

# TARUNKUMAR PALANIVELAN

Phone: +1 (347) 513-9454    Email: [tarun002kumar@gmail.com](mailto:tarun002kumar@gmail.com)    LinkedIn: <https://www.linkedin.com/in/tarunkumarp>

## EDUCATION

<b>New York University - Tandon School of Engineering, New York</b> <i>Master of Science, Mechatronics and Robotics</i>	Pursuing (2024-2026)
<b>SRM Institute of Science and Technology, Chennai</b> <i>Bachelor of Technology, Mechatronics with Specialization in Robotics</i>	2020-2024 GPA: 8.43/10

## TRAININGS

<b>Agile Robotics and Perception Lab, New York University</b> <i>Graduate Research Assistant</i>	Sept 2024 - ongoing
<ul style="list-style-type: none"><li>Conducted inertial measurement testing of quadrotors using Vicon motion capture, analyzing moments along each axis to evaluate dynamic performance and stability</li><li>Engaged in safety piloting of quadrotors, ensuring controlled operations with safety protocols</li><li>Designed CAD components and assemblies for the quadrotor platform, calibrated PX4, and integrated it with Jetson Orin for autonomous operations</li></ul>	
<b>Garuda Aerospace, Chennai</b> <i>Manufacturing and Assembly Intern</i>	June 2023 - July 2023
<ul style="list-style-type: none"><li>Assembled and tested agricultural drones under 25 kg, conducting quality inspections prior to flight testing</li><li>Engaged in mapping and path planning using QGroundControl for the Droni surveillance drone, performing pre-flight protocols and inspection checks before each flight test</li></ul>	
<b>Aerospace Systems Research Laboratory</b> <i>Team Lead</i>	May 2021 – May 2024
<ul style="list-style-type: none"><li>Led a team of 40 in drone design, material selection, and fabrication, overseeing development for competitions and projects</li><li>Directed the High-Maneuverability Drones category at the ‘World Robotics Championship’ by Technoxian, focusing on acrobatics and FPV drones</li><li>Collaborated with startups and corporate sponsors to present projects at tech expos to government and industry representatives</li></ul>	

## TECHNICAL SKILLS

**Programming Languages:** C | C++ | Python | Embedded C | MATLAB | Java | HTML/CSS  
**Software Skills:** Matlab/Simulink | ROS | SolidWorks | Fusion 360 | Ansys | Catia | AutoCAD | ArduPilot/Mission Planner | QGroundControl | PX4 | JYI K++ | INAV | XFLR5 | MS Word | MS Power Point | MS Excel | LaTeX

## COURSES & CERTIFICATIONS

- Obtained certifications in:
- Certified SolidWorks Associate (CSWA) in Mechanical Design – Dassault Systèmes (2023)
  - Certified SolidWorks Associate (CSWA) in Additive Manufacturing – Dassault Systèmes (2023)
  - Certified SolidWorks Associate (CSWA) in Electrical – Dassault Systèmes (2023)
  - Internet of Things – IIT Kharagpur (NPTEL) (2022)

## ACHIEVEMENTS

- Secured 1st place in *Rotorcraft 2024*, conducted by NITTE University, winning a cash prize of 100,000 INR (2024)

## RESEARCH PAPER

- Rathod, A., & Tarunkumar T. (2023). Enhancing Crime Scene Investigation with Drone Technology: The potential of unmanned aerial vehicles in streamlining evidence collection and analysis. *IJCSPUB (International Journal of Current Science)* March 2023

## PROJECTS

<b>Reconfigurable UAV+UGV</b>	Jan 2024 – April 2024
<ul style="list-style-type: none"><li>Developed an autonomous UAV-UGV transformable prototype inspired by the Caltech M4 bot, optimizing actuators and integrating Raspberry Pi for sensor data and telemetry. Conducted FEA, CFD, and topology analyses, earning a perfect score in my final year project.</li></ul>	
<b>Zeus</b>	Jan 2024 – Feb 2024
Developed a drone with a 1:1 weight-to-payload ratio and successfully executed an autonomous mission at Rotorcraft 2024, hosted by NITTE University, securing the first-place award.	
<b>Phoenix</b>	Oct 2023 – Dec 2023
<ul style="list-style-type: none"><li>Designed a high-altitude drone with a 1kg payload capacity and developed a MoliceL battery pack to enhance endurance over lithium polymer batteries. Successfully tested an autonomous mission at an altitude of 0.62 miles at NARL.</li></ul>	
<b>ROV</b>	Aug 2023 - Nov 2023
<ul style="list-style-type: none"><li>Designed and developed a compact 6-thruster ROV (300x300x200mm) with automatic resurfacing for safety and tethered operation. Successfully demonstrated its diving and traversing capabilities.</li></ul>	
<b>Spiderbot</b>	Jan 2023 - May 2023
<ul style="list-style-type: none"><li>Developed kinematics and control systems for robotic leg movement. Designed the internal circuit, integrating microcontrollers with sensors and wireless transmission modules.</li></ul>	