

Data Engineering

LTAT.02.007

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[https://courses.cs.ut.ee/2020/
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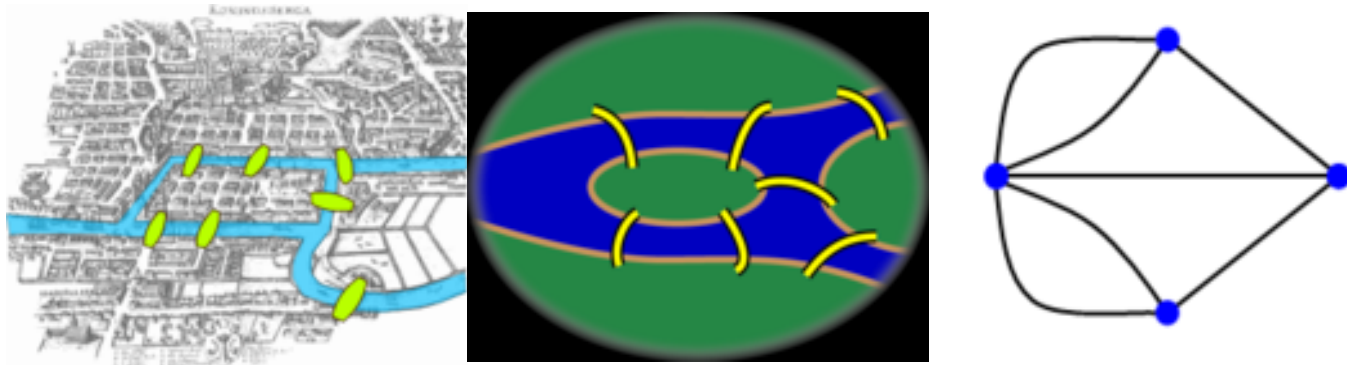
[Forum](#)

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History

Leonhard Euler's paper on "Seven Bridges of Königsberg", published in 1736.



Famous problems

- The traveling salesman problem: A traveling salesman is to visit a number of cities.
 - how to plan the trip so every city is visited once and just once and the whole trip is as short as possible ?
- Four color problem¹⁰⁰ : using only four colors, color any map of countries in such a way as to prevent two bordering countries from having the same color.
 - SOLVED ONLY 120 YEARS LATER!

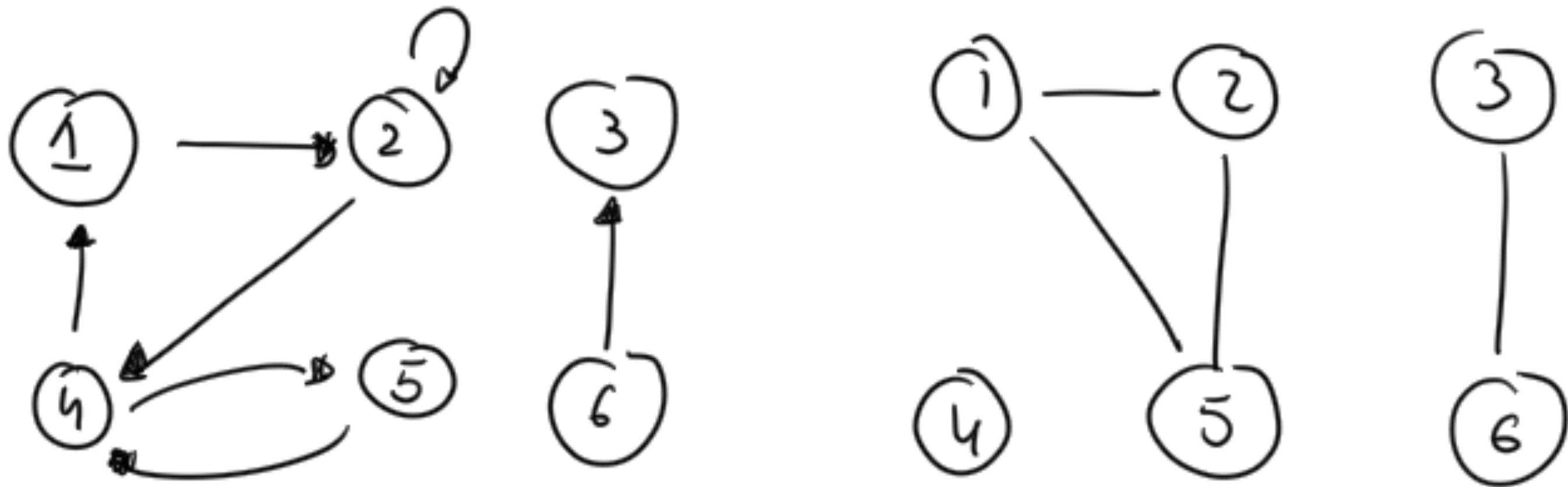
¹⁰⁰ Francis Guthrie, 1852

Other Examples of Graph Problems

- Cost of wiring electronic components
- Shortest route between two cities.
- Shortest distance between all pairs of cities in a road atlas.
- Matching / Resource Allocation
- Task scheduling
- Visibility / Coverage

What is a Graph?

Informally a *graph* is a set of nodes joined by a set of lines or arrows.



Graph

G is an ordered triple $G := (V, E, f)$

- V is a set of nodes, points, or vertices.
- E is a set, whose elements are known as edges or lines.
- f is a function
- maps each element of E
- to an unordered pair of vertices in V.

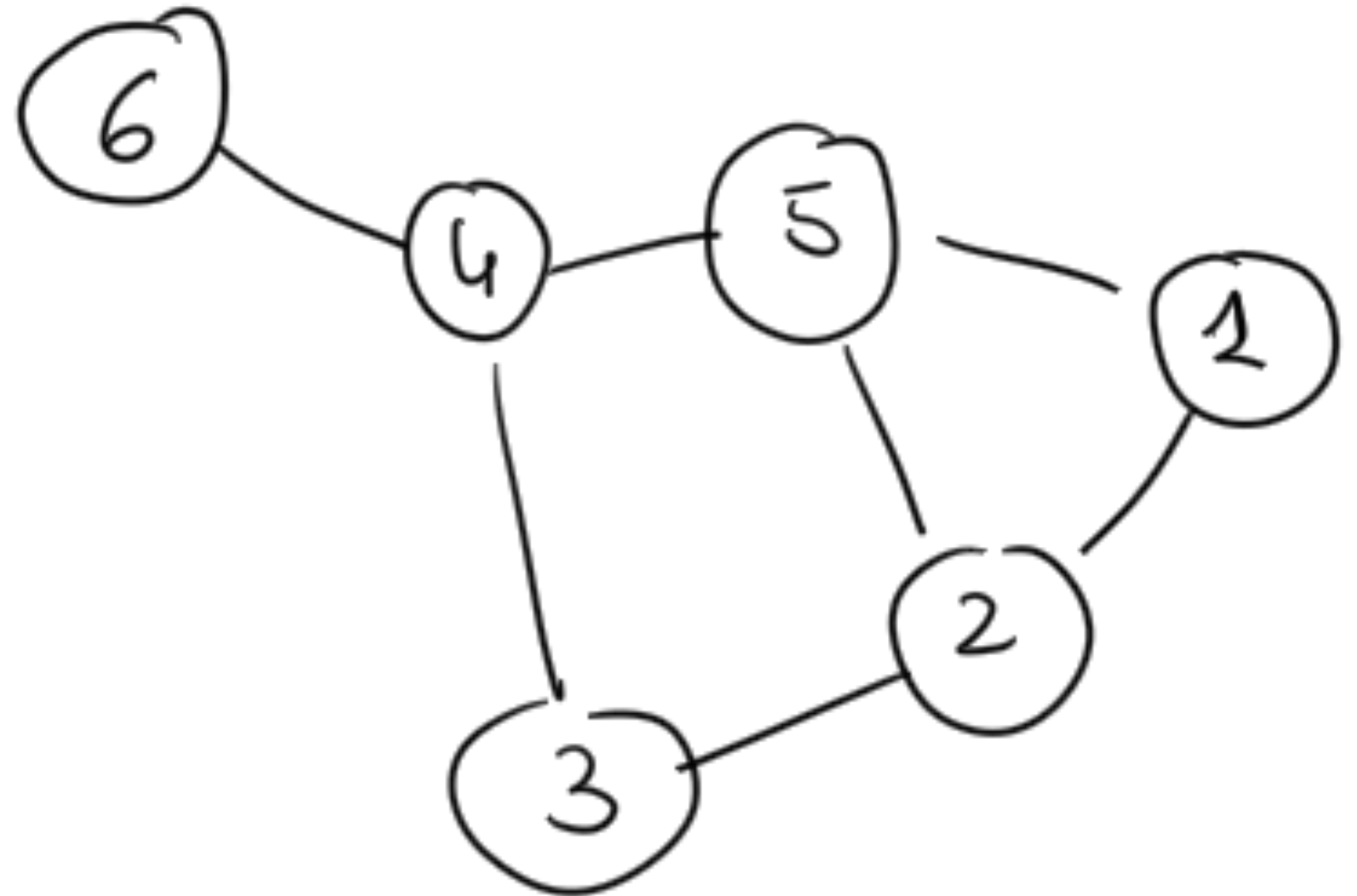
Vertexes and Edges

- A Vertex is a Basic Element
 - Drawn as a *node* or a *dot* .
 - The *Vertex set of a graph* G is usually denoted by V
- An edge is *set* of two elements
 - Drawn as a line connecting two vertices, called end vertices, or endpoints.
 - The edge set of G is usually denoted by $E(G)$, or E .

Example

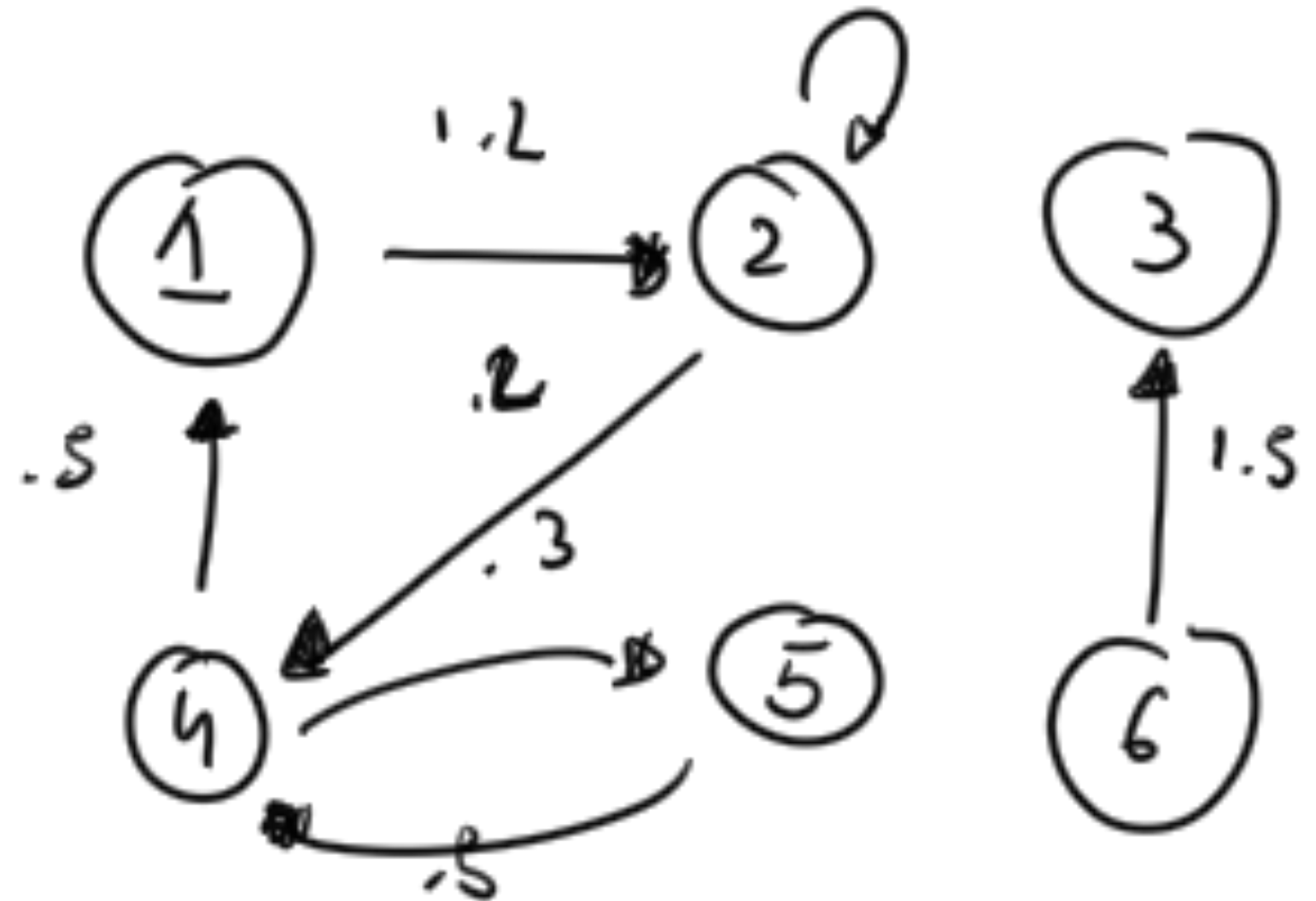
$V := \{1, 2, 3, 4, 5, 6\}$

$E := \{\{1, 2\}, \{1, 5\}, \{2, 3\}, \{2, 5\}, \{3, 4\}, \{4, 5\}, \{4, 6\}\}$



Directed Graph (digraph)

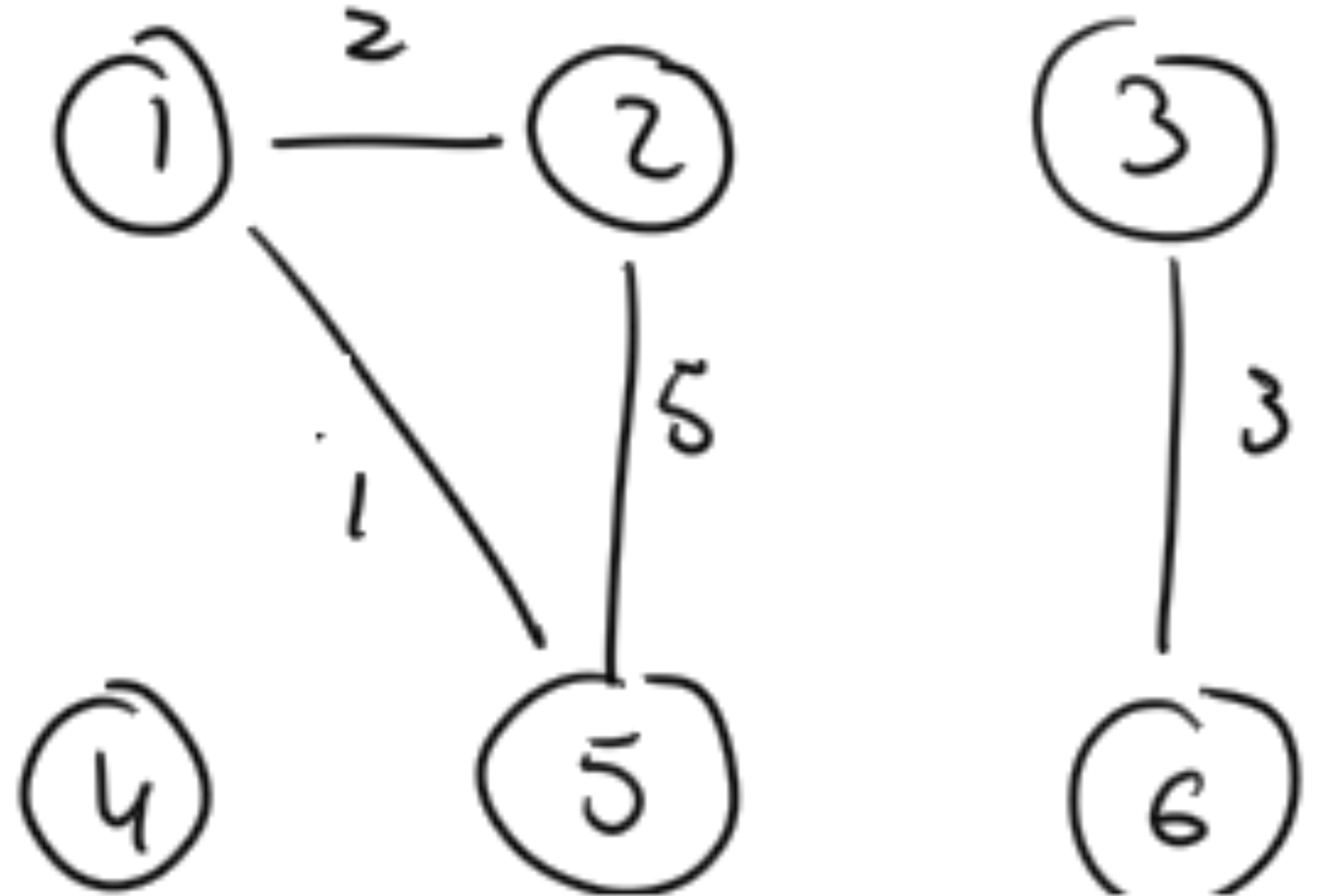
Edges have directions, i.e. an edge is an *ordered* pair of nodes



Weighted graphs

are graphs for which each edge has an associated *weight*, usually given by a *_weight* function

$$f_w : E \rightarrow R .$$

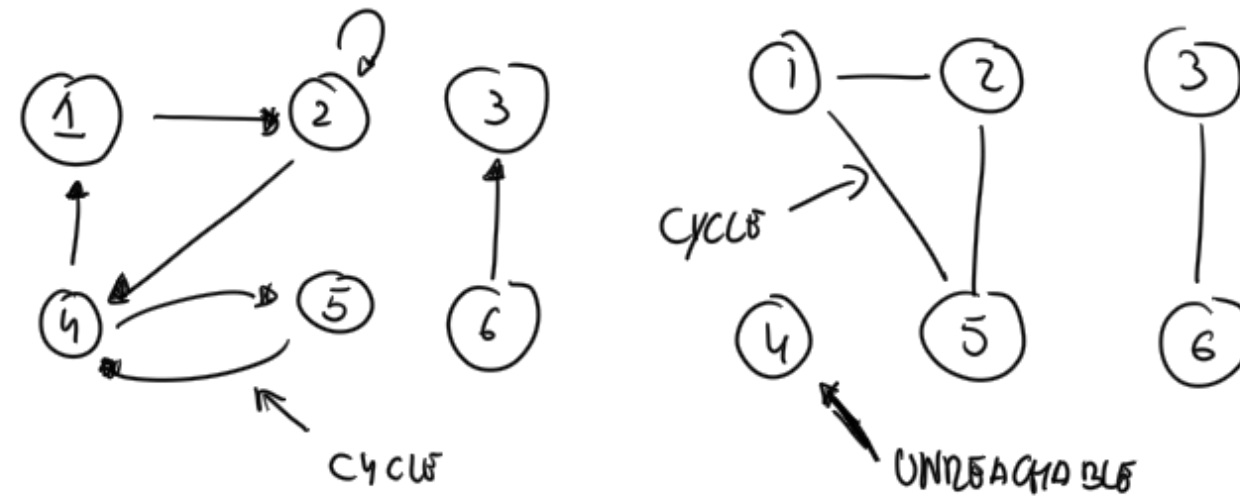


Path

A *path* is a sequence of vertices such that there is an edge from each vertex to its successor.

- A path is *simple* if each vertex is distinct.
- If there is path p from u to v then we say v is **reachable** from u via p .

Example: Simple path from 1 to 5 = [1, 2, 4, 5]



Cycle

- A path from a vertex to itself is called a *cycle* .
- A graph is called *cyclic* if it contains a cycle;
 - otherwise it is called *acyclic*

Connectivity

- A graph is *connected* if
 - you can get from any node to any other by following a sequence of edges OR
 - any two nodes are connected by a path.
- A directed graph is *strongly connected* if there is a directed path from any node to any other node.

Sparsity/Density

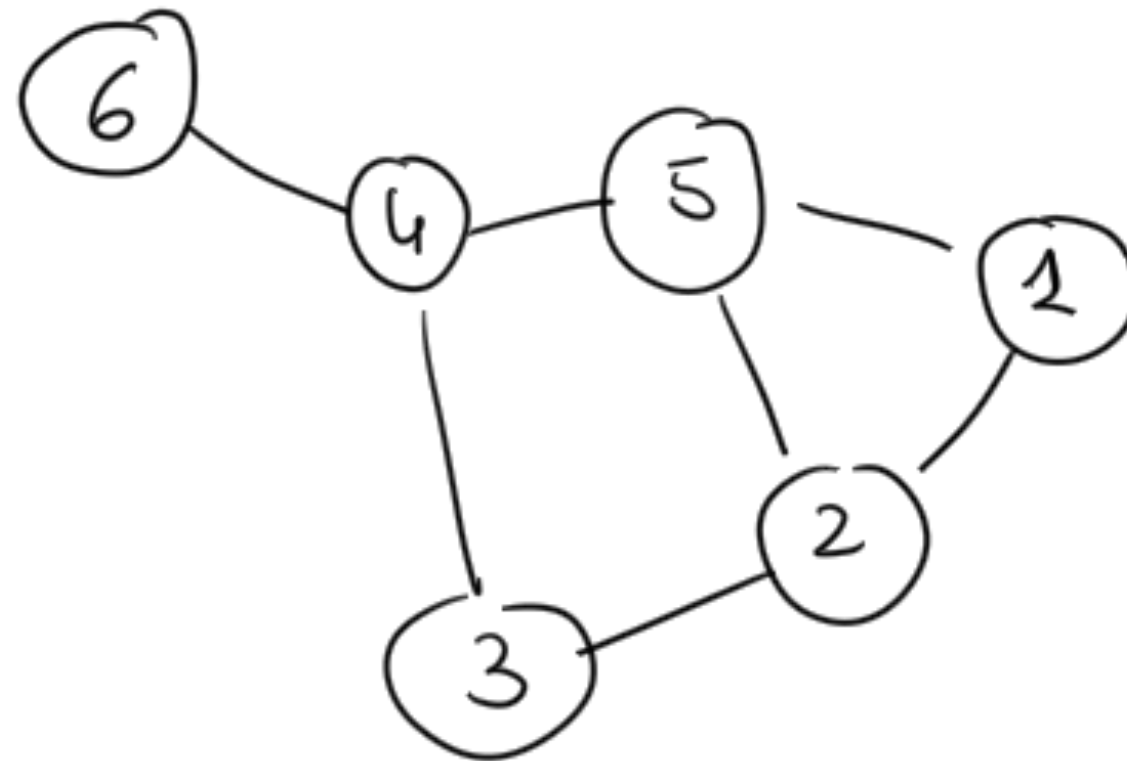
A graph is *sparse* if $|E| \approx |V|$

A graph is *dense* if $|E| \approx |V^2|$

Degree

Number of edges incident on a node

E.g., the degree of **5** is 3.



Degree (Directed Graphs)

In degree: Number of edges entering

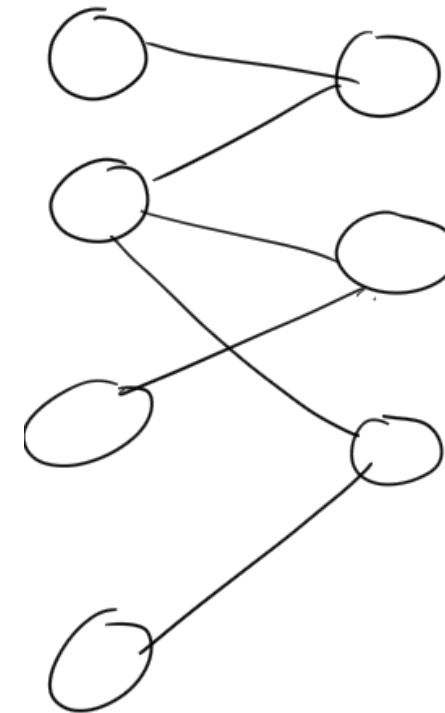
Out degree: Number of edges leaving

Degree = indegree + outdegree

Graph Types

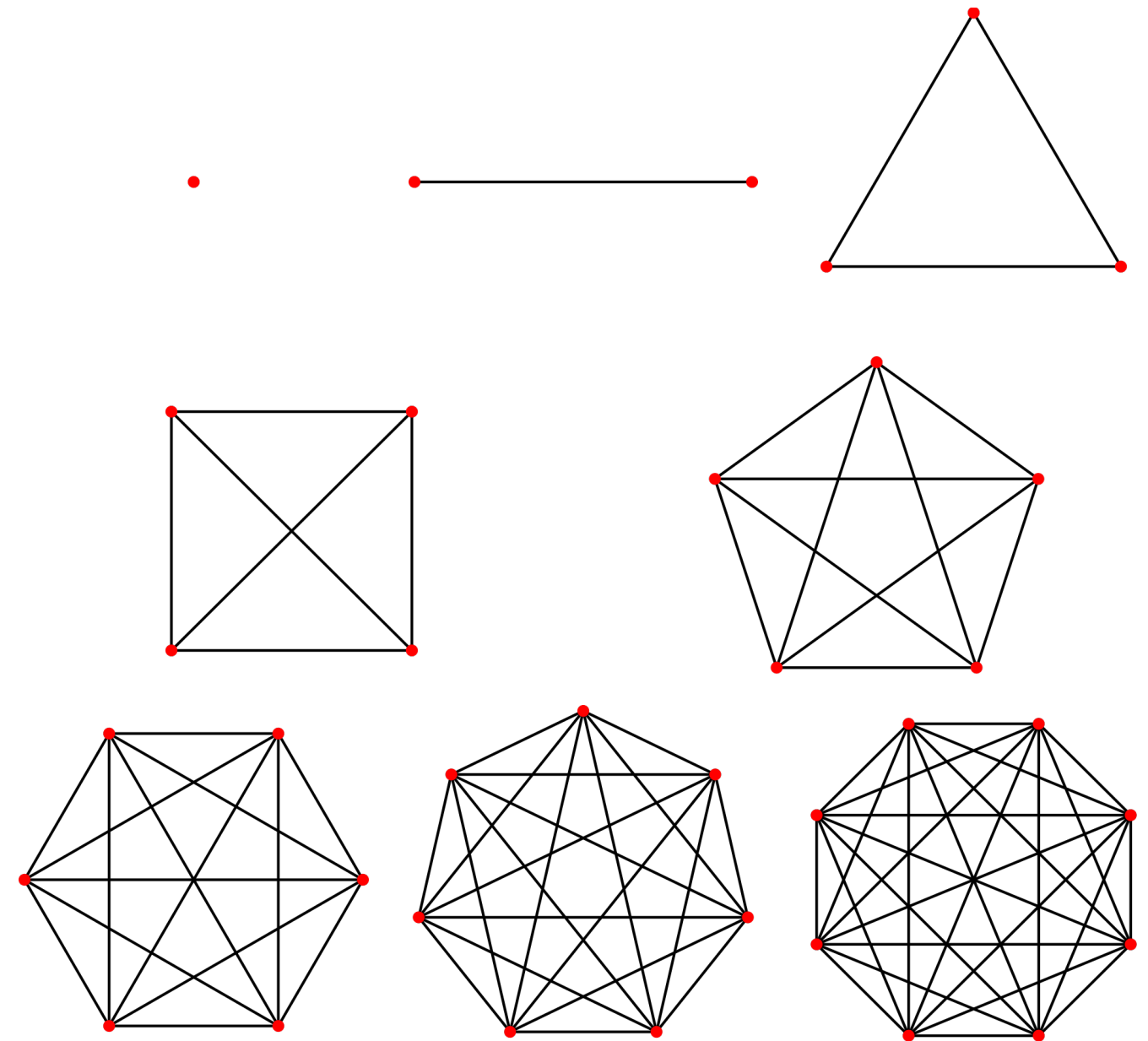
Bipartite graph

- V can be partitioned into 2 sets V_1 and V_2 such that $(u, v) \in E$ implies
 - either $u \in V_1$ and $v \in V_2$
 - or $v \in V_1$ and $u \in V_2$



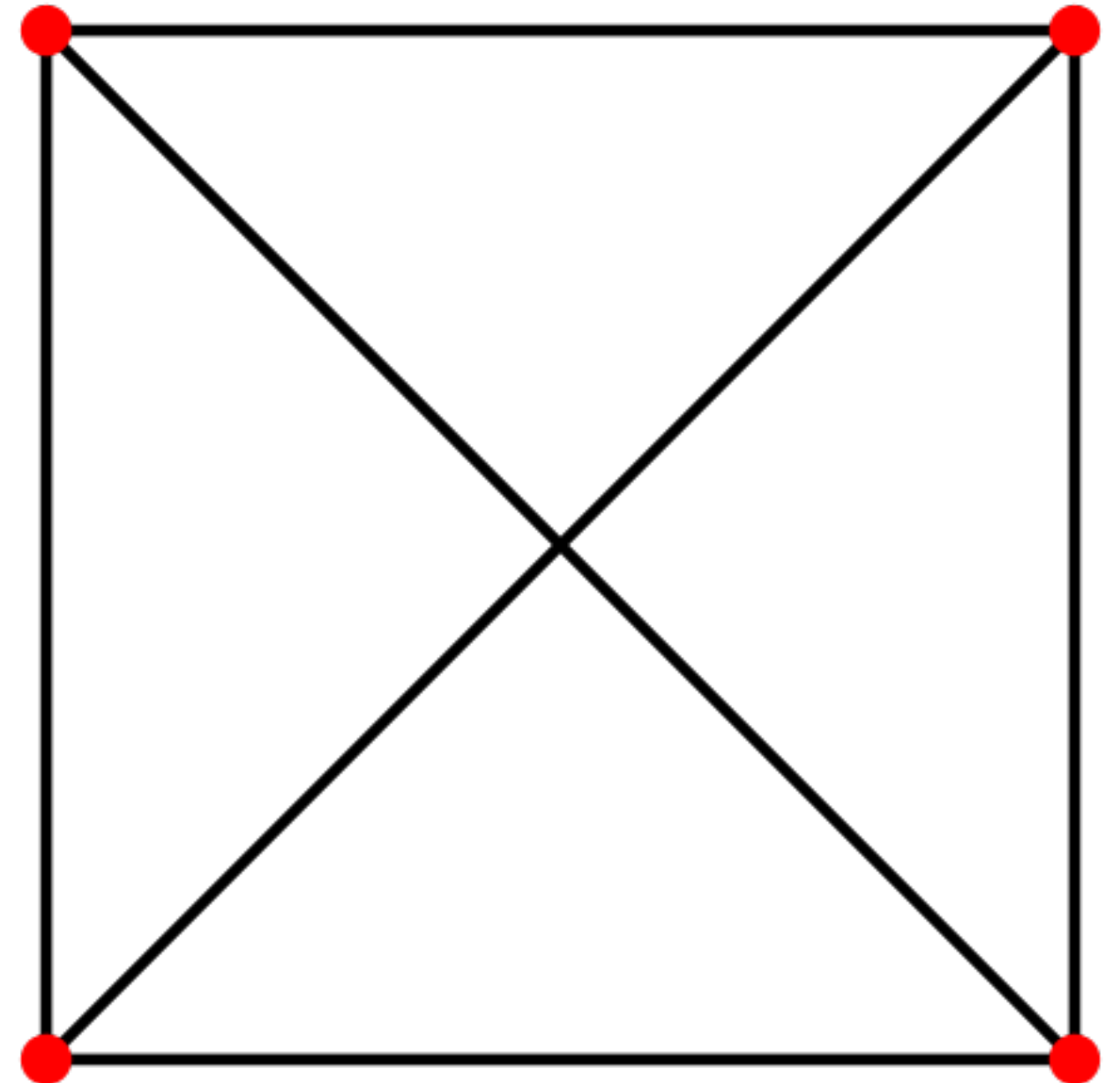
Complete Graph

- Denoted K_n
- Every pair of vertices are adjacent
- Has $n(n-1)$ edges



Planar Graph

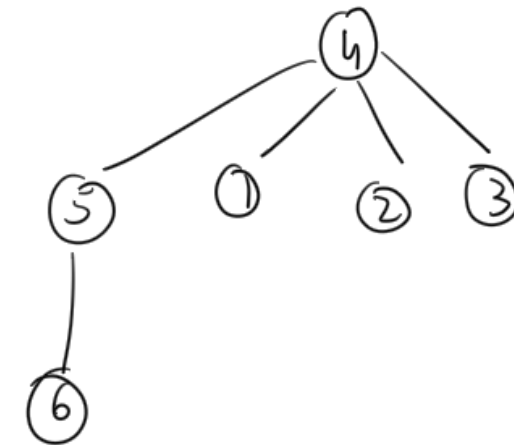
- Can be drawn on a plane such that no two edges intersect
- K_4 is the largest complete graph that is planar



Tree

Connected Acyclic Graph

Two nodes have *exactly* one path between them



Hypergraph

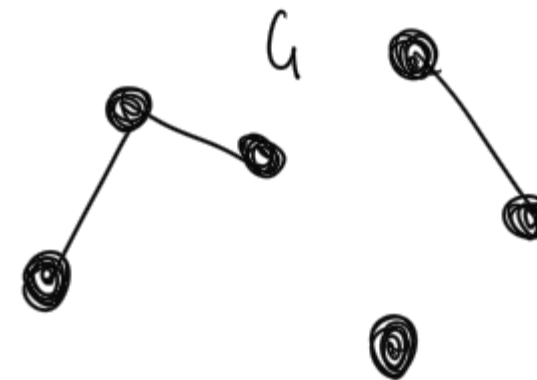
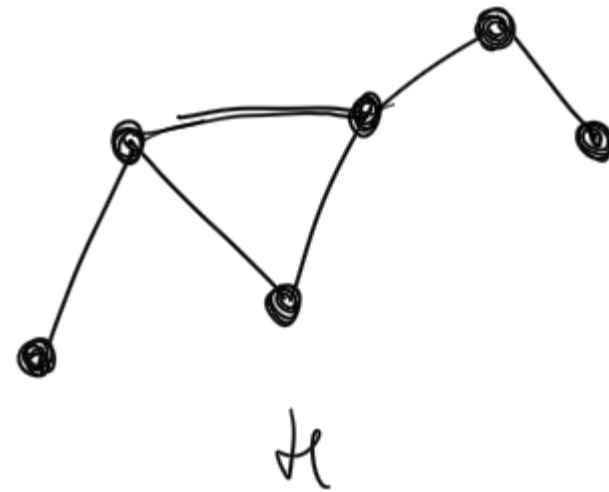
- Generalization of a graph,
 - edges can connect any number of vertices.
- Formally, an hypergraph is a pair (X,E) where
 - X is a set of elements, called nodes or vertices, and
 - E is a set of subsets of X , called hyperedges.
- Hyperedges are arbitrary sets of nodes,
 - contain an arbitrary number of nodes.

Subgraph

- Vertex and edge sets are subsets of those of G
- a *supergraph* of a graph G is a graph that contains G as a subgraph.

Spanning subgraph

- Subgraph G has the same vertex set as H .
- Possibly not all the edges
- " G spans H ".



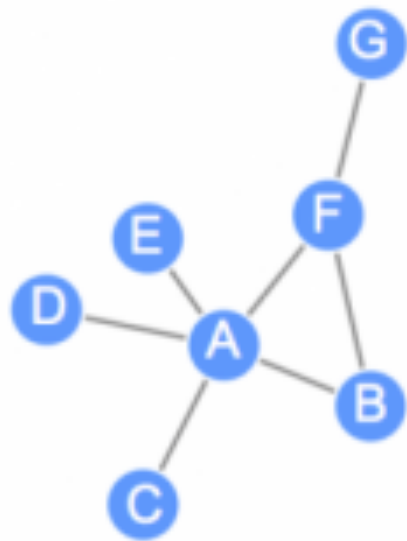
Graph ADT

- In computer science, a graph is an abstract data type (ADT)
- that consists of
 - a set of nodes and
 - a set of edges
 - establish relationships (connections) between the nodes.
- The graph ADT follows directly from the graph concept from mathematics.

Representation (Matrix)

- Incidence Matrix
 - $E \times V$
 - [edge, vertex] contains the edge's data
- Adjacency Matrix
 - $V \times V$
 - Boolean values (adjacent or not)
 - Or Edge Weights

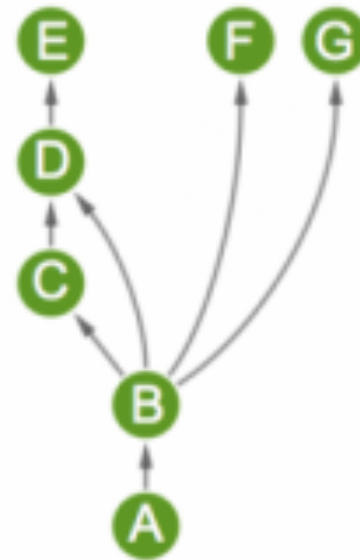
Undirected



	A	B	C	D	E	F	G	Degree
A	0	1	1	1	1	1	0	5
B	1	0	0	0	0	1	0	2
C	1	0	0	0	0	0	0	1
D	1	0	0	0	0	0	0	1
E	1	0	0	0	0	0	0	1
F	1	1	0	0	0	0	1	3
G	0	0	0	0	0	1	0	1

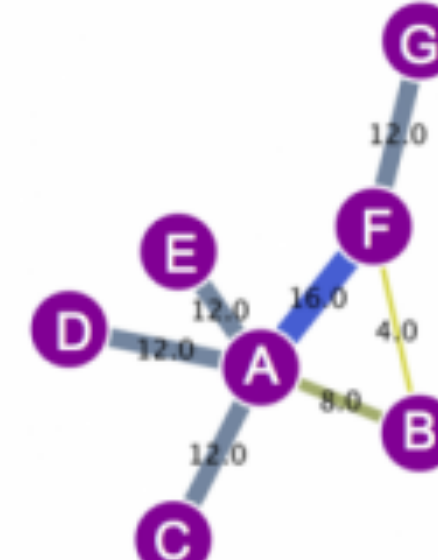
Adjacency matrices

Directed



	A	B	C	D	E	F	G	Out-degree
A	0	1	0	0	0	0	0	1
B	0	0	1	1	0	1	1	4
C	0	0	0	1	0	0	0	1
D	0	0	0	0	1	0	0	1
E	0	0	0	0	0	0	0	0
F	0	0	0	0	0	0	0	0
G	0	0	0	0	0	0	0	0

Weighted

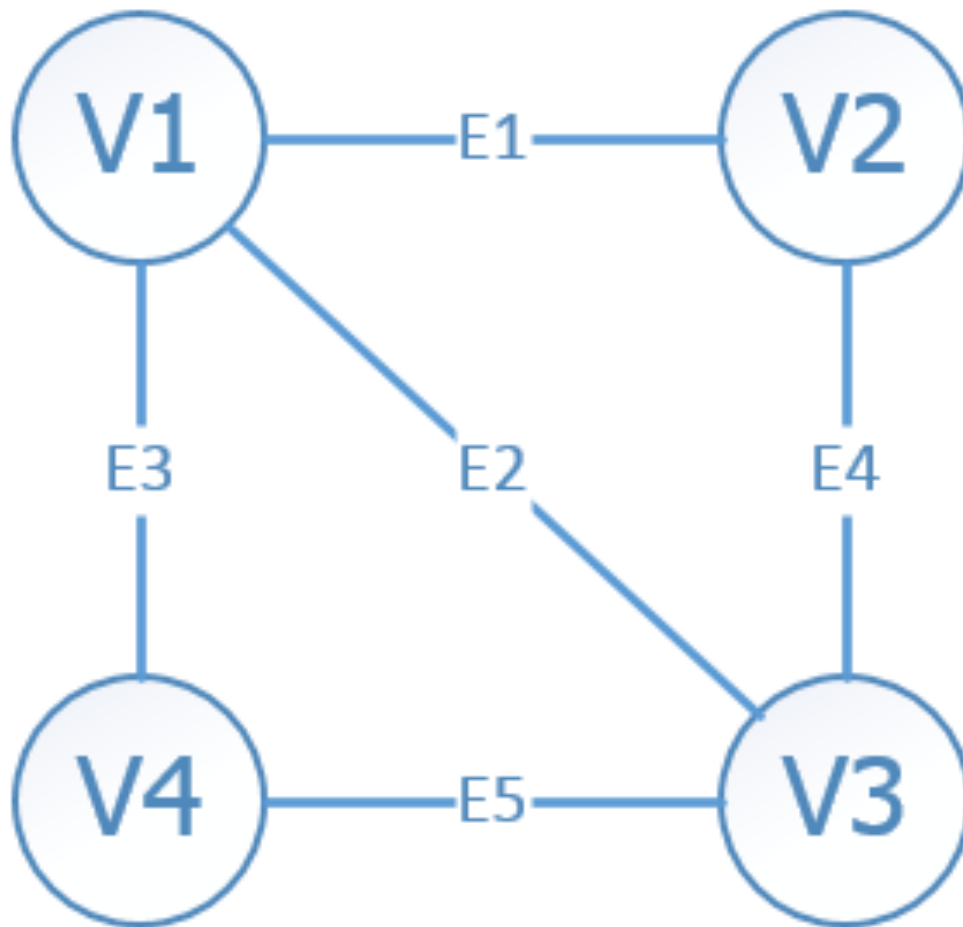


	A	B	C	D	E	F	G	Degree
A	0	8	12	12	12	16	12	72
B	8	0	0	0	0	4	0	12
C	12	0	0	0	0	0	0	12
D	12	0	0	0	0	0	0	12
E	12	0	0	0	0	0	0	12
F	16	4	0	0	0	0	12	32
G	12	0	0	0	0	12	0	24

Representation (List)

- Edge List
 - pairs (ordered if directed) of vertices
 - Optionally weight and other data
- Adjacency List

Undirected Graph



Edge List

[[0,1],[0,2],[0,3],[1,2],[3,2]]

Adjacency Matrix

X	0	1	2	3
0	0	1	1	1
1	1	0	1	0
2	1	1	0	1
3	1	0	1	0

Adjacency List

[[1,2,3],
[0,2],
[0,1,3],
[0,2]]

Graph Algorithms

- Shortest Path
 - Single Source
 - All pairs (Ex. Floyd Warshall)
- Network Flow
- Matching
 - Bipartite
 - Weighted
- Topological Ordering
- Strongly Connected
- Biconnected Component / Articulation Point
- Bridge
- Graph Coloring
- Euler Tour
- Hamiltonian Tour
- Clique
- **Isomorphism**
- Edge Cover
- Vertex Cover
- Visibility