

A Project Report on
**Mathematica as a Tool for Solving
Problems in General Relativity**

by
Tathagata Karmakar
SB-1312043

under guidance of
Dr. Tapobrata Sarkar



Department of Physics
Indian Institute of Technology, Kanpur
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CERTIFICATE

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Problems in General Relativity**

duly completed by
Tathagata Karmakar
SB-1312043

Submitted by,

Tathagata Karmakar
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Tathagata Karmakar
Junior Undergraduate
Department of Physics
IIT Kanpur

Under supervision of,

T. Sarkar
31.8.16

Dr. Tapobrata Sarkar
Professor
Department of Physics
IIT Kanpur

Date: August 1, 2016

Place: Indian Institute of Technology, Kanpur

Abstract

General theory of relativity provides us a new concept of gravity. Existence of gravitational waves, bending of starlight, precession of planetary orbits can be predicted using this theory. Beside all these, it is indispensable while exploring physics near a black hole. But it is extremely difficult, if not impossible, to solve Einstein's equations exactly. That's why various computational tools like Mathematica are becoming more useful day by day. This project explores Fermi normal coordinates near a Kerr metric and how Mathematica can be used in efficient manner to explore physics in Kerr metric. The benefit of using Fermi normal coordinates will be emphasized through expression of tidal potential in that frame in Kerr metric.

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Aim

The main objectives of the project are

- To learn the theory of general relativity beginning from the basics and then studying application in case of a massive spherically symmetric star.
- To study the construction of Fermi normal coordinates and their importance.
- To learn use of RGTC package in Mathematica for calculations in general relativity.
- To analyze the black hole tidal problem in Fermi normal coordinates with efficient algorithm in mathematica for the calculations.

Work

2.1 Part I: Studying general relativity

First and foremost requirement of the project was being familiar with general relativity. To fulfil this I had to study general relativity beginning from the basics till some advanced topics. For most of the part lecture notes of Matthias Blau were used [1]. Topics studied were:

- I. Definition of tensor, tensor algebra, covariant derivatives of tensor, parallel transport, Fermi-Walker parallel transport [1, 2].
- II. Definition of metric, geodesic equation, Christoffel symbols [1, 2].
- III. Principle of minimal coupling, energy-momentum tensor(of a perfect fluid), energy-momentum tensor as a source of gravity [1, 5].
- IV. Riemann curvature tensor and its properties, geodesic deviation equation, Lie derivatives, Killing vectors(basics) [1].
- V. Raychaudhuri equation for timelike geodesic congruences, Raychaudhuri equation for affine Null geodesic congruences, Raychaudhuri equation for non-affinely parametrized Null geodesics [1].
- VI. Einstein's equation, cosmological constant [1].

- VII. Static, spherically symmetric metrics, Schwarzschild metric, Birkhoff's theorem, interior solution for a static star, Tolman-Oppenheimer-Volkoff equation [1].
- VIII. Equation for shape of orbit in Schwarzschild geometry, timelike and null geodesics. Precession of perihelia of planetary orbits, bending of Light by a star [1].
- IX. Schwarzschild radius, Schwarzschild black holes, Eddington-Finkelstein coordinates, event horizons, Kruskal-Szekeres coordinates, maximal extension of Schwarzschild spacetime [1].
- X. Construction of Fermi normal coordinate system and Fermi normal coordinate as local inertial frame(Mikowski metric and vanishing of Christoffel symbols) [6].

2.2 Part II: Mathematica and RGTC package for calculations in general relativity

RGTC(Riemannian Geometry and Tensor Calculus) package for Mathematica can be found in <http://www.inp.demokritos.gr/~sbonano/RGTC/>. The file EDCRGTCcode.m should be kept in \$Path of Mathematica. Command `<<EDCRGTCcode.m` loads the package.

To use the package one needs to define coordinates as a list of symbols and a symmetric matrix as metric. Then command `RGtensors[metric, coordinates]` calculates the following(here U means upper index and d means lower i.e. $\Gamma^\mu_{\alpha\beta}$ is denoted as `GUdd[[μ, α, β]]`)*:

- Metric `gdd` (also a input).
- Inverse metric `gUU`.
- Chrisoffel symbols.

*See <http://www.inp.demokritos.gr/~sbonano/RGTC/NEBX-RGTC.pdf>

- Riemann tensors Rddddd i.e. $R_{\mu\nu\rho\lambda}$.
- Riemann tensors RUddddd i.e. $R^\mu_{\nu\rho\lambda}$.
- Ricci tensor Rdd.
- Scalar curvature R.
- Weyl tensor & Einstein tensors.

A sample run is shown below:

```

In[1]:=
In[2]:= (*Ishii, section III: COMPONENTS OF THE RIEMANN TENSOR FOR A KERR SPACETIME*)
(*To be remembered that index 1 corresponds to temporal component and 2,
3,4 corresponds to 1,2,3 indices in Ishii's paper*)
<< EDCRGTCcode.m

In[1]:= BLcoord = {t, r,  $\theta$ ,  $\phi$ }; (*Boyer-Lindquist coordinates*)

In[2]:=  $\Sigma = r^2 + a^2 \cos^2[\theta]$ ;  $\Delta = r^2 + a^2 - 2Mr$ ; simpRules = TrigRules;
(*Here  $\Delta$  in Ishii's paper is written as  $\Delta\Delta$ *) assmp =
((2 r^2 + a^2 + a^2 Cos[2  $\theta$ ]) > 0) && ( $\Delta \geq 0$ ) && (2  $\Sigma = 2 r^2 + a^2 + a^2 \cos[2 \theta]$ ) && (r >= 0);
(*M and a denote mass and spin parameter respectively*)

In[3]:= gBL = 
$$\begin{pmatrix} -1 + 2Mr/\Sigma & 0 & 0 & -2Mra \sin[\theta]^2/\Sigma \\ 0 & \Sigma/\Delta\Delta & 0 & 0 \\ 0 & 0 & \Sigma & 0 \\ -2Mra \sin[\theta]^2/\Sigma & 0 & 0 & ((r^2 + a^2)^2 - \Delta\Delta a^2 \sin[\theta]^2) \sin[\theta]^2/\Sigma \end{pmatrix};$$


In[4]:= RGTensors[gBL, BLcoord];

gdd = 
$$\begin{pmatrix} -1 + \frac{2Mr}{r^2 + a^2 \cos^2[\theta]} & 0 & 0 & -\frac{2Mra \sin[\theta]^2}{r^2 + a^2 \cos^2[\theta]} \\ 0 & \frac{r^2 + a^2 \cos^2[\theta]}{a^2 - 2Mr + r^2} & 0 & 0 \\ 0 & 0 & r^2 + a^2 \cos^2[\theta] & 0 \\ -\frac{2Mra \sin[\theta]^2}{r^2 + a^2 \cos^2[\theta]} & 0 & 0 & \frac{\sin[\theta]^2 ((a^2 + r^2)^2 - a^2 (a^2 - 2Mr + r^2) \sin[\theta]^2)}{r^2 + a^2 \cos^2[\theta]} \end{pmatrix}$$


```

Figure 2.1: Inputs & Commands for Running RGTC Package

$$gdd = \begin{pmatrix} -1 + \frac{2Mr}{r^2+a^2 \cos[\theta]^2} & 0 & 0 & -\frac{2aMr \sin[\theta]^2}{r^2+a^2 \cos[\theta]^2} \\ 0 & \frac{r^2+a^2 \cos[\theta]^2}{a^2-2Mr+r^2} & 0 & 0 \\ 0 & 0 & r^2+a^2 \cos[\theta]^2 & 0 \\ -\frac{2aMr \sin[\theta]^2}{r^2+a^2 \cos[\theta]^2} & 0 & 0 & \frac{\sin[\theta]^2 \left((a^2+r^2)^2 - a^2 (a^2-2Mr+r^2) \sin[\theta]^2 \right)}{r^2+a^2 \cos[\theta]^2} \end{pmatrix}$$

$LineElement = \frac{(r^2+a^2 \cos[\theta]^2) d[r]^2}{a^2-2Mr+r^2} + \frac{(2Mr-r^2-a^2 \cos[\theta]^2) d[t]^2}{r^2+a^2 \cos[\theta]^2} +$
 $(r^2+a^2 \cos[\theta]^2) d[\theta]^2 - \frac{4aMr d[t] d[\varphi] \sin[\theta]^2}{r^2+a^2 \cos[\theta]^2} + \frac{1}{r^2+a^2 \cos[\theta]^2}$
 $d[\varphi]^2 \sin[\theta]^2 (a^4+2a^2 r^2+r^4-a^4 \sin[\theta]^2+2a^2 Mr \sin[\theta]^2-a^2 r^2 \sin[\theta]^2)$

$g_{UU} = \left\{ \left\{ - \left((r^2+a^2 \cos[\theta]^2) (a^4+2a^2 r^2+r^4-a^4 \sin[\theta]^2+2a^2 Mr \sin[\theta]^2-a^2 r^2 \sin[\theta]^2) \right) / \right. \right.$
 $(-2a^4 Mr+a^4 r^2-4a^2 Mr^3+2a^2 r^4-2Mr^5+r^6+a^6 \cos[\theta]^2+2a^4 r^2 \cos[\theta]^2 +$
 $a^2 r^4 \cos[\theta]^2+2a^4 Mr \sin[\theta]^2-a^4 r^2 \sin[\theta]^2+4a^2 Mr^3 \sin[\theta]^2-a^2 r^4 \sin[\theta]^2 -$
 $a^6 \cos[\theta]^2 \sin[\theta]^2+2a^4 Mr \cos[\theta]^2 \sin[\theta]^2-a^4 r^2 \cos[\theta]^2 \sin[\theta]^2) , 0, 0,$
 $(2aMr (r^2+a^2 \cos[\theta]^2)) / (2a^4 Mr-a^4 r^2+4a^2 Mr^3-2a^2 r^4+2Mr^5-r^6-a^6 \cos[\theta]^2 -$
 $2a^4 r^2 \cos[\theta]^2-a^2 r^4 \cos[\theta]^2-2a^4 Mr \sin[\theta]^2+a^4 r^2 \sin[\theta]^2-4a^2 Mr^3 \sin[\theta]^2 +$
 $a^2 r^4 \sin[\theta]^2+a^6 \cos[\theta]^2 \sin[\theta]^2-2a^4 Mr \cos[\theta]^2 \sin[\theta]^2+a^4 r^2 \cos[\theta]^2 \sin[\theta]^2) \left. \right\} ,$
 $\left\{ 0, \frac{a^2-2Mr+r^2}{r^2+a^2 \cos[\theta]^2}, 0, 0 \right\}, \left\{ 0, 0, \frac{1}{r^2+a^2 \cos[\theta]^2}, 0 \right\},$
 $\left\{ (2aMr (r^2+a^2 \cos[\theta]^2)) / (2a^4 Mr-a^4 r^2+4a^2 Mr^3-2a^2 r^4+2Mr^5-r^6-a^6 \cos[\theta]^2 -$
 $2a^4 r^2 \cos[\theta]^2-a^2 r^4 \cos[\theta]^2-2a^4 Mr \sin[\theta]^2+a^4 r^2 \sin[\theta]^2-4a^2 Mr^3 \sin[\theta]^2 +$
 $a^2 r^4 \sin[\theta]^2+a^6 \cos[\theta]^2 \sin[\theta]^2-2a^4 Mr \cos[\theta]^2 \sin[\theta]^2+a^4 r^2 \cos[\theta]^2 \sin[\theta]^2) , \right.$
 $0, 0, ((2Mr-r^2-a^2 \cos[\theta]^2) (r^2+a^2 \cos[\theta]^2) \csc[\theta]^2) /$
 $(2a^4 Mr-a^4 r^2+4a^2 Mr^3-2a^2 r^4+2Mr^5-r^6-a^6 \cos[\theta]^2-2a^4 r^2 \cos[\theta]^2 -$
 $a^2 r^4 \cos[\theta]^2-2a^4 Mr \sin[\theta]^2+a^4 r^2 \sin[\theta]^2-4a^2 Mr^3 \sin[\theta]^2+a^2 r^4 \sin[\theta]^2 +$
 $a^6 \cos[\theta]^2 \sin[\theta]^2-2a^4 Mr \cos[\theta]^2 \sin[\theta]^2+a^4 r^2 \cos[\theta]^2 \sin[\theta]^2) \left. \right\} \}$

g_{UU} computed in 0.172 sec
 Γ computed in 0.125 sec
 $Riemann(dddd)$ computed in 1.063 sec
 $Riemann(Uddd)$ computed in 10.375 sec
 $Ricci$ computed in 2.609 sec
 $Weyl$ computed in 18.359 sec
 $Einstein$ computed in 5.625 sec
 All tasks completed in 38.359 seconds

Figure 2.2: Outputs after Running RGTC Package

2.3 Part III: Kerr Spacetime Through Mathematica

This part involved first finding Riemann tensors and its derivatives in Fermi normal coordinates. Then calculating tidal potential upto fourth order terms. For most part assistance was taken from Ishii's paper [3].

First of all, Kerr metric in Boyer-Lindquist coordinate system is given as:

$$ds^2 = -\left(1 - \frac{2Mr}{\Sigma}\right)dt^2 - \frac{4Mra \sin^2 \theta}{\Sigma} dt d\varphi + \frac{(r^2 + a^2)^2 - \Delta a^2 \sin^2 \theta}{\Sigma} \sin^2 \theta d\varphi^2 + \frac{\Sigma}{\Delta} dr^2 + \Sigma d\theta^2 \quad (2.1)$$

Where

$$\Sigma = r^2 + a^2 \cos^2 \theta, \quad \Delta = r^2 + a^2 - 2Mr \quad (2.2)$$

M and a are mass and spin parameter respectively.

In Mathematica the commands are:

```
In[1]:=
In[2]:= (*Ishii, section III: COMPONENTS OF THE RIEMANN TENSOR FOR A KERR SPACETIME*)
(*To be remembered that index 1 corresponds to temporal component and 2,
3,4 corresponds to 1,2,3 indices in Ishii's paper*)
<< EDCRGTCcode.m
In[1]:= BLcoord = {t, r, θ, ϕ}; (*Boyer-Lindquist coordinates*)
In[2]:= Σ = r^2 + a^2 Cos[θ]^2; Δ = r^2 + a^2 - 2 M r; simpRules = TrigRules;
(*Here Δ in Ishii's paper is written as ΔΔ*) assmp =
((2 r^2 + a^2 + a^2 Cos[2 θ]) ≥ 0) && (ΔΔ ≥ 0) && (2 Σ = 2 r^2 + a^2 + a^2 Cos[2 θ]) && (r >= 0);
(*M and a denote mass and spin parameter respectively*)
In[3]:= gBL = 
$$\begin{pmatrix} -1 + 2 M r / \Sigma & 0 & 0 & -2 M r a \sin[\theta]^2 / \Sigma \\ 0 & \Sigma / \Delta \Delta & 0 & 0 \\ 0 & 0 & \Sigma & 0 \\ -2 M r a \sin[\theta]^2 / \Sigma & 0 & 0 & ((r^2 + a^2)^2 - \Delta \Delta a^2 \sin[\theta]^2) \sin[\theta]^2 / \Sigma \end{pmatrix};$$

In[4]:= RGTensors[gBL, BLcoord];
gdd = 
$$\begin{pmatrix} -1 + \frac{2 M r}{r^2 + a^2 \cos[\theta]^2} & 0 & 0 & -\frac{2 a M r \sin[\theta]^2}{r^2 + a^2 \cos[\theta]^2} \\ 0 & \frac{r^2 + a^2 \cos[\theta]^2}{a^2 - 2 M r + r^2} & 0 & 0 \\ 0 & 0 & r^2 + a^2 \cos[\theta]^2 & 0 \\ -\frac{2 a M r \sin[\theta]^2}{r^2 + a^2 \cos[\theta]^2} & 0 & 0 & \frac{\sin[\theta]^2 ((a^2 + r^2)^2 - a^2 (a^2 - 2 M r + r^2) \sin[\theta]^2)}{r^2 + a^2 \cos[\theta]^2} \end{pmatrix}$$

```

Figure 2.3: Inputs & Commands for Kerr spacetime

Standard tetrad is given as(see [3] eqns 74, 75, 76, 76):

```

In[5]:= (*Standard Tetrad*)
In[6]:= evec0 = {Sqrt[ΔΔ / Σ], 0, 0, -a Sin[θ] ^ 2 Sqrt[ΔΔ / Σ]};
In[7]:= evec1 = {0, Sqrt[Σ / ΔΔ], 0, 0};
In[8]:= evec2 = {0, 0, Sqrt[Σ], 0};
In[9]:= evec3 = {-a Sin[θ] / Sqrt[Σ], 0, 0, (r^2 + a^2) Sin[θ] / Sqrt[Σ]};
In[10]:= (*To see they indeed are orthonormal*)
        {evec0.gUU.evec0, evec0.gUU.evec1, evec0.gUU.evec2, evec0.gUU.evec3} // FullSimplify
Out[10]:= {-1, 0, 0, 0}
In[11]:= {evec1.gUU.evec0, evec1.gUU.evec1, evec1.gUU.evec2, evec1.gUU.evec3} // FullSimplify
Out[11]:= {0, 1, 0, 0}
In[12]:= {evec2.gUU.evec0, evec2.gUU.evec1, evec2.gUU.evec2, evec2.gUU.evec3} // FullSimplify
Out[12]:= {0, 0, 1, 0}
In[13]:= {evec3.gUU.evec0, evec3.gUU.evec1, evec3.gUU.evec2, evec3.gUU.evec3} // FullSimplify
Out[13]:= {0, 0, 0, 1}

```

Figure 2.4: Standard Tetrad

The tetrad components ($e_{\mu}^{(a)}$) are written as a matrix named jac. The matrix inverse is ijac ($e_{(a)}^{\mu}$). R1dddd is full simplified form of Rddddd (for computations with R1dddd will take lesser time though computation of R1dddd might take 2-3 minutes). A picture is shown in the next page.

```

In[14]:= jac = {evec0, evec1, evec2, evec3}; (*Writing tetrad components  $e_{\mu}^{(a)}$  as matrix jac*)
In[15]:= ijac = FullSimplify[Inverse[jac], assmp]; (*ijac consists of  $e_{(a)}^{\mu}$ *)
In[16]:=
In[17]:= (*R1dddd is Simplified version of Rddddd*)
        R1dddd = Table[FullSimplify[Rddddd[[i, j, k, l]], assmp],
            {i, 1, 4}, {j, 1, 4}, {k, 1, 4}, {l, 1, 4}];

```

Figure 2.5: Matrix and inverse matrix of tetrad components

Calculation of components of Riemann tensor in tetrad frame is given on next page:

```

In[20]:= (*Below combpos creates all even combinations of first four inputs
and combneg creates odd combinations*)combpos[i_, j_, k_, l_, m_] :=
  {{i, j, k, l, m}, {j, i, l, k, m}, {k, l, i, j, m}, {l, k, j, i, m}};
In[21]:= combneg[i_, j_, k_, l_, m_] :=
  {{i, j, l, k, m}, {j, i, k, l, m}, {l, k, i, j, m}, {k, l, j, i, m}};
In[22]:= A = {};(*A is to be filled with independent combinations of type i-j-k-l*)
In[23]:= (*This function returns true if none of the combinations of input is already in A*)
check[i_, j_, k_, l_] :=
  check[i, j, k, l] = (! MemberQ[A, {i, j, l, k}]) && (! MemberQ[A, {j, i, k, l}]) &&
    (! MemberQ[A, {j, i, l, k}]) && (! MemberQ[A, {l, k, i, j}]) &&
    (! MemberQ[A, {k, l, i, j}]) && (! MemberQ[A, {k, l, j, i}]) && (! MemberQ[A, {l, k, j, i}])
In[24]:= Do[A = If[check[i, j, k, l], Append[A, {i, j, k, l}], A],
  {i, 1, 4}, {j, 1, 4}, {k, 1, 4}, {l, 1, 4}];
In[25]:= (*Calculation of tetrad components of Rddddd*)
calR[i_, j_, k_, l_] := calR[i, j, k, l] = If[i == j || k == l, 0,
  FullSimplify[Sum[R1dddd[[i1, i2, i3, i4]] iJac[[i1, i]] iJac[[i2, j]] iJac[[i3, k]]
    iJac[[i4, l]], {i1, 1, 4}, {i2, 1, 4}, {i3, 1, 4}, {i4, 1, 4}], assmp]];
In[26]:= Rlist = {};
In[27]:= Do[Rlist = Append[Rlist, calR[A[[i]] /. List -> Sequence]], {i, Length[A]};
In[28]:= Rtetrad[i_, j_, k_, l_] :=
  Rtetrad[i, j, k, l] = If[Intersection[A, combpos[i, j, k, l]] != {},
    Rlist[[Position[A, Intersection[A, combpos[i, j, k, l]][[1]]][[1, 1]]]],
    -Rlist[[Position[A, Intersection[A, combneg[i, j, k, l]][[1]]][[1, 1]]]];

```

Figure 2.6: Code for calculation of Riemann tensor in tetrad frame

Results can be mathced with 78, 79 of [3].

In[88]:= **Rtetrad[2, 3, 2, 3]**

$$\text{Out[88]= } \frac{M r \left(3 a^2 - 2 r^2 + 3 a^2 \cos [2 \theta] \right)}{2 \left(r^2 + a^2 \cos [\theta]^2 \right)^3}$$

Figure 2.7: $R_{(1)(2)(1)(2)}$

Here one must remember that temporal components has index 1 in code. 1, 2, 3 spatial indices are written as 2, 3, 4 indices in code. In similar manner Q and P can be calculated(see [3] 80 to 99).

```

In[29]:= (* This calculates component ijklm of covariant derivative of Rldddd,
where m is differentiation index*)
defcR[i_, j_, k_, l_, m_] := defcR[i, j, k, l, m] = If[i == j || k == l, 0, FullSimplify[
  D[Rldddd[[i, j, k, l]], BLcoord[[m]]] - Sum[GUdd[[n, m, i]] Rldddd[[n, j, k, l]] +
  GUdd[[n, m, j]] Rldddd[[i, n, k, l]] + GUdd[[n, m, k]] Rldddd[[i, j, n, l]] +
  GUdd[[n, m, l]] Rldddd[[i, j, k, n]], {n, 1, 4}], assmp]];

In[30]:= CA = {}; (*CA will contain all independent {i,j,k,l,m} *)

In[31]:= Do[CA = Append[CA, Append[A[[i]], j]], {i, 1, Length[A]}, {j, 1, 4}];

In[32]:= coCA = {};

In[33]:= Do[coCA = Append[coCA, defcR[CA[[i]] /. List -> Sequence]], {i, Length[CA]}];

In[34]:= corR[i_, j_, k_, l_, m_] :=
  corR[i, j, k, l, m] = If[Intersection[CA, combpos[i, j, k, l, m]] != {},
    coCA[[Position[CA, Intersection[CA, combpos[i, j, k, l, m]]][[1]]][[1, 1]]],
    -coCA[[Position[CA, Intersection[CA, combneg[i, j, k, l, m]]][[1]]][[1, 1]]]];

In[35]:= (*This function will return Q in tetrad frame as a vector: As written in the paper*)
Q[i_, j_, k_, l_] :=
  Q[i, j, k, l] = Q[j, i, l, k] = Q[k, l, i, j] = Q[l, k, j, i] = FullSimplify[
    Table[If[i == j || k == l, 0, Sum[corR[i1, i2, i3, i4, i5] ijac[[i5, m]] ijac[[i1, i]]
      ijac[[i2, j]] ijac[[i3, k]] ijac[[i4, l]], {i1, 1, 4}, {i2, 1, 4},
      {i3, 1, 4}, {i4, 1, 4}, {i5, 1, 4}]], {m, {2, 3, 4, 1}}], assmp];

```

Figure 2.8: Calculating Q

```

In[36]:= CCA = {}; (*CCA will be filled with independent components of {i,j,k,l,m,n} *)

In[37]:= Do[CCA = Append[CCA, Append[CA[[i]], j]], {i, 1, Length[CA]}, {j, 1, 4}];

In[38]:= co2CA = {};

In[39]:= pos[i_, j_, k_, l_, m_, n_] :=
  pos[i, j, k, l, m, n] = If[Intersection[CCA, combpos[i, j, k, l, m, n]] != {},
    {Position[CCA, Intersection[CCA, combpos[i, j, k, l, m, n]]][[1]]][[1, 1]], 1},
    {Position[CCA, Intersection[CCA, combneg[i, j, k, l, m, n]]][[1]]][[1, 1]], -1}];

```

Figure 2.9: Calculating P

```

In[40]:=
(* This calculates component ijklmn of double covariant derivative of Rldddd,
where m and n are successive differentiation index*)
def2cR[i_, j_, k_, l_, m_, n_] := def2cR[i, j, k, l, m, n] =
  If[i == j || k == 1, 0, FullSimplify[(D[corR[i, j, k, l, m], BLcoord[[n]]] -
    Sum[GUdd[[q, n, i]] corR[q, j, k, l, m] + GUdd[[q, n, j]] corR[i, q, k, l, m] +
    GUdd[[q, n, k]] corR[i, j, q, l, m] + GUdd[[q, n, l]] corR[i, j, k, q, m] +
    GUdd[[q, n, m]] corR[i, j, k, l, q], {q, 1, 4}]] /.  $\theta \rightarrow \text{Pi}/2$ , assmp]]];

In[41]:= cor2R[i_, j_, k_, l_, m_, n_] :=
  cor2R[i, j, k, l, m, n] = co2CA[[pos[i, j, k, l, m, n][[1]]]] pos[i, j, k, l, m, n][[2]];

In[42]:= calc2R[i_, j_, k_, l_, m_, n_] :=
  calc2R[i, j, k, l, m, n] = If[pos[i, j, m, k, l, n][[1]] < pos[i, j, k, l, m, n][[1]] &&
    pos[i, j, l, m, k, n][[1]] < pos[i, j, k, l, m, n][[1]],
    -cor2R[i, j, m, k, l, n] - cor2R[i, j, l, m, k, n], def2cR[i, j, k, l, m, n]];

In[43]:= Do[co2CA = Append[co2CA, calc2R[CCA[[i]]] /. List -> Sequence]], {i, Length[CCA]};

In[44]:= iJac1 = FullSimplify[iJac /.  $\theta \rightarrow \text{Pi}/2$ , assmp];
(*P is calculated only on equatorial plane*)

In[45]:= (*This function will return P in tetrad frame as a vector: As written in the paper*)
P[i_, j_, k_, l_] := P[i, j, k, l] =
  P[j, i, l, k] = P[k, l, i, j] = P[l, k, j, i] = Table[If[i == j || k == 1, 0, FullSimplify[
    Sum[(1/2) (cor2R[i1, i2, i3, i4, i5, i6] + cor2R[i1, i2, i3, i4, i6, i5])
    iJac1[[i1, i]] iJac1[[i2, j]] iJac1[[i3, k]] iJac1[[i4, l]] iJac1[[i5, m]]
    iJac1[[i6, n]], {i1, 1, 4}, {i2, 1, 4}, {i3, 1, 4}, {i4, 1, 4},
    {i5, 1, 4}, {i6, 1, 4}], assmp]], {n, {2, 3, 4, 1}}, {m, {2, 3, 4, 1}}]

```

Figure 2.10: Calculating P

Result can be matched:

```

In[92]:= MatrixForm[P[2, 3, 2, 3]]
Out[92]//MatrixForm=

```

$$\begin{pmatrix}
\frac{3M(-5a^2 + (9M-4r)r)}{r^7} & 0 & 0 & 0 \\
0 & \frac{3M(5a^2 + r(-2M+r))}{r^7} & 0 & 0 \\
0 & 0 & \frac{9M(a^2 + r(-2M+r))}{r^7} & \frac{9aM\sqrt{a^2 + r(-2M+r)}}{r^7} \\
0 & 0 & \frac{9aM\sqrt{a^2 + r(-2M+r)}}{r^7} & -\frac{3M(-3a^2 + Mr)}{r^7}
\end{pmatrix}$$

Figure 2.11: $P_{(a)(b)(1)(2)(1)(2)}$

$$\begin{aligned} \text{In[90]} &:= \mathbf{Q}[2, 3, 2, 3] \\ \text{Out[90]} &= \left\{ \left(3 M \sqrt{a^2 + r} (-2 M + r) (-24 a^2 r^2 + 8 r^4 + 4 a^2 (a^2 - 6 r^2) \cos[2 \theta] + a^4 (3 + \cos[4 \theta])) \right) / \right. \\ &\quad \left. (8 (r^2 + a^2 \cos[\theta]^2)^{9/2}), \frac{3 a^2 M r (a^2 - 2 r^2 + a^2 \cos[2 \theta]) \sin[2 \theta]}{(r^2 + a^2 \cos[\theta]^2)^{9/2}}, 0, 0 \right\} \end{aligned}$$

Figure 2.12: $Q_{(a)(1)(2)(1)(2)}$

$\Lambda_a^{(a)}$ denotes components of the four vecotrs, used for construction of Fermi normal coordinates, in tetrad frame. Components $\tilde{\Lambda}$ (see 100 to 147 in [3]) are also calculated.

```

 $\Lambda_0 = \{\text{Sqrt}[1 + B^2 / r^2], 0, 0, B / r\};$  (*B=L-a E*)

In[48]:=  $\Lambda_1 = \{-B \sin[\Psi] / r, \cos[\Psi], 0, -\text{Sqrt}[1 + B^2 / r^2] \sin[\Psi]\};$ 

In[49]:=  $\Lambda_2 = \{0, 0, 1, 0\};$ 

In[50]:=  $\Lambda_3 = \{B \cos[\Psi] / r, \sin[\Psi], 0, \text{Sqrt}[1 + B^2 / r^2] \cos[\Psi]\};$ 

In[51]:=  $\text{Atilde}_0 = \Lambda_0;$ 

In[52]:=  $\text{Atilde}_1 = \Lambda_1 \cos[\Psi] + \Lambda_3 \sin[\Psi];$ 

In[53]:=  $\text{Atilde}_2 = \Lambda_2;$ 

In[54]:=  $\text{Atilde}_3 = \Lambda_3 \cos[\Psi] - \Lambda_1 \sin[\Psi];$ 

In[55]:=  $\Lambda = \text{Transpose}[\{\Lambda_0, \Lambda_1, \Lambda_2, \Lambda_3\}];$ 

In[56]:=  $\text{Atilde} = \text{Transpose}[\{\text{Atilde}_0, \text{Atilde}_1, \text{Atilde}_2, \text{Atilde}_3\}];$ 

In[57]:=  $\text{IAtilde} = \text{FullSimplify}[\text{Inverse}[\text{Atilde}]];$ 

In[58]:=  $\text{AAA} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos[\Psi] & 0 & -\sin[\Psi] \\ 0 & 0 & 1 & 0 \\ 0 & \sin[\Psi] & 0 & \cos[\Psi] \end{pmatrix};$ 

In[59]:=  $\text{mat} = \text{FullSimplify}[\Lambda.\text{AAA}];$ 

```

Figure 2.13: Λ and $\tilde{\Lambda}$

Results

Tidal component of gravitational potential is given as(see 129 of [3]):

$$\phi_{tidal} = \frac{1}{2}C_{ij}x^i x^j + \frac{1}{6}C_{ijk}x^i x^j x^k + \frac{1}{24}[C_{ijkl} + 4C_{(ij}C_{kl)} - 4B(kl|n|B_{ij})_n]x^i x^j x^k x^l + O(x^5) \quad (3.1)$$

Where i,j,k,l are summed over spatial components and*

$$C_{ij} = R_{0i0j}, C_{ijk} = R_{0(i0|j;k)}, C_{ijkl} = R_{0(i0|j;kl)}, B_{ijk} = R_{k(ij)0}$$

In tilde frame, assuming $r \gg M(>a)$:

$$\phi_{tidal} = \frac{1}{2}\tilde{C}_{ij}\tilde{x}^i \tilde{x}^j + \frac{1}{6}\tilde{C}_{ijk}\tilde{x}^i \tilde{x}^j \tilde{x}^k + \frac{1}{24}[\tilde{C}_{ijkl} + 4\tilde{C}_{(ij}\tilde{C}_{kl)} - 4\tilde{B}(kl|n|\tilde{B}_{ij})_n]\tilde{x}^i \tilde{x}^j \tilde{x}^k \tilde{x}^l + O(\tilde{x}^5) \quad (3.2)$$

Code for calculating \tilde{C} & \tilde{B} components is given below:

*Where first bracket means averaged over permutations.

$$A_{(p_1 p_2 \dots | q_1 | \dots | q_2 | \dots p_n)} = \frac{1}{n!} \sum_{\text{permutations}} A_{\text{permutations of } p \text{ with } q \text{ fixed.}}$$

```

In[60]:= (*Riemann tensor in tilde frame*)
calRtilde[i_, j_, k_, l_] := calRtilde[i, j, k, l] = If[i == j || k == l, 0,
  FullSimplify[Sum[(Rtetrad[i1, j1, k1, l1] /.  $\theta \rightarrow \pi/2$ ) mat[[i1, i]] mat[[j1, j]]
    mat[[k1, k]] mat[[l1, l]], {i1, 1, 4}, {j1, 1, 4}, {k1, 1, 4}, {l1, 1, 4}]]];
In[61]:= Rtildelist = {};
In[62]:= Do[Rtildelist = Append[Rtildelist, calRtilde[A[[i]] /. List  $\rightarrow$  Sequence]], {i, Length[A]}];
In[63]:= Rtilde[i_, j_, k_, l_] := Rtilde[i, j, k, l] = If[Intersection[A, combpos[i, j, k, l]]  $\neq$  {},
  Rtildelist[[Position[A, Intersection[A, combpos[i, j, k, l]][[1]]][[1, 1]]]],
  -Rtildelist[[Position[A, Intersection[A, combneg[i, j, k, l]][[1]]][[1, 1]]]]];
In[64]:= Ctilde[i_, j_] := Ctilde[i, j] = Rtilde[1, i, 1, j];
In[65]:= Btilde[i_, j_, k_] := Btilde[i, j, k] = (1/2) (Rtilde[k, i, j, 1] + Rtilde[k, j, i, 1]);
In[66]:= perm[ls_List] :=
  Module[{n = 0, htemp = {}, m = 0}, n = Length[ls]; htemp = Permutations[Range[n]];
  m = Length[htemp]; Table[ls[[htemp[[i, j]]]], {i, m}, {j, n}]]
In[67]:= QA = CA;
In[68]:= calQ[i_, j_, k_, l_, m_] :=
  calQ[i, j, k, l, m] = calQ[j, i, l, k, m] = calQ[k, l, i, j, m] = calQ[l, k, j, i, m] =
  If[i == j || k == l, 0, FullSimplify[Sum[(corR[i1, i2, i3, i4, i5] /.  $\theta \rightarrow \pi/2$ )
    ijac1[[i5, m]] ijac1[[i1, i]] ijac1[[i2, j]] ijac1[[i3, k]] ijac1[[i4, l]],
    {i1, 1, 4}, {i2, 1, 4}, {i3, 1, 4}, {i4, 1, 4}, {i5, 1, 4}]]];

```

Figure 3.1: \tilde{C}_{ij} , \tilde{C}_{ijk} & \tilde{B}_{ijk}

Calculating \tilde{C}_{ijkl} needs extra care because we have to find a way to calculate sum of all combination of indices of double covariant derivative of Riemann tensor. The code is shown on next page.

```

In[69]:= coRtilde[i_, j_, k_, l_, m_] :=
  coRtilde[i, j, k, l, m] = coRtilde[j, i, l, k, m] = coRtilde[k, l, i, j, m] =
  coRtilde[l, k, j, i, m] = If[i == j || k == l, 0, FullSimplify[Sum[
    calQ[i1, j1, k1, l1, m1] mat[[i1, i]] mat[[j1, j]] mat[[k1, k]] mat[[l1, l]] mat[[
      m1, m]], {i1, 1, 4}, {j1, 1, 4}, {k1, 1, 4}, {l1, 1, 4}, {m1, 1, 4}]]];

In[70]:= Ctilde[i_, j_, k_] := Ctilde[i, j, k] =
  Module[{temp = {}, len = 1, s = 0}, temp = perm[{i, j, k}]; len = Length[temp];
  Do[s = s + coRtilde[l, temp[[l, 1]], 1, temp[[l, 2]], temp[[l, 3]]], {l, len}];
  FullSimplify[s / len];

In[71]:= calP[i_, j_, k_, l_, m_, n_] := calP[i, j, k, l, m, n] =
  calP[j, i, l, k, m, n] = calP[k, l, i, j, m, n] = calP[l, k, j, i, m, n] =
  If[i == j || k == l, 0, Module[{m1 = 1, n1 = 1}, m1 = Which[m == 1, 4, m > 1, m - 1];
  n1 = Which[n == 1, 4, n > 1, n - 1]; P[i, j, k, l, m1, n1]]];

In[72]:= co2Rtilde[i_, j_, k_, l_, m_, n_] :=
  co2Rtilde[i, j, k, l, m, n] = co2Rtilde[j, i, l, k, m, n] =
  co2Rtilde[k, l, i, j, m, n] = co2Rtilde[l, k, j, i, m, n] = If[i == j || k == l, 0,
  FullSimplify[Sum[(calP[i1, j1, k1, l1, m1, n1] mat[[i1, i]] mat[[j1, j]]
    mat[[k1, k]] mat[[l1, l]] mat[[m1, m]] mat[[n1, n]]),
    {i1, 1, 4}, {j1, 1, 4}, {k1, 1, 4}, {l1, 1, 4}, {m1, 1, 4}, {n1, 1, 4}]]];

In[73]:= H[i_, j_, k_, l_, m_, n_] := H[i, j, k, l, m, n] = P[i, j, k, l][[m, n]];

In[74]:= Ctilde[i_, j_, k_, l_] := Ctilde[i, j, k, l] =
  Module[{temp = {}, len = 1, s = 0}, temp = perm[{i, j, k, l}]; len = Length[temp];
  Do[s = s + co2Rtilde[l, temp[[m, 1]], 1, temp[[m, 2]], temp[[m, 3]], temp[[m, 4]]],
    {m, len}]; FullSimplify[(s / len) /. P -> H];

```

Figure 3.2: \tilde{C}_{ijkl}

```

In[75]:= Ctilde[4, 4, 4, 4]

Out[75]= -\frac{1}{r^9} 3 M \left( 3 a^2 (2 B^2 + r^2) + 6 a B \sqrt{1 + \frac{B^2}{r^2}} r \sqrt{a^2 + r (-2 M + r)} + r (3 r^2 (-2 M + r) + B^2 (-7 M + 3 r)) \right)

```

Figure 3.3: \tilde{C}_{3333} : Matches with 160 of [3]

With these \tilde{C} & \tilde{B} we get (3.2). As shown:

```

In[76]:= xtilde = {y0, y1, y2, y3};
In[78]:=  $\phi_{1\text{tidal}}$  = FullSimplify[Sum[
  (1/2) (Ctilde[i, j] /. B → 0) xtilde[[i]] xtilde[[j]], {i, {2, 3, 4}}, {j, {2, 3, 4}}]];
In[79]:=  $\phi_{2\text{tidal}}$  =
  FullSimplify[Sum[(1/6) (Ctilde[i, j, k] /. B → 0) xtilde[[i]] xtilde[[j]] xtilde[[k]],
    {i, {2, 3, 4}}, {j, {2, 3, 4}}, {k, {2, 3, 4}}] /. Sqrt[a^2 + r (-2 M + r)] → r];
In[80]:=  $\phi_{31\text{tidal}}$  =
  FullSimplify[Expand[FullSimplify[Sum[(1/24) (Ctilde[i, j, k, l] /. B → 0) xtilde[[i]]
    xtilde[[j]] xtilde[[k]] xtilde[[l]], {i, {2, 3, 4}},
    {j, {2, 3, 4}}, {k, {2, 3, 4}}, {l, {2, 3, 4}}] /. a → 0] /. M^2 → 0];
In[81]:= Cproduct[i_, j_, k_, l_] :=
  Cproduct[i, j, k, l] = Module[{sums = 0, pp = {}, len = 1}, pp = perm[{i, j, k, l}];
    len = Length[pp]; (1/len) Do[sums = sums + (Ctilde[pp[[m, 1]], pp[[m, 2]]]
      Ctilde[pp[[m, 3]], pp[[m, 4]]] /. B → 0), {m, len}]; sums];
In[82]:=  $\phi_{32\text{tidal}}$  = FullSimplify[
  Sum[(1/6) Cproduct[i, j, k, l] xtilde[[i]] xtilde[[j]] xtilde[[k]] xtilde[[l]],
    {i, {2, 3, 4}}, {j, {2, 3, 4}}, {k, {2, 3, 4}}, {l, {2, 3, 4}}] /. M^2 → 0];
In[83]:= Bsum[i_, j_, k_, l_] := Sum[Btilde[i, j, n] Btilde[k, l, n] /. B → 0, {n, {2, 3, 4}}]
In[84]:= Bproduct[i_, j_, k_, l_] := Bproduct[i, j, k, l] =
  Module[{sums = 0, pp = {}, len = 1}, pp = perm[{i, j, k, l}]; len = Length[pp]; (1/len)
    Do[sums = sums + Bsum[pp[[m, 1]], pp[[m, 2]], pp[[m, 3]], pp[[m, 4]]], {m, len}]; sums];
In[85]:=  $\phi_{33\text{tidal}}$  = FullSimplify[
  -Sum[(1/6) Bproduct[i, j, k, l] xtilde[[i]] xtilde[[j]] xtilde[[k]] xtilde[[l]],
    {i, {2, 3, 4}}, {j, {2, 3, 4}}, {k, {2, 3, 4}}, {l, {2, 3, 4}}] /. M^2 → 0];
In[86]:=  $\phi_{\text{tidal}}$  =  $\phi_{1\text{tidal}}$  +  $\phi_{2\text{tidal}}$  +  $\phi_{31\text{tidal}}$  +  $\phi_{32\text{tidal}}$  +  $\phi_{33\text{tidal}}$ 
Out[86]:= 
$$\frac{M (-2 y1^2 + y2^2 + y3^2)}{2 r^3} + \frac{M y1 (2 y1^2 - 3 (y2^2 + y3^2))}{2 r^4} - \frac{M (8 y1^4 - 24 y1^2 (y2^2 + y3^2) + 3 (y2^2 + y3^2)^2)}{8 r^5}$$


```

Figure 3.4: ϕ_{tidal}

Here, \tilde{x} is written as y. Code reproduces result 165 of Ishii's paper [3].

Thus, through Mathematica we have been able to calculate tidal potential in Fermi normal coordinate system in Kerr spacetime. This result can be used for further calculations.

Conclusions

The tidal potential that we have finally got is*:

$$\begin{aligned}\phi_{tidal} = & \frac{M}{2r^3}[-2(\tilde{x}^1)^2 + (\tilde{x}^2)^2 + (\tilde{x}^3)^2] \\ & - \frac{M}{2r^4}\tilde{x}^1[-2(\tilde{x}^1)^2 + 3\{(\tilde{x}^2)^2 + (\tilde{x}^3)^2\}] \\ & - \frac{M}{8r^5}[8(\tilde{x}^1)^4 + 3(\tilde{x}^2)^4 + 3(\tilde{x}^3)^4 - 24\{(\tilde{x}^1)^2(\tilde{x}^2)^2 \\ & + (\tilde{x}^1)^2(\tilde{x}^3)^2\} + 6(\tilde{x}^2)^2(\tilde{x}^3)^2] \quad (4.1)\end{aligned}$$

As noted in [3], this matches with Newtonian tidal potential from a point source of mass M at a distance r as $-\frac{M}{\sqrt{(\tilde{x}^1+r)^2+(\tilde{x}^2)^2+(\tilde{x}^3)^2}}$.

To conclude :

- We see that, Fermi normal coordinates indeed serves as a useful frame as calculation involved gets simplified there.
- Though solution of geodesic equation, consequently the choice of Fermi normal coordinates are themselves dependent on spin parameter a, in Newtonian limit ϕ_{tidal} does not depend on a. Thus a freely falling observer locally can not distinguish between spinning and non-spinning star unless a and M is large, as expected.
- This result can be used in slow rotations also i.e. when a is a function of t but it can be, for practical purposes, assumed to be a constant.

*See 165 of [3]

Future Prospects

The whole work done throughout summer is a part of a bigger project which will run throughout semester I of academic year 2016-17. This part is mainly comprised of learning relevant theory and Mathematica. The ultimate goal of the project is to calculate tidal disruption rate of stars near naked singularity and I hope I will get some really useful and interesting results at the end. Beside this, in future, I wish to study physics near a black hole more rigorously. Also, if I get any chance, I wish to explore origin of gravitational waves near a black hole and using computational tools I would like to build a simulation for that.

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