17-05-2020

## ME6230: END-SEMESTER

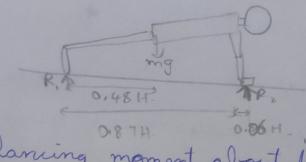
S. TARUN PRASA MEITBILY

TAKE-HOME EXAM.

- My Height: 170 cm.

-> My Weight: 86 kg.

## (1) (i) Plank;



Balancing moment about foot R<sub>2</sub> = mg x 0.48 = 434,99 N.

0.87 +0.06

DR, = mg-434.99N= 407.81N

Hip Analysis (Plank): 5 MJ = 0 -=> MF Sin70° x 0.091 H = W, x b. D2 H + R, x (0.191 -0.0273) H -), M.F x0.07 = 334.76 x0.02 +.407.81 ×0.1635 >M.F=571.91=> M.P. 1048.17N. 57197N. 10.027511 EFX=0=) Jx=-MFCOS70=-362. = Fy=0=) W2-R, - MFsin70" = Jy.
571.91 = ) Jy = 334.76 - 407.81 => Jy = -884 2200) => Jy = -311.74 Woust Analysis: Assuming flescor carpirulnaris to be the sole stabilising muscle witing at themiddle of the palm and the treation force selso acting at the middle of the palm. Asserming muscle force at 45° to palm. SM=0=) M.Fsin45° = R2-mng = R2-0.006mg =) M.F = \( \int \int \( \text{(434.99} - 0.006 \times \text{9.8 \times 86} \) = \( \text{bos action} \)

300.39 N SFX=0=) Jx= MF(0545°= 429-983 N, 212.44N

Shoulder analysis

Assuming latismus donsi to stability

M.F. I. J. O.O.S. H. the ashoulder with parameters as

shown in the diagram.

SEM\_=0 => MFSin30° × 0.08 H = 0.06 H(R\_3-m\_n g).

=> M.F. = 644-89 N 318.66 N.

SEF\_y=0=> J\_y=-(MFcos30+R\_2)
+(mu+me+mn) g.

=> J\_y=-972-04 + (0.0271+0.0162+0006)×86

-266.65

-372-04 + 41.38 = -876.43 N.

M.F. Sin30° = 222.43 N 159.33 N.

L-5 Sovral Analysis: In the plant position to core saldominal musta are the ent major stabliser at a summy the anesto spina to at M, Fx0.02H= +R, X 0.53H In the plant position oussering Du abdomined \$ (mf + 700 × 0.53H + m × 0.23H) × 9 muscles to be the major stabilisers => M. F X 0.0 2 H = +407.81 X 0.5 3 H  $= \left(\frac{1.37 \times 2}{100} \times 0.53\right) + \left(\frac{(14.1644.33) \times 2}{100} \times 0.23\right) \times 86 \times 9.8$ M, F X 0, 02 = -0, 1 x 86 x 9, 8 + 216, 14. => M.F = 6593N, \$ Fx = 0 =) Jx + M. F(0545° = 0.  $5) J_{X} = -\frac{6593}{\sqrt{2}} = -\frac{4661.96N}{}$ E Fy=0 =) Jy+M.Fsin45°+R, = (m\_L+m\_F) g =) Jy +4661.96 + 407.81 = (14.16+4.33) +1.37) x 2x81x1.8 Jy = 334.76-401.81-4661.96 = -4735.01N Ankle Analysis: & MT =0 7 M.F (cos 45 x 0.0756H=sin45 x. D.01H) = (R,-m,g) x0.01 H => M.Fx. 0.046 = (407.81 = 1.37 x86 x9.8) x 0.01 5) M.F = 8614.43N 8514N 41.8 2N

SFY=0=> JY= mEg-R,-MESIN45.  $= \frac{1.37 \times 86 \times 9.8 - 407.81 - 86.44}{2} 29.57$ = 221.93 N. (ii) Dog-faing ground postere: Assuming the posture to chave the following values with references from slides anthropometric data & online Balancing moment about foot:  $= mg \times 0.53 H \times (0.545)^{\circ} = R_{2} \times \left[ 0.53 H \cos 45 + 0.29 H \cos 45 \right] + 0.33 H \cos 30 + 0.056 H$  $= R_{2} = \frac{86 \times 9.8 \times 0.53}{0.922 \times \sqrt{2}}.$ = 342.72 N. > R\_= mg - R\_ = 500.08N. All assumptions valid as fer the wrist analysis in the plant part. Worist Analysis; Typez. Moule EMJ=0=) MFSin45°= 12-mng. =>MF = J2 (342.72/2-0.006×9.8×86) EFX =0 =) JX = MF COS45° = 337.66N 166.30N

Larrying forward the same assemption from shoulder analysis in plant posters Shoulder Analysis a = 57.72 x 0.18614 = 0.1074 0.1861-1 + 45.74 × 0.146 H = 0.253 H C = 0.186H + 0.146H = 0.332 H My=0=) muag x a cosso + mpag x b cosso + MF sinso x 0.08 14 = R (ccos30 +0.0614) => (0.0271 × 0.107 × 53 + 0.0162 × 0.253 × 53) × 86 × 9.8 + MFx0.04  $= \frac{342.72 \left(0.332 \times \sqrt{3} + 0.06\right)}{^{2}59.55}$   $= \frac{342.72 \left(0.332 \times \sqrt{3} + 0.06\right)}{^{2}59.55}$   $= \frac{2542.72 \left(0.332 \times \sqrt{3} + 0.06\right)}{^{2}59.55}$ € Fx=0=> Jx = MF = 2849.81 Bl. 1361.03 N. ¿ Fy=0=) Jy = (mua+mfo) g - Rz = (0.027) + 10+02 0.0162) x9.8 x 86--254 = -36 2. 23 N - 134-87N L-5 Lacral Analysis: young with the same assumptions for the sound analysis in the plant EM 2. SMF X0.02H+ m\_gx0.23 x cos 45° + m\_cg x 0.53 x cos 45° = R, x0,53 x c0545 D M.F = 560.08 x 0,53 - (1.37 x 2 x 0.53 + (14.16 + 4.33) x 2x.23) 128 010 6403.55N

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STx =0 27 Jx =0.
 5 Fy=0=) Jy= M.F+ (m2+mx) g-R,
   =) Jy = 6403.55 + (14.16+4.33+1.37) x2 x86 x 9.8-500-08
          = 6238,23N,
Ankle Analysis:
             EM+=0.
            M.F (cos45 x0.0756 - Sin45 x0.01H)
                     = (R, -mpg) x0.011-1
             => M. F x 0.046 = (500.08 - 1.31 x 86 x 9-8) x 0.01
                       > M.F = +08-2012 51.85N
       Jx = - MF(0545" = -757092N . - 36.66N
        Jy= meg - R1 - MFsin45°.
            = 1.37 ×86×9.8 - 500.08 - 106.2
          Jy = -583.62A2 -275,16N
Hip Analysis
              5MJ = 0
              =) M.Fsin70° X 0.091H = 图 X 0.02H
                                  + R × (0.191 - 0.02757
              =) M.Fx. 0,07 = 334.76x0.02
                                  + 550.08(0.16)
                    =) M.F= 1253.647.667.16 N
            SFx=0=) Jx = -Mfc0570. = -800-30 N -422.53N
             EFY=0=) Jy= W_- R1/2-MFsin70.
                         = 334.76 - 500.09 - 800037
                        =) Jy= +43-28N
                                 -431,59N
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