17-05-2020

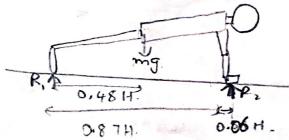
ME6230: END-SEMESTER

TAKE-HOME EXAM.

S. TARUN PRASAD ME178114

-> My Height: 170 cm. -> My Weight: 86 kg.

(1.) [i.) Plank;



Balancing moment about foot.

= 434,99 N. 0.8710.06

=> R, = mg-434.99N= 407.81N

Woust Analysis Assuming esclensor corpi ulnaris to be 45 the sole stabilising muscle acting at the middle of the palm where weight of the hand site and the reaching oreaction force to act directly under M.F Jy mrg. force to be at 45° to ground > EM_= 0 =) MFSin45 = mng = 0,00 (mg. =) MF = 7.15N. \(\frac{1}{2} \) \(\frac{1}{2} \) = \(\frac{1}{2} \) = \(\frac{1}{2} \) = \(\frac{1}{2} \) = \(\frac{1}{2} \) \(\ ¿ Fx = 0=) Jx = MF. cos45° = 5.05 N. Hip Analysis Assuming the sole acting muscle to de agluteus medius All the oreaction and weights at have only a small component on the deg hip splane. Assuming the deg to ground rangle to be 5° the court component in sin 5° Assuming muscle insurtion angle: 70? = MFSin70 x0.091H M.F TO GOZU | medial = Sin5 x (W_X0.0211 + R1x(0.1914-0.0275H) ⇒ M.F = 49.85 N.

 $W_{L} \sin s \cdot \sqrt{\frac{2f_{\chi}=0}{2}} J_{\chi}=-M.Fcos70'=\frac{26}{2}-17.05N}$ $Sf_{\chi}=0 \Rightarrow J_{\chi}=-M.Fcos70'=\frac{26}{2} -17.05N$ $Sf_{\chi}=0 \Rightarrow J_{\chi}=-M.Fcos70'=\frac{26}{2}-17.05N$ $Sf_{\chi}=0 \Rightarrow J_{\chi}=-M.Fcos70'=\frac{26}{2}-17.05N$ $Sf_{\chi}=0 \Rightarrow J_{\chi}=-M.Fcos70'=\frac{26}{2}-17.05N$ Shoulder analysis

Assuming latismus dorsi to stabilism

M.F. T. J. J. 0.08 H. the oshoulder with parameters as

shown in the diagram.

Mey J. J. S. M. = 0 = 0 MFS in 30° × 0.08 H = 0.06 H(R. -m. g).

D. M. F. = bt. 1.59.33

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E. F. = 0 -) J. = - (MFcos 30 + R.)

+ (mu+me+m.) g.

- 266.65

J. = MF sin 30° = 222.45 M + 542.37

T. = MF sin 30° = 222.45 M + 542.37

79.665 N

L-5 Socral Analysis: In the part postor to co alsominal musles can the PM mis 57 1000214 MF major statistics at an art was spinas to at. In the plant position oussuming the abdominal 7 (mf + 20,53H + m x 0.23H) x 9 muscles to be the major stabiliers ⇒ M. F X 0.0 2 H = 4407.81 X0.5 3 H $= \sqrt{\frac{1.37 \times 2}{100} \times 0.53} + \frac{(14.1644.33) \times 2}{100} \times 0.23.} \times 86 \times 9.8$ -> M.F X 0,02 = -0,1 x 86x9.8 + 216,14 => M.F = 6593N, > Fx = 0 =) Jx + M. F(0545° = 0. $\Rightarrow J_{X} = -\frac{6593}{\sqrt{5}} = -4661.96N$ EFy=0=) Jy+M.Fsin45°+R, = (m_L+m_F)g. => Jy +4661.96 + 407.81 = (14.16+4.33) +1.37) x 2x81 x9.8 Jy = 334.76 -401.81 -4661.96 = -4735.01N Ankle Analysis: (The muscle is soleus). & MT =D. > M.F (cos 45 x 0.0756H=sin45 x. 0.01H) = (R,-m,g) x0.01 H. => M.Fx.0.046 = (407.812 1.37 x86 x9.8) X0.01 M.F = 8614-13N -81214 41.82N,

& Fx=0=>. Jx = -M.F.cos45 - -60,91:22 M. -29.57N Jy= mfg-Rj-MFsin45°. = 1.37 x86 x 9.8 - 407.81 - 86 x = 221.93 N. (ii) Dog-faing ground postere: Assuming the posture to chave the following values with references from slides anthropometric data & online Balancing moment about foot: mgx 0.53Hx(0.345° = R2x[0.53H(0.545+0.29 H(0.545)) + 0.33H(0.30)+0.056H = $R_{2} = 86 \times 9.8 \times 0.53$ 0.922 X JZ. = 342.72 N. > R_= mg- R_= 500.08N. Worist Analysis: All assumptions valid as feer the EXTENSOR wrist analysis in the plant foot.

LINE 45 A SMJ = 0 => MF SIN45 = B +- m n g.

-> MF = 52 (3F272/2 0.006 × 9.8 × 86) =)MF = \(\frac{1}{2} \) \(\frac{2}{3} \) \(\frac{2} \) \(\frac{2}{3} \) \(\frac{2}{3} \) \(\frac El Jy mag $\Sigma F_{y} = 0 \Rightarrow T_{y} = 9 - \frac{R_{1}}{2} = -171/36$ EFX =0 =) JX = MF COSYS = 337 - 1000 = 5,06 N

Larrying forward the same assemblion from shoulder analysis in plank forture Shoulder Analysis: a = 57.72 × 0.18614 = 0.1074. med to b= 0.1861-1 45.74 × 0.146 H = 0.253 H C = 0.186H + 0.146H = 0.332 H. = R, (ccos30 +0.0614) => = (0.0271 × 0.107 × 53 + 0.0162 × 0.253 × 53) ×86 × 9.8+MFx0.00 $= \frac{342.72 \left(0.332 \times \sqrt{3} + 0.06\right)}{259.55}$ = 0.06 = 0.06 = 0.06€ F_x=0=> J_x = MF = 2849.81 Db. 1361.03 N. ¿ Fy=0=) Jy = (mua+mpo)g-Rz = (0.027) + 20102 0,0162) x9.8 x 86 - 342.72 => Jy = -36 2.23 N .- 134-87N. L-5 Sacral Analysis: going with the same assumptions for the savral analysis in the plank mig o other was a chart. IF, 0.34 EMJ => MFX0.02H+ mlgx0.23xcos45 + mfg x 0.53 x c 0 5 4 5 ° = R, x0.53 x cos45. => M.F = 560.08 x 0,53 - (1.37 x 2 x 0.53 + (14.16 + 4.33) x 2x.23) 75 X0.05. - 128 00 .6403.55N

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SFx=0 27 Jx=0.
 & Fy=0=). Jy=M.F+ (m,+m)g-R,
    =) J_{\gamma} = 6403.55 + (14.16+4.33+1.37) \times 2 \times 86 \times 9.8 - 500-08
           = 6238,23N.
Ankle Analysis: Ide musele is solew.
               5 MJ = 0
             M.F. Ccos45 x0.0756 - Sin46 x0.01H)
 R Imag
                      = (R, -mpg) x0.011-1
             => M.F x0.046= (500.08 - 1.37 x86 x 9-8) x0.01
                        > M.F = 102-2002 51.85N
      Jx = - MFCOSYS = -750000 . -36.66N
       Jy= mrg - R1 - MFsin45°.
            2 1.87 ×86×9.8 - 500.08 - 186.2
          D Jy = -583-63N2 -275.16N
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Wife drolysis 0.19114 0.19114

All the assumption of the hip analysis ravey forward from the plank position to hear except for the weight and recution force sin 45°. This higher component will have a significant impact as poiessi you can senbelow;

5 MJ=0

=> MFSin70x0.091H=Sin45°x (W_K0.02H+R, x(0.191-0.275H)

=> M. Fx0.01 = 1 (334.76 x0.02 + 500.08 (0.16)

=> M.F=471.76N.

EFx = 0=) Jx= -M.Fc0570 = -161.35 N

Ty = sinus (WL - Ri) - M.F sin 70.

= -383,4N,