## Stochastic Intervention with Large Action Space

BIS631 Advance Topics in Causal Inference Tatsuhiro Shimizu

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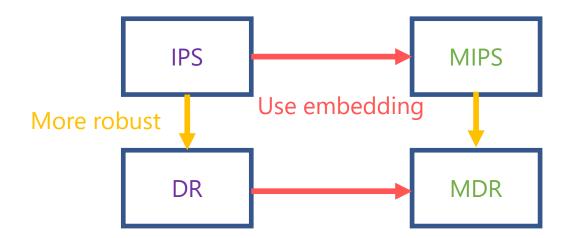
# Introduction

## Introduction

- We generalize the theory in Causal Inference with stochastic intervention
- Why stochastic intervention?
  - 1. For risk aversion
    - Variance of the effect of deterministic intervention is different
      - Example in Finance: Even if the expected return is the highest stock, we try to have the optimal portfolio by having multiple different stocks
  - 2. For exploration in Online Learning
- We can use the classical Causal Inference methods
  - ► E.g., Inverse Propensity Score (IPS) and Doubly Robust (DR)

## Introduction

- We consider the irregular setting where we have lots of deterministic interventions
  - >IPS and DR are not good estimators due to the high variance
  - ➤ Marginalized Inverse Propensity Score (MIPS) works well using the embedding of the action
  - ➤I introduce Marginalized Doubly Robust (MDR) to achieve better estimator



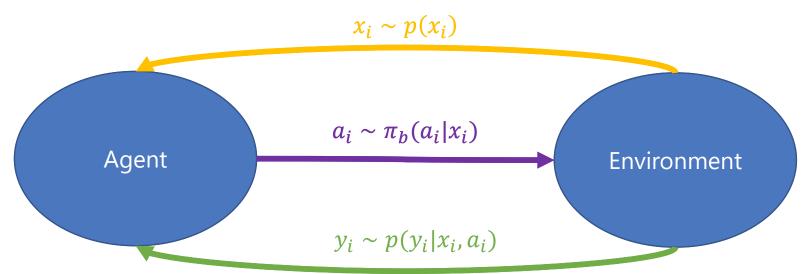
# Setting of the Problem

## Setting of Problem: Data

- We consider the data
  - $\triangleright$  Contextual vector (covariate):  $x \in \mathcal{X} = \mathbb{R}^{d_x}$
  - $\triangleright$  Action (deterministic intervention):  $a \in \mathcal{A}$
  - $\triangleright$  Outcome:  $y \in [0, y_{max}]$
- Data generating Process
  - $> x \sim p(x)$  where p(x) is an unknown distribution
  - $\triangleright a \sim \pi(a|x)$  where  $\pi: \mathcal{X} \to \Delta(\mathcal{A})$  is the stochastic intervention called policy
  - $> y \sim p(y|x,a)$  where p(y|x,a) is an unknown distribution

## Setting of Problem: Data

- Observed Data
  - >n units
  - $\triangleright \mathcal{D} = \{(x_i, a_i, y_i)\}_{i \in [n]}$ 
    - For each unit  $i \in [n]$ , we observe i.i.d.
      - $x_i \sim p(x_i)$
      - $a_i \sim \pi_b(a_i|x_i)$  where  $\pi_b$  is the already used policy in the system called behavior policy
      - $y_i \sim p(y_i|x_i,a_i)$



## Setting of Problem: Problem

- We define how good a policy  $\pi$  is
  - $\triangleright$  Definition of Value function  $V(\pi)$ 
    - $V(\pi) := \mathbb{E}_{p(x)\pi(a|x)p(y|x,a)}[y] = \mathbb{E}_{p(x)\pi(a|x)}[q(x,a)]$
    - Where  $q(x, a) = \mathbb{E}_{p(y|x, a)}[y|x, a]$  is the expected outcome given x and a
- If we know p(x) and p(y|x,a), then we can find the best policy
- As we do not know p(x) and p(y|x,a), we construct estimator  $\hat{V}(\pi_e;\mathcal{D}) \approx V(\pi_e)$
- Use Mean Squared Error (MSE) as the metric of how good the estimator is  $MSE(\hat{W}(-1,T)) = \mathbb{E}\left[\left(W(-1,T),\hat{W}(-1,T)\right)^2\right]$

$$MSE\left(\hat{V}(\pi_e; \mathcal{D})\right) = \mathbb{E}_{\mathcal{D}}\left[\left(V(\pi) - \hat{V}(\pi_e; \mathcal{D})\right)^2\right]$$

# Literature Review

## Literature Review: Direct Method (DM)

• Direct Method (DM) (Beygelzimer and Langford 2009) 
$$\hat{V}_{\mathrm{DM}}(\pi_e; \mathcal{D}, \hat{q}) \coloneqq \frac{1}{n} \sum_{i \in [n]} \mathbb{E}_{\pi_e(a|x_i)} \left[ \hat{q}(x_i, a) \right]$$

where 
$$\hat{q}(x, a)$$
 is the estimated expected outcome 
$$\hat{q} \leftarrow \operatorname*{argmin}_{q' \in \mathcal{Q}} \left\{ \frac{1}{n} \sum_{i \in [n]} \left( y_i - q'(x_i, a_i) \right)^2 \right\}$$

 $\triangleright$  Unbiased under the unbiasedness of  $\hat{q}$ 

## Literature Review: Inverse Propensity Score (IPS)

• Inverse Propensity Score (IPS) (Horvitz and Thompson 1952)

$$\hat{V}_{\text{IPS}}(\pi_e; \mathcal{D}) \coloneqq \frac{1}{n} \sum_{i \in [n]} w(x_i, a_i) y_i$$

 $\triangleright$  Where the importance weight  $w(x_i, a_i)$  is

$$w(x_i, a_i) \coloneqq \frac{\pi_e(a_i|x_i)}{\pi_b(a_i|x_i)}$$

- > Unbiased under the common support
  - Common Support:  $\pi_e(a|x) > 0 \implies \pi_b(a|x) \ \forall x \in \mathcal{X}, a \in \mathcal{A}$
- ➤ Variance of IPS (Saito and Joachims 2022) is

$$n\mathbb{V}_{\mathcal{D}}[\hat{V}_{\mathrm{IPS}}(\pi_e;\mathcal{D})] = \underbrace{\mathbb{E}_{p(x)\pi_b(a|x)}[w(x,a)^2\sigma(x,a)^2]}_{\text{large when } |\mathcal{A}|\gg 1} + \mathbb{V}_{p(x)}\left[\mathbb{E}_{\pi_b(a|x)}[w(x,a)q(x,a)]\right] + \underbrace{\mathbb{E}_{p(x)}\left[\mathbb{V}_{\pi_b(a|x)}[w(x,a)q(x,a)]\right]}_{\text{large when } |\mathcal{A}|\gg 1}$$

## Literature Review: Doubly Robust(DR)

Doubly Robust(DR) (Dudik et al 2011, Cassel et al 1976)

$$\hat{V}_{DR}(\pi_e; \mathcal{D}; \hat{q}) := \frac{1}{n} \sum_{i \in [n]} \{ \mathbb{E}_{\pi_e(a|x_i)}[\hat{q}(x_i, a)] + w(x_i, a_i) (y_i - \hat{q}(x_i, a_i)) \}$$

- $\triangleright$ Unbiased under the common support or unbiasedness of  $\hat{q}$
- ➤ Variance of DR (Huang et al 2021) is

$$n\mathbb{V}_{\mathcal{D}}\big[\widehat{V}_{\mathrm{DR}}(\pi_e;\mathcal{D},\widehat{q})\big] =$$

$$\underbrace{\mathbb{E}_{p(x)\pi_b(a|x)}[w(x,a)^2\sigma(x,a)^2]}_{\text{large when }|\mathcal{A}|\gg 1} + \mathbb{V}_{p(x)}\left[\mathbb{E}_{\pi_b(a|x)}[w(x,a)q(x,a)]\right] + \underbrace{\mathbb{E}_{p(x)}\left[\mathbb{V}_{\pi_b(a|x)}[w(x,a)\Delta(x,a)]\right]}_{\text{large when }|\mathcal{A}|\gg 1}$$

where  $\Delta(x, a) = q(x, a) - \hat{q}(x, a)$  is the error of the estimation of expected outcome

### Literature Review: Marginalized Inverse Propensity Score (MIPS)

- To overcome the high variance of IPS and DR
- MIPS use the embedding  $e \in \mathcal{E} \subset \mathbb{R}^{d_e}$  of the action  $a \in \mathcal{A}$  for the importance weight
- Example
  - > Want to construct the optimal movie recommendation system (e.g. Netflix)
    - Action *a*: movies
    - Action embedding e: movie genres, actors, director
- To use MIPS, we need the modified data generating process
  - $\triangleright$  Context vector (covariates)  $x \sim p(x)$
  - $\triangleright$  Action  $a \sim \pi(a|x)$
  - $\triangleright$  Action embedding  $e \sim p(e|x,a)$
  - $\triangleright$  Outcome  $y \sim p(y|x, a, e)$

### Literature Review: Marginalized Inverse Propensity Score (MIPS)

#### New observed data

$$\triangleright \mathcal{D} = \{(x_i, a_i, e_i, y_i)\}_{i \in [n]}$$

- For each unit  $i \in [n]$ , we observe i.i.d.
  - $x_i \sim p(x_i)$
  - $a_i \sim \pi_b(a_i|x_i)$
  - $e_i \sim p(e_i|x_i,a_i)$
  - $y_i \sim p(y_i|x_i, a_i, e_i)$

### • New value function $V(\pi)$

$$V(\pi) \coloneqq \mathbb{E}_{p(x)\pi(a|x)p(e|x,a)p(y|x,a,e)}[y]$$
$$= \mathbb{E}_{p(x)\pi(a|x)p(e|x,a)}[q(x,a,e)]$$
$$= \mathbb{E}_{p(x)\pi(a|x)}[q(x,a)]$$

### Literature Review: Marginalized Inverse Propensity Score (MIPS)

• Marginalized Inverse Propensity Score (MIPS) (Saito and Joachims 2022)  $\hat{V}_{\text{MIPS}}(\pi_e; \mathcal{D}) \coloneqq \frac{1}{n} \sum_{i \in [n]} w(x_i, e_i) y_i$ 

$$\widehat{V}_{\mathrm{MIPS}}(\pi_e; \mathcal{D}) \coloneqq \frac{1}{n} \sum_{i \in [n]} w(x_i, e_i) y_i$$

 $\geq$  Where the marginalized importance weight  $w(x_i, e_i)$  is

$$w(x_i, e_i) \coloneqq \frac{p(e|x, \pi_e)}{p(e|x, \pi_b)}$$

- $w(x_i,e_i) \coloneqq \frac{p(e|x,\pi_e)}{p(e|x,\pi_b)}$  Where  $p(e|x,\pi) = \sum_{a \in \mathcal{A}} \pi(a|x)p(e|x,a)$  is the marginal distribution of embedding
- > Unbiased under 1. no direct effect and 2. common embedding support
  - No direct effect: a and y is independent given x and e
  - Common embedding support:  $p(e|x,\pi_e) > 0 \implies p(e|x,\pi_b) > 0 \quad \forall x \in \mathcal{X}, e \in \mathcal{E}$
- If we can find the good representation of action, then we can have the lower variance than IPS and DR

- Idea: Combine MIPS and DR to obtain the better estimator of  $V(\pi)$
- Marginalized Doubly Robust (MDR)

$$\hat{V}_{\text{MDR}}(\pi_e; \mathcal{D}; \hat{q}) \coloneqq \frac{1}{n} \sum_{i \in [n]} \{ \mathbb{E}_{\pi_e(a|x_i)} \left[ \hat{q}(x_i, a) \right] + w(x_i, e_i) \left( y_i - \hat{q}(x_i, a_i, e_i) \right) \}$$

- ➤ Unbiased under
  - 1. the no direct effect
  - 2. either common embedding support or unbiasedness of  $\hat{q}(x, a, e)$
- ➤ More robust than MIPS

Variance reduction of MDR against DR

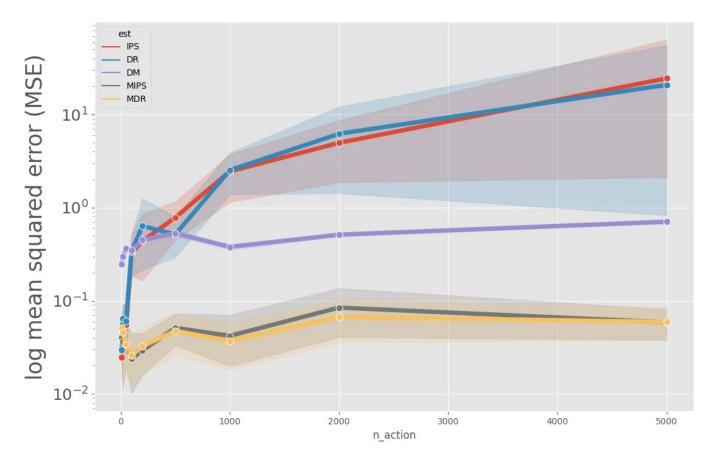
$$n \mathbb{V}_{\mathcal{D}} [\hat{V}_{\mathrm{DR}}(\pi_e; \mathcal{D}, \hat{q})] - n \mathbb{V}_{\mathcal{D}} [\hat{V}_{\mathrm{MDR}}(\pi_e; \mathcal{D}, \hat{q})]$$
  
=  $\mathbb{E}_{\bar{d}_{\pi_b}} [w(x, a)^2 \Delta(x, a)^2 - w(x, e)^2 \Delta(x, a, e)^2]$ 

#### > where

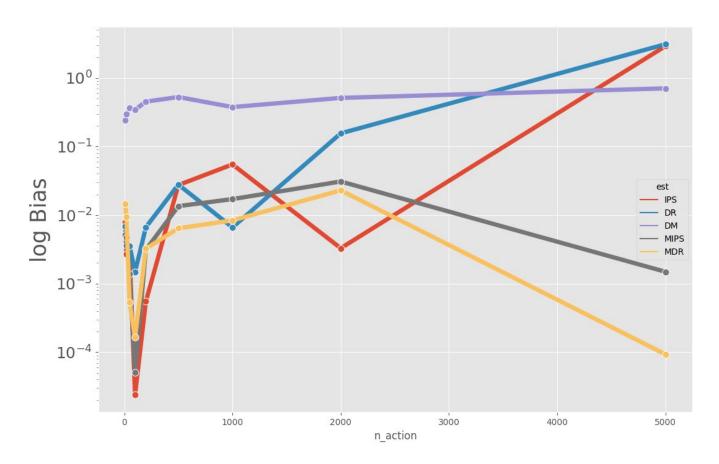
- $\bar{d}_{\pi_b} \coloneqq p(x)\pi_b(a|x)p(e|x,a)$  is the visitation measure
- $\Delta(x, a) = q(x, a) \hat{q}(x, a)$  is the estimation error of expected outcome given x and a
- $\Delta(x, a, e) = q(x, a, e) \hat{q}(x, a, e)$  is the estimation error of expected outcome given x, a, and e

• If the embedding e represents action a well, then w(x, a) > w(x, e)  $n\mathbb{V}_{\mathcal{D}}[\widehat{V}_{\mathrm{DR}}(\pi_e; \mathcal{D}, \widehat{q})] > n\mathbb{V}_{\mathcal{D}}[\widehat{V}_{\mathrm{MDR}}(\pi_e; \mathcal{D}, \widehat{q})]$ 

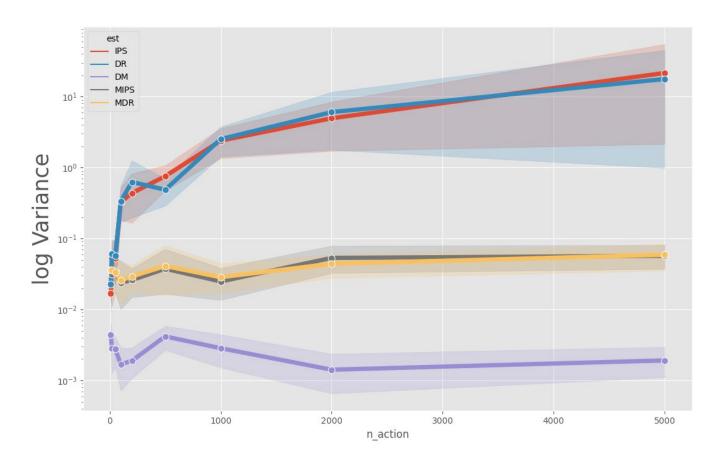
- Simulation study (MSE)
  - >MDR is the best of all estimators DM, IPS, DR, and MIPS



- Simulation study (Bias)
  - >MDR improve the bias of MIPS by the doubly robust properties



- Simulation study (Variance)
  - >MDR has the variance reduction against DR



## Limitation and Future Work

## Limitation and Future Work

#### Limitation

- Simply used the exactly same setting for the simulation study(Saito and Joachism 2022)
- $\triangleright$  Did not cover how to find the better embedding e

#### Future Work

- Empirically analyze how robust MDR is against the violation of the assumptions
- ➤ Construct the comprehensive algorithm or way to find the best embedding of action

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