0\} \rightarrow \mathbb{C} \setminus \{0\}$  is  $z \rightarrow \frac{1}{z}$ , which is holomorphic. This Riemann surface structure is the Riemann Sphere

Are there any more atlas?



# Examples of Riemann Surfaces

## Uniformization Theorem

Every simply connected Riemann surface is conformally equivalent to one of three Riemann surfaces: the open unit disk  $\Delta$ , the complex plane  $\mathbb{C}$ , or the Riemann sphere  $\mathbb{C} \cup \infty$ .

*Simply connected*: I.e. an object which consists of one piece and does not have any holes that pass all the way through it.



# Examples of Riemann Surfaces

## Automorphisms

Final note before we look at applications.

Automorphisms of the Riemann sphere are Möbius transformations

$$z \rightarrow \frac{az + b}{cz + d}, \quad ad - bc = 1 \quad (16)$$



## QFT scattering

Overlap between two asymptotic states

$$\langle f|i\rangle = (2\pi)^D \delta^D \left( \sum_i k_i \right) (\mathbb{1}_{fi} + iT_{fi}), \quad (17)$$

Scattering cross section proportional to  $|T_{fi}|^2$ .

We refer to  $T_{fi}$  as the scattering amplitude and denote it by  $\mathcal{A}(\dots)$  where  $(\dots)$  is the scattering data.





# The Scattering Equations

## Scattering equations and amplitudes

The *scattering equations* live on the Riemann sphere through  $z_i$  and are given by

$$\mathcal{S}_i = \sum_{j \neq i} \frac{s_{ij}}{z_i - z_j} = 0, \quad i \in \{1, 2, \dots, n\}. \quad (18)$$

One can obtain amplitudes of various theories from the formula

$$\mathcal{A}_n(1, \dots, n) = \int d\Omega_{\text{CHY}} \mathcal{I}(z_i, k_i, \epsilon_i, \dots), \quad (19)$$

with  $d\Omega_{\text{CHY}} = \frac{d^n z}{\text{Vol}(\text{SL}(2, \mathbb{C}))} \prod_i' \delta(\mathcal{S}_i)$ .



# Complex analysis tools

## Scattering equations and amplitudes

Since the space is the Riemann sphere, one can use tools of complex analysis. Remember

$$f(a) = \frac{1}{2\pi i} \oint dz \frac{f(z)}{z - a} \quad (20)$$

Reformulate the delta-functions  $\rightarrow$  use complex analysis.

From the global residue theorem one can obtain diagrammatic rules to calculate amplitudes.



# Integration rules

## Graphic representation of Möbius invariant integrands

We represent the integrands by four-regular graphs. Every factor of  $z_{ij}^{-1}$  is a line between vertices  $i$  and  $j$  and every factor  $z_{ij}$  is a dashed line.

$$A_n^{\varphi^3}(1, 2, 3, \dots, n) = \int d\Omega_{\text{CHY}} \frac{1}{z_{12}^2 z_{23}^2 \cdots z_{n1}^2}. \quad (21)$$

The integrand is

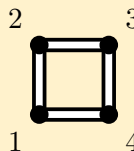
$$\mathcal{I}(z) = \frac{1}{z_{12}^2 z_{23}^2 z_{34}^2 z_{41}^2} \rightarrow \begin{array}{c} 2 \qquad 3 \\ \text{---} \text{---} \\ | \quad | \\ \text{---} \text{---} \\ 1 \qquad 4 \end{array} . \quad (22)$$



# Integration rules

## Graphic representation of Möbius invariant integrands

Using simple derived rules


$$\rightarrow -\frac{1}{s_{12}} - \frac{1}{s_{14}}, \quad (23)$$

We get the final amplitude to be

$$A_4^{\varphi^3}(1, 2, 3, 4) = -\frac{1}{s_{12}} - \frac{1}{s_{14}}. \quad (24)$$

It only took 1 diagram!



# Summary

- Started with a real surface  $X$  on which we wanted to do complex analysis
- This was achieved by using complex charts  $\{(\mathcal{U}_i, \phi_i) \mid i \in I\}$  such that  $\mathcal{U}_i$  covers all of  $X$
- We checked that  $f$  was holomorphic by using  $f \circ \phi^{-1}$
- Compatible charts (atlas) were introduced to make sure the functions were holomorphic even if charts overlapped.
- We analyzed different Riemann structures and introduced the uniformization theorem.
- Finally an application in scattering amplitudes was reviewed.



Thank you for your attention.

