

Mathematical Economics

Alpha Chiang

Chapter 4-5

Chapter 4 Linear Models and Matrix Algebra Matrices as Arrays

```
In [1]: from sympy import symbols, Matrix
x1, x2, x3 = symbols('x_1,x_2,x_3')
A = Matrix([[6, 3, 1], [1, 4, -2], [4, -1, 5]])
A
```

```
Out[1]: 
$$\begin{bmatrix} 6 & 3 & 1 \\ 1 & 4 & -2 \\ 4 & -1 & 5 \end{bmatrix}$$

```

```
In [2]: x = Matrix((x1,x2,x3))
x
```

```
Out[2]: 
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

```

```
In [3]: d = Matrix((22,12,10))
d
```

```
Out[3]: 
$$\begin{bmatrix} 22 \\ 12 \\ 10 \end{bmatrix}$$

```

```
In [4]: A * x
```

Out[4]:
$$\begin{bmatrix} 6x_1 + 3x_2 + x_3 \\ x_1 + 4x_2 - 2x_3 \\ 4x_1 - x_2 + 5x_3 \end{bmatrix}$$

```
In [5]: import numpy as np
npA = np.array([6, 3, 1], [1, 4, -2], [4, -1, 5])
# To be able to solve this system linearly, we need to use numpy arrays
npA
npd = np.array((22,12,10))
npd
x = np.linalg.solve(npA, npd)
x
```

Out[5]: array([2., 3., 1.])

Basic Matrix Operations and other operations can be found the below websites

<https://numpy.org/doc/stable/reference/generated/numpy.matrix.html>

<https://docs.sympy.org/latest/tutorial/matrices.html>

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```
In [7]: from sympy import symbols, Eq, solve
Y, C, I0, G0, a, b = symbols('Y, C, I_0, G_0, a, b')
eq1 = Eq(Y, C + I0 + G0)
eq2 = Eq(C, a + b*Y)

result = solve([eq1, eq2], (Y, C))

print(result[Y])
print(result[C])
```

$$-(G_0 + I_0 + a)/(b - 1)$$
$$-(a + b*(G_0 + I_0))/(b - 1)$$

```
In [8]: from sympy import symbols, Matrix
from sympy import Symbol, dsolve, Function, Derivative, Eq
Y, C, I0, G0, a, b = symbols('Y, C, I_0, G_0, a, b')
eq1 = Eq(Y, C + I0 + G0)
eq1
```

Out[8]:

$$Y = C + G_0 + I_0$$

```
In [9]: eq2 = Eq(C, a + b*Y)
eq2
```

```
Out[9]: C = Yb + a
```

```
In [10]: from sympy import *
Y, C, I0, G0, a, b = symbols('Y, C, I_0, G_0, a, b')
eqns = [ (Y - C - I0 - G0), (C - a - b*Y)]
linsolve(eqns, [Y, C])
```

```
Out[10]: {(- (G_0 + I_0 + a)/(b - 1), - (G_0 b + I_0 b + a)/(b - 1))}
```

CHAPTER 5

Linear Models and Matrix Algebra (Continued)

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```
In [12]: from sympy import symbols, Matrix
x1, x2, x3 = symbols('x_1, x_2, x_3')
A = Matrix([[7, -3, -3], [2, 4, 1], [0, -2, -1]])
A
```

```
Out[12]: 
$$\begin{bmatrix} 7 & -3 & -3 \\ 2 & 4 & 1 \\ 0 & -2 & -1 \end{bmatrix}$$

```

```
In [13]: x = Matrix((x1, x2, x3))
x
```

```
Out[13]: 
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

```

```
In [14]: A * x
```

```
Out[14]: 
$$\begin{bmatrix} 7x_1 - 3x_2 - 3x_3 \\ 2x_1 + 4x_2 + x_3 \\ -2x_2 - x_3 \end{bmatrix}$$

```

```
In [15]: import numpy as np
npA = np.array([[7, -3, -3], [2, 4, 1], [0, -2, -1]])
D1 = np.linalg.det(npA)
D1
```

```
Out[15]: -7.999999999999998
```

```
In [16]: npd = np.array((7,0,2))
npd
x = np.linalg.solve(npA, npd)
x
```

```
Out[16]: array([-0.5,  1.5, -5. ])
```

```
In [17]: from numpy.linalg import matrix_rank
matrix_rank(npA) #Rank of a Matrix
```

```
Out[17]: 3
```

5.4 Finding the Inverse Matrix

Example 1

```
In [18]: import numpy as np
npA = np.array([[4, 1, 2], [5, 2, 1], [1, 0, 3]])
npA
```

```
Out[18]: array([[4, 1, 2],
               [5, 2, 1],
               [1, 0, 3]])
```

```
In [19]: from numpy.linalg import inv
inv(npA)
```

```
Out[19]: array([[ 1.          , -0.5          , -0.5          ],
```

```

        [-2.33333333, 1.66666667, 1.      ],
        [-0.33333333, 0.16666667, 0.5     ]])

```

Example 2

```

In [20]: npA = np.array([[3, 2], [1, 0]])
         inv(npA)

```

```

Out[20]: array([[ 0. ,  1. ],
               [ 0.5, -1.5]])

```

Example 3

```

In [21]: npA = np.array([[4, 1, -1], [0, 3, 2], [3, 0, 7]])
         D2 = np.linalg.det(npA)
         D2

```

```

Out[21]: 98.99999999999999

```

```

In [22]: inv(npA)

```

```

Out[22]: array([[ 0.21212121, -0.07070707,  0.05050505],
               [ 0.06060606,  0.31313131, -0.08080808],
               [-0.09090909,  0.03030303,  0.12121212]])

```

5.6 Application to Market and National-Income Models

Market Model

```

In [24]: P1 = Symbol('P_1')
         P2 = Symbol('P_2')
         c0 = Symbol('c_0')
         c1 = Symbol('c_1')
         c2 = Symbol('c_2')
         gamma0 = Symbol('\gamma_0')
         gamma1 = Symbol('\gamma_1')
         gamma2 = Symbol('\gamma_2')
         eq1 = Eq(c1*P1 + c2*P2, -c0)
         eq2 = Eq(gamma1*P1 + gamma2*P2, -gamma0)
         display(eq1, eq2)

```

$$P_1 c_1 + P_2 c_2 = -c_0$$

$$P_1 \gamma_1 + P_2 \gamma_2 = -\gamma_0$$

```
In [25]: from sympy import symbols, Eq, solve
         solve((eq1,eq2), (P1,P2))
```

```
Out[25]: {P_1: (-\gamma_0*c_2 + \gamma_2*c_0)/(\gamma_1*c_2 - \gamma_2*c_1),
         P_2: (\gamma_0*c_1 - \gamma_1*c_0)/(\gamma_1*c_2 - \gamma_2*c_1)}
```

IS-LM Model: Closed Economy

```
In [26]: Y = Symbol('Y')
         C = Symbol('C')
         I = Symbol('I')
         G = Symbol('G')
         a = Symbol('a')
         b = Symbol('b')
         t = Symbol('t')
         d = Symbol('d')
         e = Symbol('e')
         i = Symbol('i')
         G0 = Symbol('G_0')
         M0 = Symbol('M_0')
         Md = Symbol("M_d")
         Ms = Symbol("M_s")
         l = Symbol('l')
         k = Symbol('k')
         eq1 = Eq(Y, C + I + G)
         eq2 = Eq(Md, Ms)
         eq3 = Eq(C, a + b*(1 - t)*Y)
         eq4 = Eq(I, d - e*i)
         eq5 = Eq(G, G0)
         eq6 = Eq(M0, k*Y - l*i)
```

```
In [28]: display(eq1,eq2,eq3,eq4,eq5,eq6)
```

$$Y = C + G + I$$

$$M_d = M_s$$

$$C = Yb(1 - t) + a$$

$$I = d - ei$$

$$G = G_0$$

$$M_0 = Yk - il$$

```
In [29]: from sympy import symbols, Matrix
A = Matrix([[1, -1, -1, 0], [b*(1-t), -1, 0, 0],
            [0, 0, 1, e], [k, 0, 0, -l]])
A
```

```
Out[29]:
```

$$\begin{bmatrix} 1 & -1 & -1 & 0 \\ b(1-t) & -1 & 0 & 0 \\ 0 & 0 & 1 & e \\ k & 0 & 0 & -l \end{bmatrix}$$

```
In [30]: x = Matrix((Y,C,I,i))
x
```

```
Out[30]:
```

$$\begin{bmatrix} Y \\ C \\ I \\ i \end{bmatrix}$$

```
In [31]: d = Matrix((G0,-a,d,M0))
d
```

```
Out[31]:
```

$$\begin{bmatrix} G_0 \\ -a \\ d \\ M_0 \end{bmatrix}$$

```
In [32]: A * x
```

```
Out[32]:
```

$$\begin{bmatrix} -C - I + Y \\ -C + Yb(1-t) \\ I + ei \\ Yk - il \end{bmatrix}$$

```
In [33]: from sympy import *
Y, C, I, G, G0, a, b = symbols('Y, C, I, G, G_0, a, b')
```

```
t, d, e, i, M0, Md, Ms, l, k = symbols("t, d, e, i, M_0, M_d, M_s, l, k")
eqns = [(Y - C - I - G0), (-C + a + (b*(1 - t)*Y)), (I - d + (e*i)), (-M0 + (k*Y) + (-l*i))]
eqns
```

```
Out[33]: [-C - G_0 - I + Y, -C + Y*b*(1 - t) + a, I - d + e*i, -M_0 + Y*k - i*l]
```

```
In [46]: SOL = linsolve(eqns, [Y,C,i,I])
# Run the SOL
```

EXERCISE 5.6 --Q3--

```
In [38]: from sympy import symbols, Matrix
A = Matrix([[0.3, 100], [0.25, -200]])
A
```

```
Out[38]: 
$$\begin{bmatrix} 0.3 & 100 \\ 0.25 & -200 \end{bmatrix}$$

```

```
In [39]: x = Matrix((Y,i))
x
```

```
Out[39]: 
$$\begin{bmatrix} Y \\ i \end{bmatrix}$$

```

```
In [40]: d = Matrix((252,176))
d
```

```
Out[40]: 
$$\begin{bmatrix} 252 \\ 176 \end{bmatrix}$$

```

```
In [41]: A * x
```

```
Out[41]: 
$$\begin{bmatrix} 0.3Y + 100i \\ 0.25Y - 200i \end{bmatrix}$$

```

```
In [42]: import numpy as np
npA = np.array([[0.3, 100], [0.25, -200]])
npA
npd = np.array((252,176))
npd
```



```
x = np.linalg.solve(npA, npd)
x
```

Out[42]: array([8.0e+02, 1.2e-01])

Furkan zengin