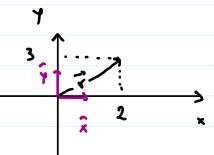
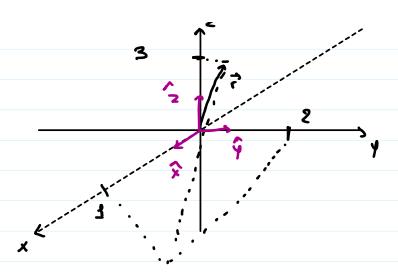
Tuesday, September 23, 2025 12:17 AM

Scalars and Vectors.

Vectors.



$$\vec{r} = 2 \hat{x} + 3 \hat{y} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$



$$\vec{r} = 1 \cdot + 2 \cdot + 3 \cdot = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

40 Universe: We con't draw it!

$$\vec{\tau} = \begin{pmatrix} 0.7 \\ 0 \\ 0.7 \\ 0 \end{pmatrix}$$

We need matrices to understand Quantum mechanics

Heissenberg

1925 - Matrix Formulation of QM

Born

Jordon

1. Definition of a matrix

$$A = \begin{pmatrix} a_{00} & a_{01} & \dots & a_{nm} \\ \vdots & \vdots & & \vdots \\ a_{nm} & a_{nm} & \vdots & \vdots \\ a_{nm} & \vdots & \vdots & \vdots \\ a_{$$

$$a_{os} = 4$$

$$a_{20} = 5$$

2×3

Example 3.
$$\Psi = \begin{pmatrix} 1 \\ 6 \end{pmatrix}$$
 $\Psi \in \mathbb{R}$

$$\frac{\varphi_{\bullet \bullet} = 1}{\varphi_{\bullet \bullet} = 0}$$

2. Bosic Operations

1. Add: Lion | Substraction

position

Example 1.
$$A = \begin{pmatrix} 1 & 0 \\ 0 & 2 \end{pmatrix}$$
 $B = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$

$$\varphi_{\underline{1}} = \begin{pmatrix} \underline{1} \\ \underline{0} \end{pmatrix} \qquad \varphi_{\underline{2}} = \begin{pmatrix} \underline{0} \\ \underline{1} \end{pmatrix}$$

$$A + B = \left(\frac{1}{0} \quad \frac{0}{2} \right) + \left(\frac{0}{i} \quad \frac{-i}{0} \right) =$$

$$= \left(\begin{array}{ccc} \underline{1} & -\mathbf{j} \\ \mathbf{j} & 9 \end{array}\right)$$

$$\varphi_{1} + \varphi_{2} = \left(\frac{1}{2}\right) + \left(\frac{0}{2}\right) = \left(\frac{1}{2}\right)$$

$$Z = \begin{pmatrix} \underline{1} & 0 \\ 0 & -\underline{1} \end{pmatrix} \qquad \underline{T} = \begin{pmatrix} \underline{1} & 0 \\ 0 & \underline{1} \end{pmatrix}$$

$$\overline{1}-2=\left(\begin{array}{cc}\underline{1}&0\\0&\underline{1}\end{array}\right)-\left(\begin{array}{cc}\underline{1}&0\\0&\underline{1}\end{array}\right)=\left(\begin{array}{cc}0&0\\0&2\end{array}\right)$$

2. Scalor Multiplication

Pule. Foch element is multiplied by the scalar

$$A = \begin{pmatrix} o_{00} & o_{01} \\ o_{10} & o_{11} \end{pmatrix}$$

$$c \forall = c \begin{pmatrix} a^{10} & a^{11} \\ \bullet^{00} & a^{01} \end{pmatrix} = \begin{pmatrix} c a^{10} & c a^{11} \\ c a^{00} & c a^{01} \end{pmatrix}$$

Example 1.

$$H = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

C = j

$$cH = j \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} \frac{j}{\sqrt{2}} & \frac{j}{\sqrt{2}} \\ \frac{j}{\sqrt{2}} & \frac{j}{\sqrt{2}} \end{pmatrix}$$

Example 2.

$$\varphi = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \qquad c \varphi = \begin{pmatrix} -i \\ 0 \end{pmatrix}$$

د - - غ

4. Transposition

Denoted : AT

Pule: Turn rous into columns

If A \in R A \in R mxn

Example 1. Y= 0 0 0 0 6.7

(F.O O 7.0) = " ()

Example 2.

$$\rho = \begin{pmatrix}
1 & 0 \\
0 & 0
\end{pmatrix}$$

$$\rho = \begin{pmatrix}
1 & 0 \\
0 & 0
\end{pmatrix}$$

$$\rho = \begin{pmatrix}
1 & 0 \\
0 & 0
\end{pmatrix}$$

5. Dogger : Complex Conjugate and Transpose

$$A^{\dagger} = (\bar{A})^{\mathsf{T}}$$

Example 2.

$$A = \begin{pmatrix} j & 0 \\ -3j & 4 \end{pmatrix} \rightarrow A^{\dagger} = \begin{pmatrix} -j & 3j \\ 0 & 4 \end{pmatrix}$$

6. Malix Nulliplication

Restriction: The motrix multiplication is defined only if

m = P

The result is an nxq matrix

Rule: In order to find the cii, multiply the i-th rw of A by the i-th column of B element by element add the results

$$(2\times 1)(2\times 2)$$

$$(2\kappa2)(2\pi3)$$

$$(2\kappa2)(2\pi3)$$

$$(2\kappa2)(2\pi3)$$

$$(2\kappa2)(2\pi3)$$

Example 2.

$$T = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \qquad Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$\underline{I} \gamma = \begin{pmatrix} \underline{1} & 0 \\ 0 & \underline{1} \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} =$$

$$= \begin{pmatrix} 4.0 & 0.5 & 0.6 & 0.6 \\ 0.0 & 0.5 & 0.6 & 0.6 \end{pmatrix} = \begin{pmatrix} 0.0 & 0.1 & 0.6 & 0.6 \\ 0.0 & 0.1 & 0.6 & 0.6 \end{pmatrix}$$

$$= \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

Example 3.

$$SW = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \qquad \begin{array}{c} 0 \\ \phi \\ 1 \\ 0 \\ \end{array}$$

$$SW = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

Example 4

$$H = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \qquad \qquad \Psi = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

7. Tensor Product (Kronecker product)

Pule: Hultiply each entry asis of A with the entire matrix B

Example 1.

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \qquad B = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}$$

Example 2.

$$\theta_1 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

Example 3.

$$T = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \qquad \qquad X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$T \otimes X = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} & O \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} & \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Figenvalues and Eigenvectors

Let A be a non metrix and let X be a nonzero vector

for which

 $X \mathcal{L} = X A$

for some scalar 7. The 7 is called an eigenvalue and X eigenvector of A.

The set of all eigenvalues is denoted by 3(A) and is referred as the spectrum of A.

Hermitian and Unitory Matrices

J. Hermitian Matrices

$$A = A^{\dagger} = (\bar{A})^{\dagger}$$

Observables physical quantities are represented by Hermitian operators. Measument outcomes are the real eigenvalues of these operators

2. Un: tony Matrices

A matrix is Univery if

$$U^{\dagger}U = UU^{\dagger} = I \Rightarrow U = U$$

Quantum gales are represented by unitary matrices

So unitary matrices describe how quantum states are

change.