

Exercise Sheet 9

25.06.2021 – 02.07.2021

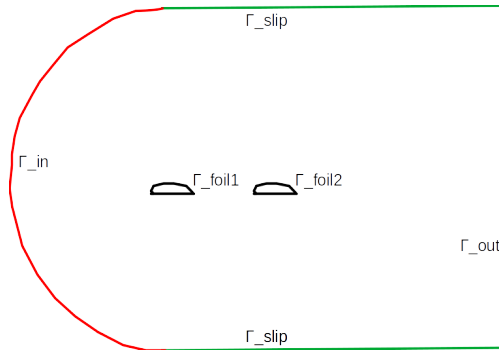
Computational Fluid Dynamics (Summer Term 2021)

Exercise 1 (Programming). The effect of dirty air (15 Points)

In this exercise you will solve the instationary Navier-Stokes equations to compute the flow around two airfoils:

$$\begin{aligned}\partial_t \mathbf{v} - \nu \Delta \mathbf{v} + (\mathbf{v} \cdot \nabla) \mathbf{v} + \nabla p &= \mathbf{f} \quad \text{in } [0, T] \times \Omega \\ \nabla \cdot \mathbf{v} &= 0 \quad \text{in } [0, T] \times \Omega \\ \mathbf{v} &= (v_x, 0) \quad \text{on } [0, T] \times \Gamma_{in} \cup \Gamma_{slip} \\ \mathbf{v} &= 0 \quad \text{on } [0, T] \times \Gamma_{foil} \\ (\nu \nabla \mathbf{v} - pI) \vec{n} &= 0 \quad \text{on } [0, T] \times \Gamma_{out} \\ \mathbf{v}(0) &= 0 \quad \text{on } \Omega\end{aligned}$$

with $\nu > 0$, $v_x > 0$, $\mathbf{f} = (0, -1)$ and domain Ω and boundaries given by the figure below.



In this setting, the foils are exposed to the force

$$\mathbf{f}_{foil} = \int_{\Gamma_{foil}} \sigma(\mathbf{v}, p) \vec{n}_{foil} \, dS$$

with Cauchy stress tensor

$$\sigma(\mathbf{v}, p) = \mu(\nabla \mathbf{v} + \nabla \mathbf{v}^T) - pI, \quad \text{and } \mu = \nu \text{ (unit density) },$$

and \vec{n}_{foil} denotes the unit normal on Γ_{foil} directing into the fluid domain.

Using the backward Euler method, the time-discrete system reads: for $n = 1, \dots, N$:

$$\begin{aligned}\frac{1}{k}(\mathbf{v}_n - \mathbf{v}_{n-1}) - \nu \Delta \mathbf{v}_n + (\mathbf{v}_n \cdot \nabla) \mathbf{v}_n + \nabla p_n &= \mathbf{f}(t_n) \quad \text{in } \Omega \\ \nabla \cdot \mathbf{v}_n &= 0 \quad \text{in } \Omega \\ \mathbf{v}_n &= \mathbf{v}_D(t_n) \quad \text{on } \partial\Omega \\ \mathbf{v}_0 &= 0\end{aligned} \tag{1}$$

Here, (\mathbf{v}_n, p_n) denotes the approximation to $(\mathbf{v}, p)(t_n)$ at time $t_n = nk$ with time step size $k > 0$. The time-discretized system has to be solved for (\mathbf{v}_n, p_n) while \mathbf{v}_{n-1} is used from the previous time step. System (1) corresponds to the nonlinear, stationary Navier-Stokes equations (with additional term $\frac{1}{k}(\mathbf{v}_n - \mathbf{v}_{n-1})$) which can be solved by Newton's method, analogously to sheet 8.

- a. Modify the matrix assembly routine of the class `LocalFlowAssembler` at the location marked by `TODO` exercise A in `ex8.FoilNavierStokes.h` to compute $D_{(\mathbf{v}, p)} F_\nu((\mathbf{v}_l, p_l); \cdot, \cdot)$.

Hint: In this routine, the data fields `sol_ns.[q]`, `grad_sol_ns.[q]` store the values of the previous Newton iterate at quadrature point q , i.e. $(\mathbf{v}^l, p^l)(x_q)$ and $(\nabla \mathbf{v}^l, \nabla p^l)(x_q)$, respectively.

- b. Modify the vector assembly routine of the class `LocalFlowAssembler` at the location marked by `TODO` exercise B in `ex8.FoilNavierStokes.h` to compute $F_\nu((\mathbf{v}_l, p_l), \cdot)$.

Hint: In this routine, the data fields `sol_ns.[q]`, `grad_sol_ns.[q]` store the values of the previous Newton iterate at quadrature point q , i.e. $(\mathbf{v}^l, p^l)(x_q)$ and $(\nabla \mathbf{v}^l, \nabla p^l)(x_q)$, respectively. Further, the data fields `sol_ts.[q]`, `grad_sol_ts.[q]` store the values of the previous time step at quadrature point q , i.e. $(\mathbf{v}_n, p_n)(x_q)$ and $(\nabla \mathbf{v}_n, \nabla p_n)(x_q)$, respectively.

- c. Run the code on up to 12 MPI processes for $\nu = 1e-1$, $f_z = -1$, $v_X = 1$, $T = 0.05$, $k = 0.005$. Note that all parameters are defined in the parameter file `ex8.FoilNavierStokes.xml` and can be changed without recompilation.

The program output is given by a series of pvtu files `ex8.solution.n.pvtu` with n denoting the time step and a csv file `pp_values.csv`. Each row in the csv file corresponds to one time step n and is of the form

$$(t_n \quad \|\nabla \cdot \mathbf{v}(t_n)\|_2 \quad \mathbf{f}_{foil1}[0] \quad \mathbf{f}_{foil1}[1] \quad \mathbf{f}_{foil1}[1]\mathbf{f}_{foil1}[0]^{-1} \quad \mathbf{f}_{foil2}[0] \quad \mathbf{f}_{foil2}[1] \quad \mathbf{f}_{foil2}[1]\mathbf{f}_{foil2}[0]^{-1} \quad)$$

Plot these quantities over time t_n and submit it.

Load the provided paraview state file. This will automatically perform the setup of visualization filters. See the pdf `paraview.notes.pdf`, provided by sheet 8, for further details. Save an animation for the loaded solution files.

- d. The mesh file is created by the python script `ex8.FoilStokes/mesh_generation/create_channel_mesh.py`. You can run it by the terminal command `python3 create_channel_mesh.py` inside the directory `mesh_generation`. Afterwards, you have to run `ccmake ../` inside the `Hiflow` build directory in order to copy the newly created mesh `channel.inp` into the example build directory.

In this script, the variables `angle_foil.1`, `angle_foil.2` (in radians, $\in [-\pi, \pi]$) set the angles of attack for both foils. Moreover, the variable `foil.dist` determines the distance between both foils.

Vary the angles and the distance to see how these variables affect the drag and down force acting on foil2, which is located in the slipstream of foil1.

This short video shows what may happen in practice, if a foil is located in the dirty air, created by another foil: <https://www.youtube.com/watch?v=e06bEuBOEG4>

The corresponding code framework is `ex8.FoilNavierStokes`. Don't forget to the modify the file `exercises/C-MakeLists.txt` accordingly, see the first exercise sheet for details.

Submission: until 02.07.2021, 11 am, moodle upload