

Rishitha S S

```
#include <Servo.h>

int pirSensor1 = 2;
int pinLed = 12;
int pinBuzzer = 13;
int pirSensor2 = 3;
int pos = 0;

Servo myservo;

void setup() {
    pinMode(pirSensor1 ,INPUT);
    pinMode(pinLed ,OUTPUT);
    pinMode(pinBuzzer ,OUTPUT);
    pinMode(pirSensor2 , INPUT);
    myservo.attach(6);
}

void loop() {
    int x = digitalRead(pirSensor1);
    if(x == HIGH){
        digitalWrite(pinLed ,HIGH);
        tone(pinBuzzer ,1000,500);
    }else{
        digitalWrite(pinLed ,LOW);
    }
    delay(10);
    int y = digitalRead(pirSensor2);
    if(y == HIGH)
    {
        for(pos=90; pos>=0; pos-=1){
            myservo.write(pos);
```

```

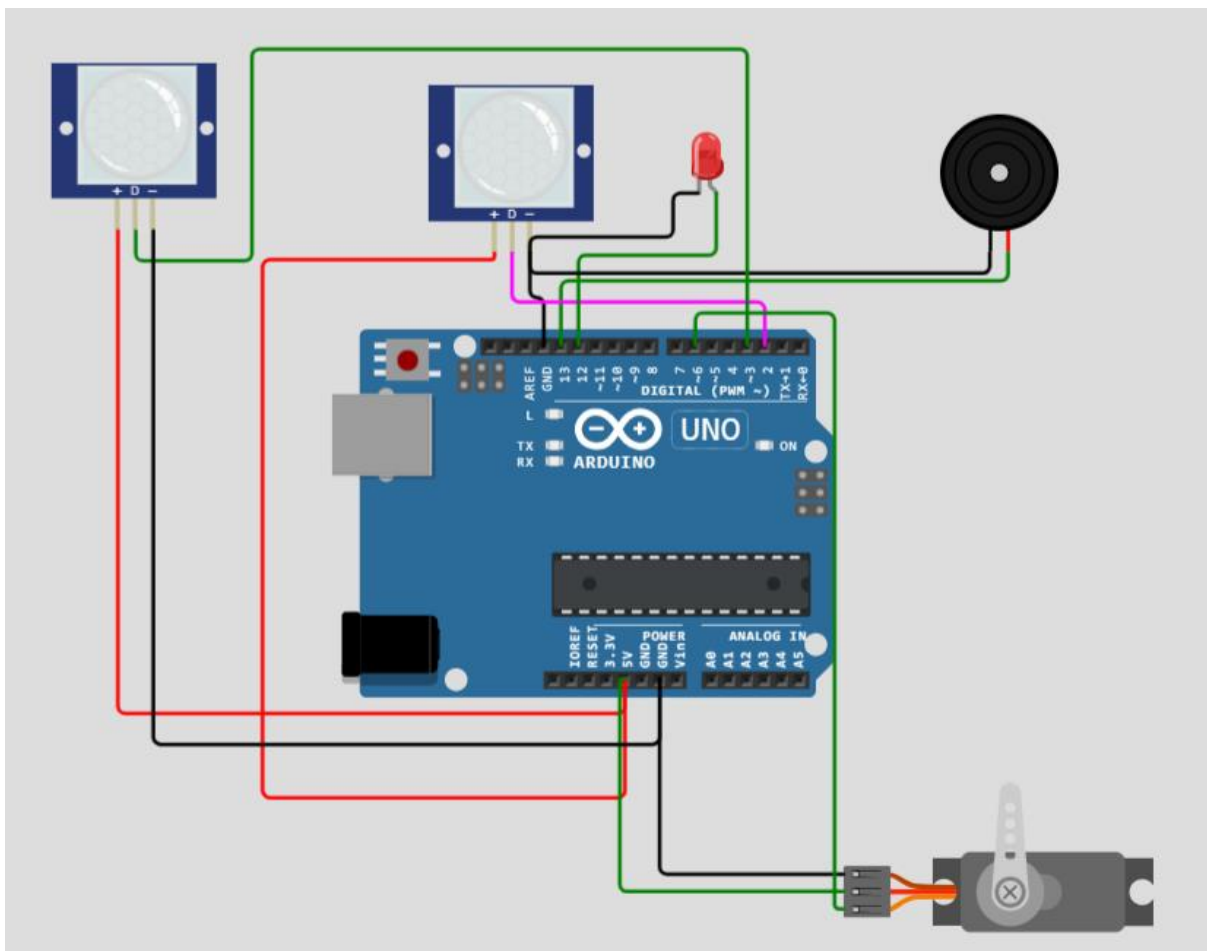
    delay(10);
}
delay(5000);
for(pos=0; pos<=90; pos+=1){
    myservo.write(pos);
    delay(10);

}

}

}

```



Link: [smart home Copy - Wokwi Arduino and ESP32 Simulator](#)