

Introduction to Neural Computation

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MIT BCS 9.40 — 2018

Lecture 19
Neural Integrators

Short-term vs long-term memory

- Long-term memory

- Can last a lifetime

- Large capacity—can hold many memories

- Mechanism: physical changes in neurons and synapses

- Short-term memory

- Lasts tens of seconds

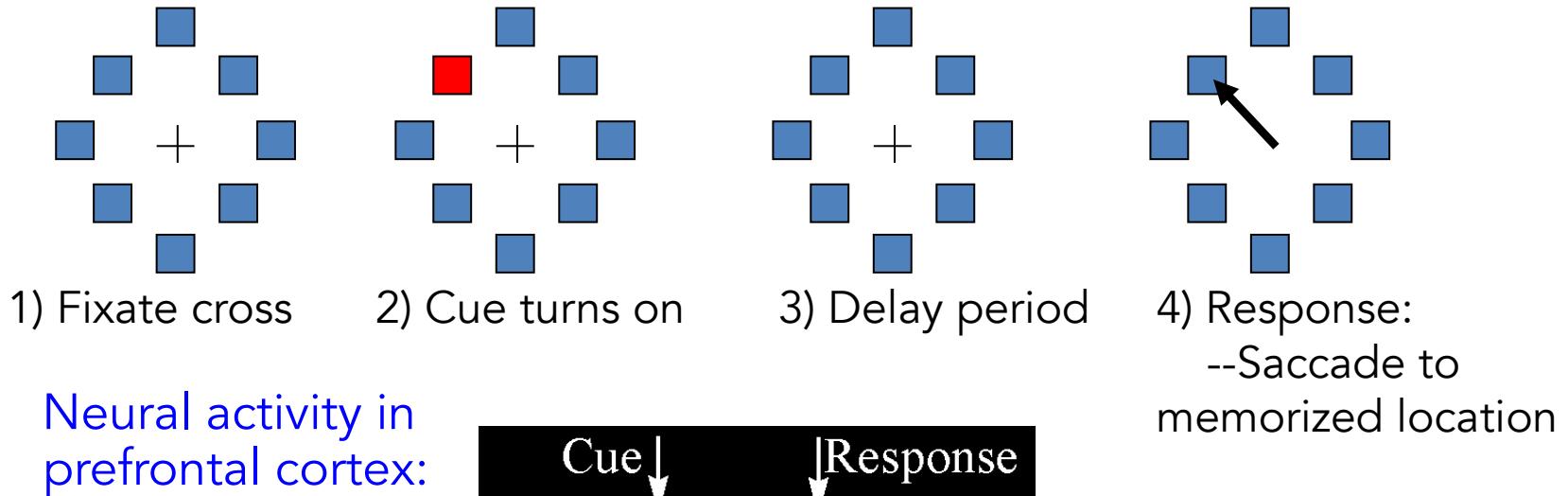
- Small capacity—only can hold a small number at any time

- Mechanism: persistent firing in a population of neurons

Short-term memory

- Persistent firing is the neural correlate of short-term memory

Delayed Saccade Task:

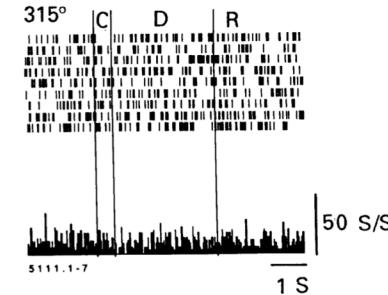
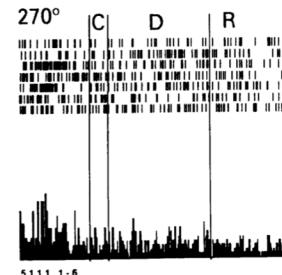
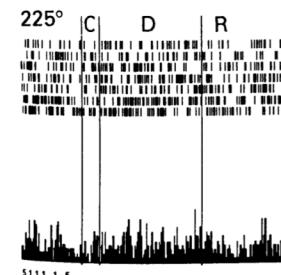
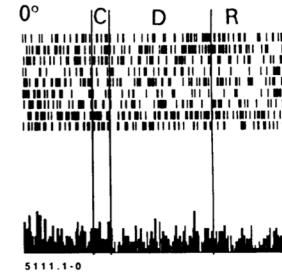
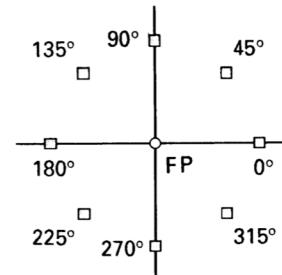
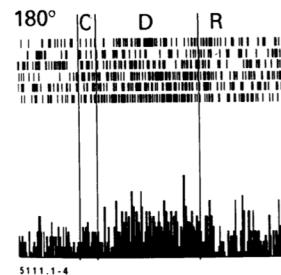
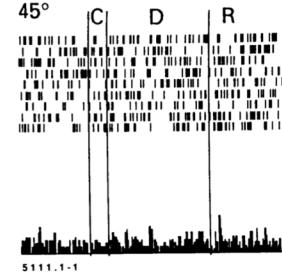
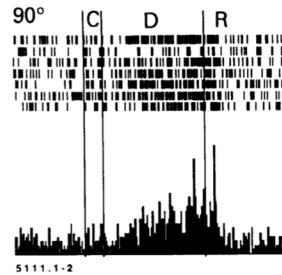
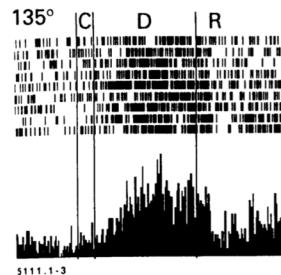


Funahashi,
Goldman-Rakic (1991)

Short-term memory

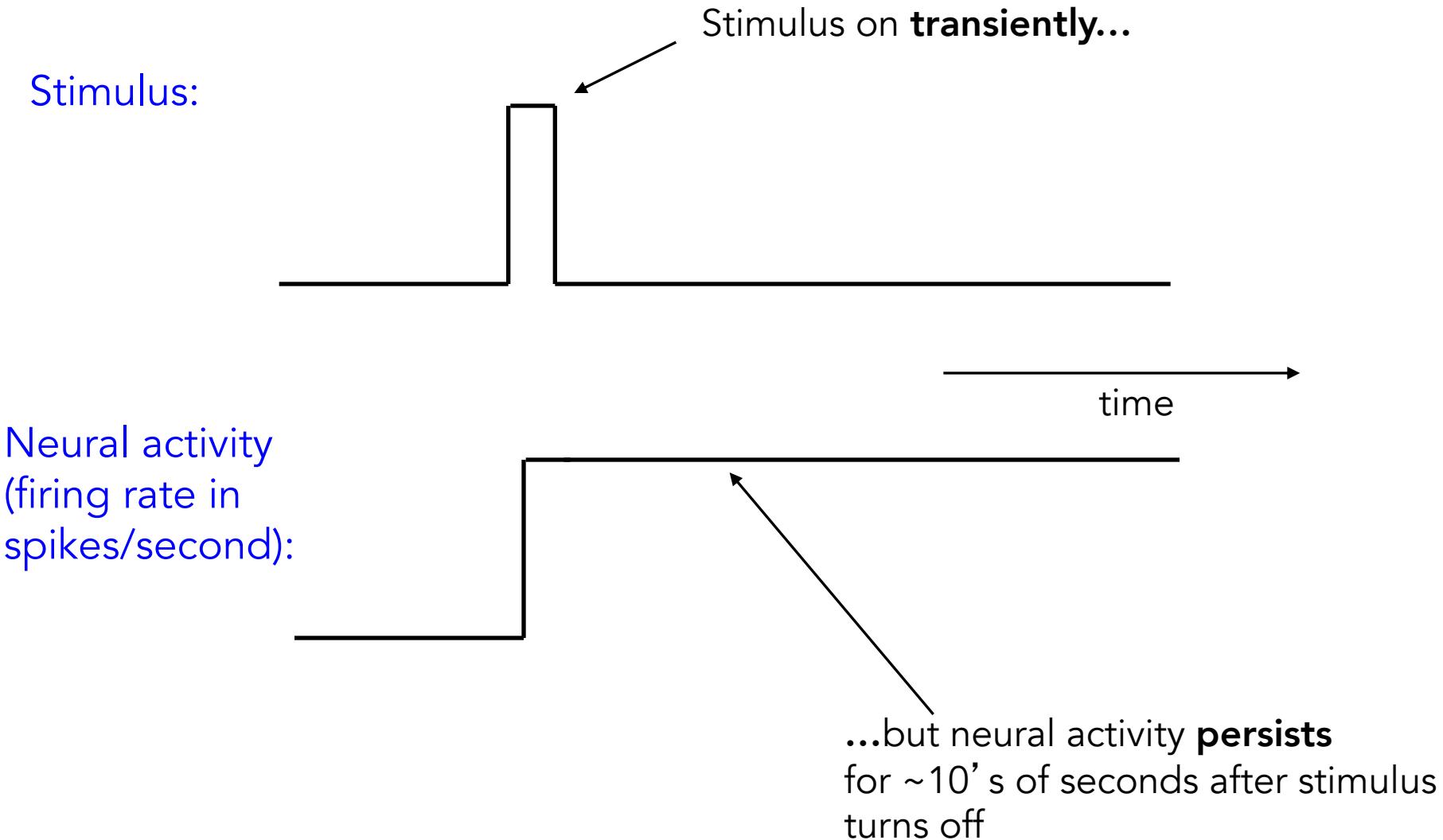
- Delay activity is selective for remembered cue location

Single neuron response to different memorized target locations:

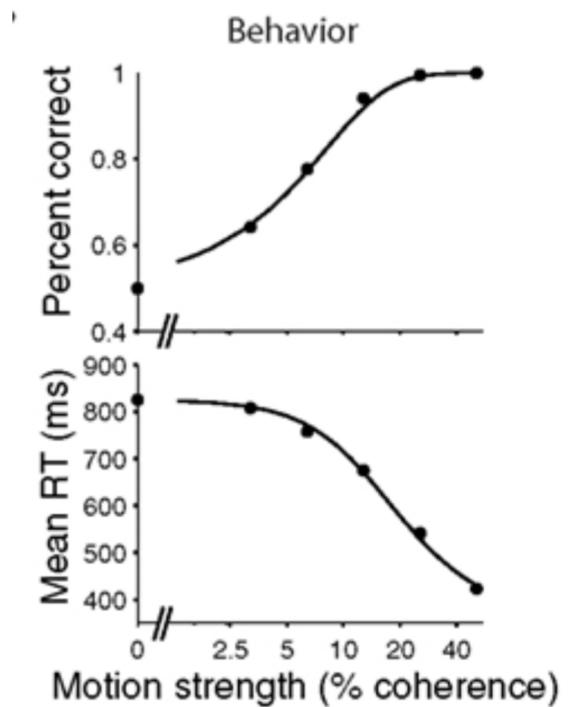
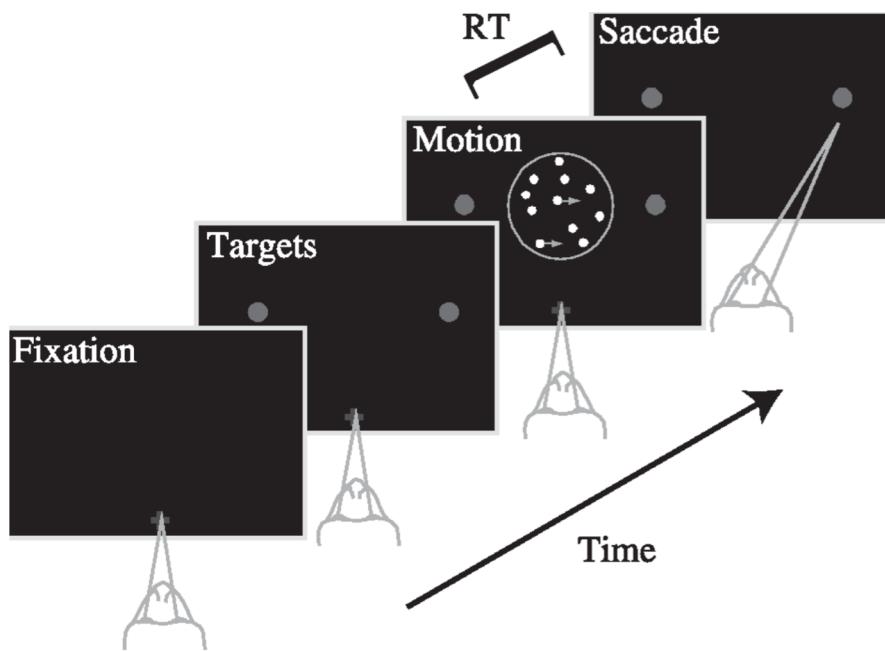


Short-term memory

- Persistent activity is the neural correlate of short-term memory

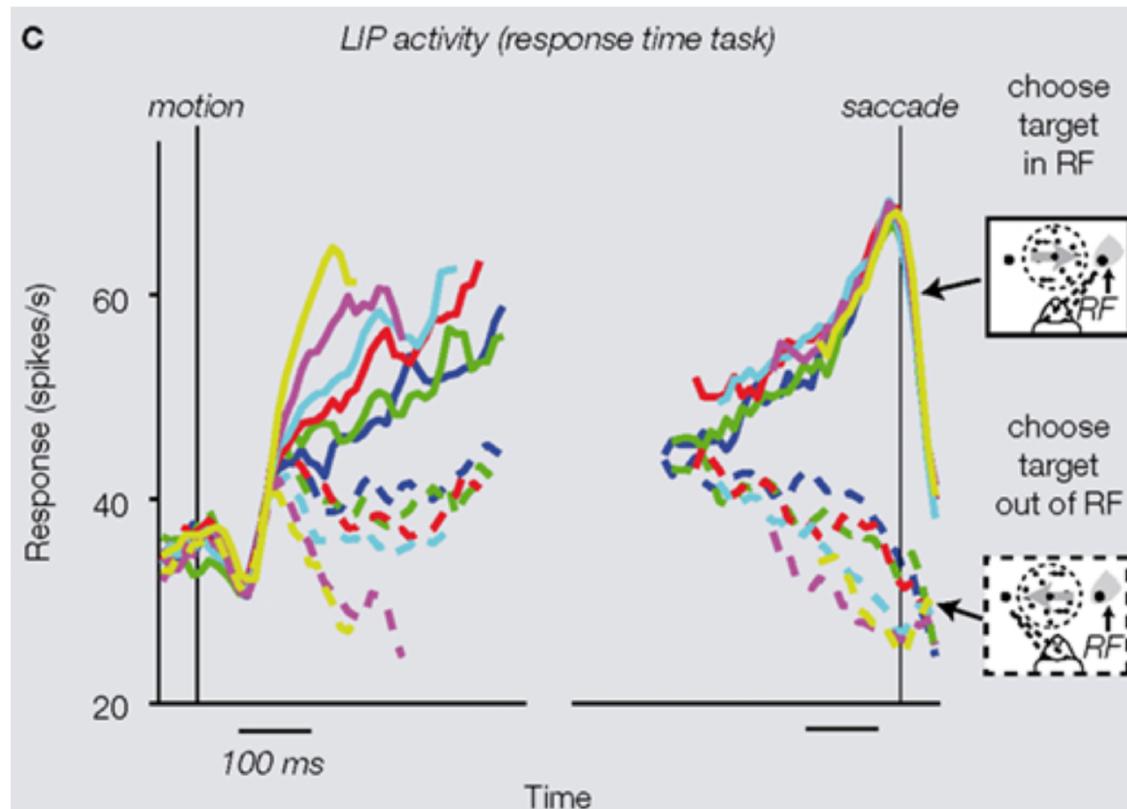


Evidence accumulation for decision-making





Evidence accumulation for decision-making

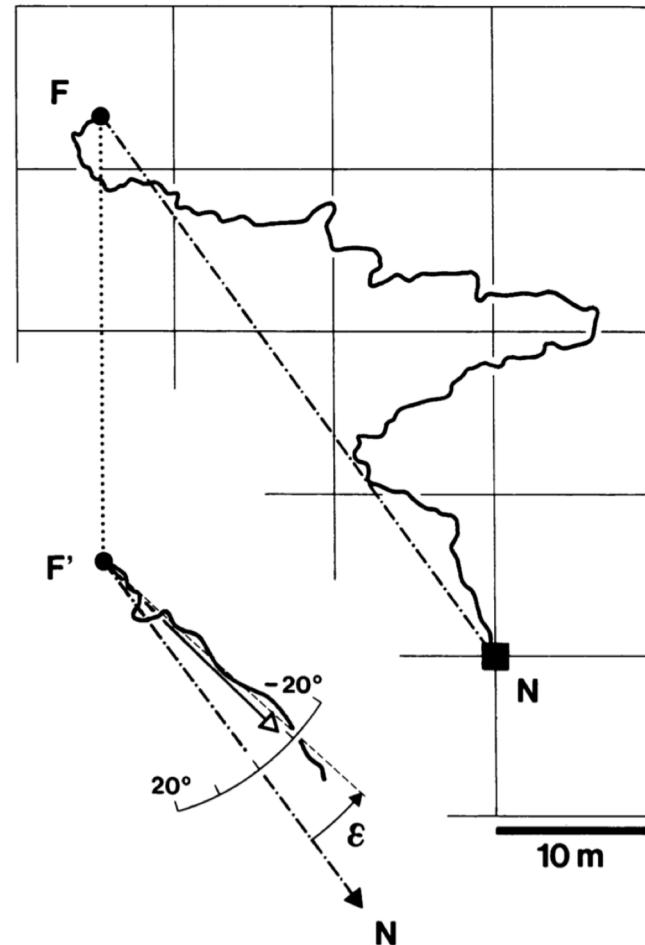
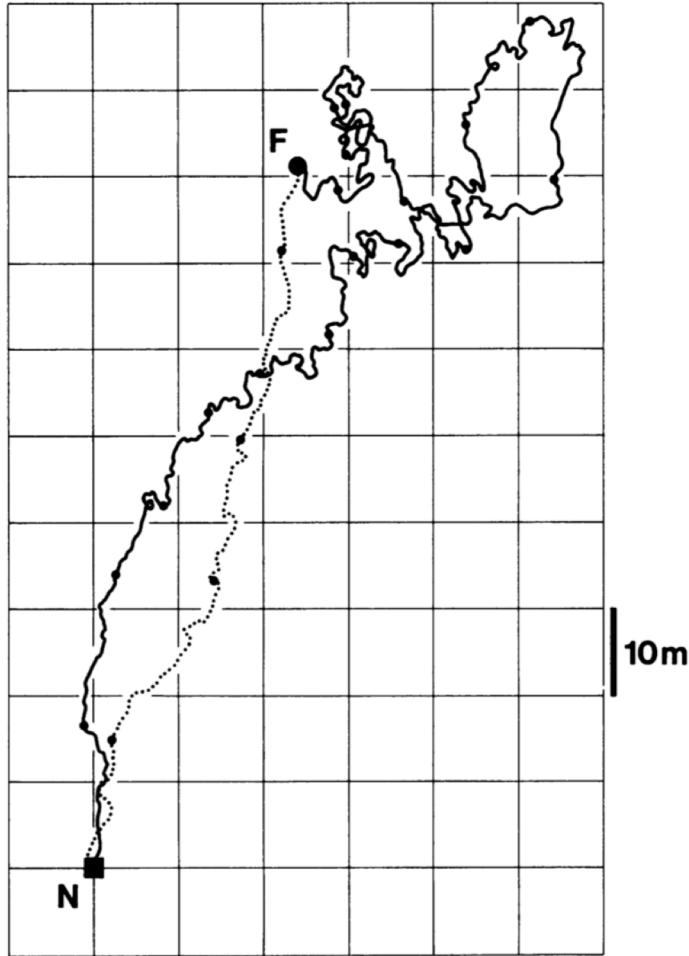


desert ants



Other Integrators

-Navigation by path integration:

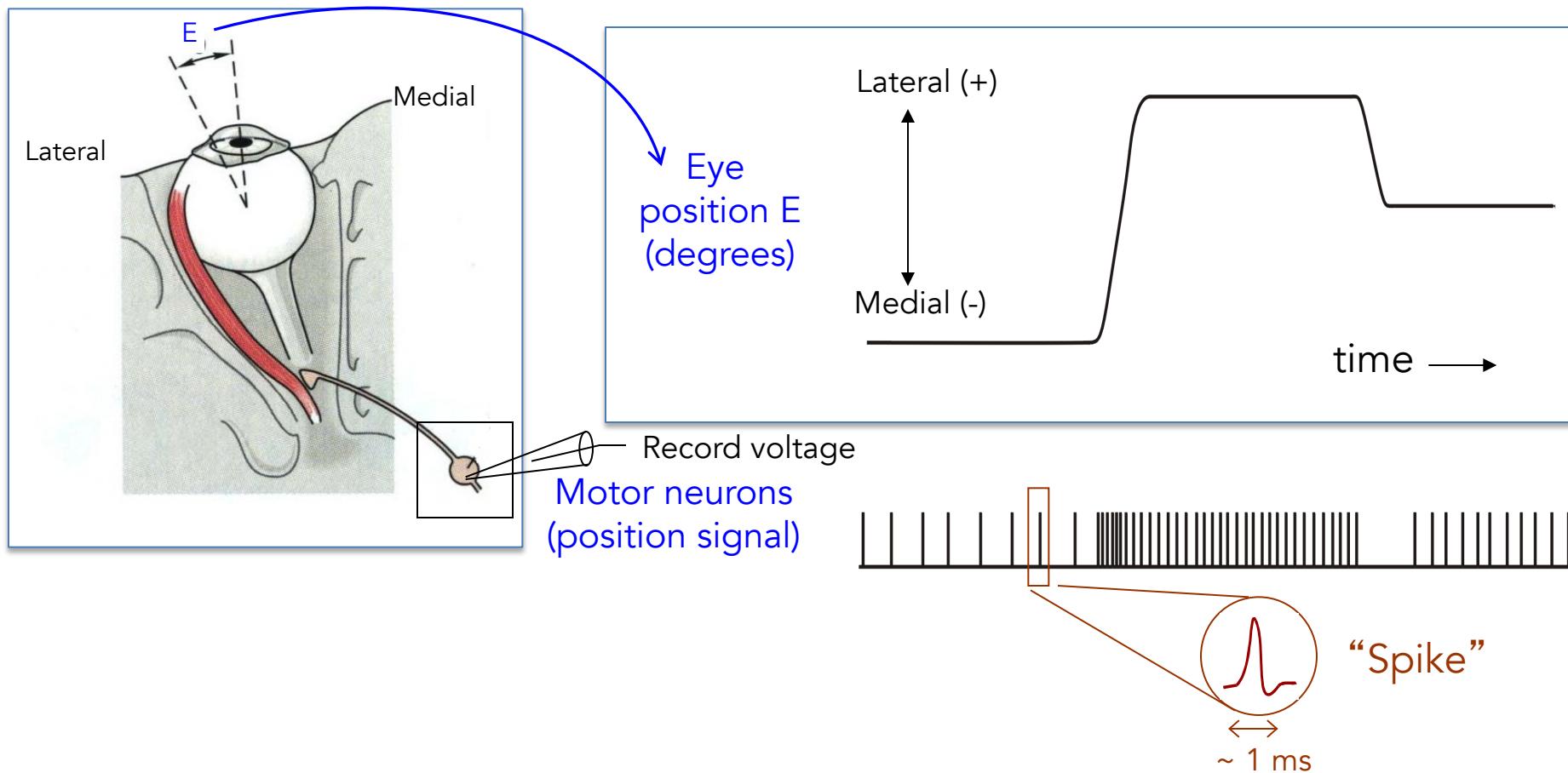


(Müller & Wehner, 1988)

Short-term memory in the eye-movement system



The eye-movement system



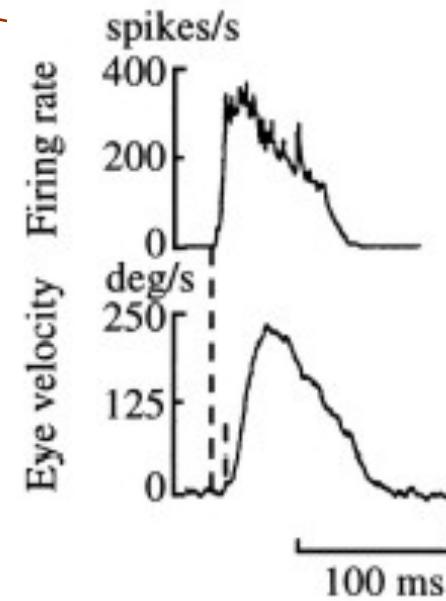
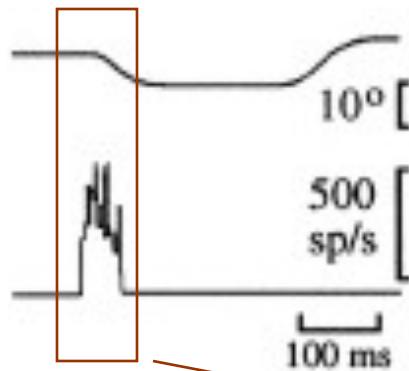
Saccade burst generator neurons

(adapted from Yoshida et al., 1982)

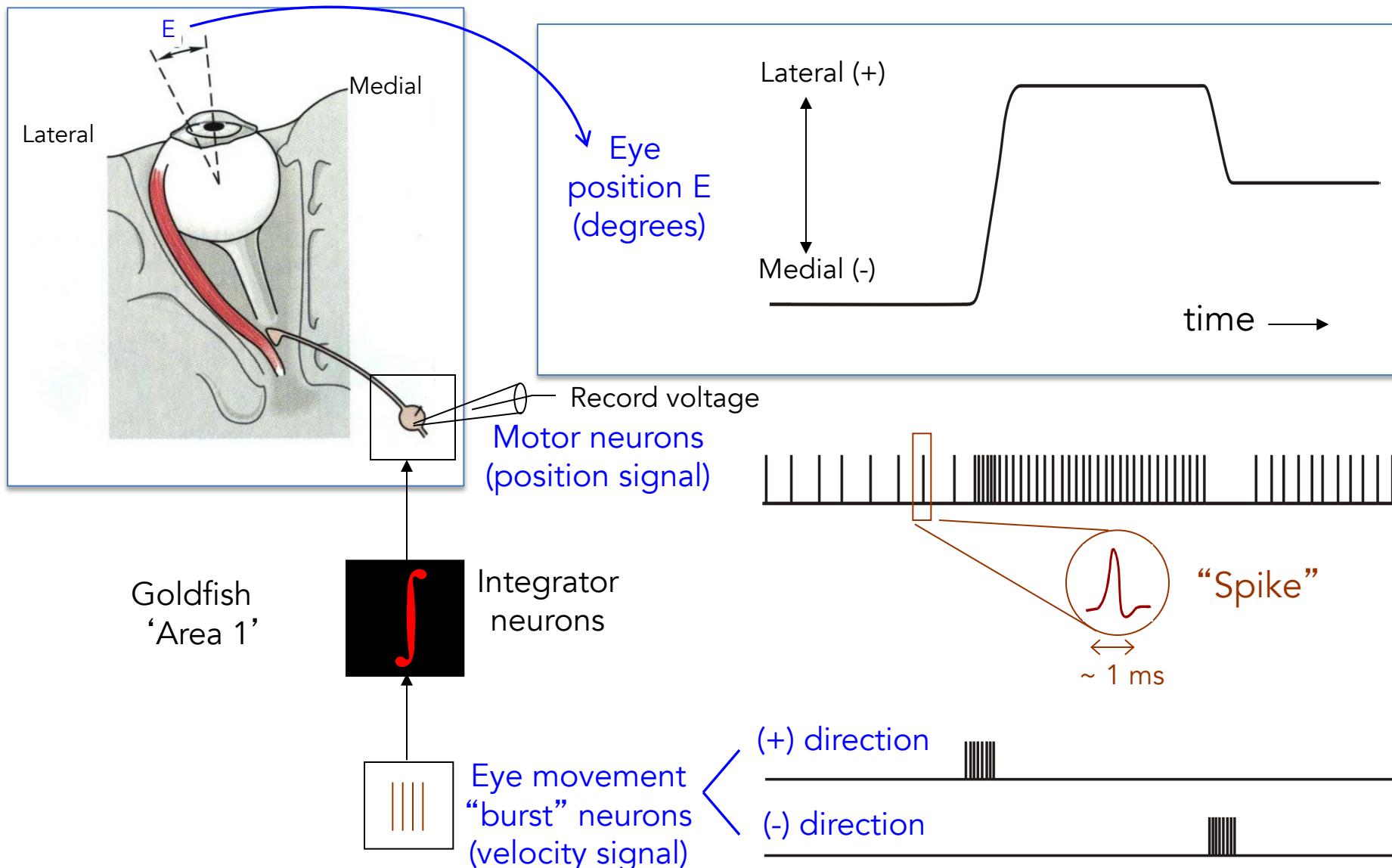
Eye Position
(degrees)

Eye movement neuron
firing rate (# spikes/sec)

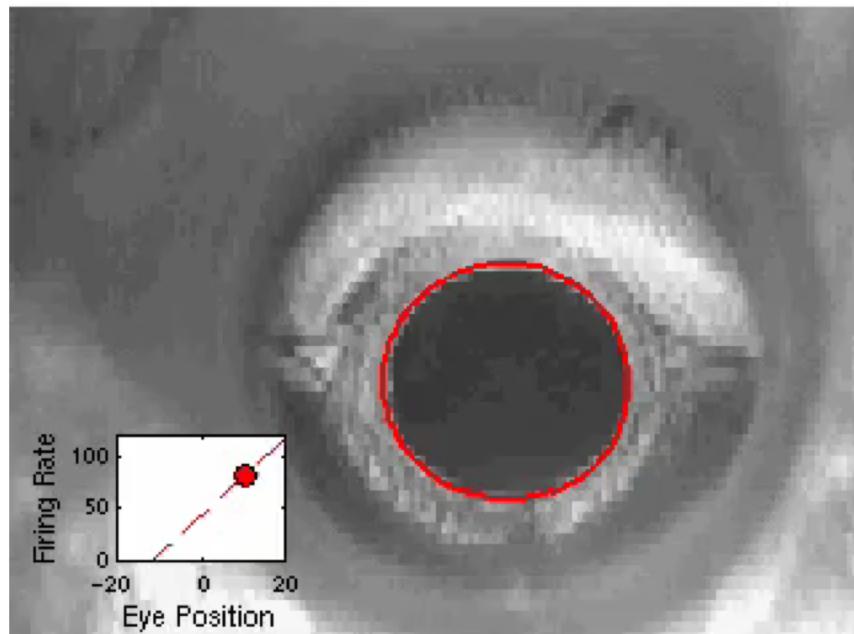
Burst neurons code
for eye velocity



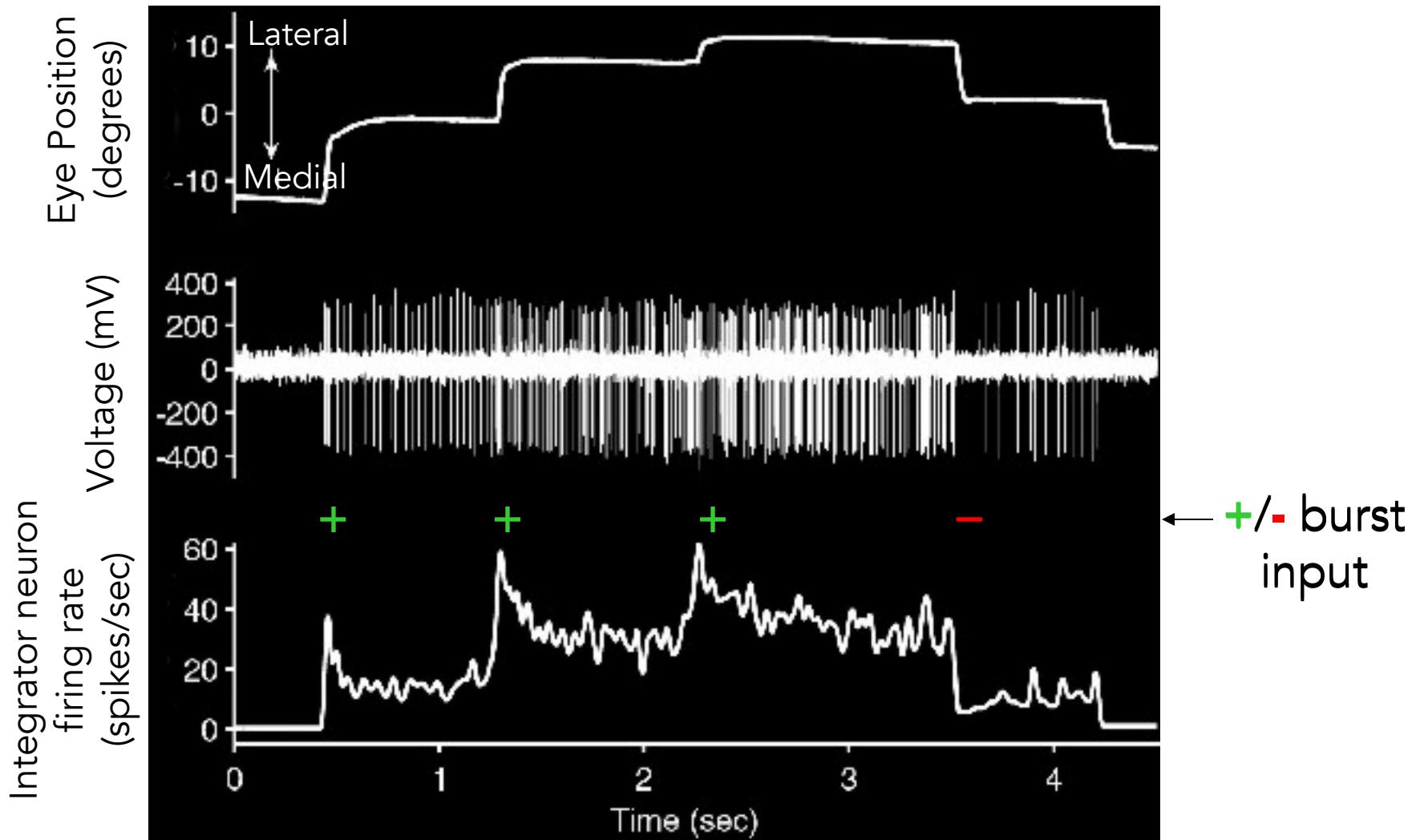
The eye-movement system



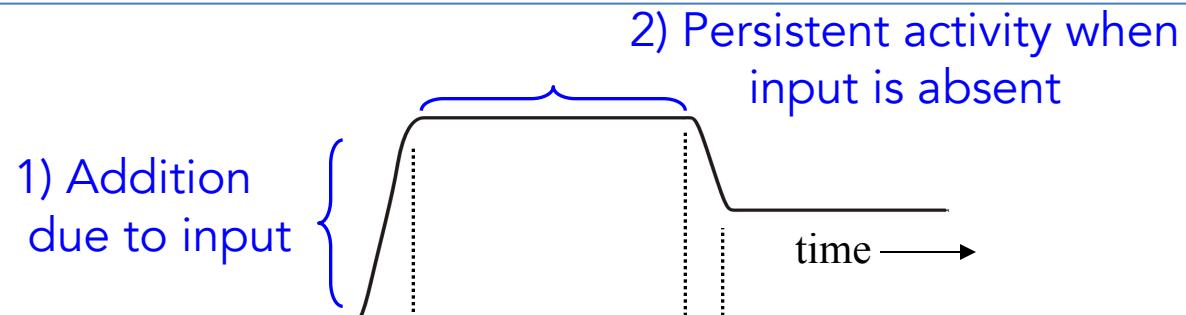
Integrator neurons



Integrator neuron carry an eye-position signal



How neurons integrate

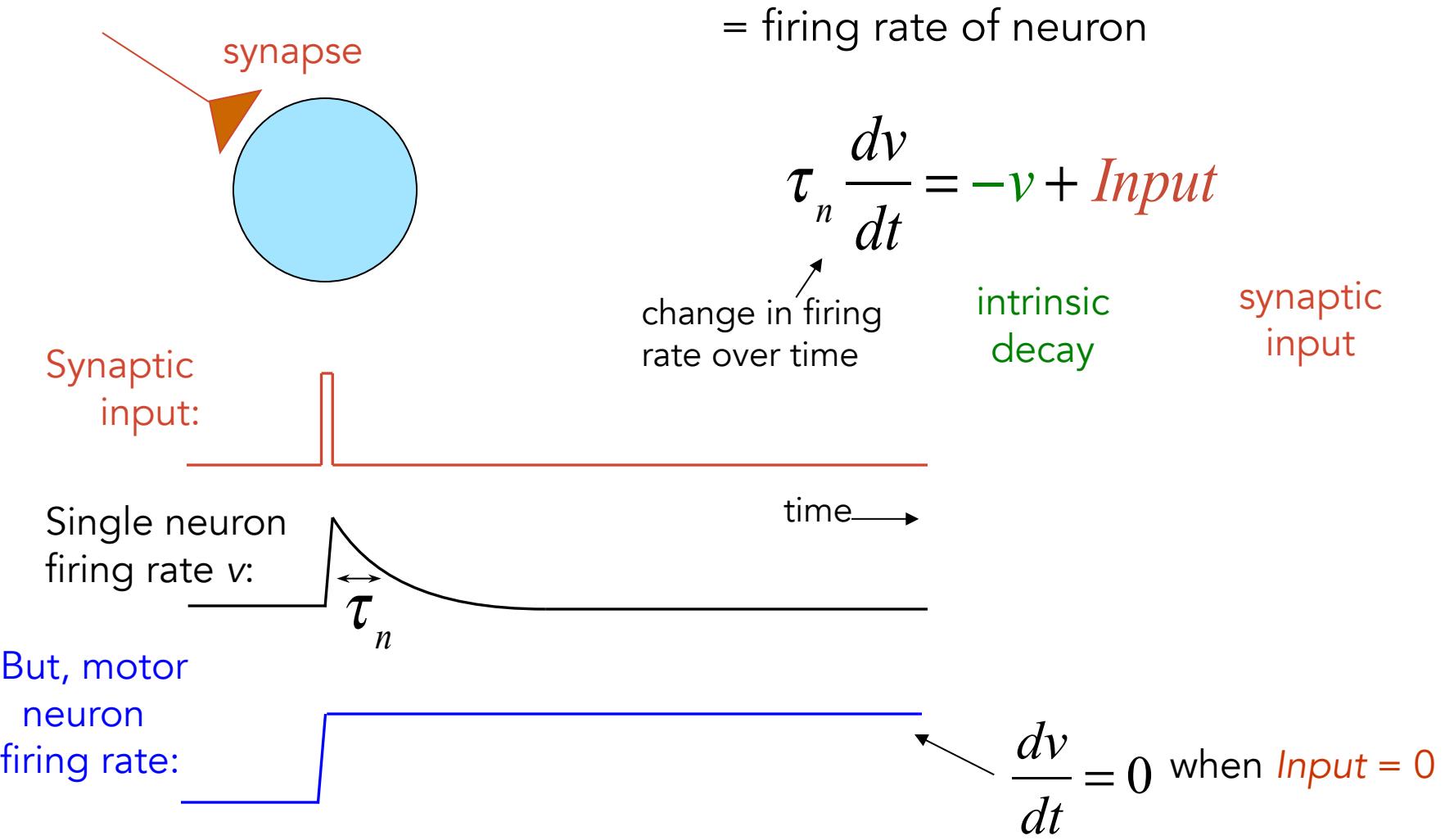


$$v(t) = \int h(t) dt$$

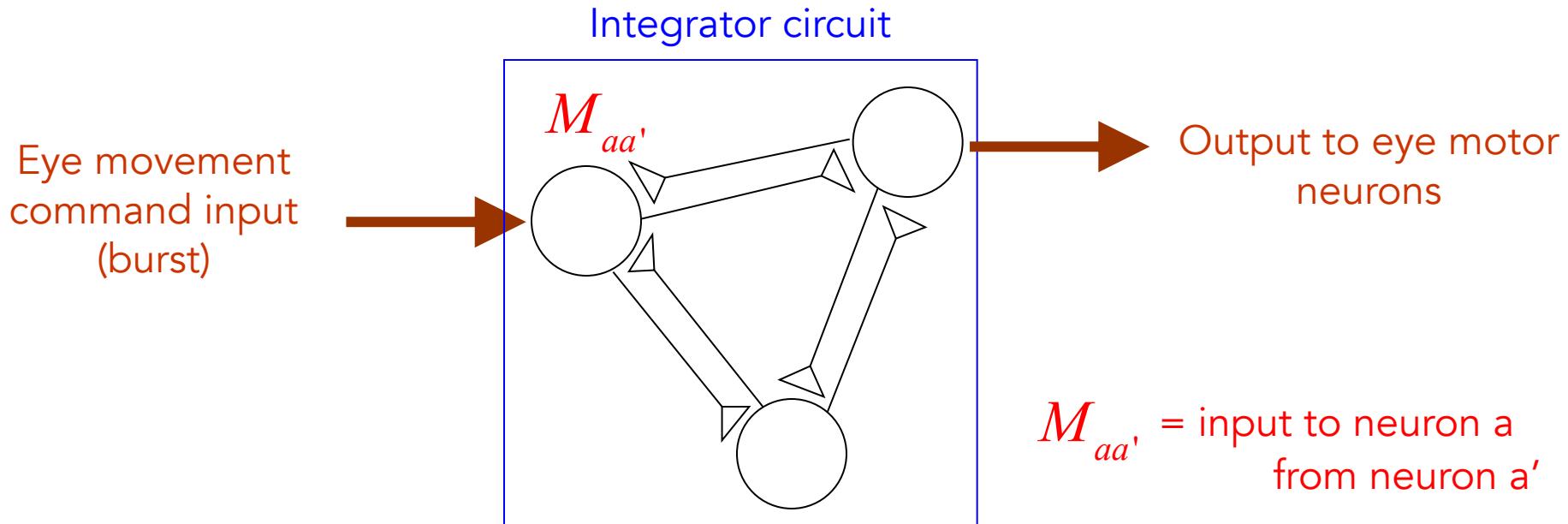
$h(t)$

time →

Basic model of a neuron



Network mechanism of persistence



$$\tau_n \frac{dv_a}{dt} = -v_a + \sum_{a'} M_{aa'} v_{a'} + \text{burst input}$$

~~Leak~~ ~~Feedback from other neurons~~

If Feedback balances Leak

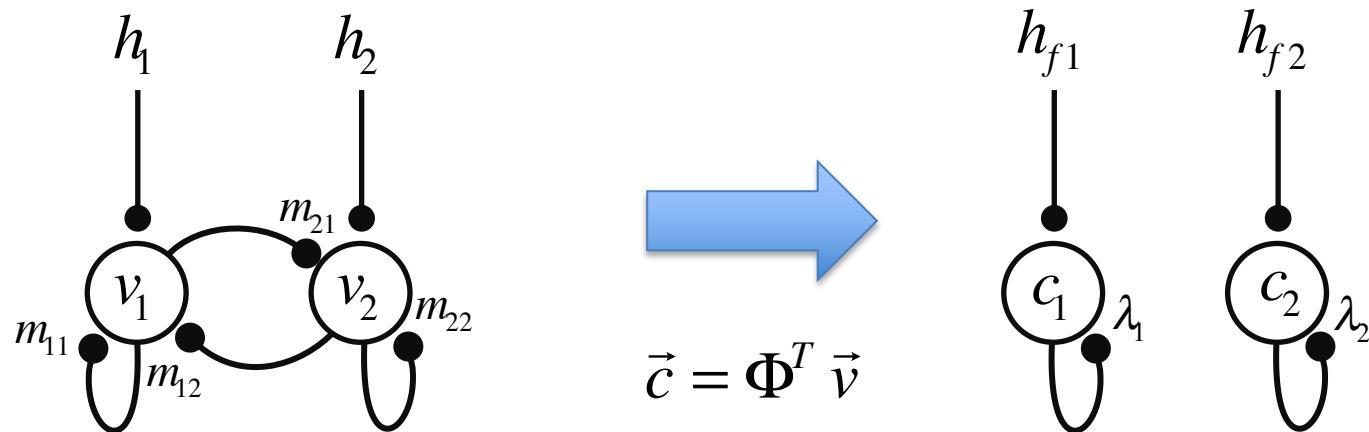
$$r = \frac{1}{\tau_{neuron}} \int (\text{burst input}) dt$$

Recurrent networks

- We saw how the behavior of a recurrent network can be described if M is symmetric.

$$M = \Phi \Lambda \Phi^T$$

$$M = \begin{pmatrix} m_{11} & m_{12} \\ m_{21} & m_{22} \end{pmatrix} \quad \Lambda = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} \quad \Phi = \left[\hat{f}_1 \mid \hat{f}_2 \right]$$



Network mechanism of persistence

- Eigenvectors:
- Most have eigenvalue $\ll 1$: rapid exponential decay after burst terminates
 - One has eigenvalue ≈ 1 :

Equation for component along this eigenvector: Between bursts

$$\rightarrow \tau_n \frac{dc_1}{dt} = -c_1 + \lambda_1 c_1 + \text{burst input}$$
$$\frac{dc_1}{dt} = \left(\frac{\lambda_1 - 1}{\tau_n} \right) c_1$$

If $\lambda_1 = 1$ → Perfect integrator!

feedback balances leak

$$c(t) = \frac{1}{\tau_{\text{neuron}}} \int (\text{burst input}) dt$$

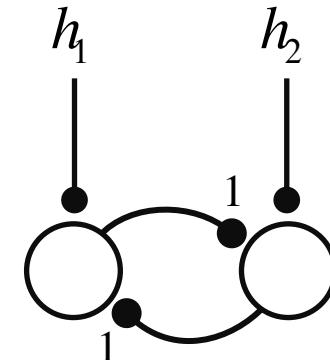
Integrating network

- Now let's look at a case where two output neurons are connected to each other by mutual excitation with synaptic strength of one.

What is the weight matrix?

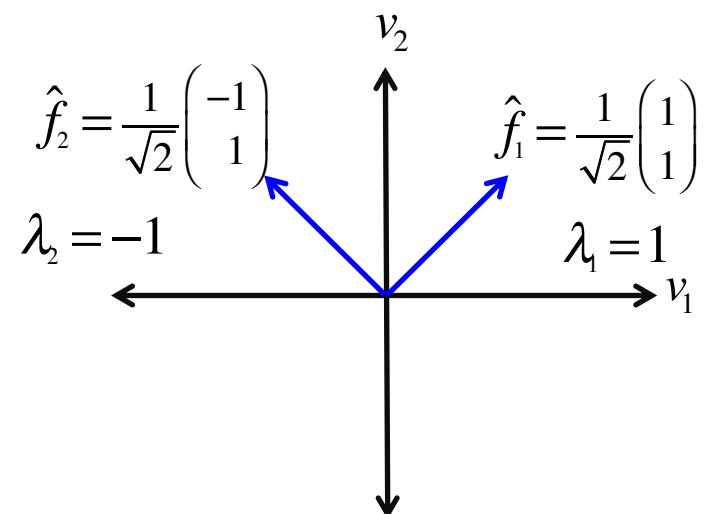
$$M = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$M\Phi = \Phi\Lambda$$



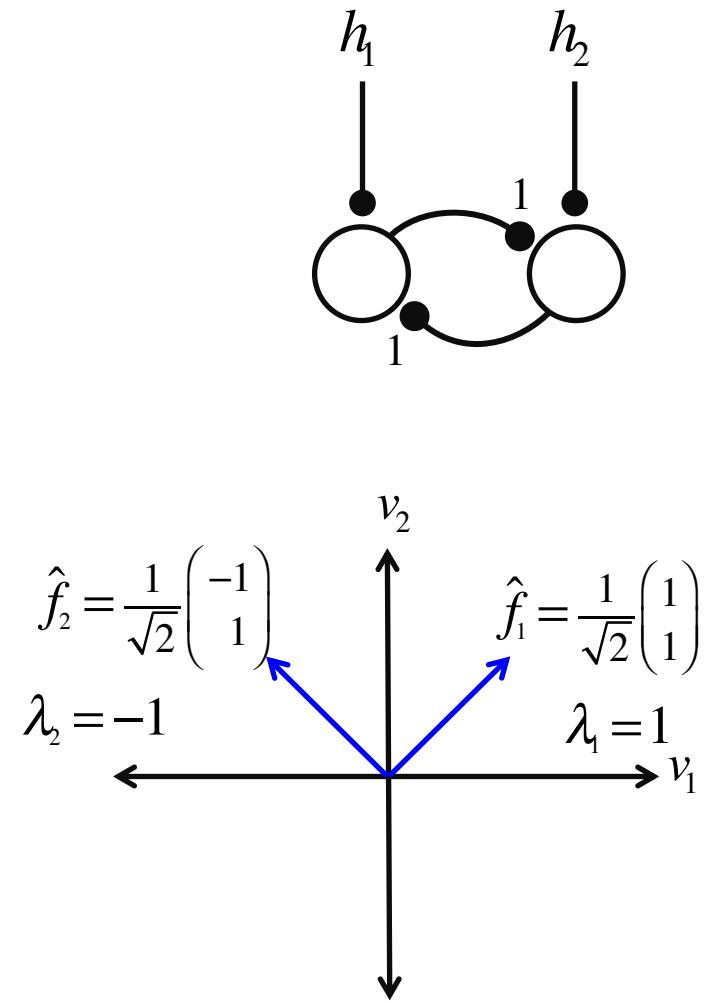
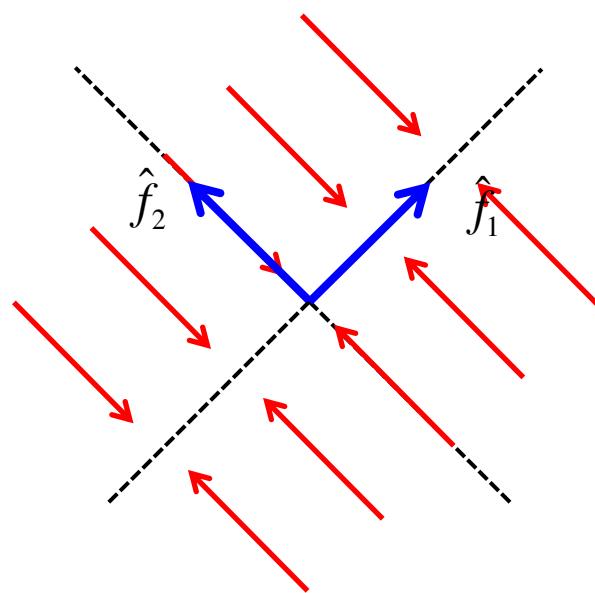
$$\Phi = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$$

$$\Lambda = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$



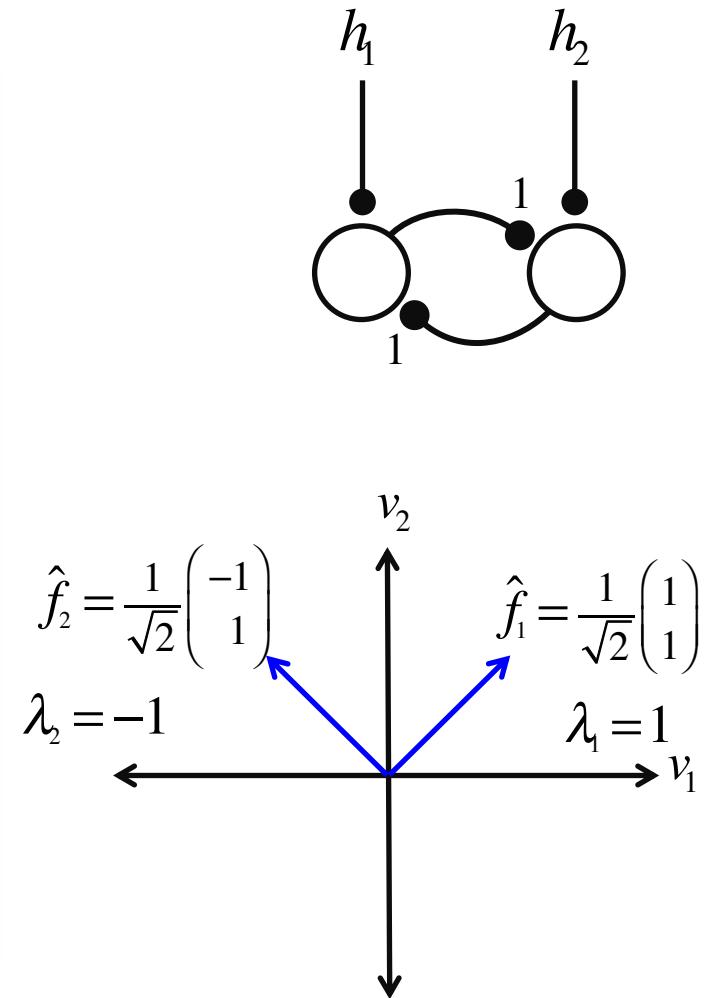
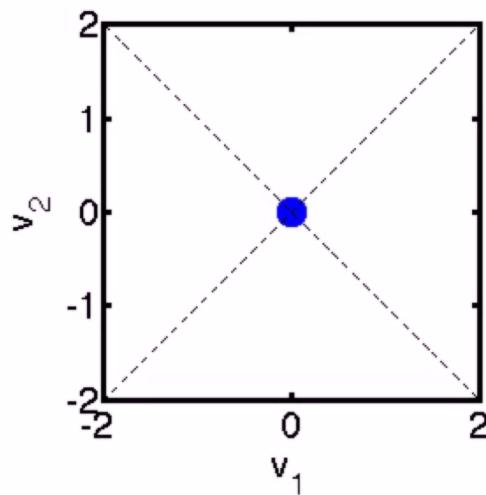
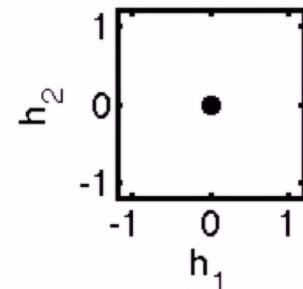
Recurrent networks

- If the input is parallel to the eigenvectors, then only one mode is excited.



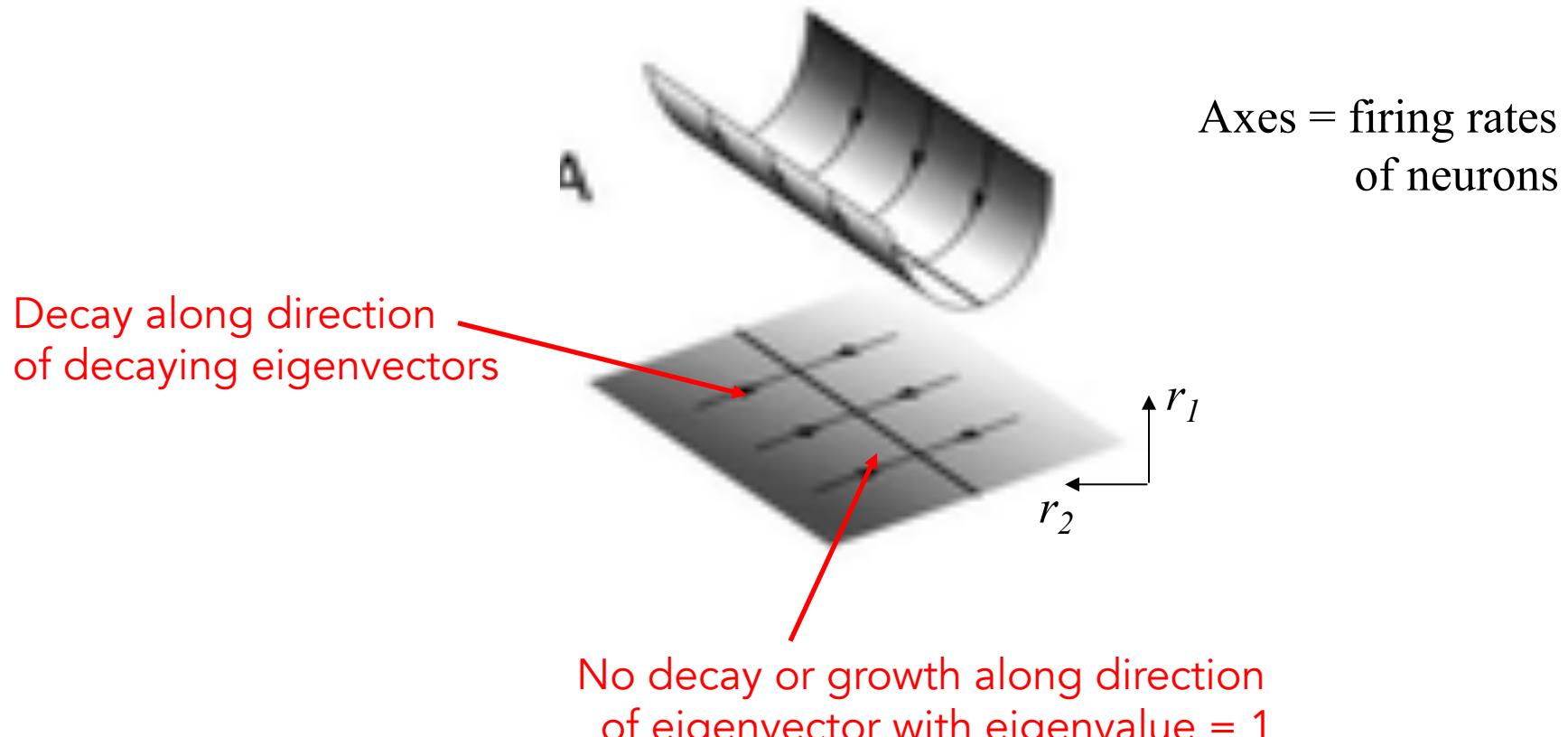
Recurrent networks

- If the input is parallel to the eigenvectors, then only one mode is excited.



Geometric interpretation

- Line attractor picture of neural integrator

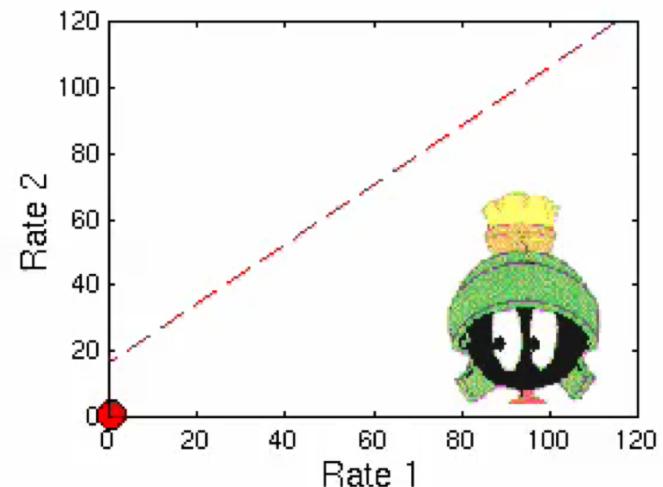
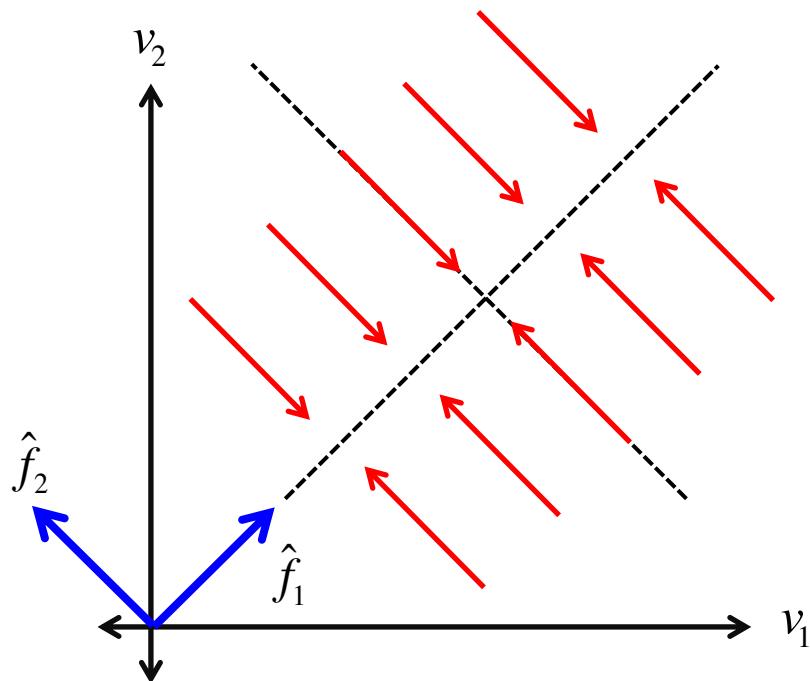


“Line Attractor” or “Line of Fixed Points”

Geometric interpretation

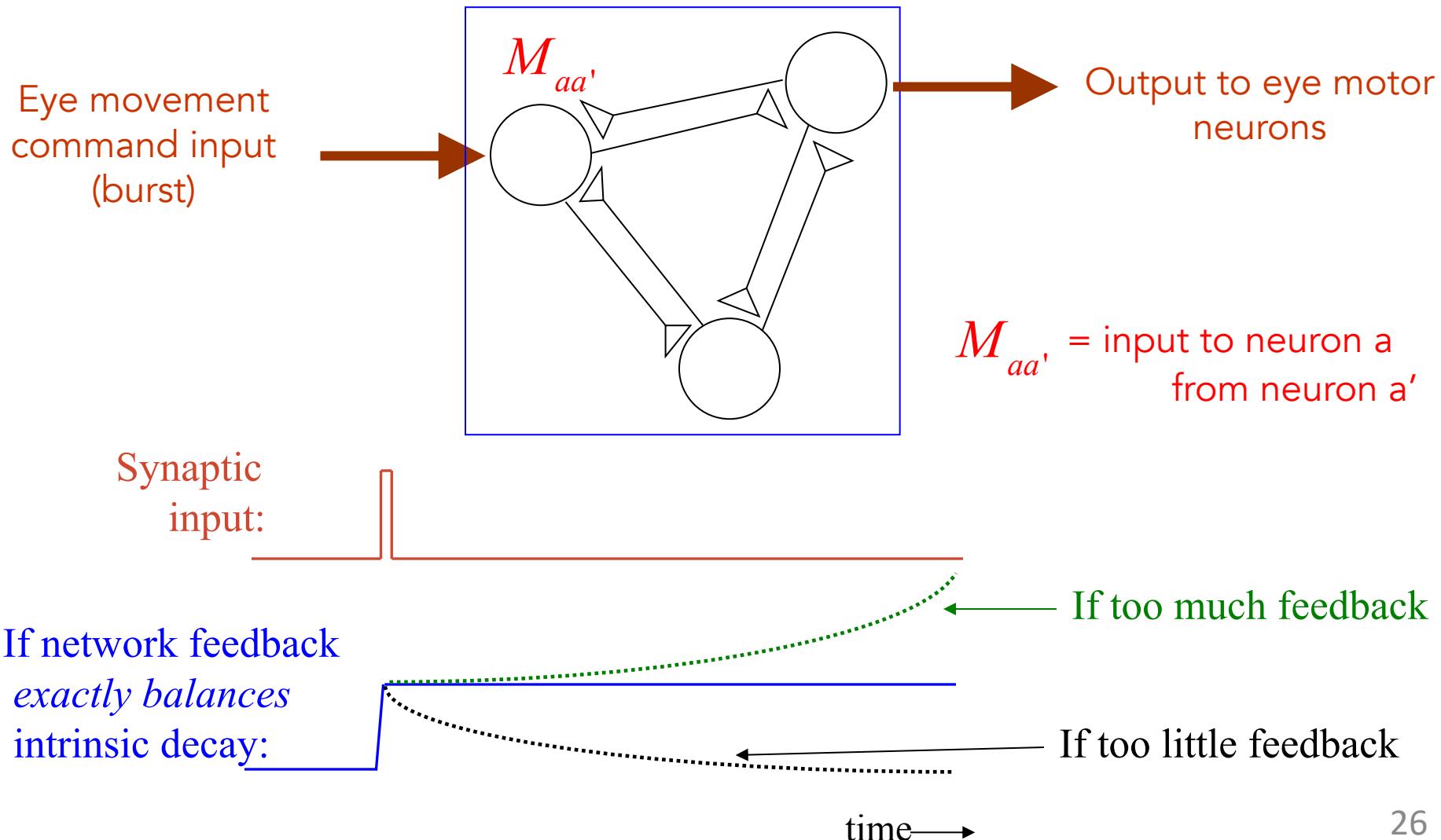
- Line attractor picture of neural integrator

Geometrical picture of line attractor



Perfect, leaky, and unstable integrators

- Network requires precise tuning of feedback strength



Perfect, leaky, and unstable integrators

Between bursts:

$$\frac{dc}{dt} = kc, \quad \text{where} \quad k = \frac{\lambda - 1}{\tau_n}$$

$\lambda = 1$: Perfect integrator

$$c(t) \sim \text{constant}$$

$\lambda < 1$: Leaky integrator

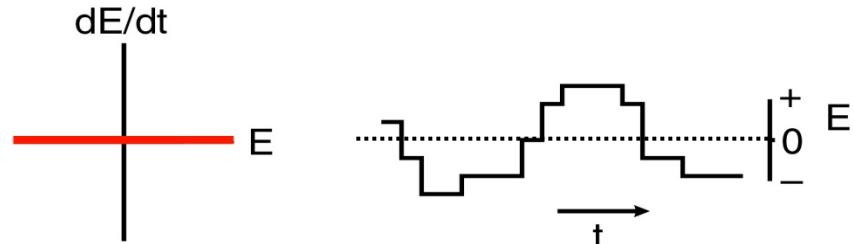
$$c(t) \sim e^{-|k|t}$$

$$\tau_{\text{leak}} = \frac{1}{|k|} = \frac{\tau_n}{1 - \lambda}$$

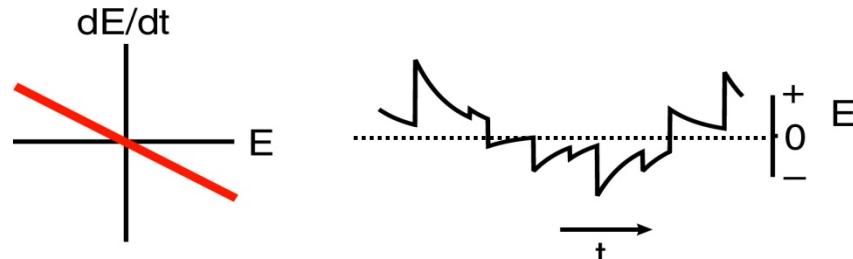
$\lambda > 1$: Unstable integrator

$$c(t) \sim e^{+|k|t}$$

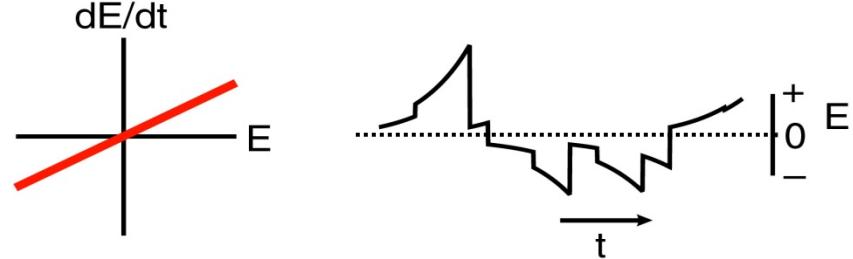
STABLE INTEGRATOR



LEAKY INTEGRATOR

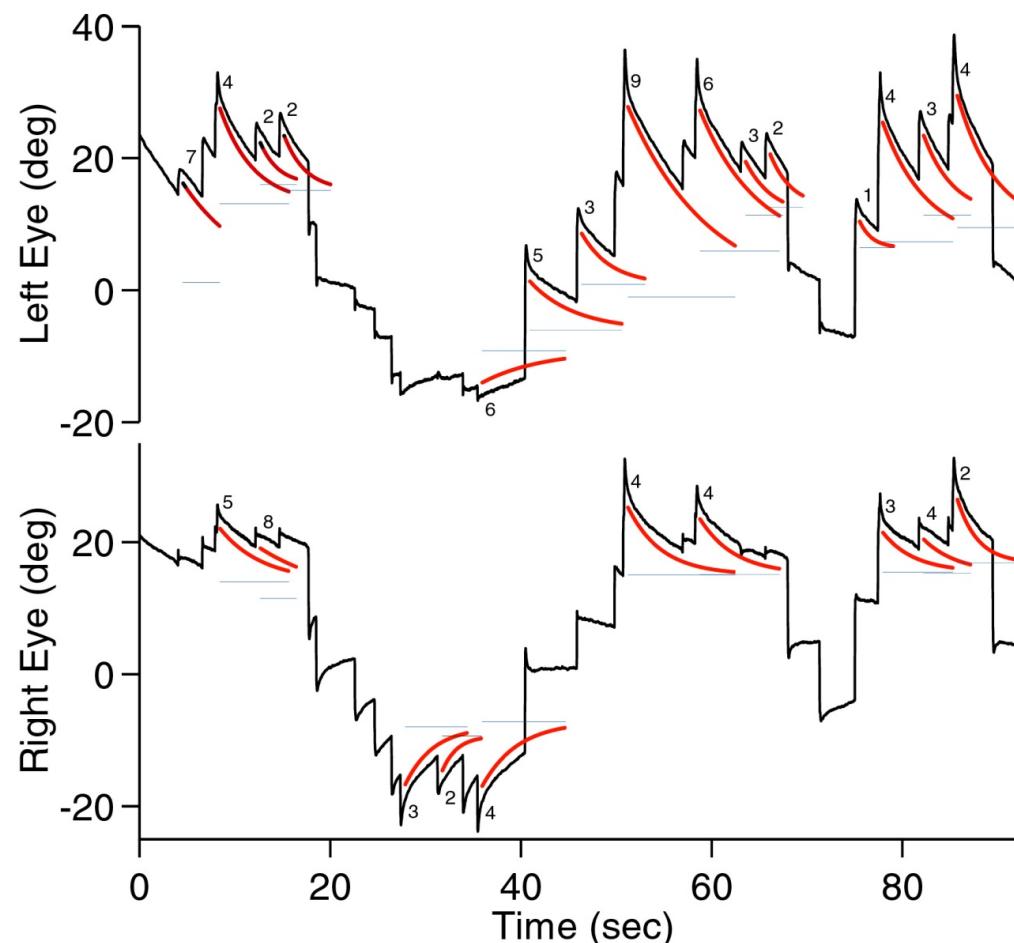


UNSTABLE INTEGRATOR



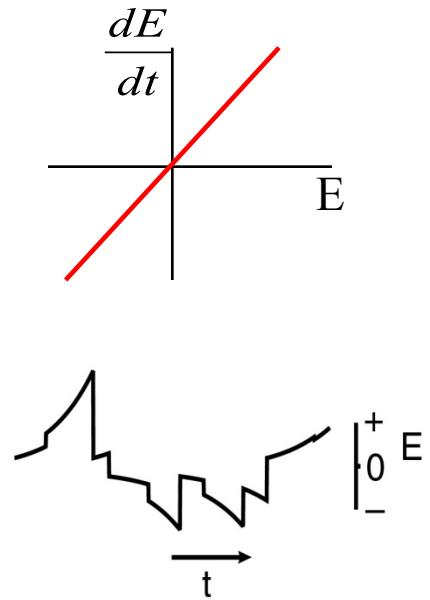
leaky integrator

- Experiment: reduce feedback in the integrator circuit with local anesthetic



unstable integrator

- Human patient with unstable congenital nystagmus



Unstable neural integrator!

Robustness of the integrator

Integrator equation: $\frac{dc}{dt} = \frac{(\lambda - 1)}{\tau_n} c + \text{burst input}$

Experimental values:

Single isolated neuron: $\tau_n \approx 10 - 100 \text{ ms}$

Integrator circuit: $\tau_{\text{network}} = \frac{\tau_n}{|1 - \lambda|} \approx 30 \text{ sec}$

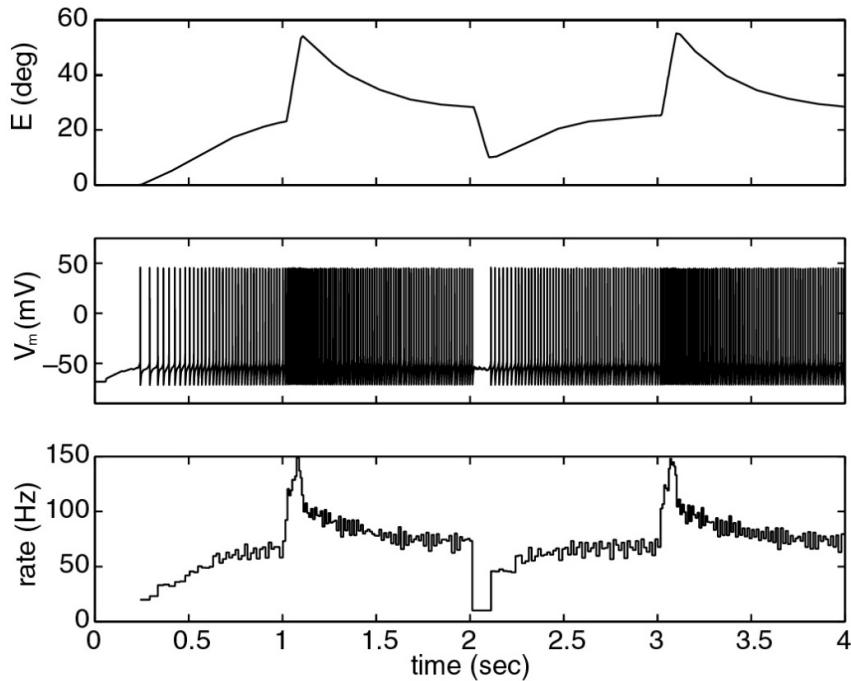
→ Synaptic feedback λ must be tuned to accuracy of:

$$|1 - \lambda| = \frac{\tau_n}{\tau_{\text{network}}} \approx 0.3\%$$

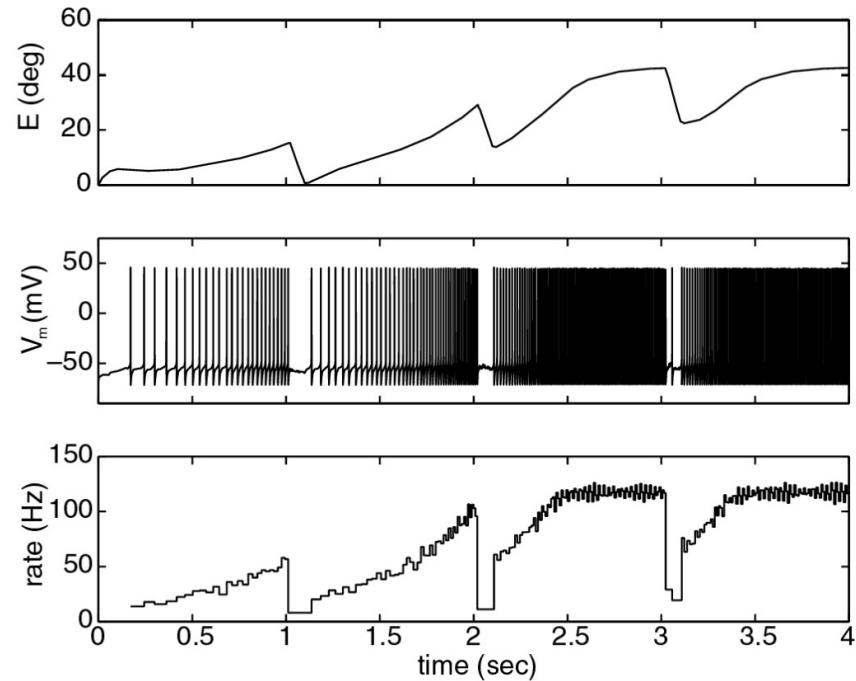
Robustness of the integrator

- Results with spiking network model

(Seung et al., 2000)



Leaky integrator
(synaptic weights
decreased 10%)



Unstable integrator
(synaptic weights
increased 10%)

Part III: Learning to Integrate

- How to accomplish fine-tuning of synaptic weights?

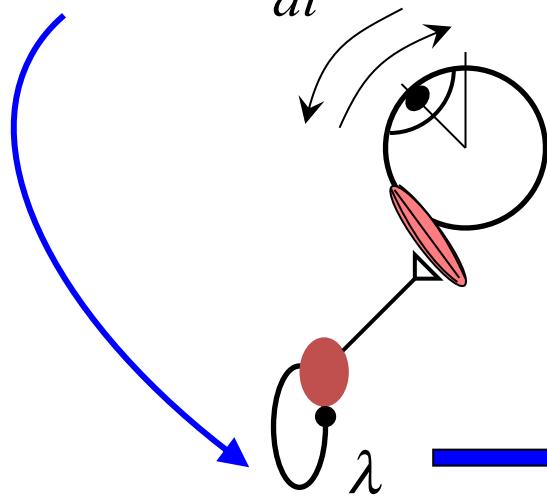


IDEA: Synaptic weights learned from “image slip”

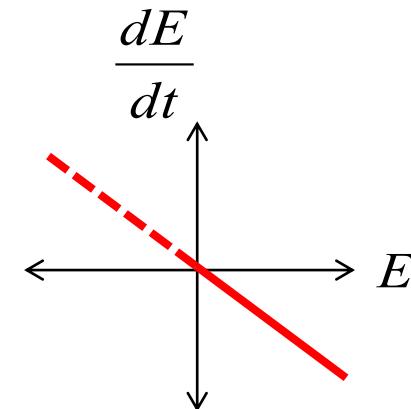
(Arnold & Robinson, 1992)

- Imagine we have a leaky integrator

$$\text{Image slip} = -\frac{dE}{dt}$$



$$\text{Eye slip (decay)} = \frac{dE}{dt} < 0$$

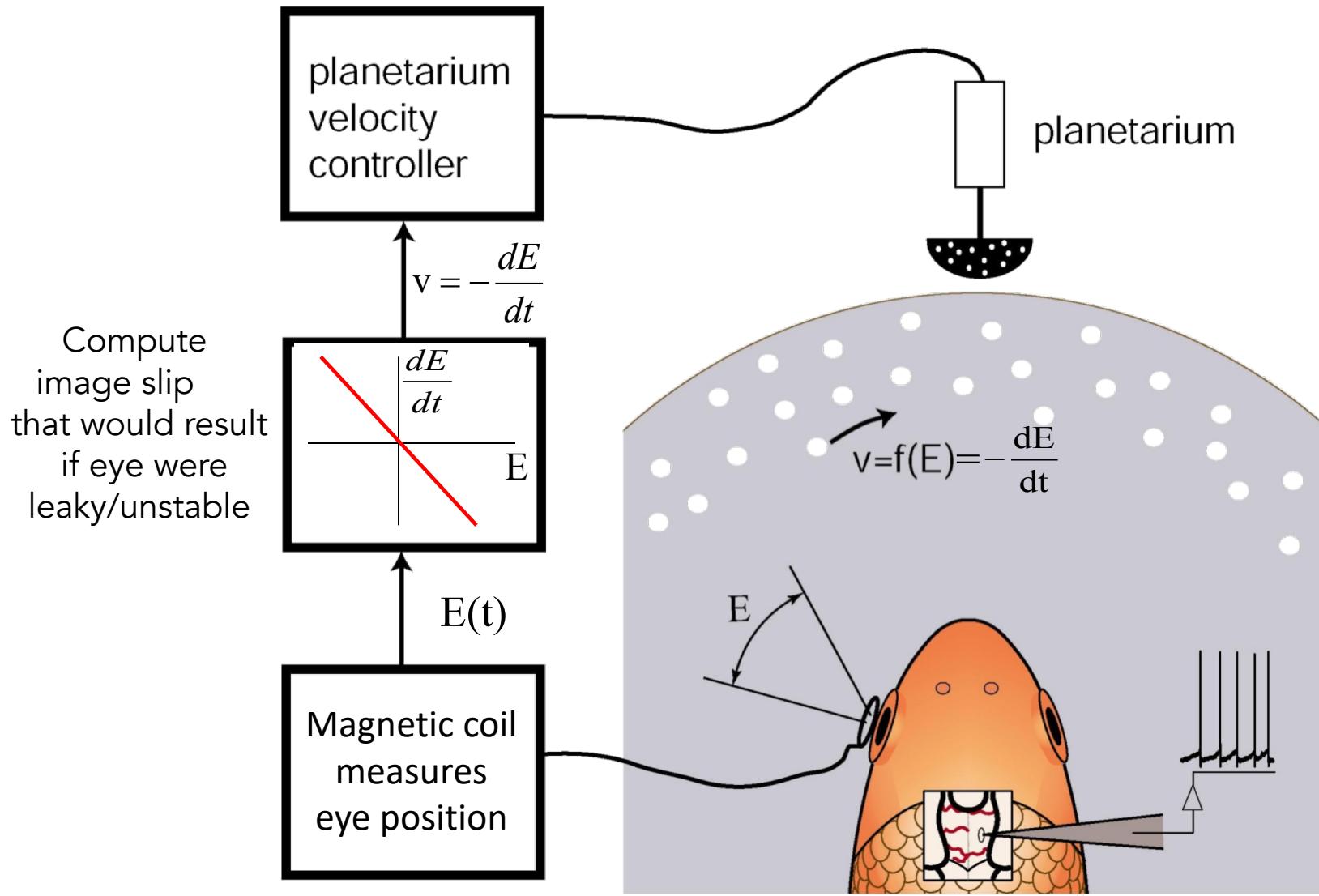


Need to turn up feedback

$$\Delta\lambda \propto -\frac{dE}{dt}$$

Learning to Integrate

- Experiment: Give feedback as if integrator is leaky or unstable



Learning to Integrate

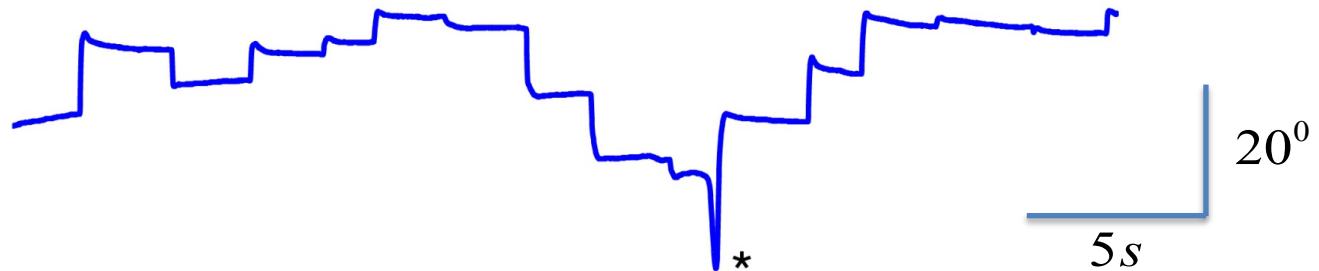
- Experimental setup for tuning integrator



Learning to Integrate

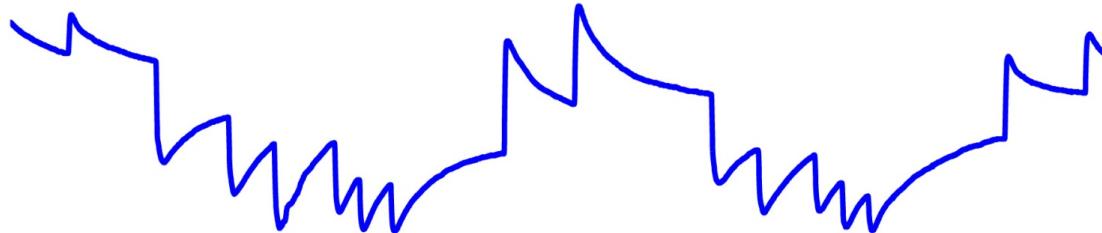
- Integrator can be trained to become leaky or unstable

Control (in dark):



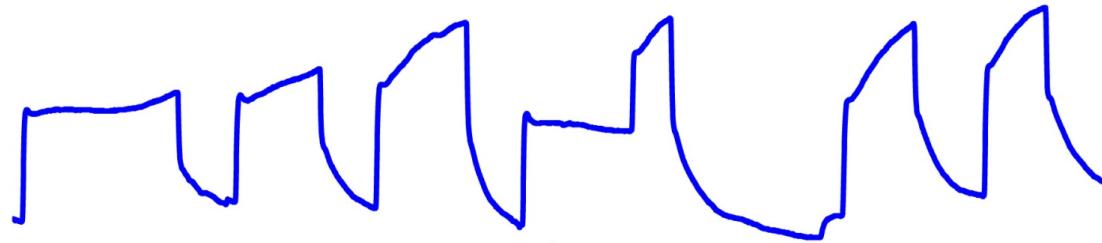
Give feedback
as if unstable

→ Leaky:



Give feedback
as if leaky

→ Unstable:



Summary and open questions

I. Goldfish do integrals!

$$Eye\ Position = \int Eye\ Velocity\ dt$$

Integrator neurons burst input

II. How goldfish do integrals: neural mechanism

- Network feedback balances leakiness of neurons
- But...model is less robust than real integrator

III. Goldfish learn to do integrals!

- Integrator compensates for image slip
- How and where does learning occur?
Synapse modification? Intrinsic neuronal modification?
- Is visual feedback the only learning signal?

Acknowledgements

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Mark Goldman

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David Tank

Guy Major (Cardiff Univ.)

Emre Aksay (Cornell Med.)

N.Y.U.

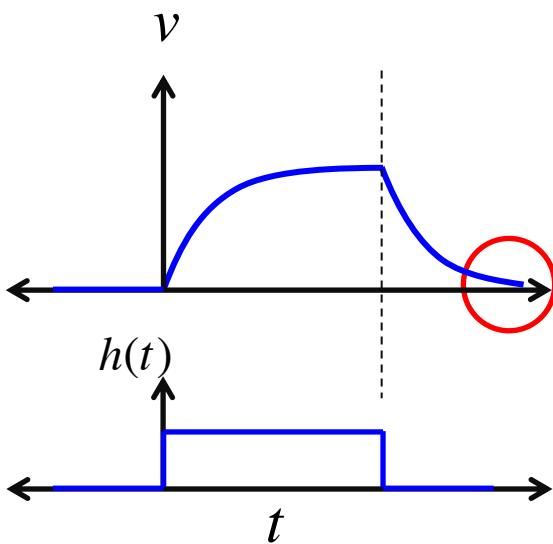
Bob Baker

Recurrent networks

- The behavior of the network depends critically on λ

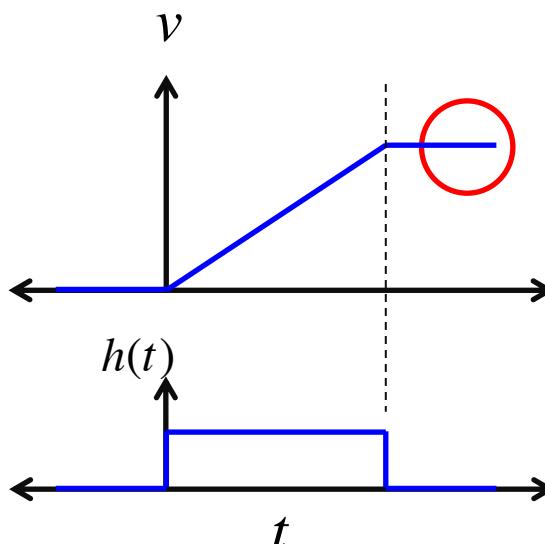
$$\lambda < 1$$

Exponential relaxation



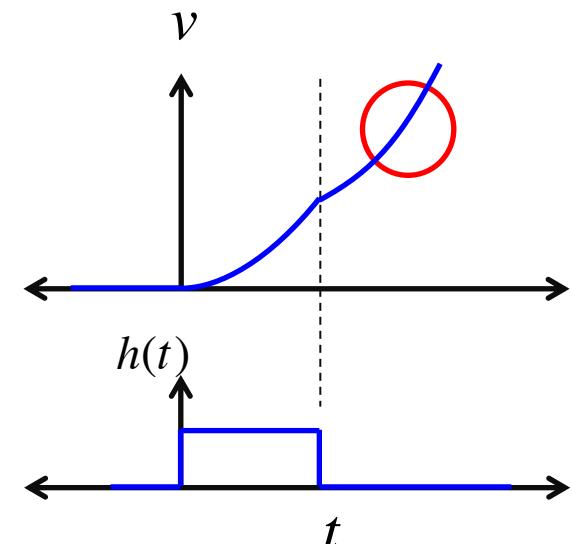
$$\lambda = 1$$

Integration



$$\lambda > 1$$

Exponential growth



With zero input...
relaxation back to zero

With zero input...
persistent activity!

MEMORY!