



$$l_{DE} = \sqrt{(x_D - x_1)^2 + (y_D - y_1)^2} \quad ; \quad l_{CD} = \sqrt{(x_D - x_2)^2 + (y_D - y_2)^2} \quad \text{--- (1)}$$

$(x_1, y_1)$  are coordinates of E ;  $(x_2, y_2)$  are coordinates of C

$$\begin{aligned} x_1 &= -l_{AE} \cos \theta_1 & ; & & x_2 &= l_{AB} + l_{BC} \cos \theta_4 \\ y_1 &= l_{AE} \sin \theta_1 & & & y_2 &= l_{BC} \sin \theta_4 \end{aligned} \quad \text{--- (2)}$$

~~Q. B. Q. Q. Q. Q.~~

$$\textcircled{1} \Rightarrow (x_D - x_1)^2 + (y_D - y_1)^2 = l_{DE}^2 \quad \textcircled{3} \quad (x_D - x_2)^2 + (y_D - y_2)^2 = l_{CD}^2 \quad \textcircled{4}$$

$$\textcircled{3} - \textcircled{4} \Rightarrow x_D(2x_2 - 2x_1) + y_D(2y_2 - 2y_1) = l_{DE}^2 - l_{CD}^2 + x_2^2 - x_1^2 + y_2^2 - y_1^2$$

$$\textcircled{3} + \textcircled{4} \Rightarrow$$

$$2x_D^2 + 2y_D^2 - 2x_D(x_1 + x_2) - 2y_D(y_1 + y_2) = l_{DE}^2 + l_{CD}^2 - x_1^2 - x_2^2 - y_1^2 - y_2^2$$

Except  $x$  and  $y$ , all are known.

Solving in Matlab yields 2 solutions, One is invalid.

Once  $x$  and  $y$  are known, Sub in Section formula.

D, C, F lie in a straight line  $+y_2^2 = l_{dc}^2$

$$\therefore \quad \cancel{mD_x + nD_x} \quad \frac{mF_x + nD_x}{m+n} = C_x \quad \left\{ \begin{array}{l} \text{Section} \\ \text{Formula} \end{array} \right\}$$

$$\frac{mF_y + nD_y}{m+n} = C_y \quad \cancel{A + B =}$$

$m = \text{length of CD}$ ,  $n = \text{length of CF}$

$$\Rightarrow \left. \begin{array}{l} l_{CD} X + l_{CF} X_1 = C_x (l_{CD} + l_{CF}) \\ l_{CD} Y + l_{CF} Y_1 = C_y (l_{CD} + l_{CF}) \end{array} \right\} \text{--- (1)}$$

```
>> test3
```

```
theta1 =
```

```
-5.1748
```

```
theta4 =
```

```
0.9454
```

```
X =
```

```
18
```

```
Y =
```

```
4.0000
```

```
fx>>
```