

# Introduction to Netlogo

Agent-based simulation

# Netlogo

## Modeling complex systems

- Programmable modeling environment for simulating natural and social phenomena
  - Well suited for modeling complex systems evolving over time
  - Hundreds or thousands of independent agents operating concurrently
  - Exploring the connection between the micro-level behavior of individuals and the macro-level patterns that emerge from the interaction of many individuals

# Netlogo

## Modeling complex systems

- Easy-to-use application development environment
  - creating custom models and quickly testing hypotheses about self-organized systems
  - simple scripting language
  - user-friendly graphical interface
  - runs on JVM

*Wilensky, U. (1999). NetLogo. <http://ccl.northwestern.edu/netlogo/>. Center for Connected Learning and Computer-Based Modeling, Northwestern University, Evanston, IL*

# Netlogo

## Practical Info

- Download link:
  - <http://ccl.northwestern.edu/netlogo/download.shtml>
  - Launch Netlogo through command line:
    - `$ /{netlogo_download_folder}/netlogo.sh`
- Online doc:
  - <https://ccl.northwestern.edu/netlogo/docs/>
- Book for agent-based modeling (special focus on Netlogo):
  - <http://www.intro-to-abm.com/>

# Netlogo

## History snapshot

- LOGO (Papert & Minsky, 1967)
  - theory of education based on Piaget's constructionism (“hands-on” creation and test of concepts)
  - simple language derived from LISP
  - turtle graphics and exploration of “micro-worlds”
- StarLogo (Resnick, 1991), MacStarLogo, StarLogoT
  - agent-based simulation language
- NetLogo (Wilensky, 1999)
  - further extending StarLogo (continuous turtle coordinates, cross-platform, networking, etc.)

# Netlogo

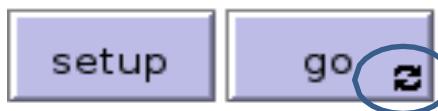
## The world of Netlogo

- NetLogo is a 2-D world made of 4 kinds of agents:
  - *Patches* - make up the background or “landscape”
  - *Turtles* - move around on top of the patches
  - *Links* - connect two turtles
  - *The Observer* - oversees everything going on in the world

# Graphical Interface

## Controls

- Controls allow to run and manage the flow of execution
  - Buttons: initialize, start, stop, step through the model
    - “Once” button execute one action
    - “Forever” button repeat the same action until pressed again
  - Functions with the name of the buttons specify the action executed on click
  - Command centre: ask agents to execute specific commands “on the fly”



# Graphical Interface

## Settings

- Settings allow to modify parameters
  - Sliders: adjust a quantity from *min* to *max* by an *increment*



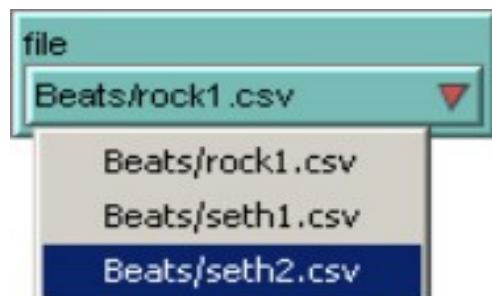
`population = 126`

- Switches: set a Boolean variable



`incentivi_installazione? = false`

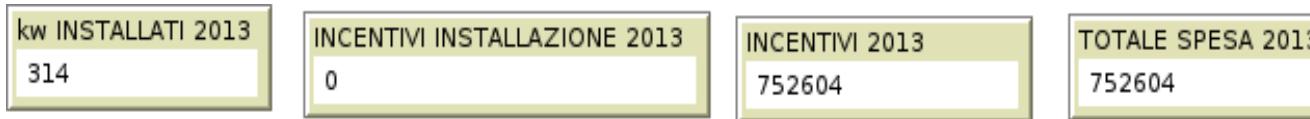
- Choosers: set a value from a list



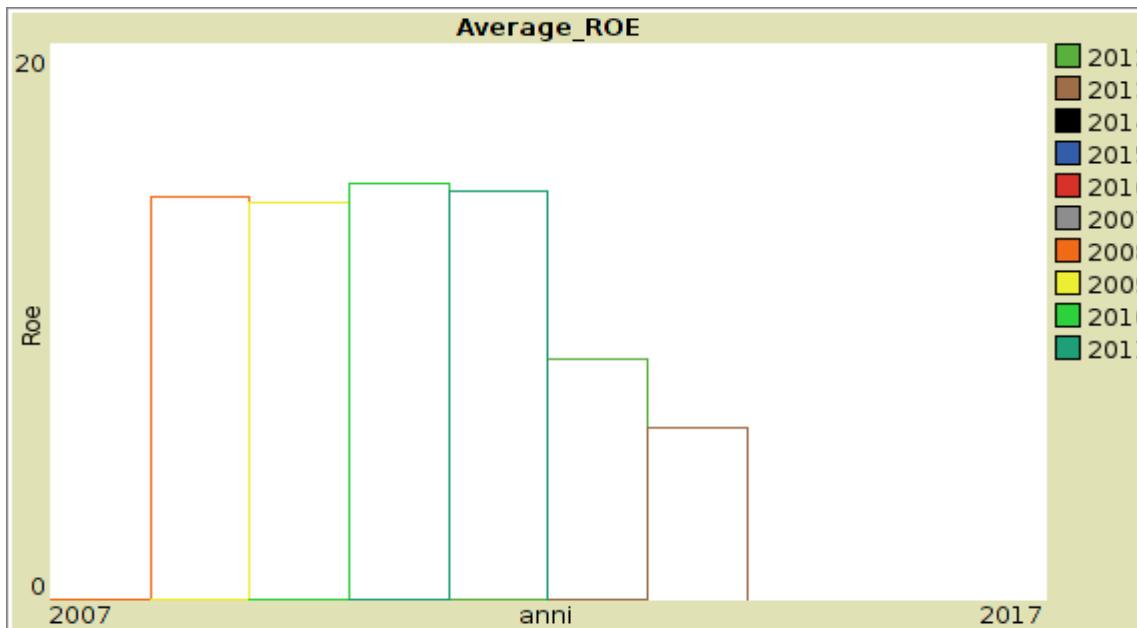
`file = "Beats/seth2.csv"`

# Graphical Interface Views

- Views allow to display information
    - Monitors display the current value of variables



- Plots: display the history of a variable’s value



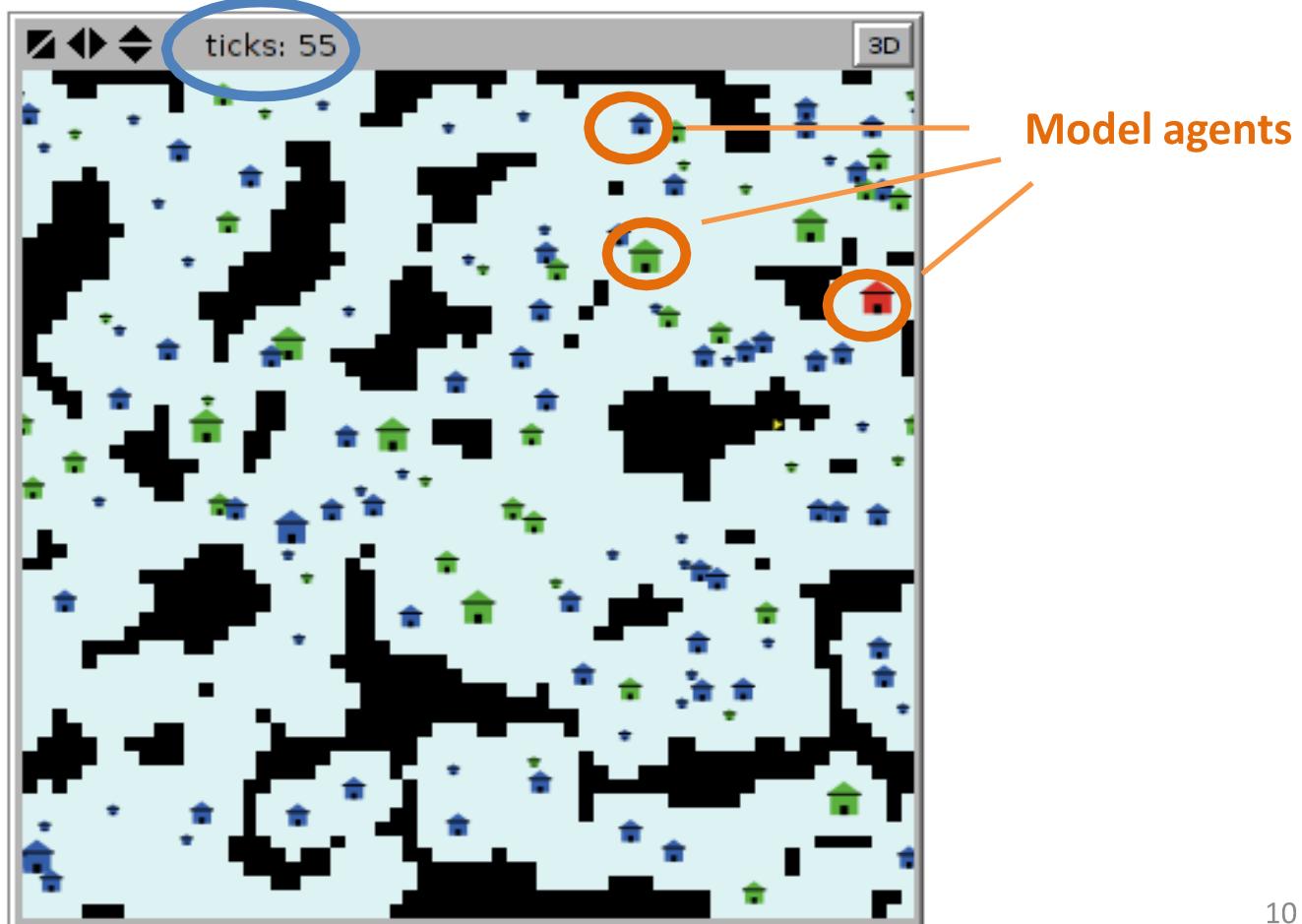
- Output text areas, log text info

# Graphical Interface

## Views

- Graphic window, the main view of the 2-D Netlogo world

Model evolution  
(based on discrete  
time-steps)



# Programming Concepts

## Agents

- Agents carry out their activity, all simultaneously
  - Patches don't move, form a 2-D wrap-around grid, have integer coordinates (*pxcor,pycor*)
  - Turtles move on top of patches (not necessarily in their centre), have decimal coordinates (*xcor,ycor*) and orientation (*heading*)
  - Observer can create new turtles, can have read/write access to all the agents and variables

# Programming Concepts

## Procedures & Functions

- Commands (“**to**” keyword)
  - Action for the agents to carry out (“void” functions)
  - Example with 2 input arguments:

```
to draw-polygon [ num-sides size ]
    pd      ;; pen down, draw
    repeat num-sides
        [      fd size    ;; forward 'size' steps
              rt (360 / num-sides) ]  ;; rotate
end
```

# Programming Concepts

## Procedures & Functions

- Reporters (“**to-report**”)
  - Report a result value
  - Example with 1 input arguments:

```
to-report absolute-value [ number ]
  if-else number >= 0
    [ report number ]
    [ report 0 - number ]
end
```

- Primitives
  - Built-in command or reporters
  - Some have an abbreviated form (create-turtle <--> crt)
- Procedures
  - Custom commands or reporters (user made)

# Programming Concepts

## Variables

- Variables – places to store values
  - Global variables: only one value for the variable and every agent can access it
  - Turtle and Patch variables: each turtle/patch has its own value for every turtle/patch variable
  - Local variables: defined and accessible only inside a procedure (scope=narrowest square brackets or procedure itself)

# Programming Concepts

## Variables

- Built-in variables
  - Ex. turtle variables: color, xcor, ycor, etc.
  - Ex. Patch variables: pcolor, pxcor, etc.
- Custom variables
  - Defining global variables

```
global [ clock ]
```
  - Defining turtle/patch variables

```
turtles-own [ energy speed ]  
patches-own [ friction ]
```

# Programming Concepts

## Variables

- Custom variables
  - Defining global variables
  - Defining turtle/patch variables
  - Defining local variables:
    - **let variable value**
    - Creates a new local variable and gives it the desired value
- Setting a variable values (after its definition):
  - **set variable value**

# Programming Concepts

## Ask

- Ask – specify commands to be run by turtles or patches
  - Asking all turtles

```
ask turtles [ ... ]
```
  - Asking all patches
  - Asking  $N$  turtles

```
ask n-of N turtles [ ... ]
```
- Observer code *cannot* be inside any “ask” block

# Programming Concepts

## Variables

- Setting variables
  - Setting the color of all turtles

```
ask turtles [ set color red ]
```
  - Setting the color of all patches

```
ask patches [ set pcolor red ]
```
  - Setting the color of the patches under the turtles

```
ask turtles [ set pcolor red ]
```
  - Setting the color of one turtle (identify by ID)

```
ask turtle 5 [ set color green]
```
  - or  

```
set color-of turtle 5 green
```
  - Setting the color of one patch (identified with coordinates)

```
ask patch 2 3 [ set pcolor green ]
```

# Programming Concepts

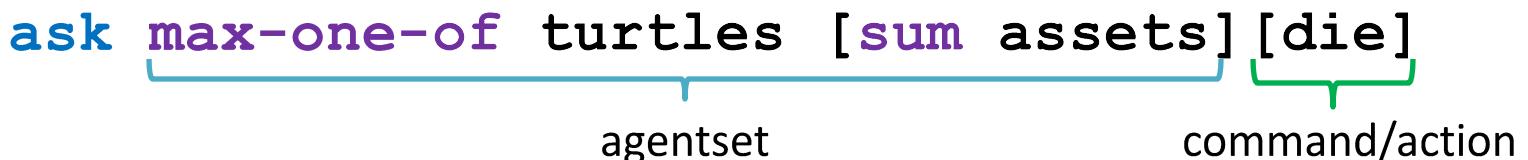
## Agent sets

- Agent set, definition of a subset of agents (not a keyword)
  - All blue turtles
    - `turtles with [ color = blue ]`
  - All blue turtles on the patch of the current caller (patch or turtle)
    - `turtles-here with [ color = blue ]`
  - All turtles less than 5 patches away from caller
    - `turtles in-radius 5`
  - The 4 patches to the east, north, west and south of the caller
    - `patches at-points [[1 0] [0 1] [-1 0] [0 -1]]`

# Programming Concepts

## Agent sets

- Using agent sets
  - Ask such agents to execute a command  
`ask <agentset> [ ... ]`
  - Check if there are such agents  
`show any? <agentset>`
  - Count such agents  
`show count <agentset>`
- Ex. - remove the richest turtle (with the maximum “assets” value):  
`ask max-one-of turtles [sum assets] [die]`



ask max-one-of turtles [sum assets] [die]  
agentset                                                    command/action

# Programming Concepts

## Breeds

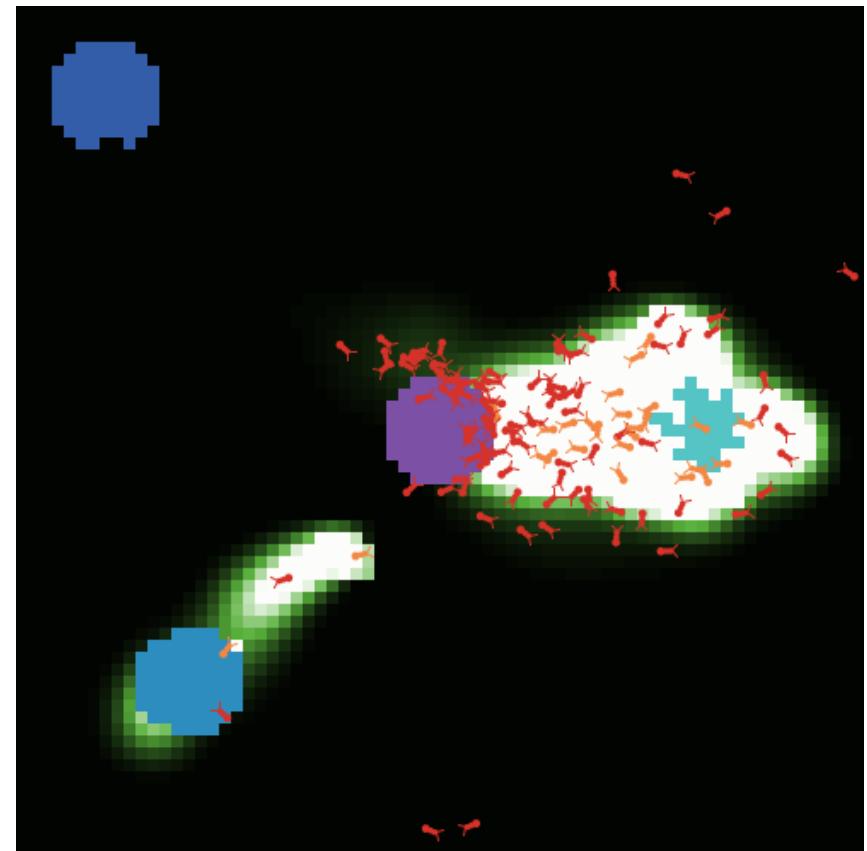
- *Breed*, a “natural” kind of agent set (other species than turtle)  
`breed [ wolves sheep ]`
- A new breed comes with automatically derived primitives:  
`create-<breed>`  
`create-custom-<breed>`  
`<breed>-here`  
`<breed>-at`
- The breed is a turtle variable  
`ask turtles 5 [ if breed=sheep ]`
- A turtle agent can change breed  
`ask turtles 5 [ set breed sheep ]`

# Exercise 1

## Basic Ants Model

- Very simple model as a first “hands-on” experience
- A colony of ants forages for food
  - Though each ant follows a set of simpler rules, the colony as a whole act in a sophisticated way

*Wilensky, U. (1997). NetLogo Ants model.  
<http://ccl.northwestern.edu/netlogo/models/Ants>. Center for Connected Learning  
and Computer-Based Modeling,  
Northwestern University, Evanston, IL.*



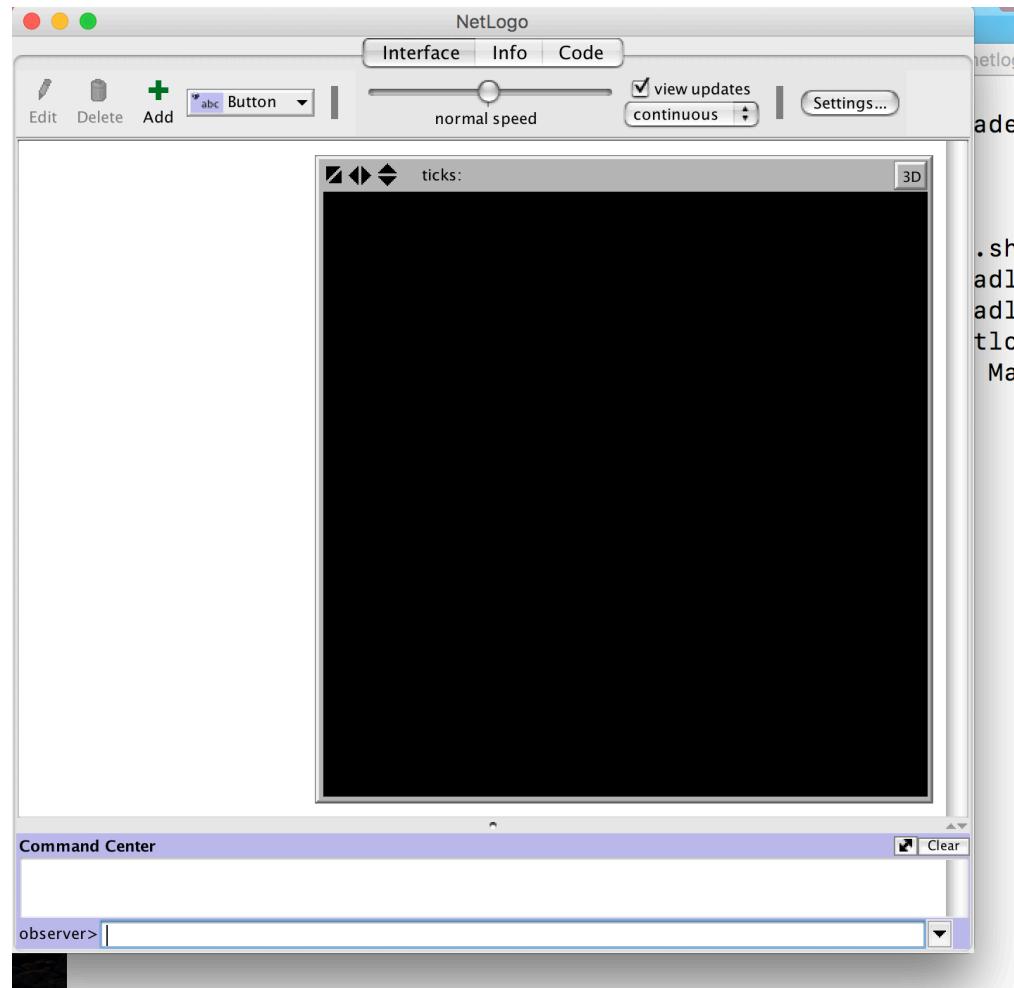
# How to start

```
Last login: Thu Oct 29 20:03:37 on ttys005
(base) MBP-di-Allegra:~ allegradefilippo$ cd /Users/allegradefilippo/Desktop/esercitazioneNetlogo/netlogo-5.0.2
(base) MBP-di-Allegra:netlogo-5.0.2 allegradefilippo$ ls
HubNet.jar          docs           lib           netlogo.sh
Mathematica Link    extensions     models        netlogo.sh~
NetLogo.jar         hs_err_pid11496.log netlogo-3D.sh   netlogo_logging.xml
NetLogoLite.jar     hubnet.sh      netlogo-headless.sh   readme.txt
NetLogoLite.jar.pack.gz icon.ico    netlogo-headless.sh~
(base) MBP-di-Allegra:netlogo-5.0.2 allegradefilippo$ ./netlogo.sh
Java HotSpot(TM) 64-Bit Server VM warning: ignoring option MaxPermSize=128m; support was removed in 8.0

```

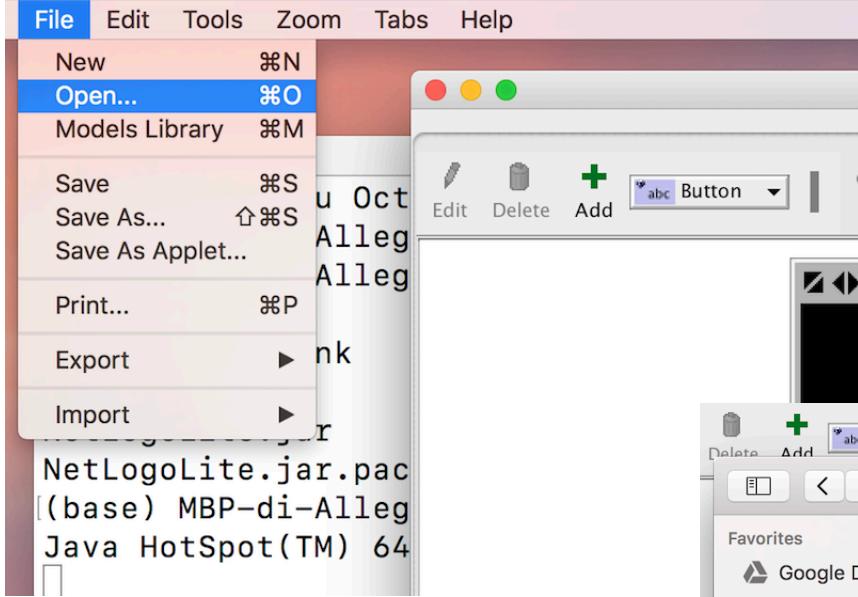


# How to start

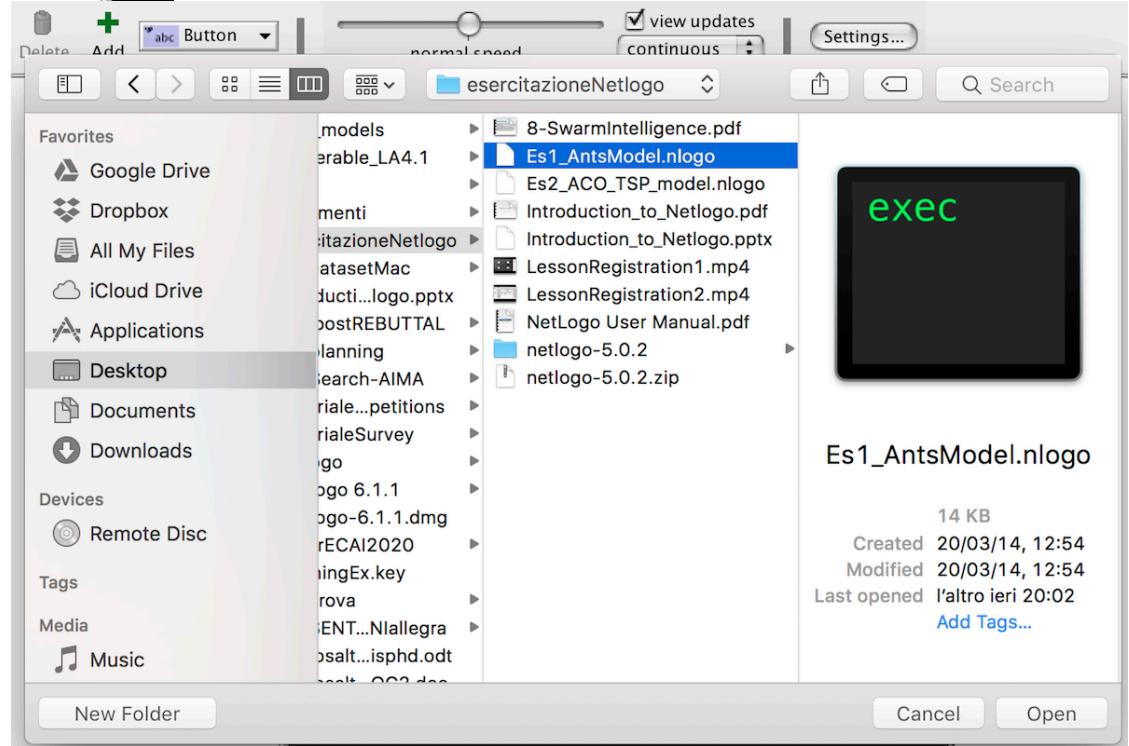
A screenshot of a terminal window titled 'netlogo.sh — 113x30'. The path shown is 'aedefilippo/Desktop/esercitazioneNetlogo/netlogo-5.0.2'. The terminal lists several files: 'netlogo.sh', 'netlogo.sh~', '.sh', 'netlogo\_logging.xml', 'adless.sh', 'readme.txt', 'adless.sh~', 'tlogo.sh', and a warning message 'MaxPermSize=128m; support was removed in 8.0'. The terminal window has a standard OS X style with colored horizontal bars at the top.

# How to start

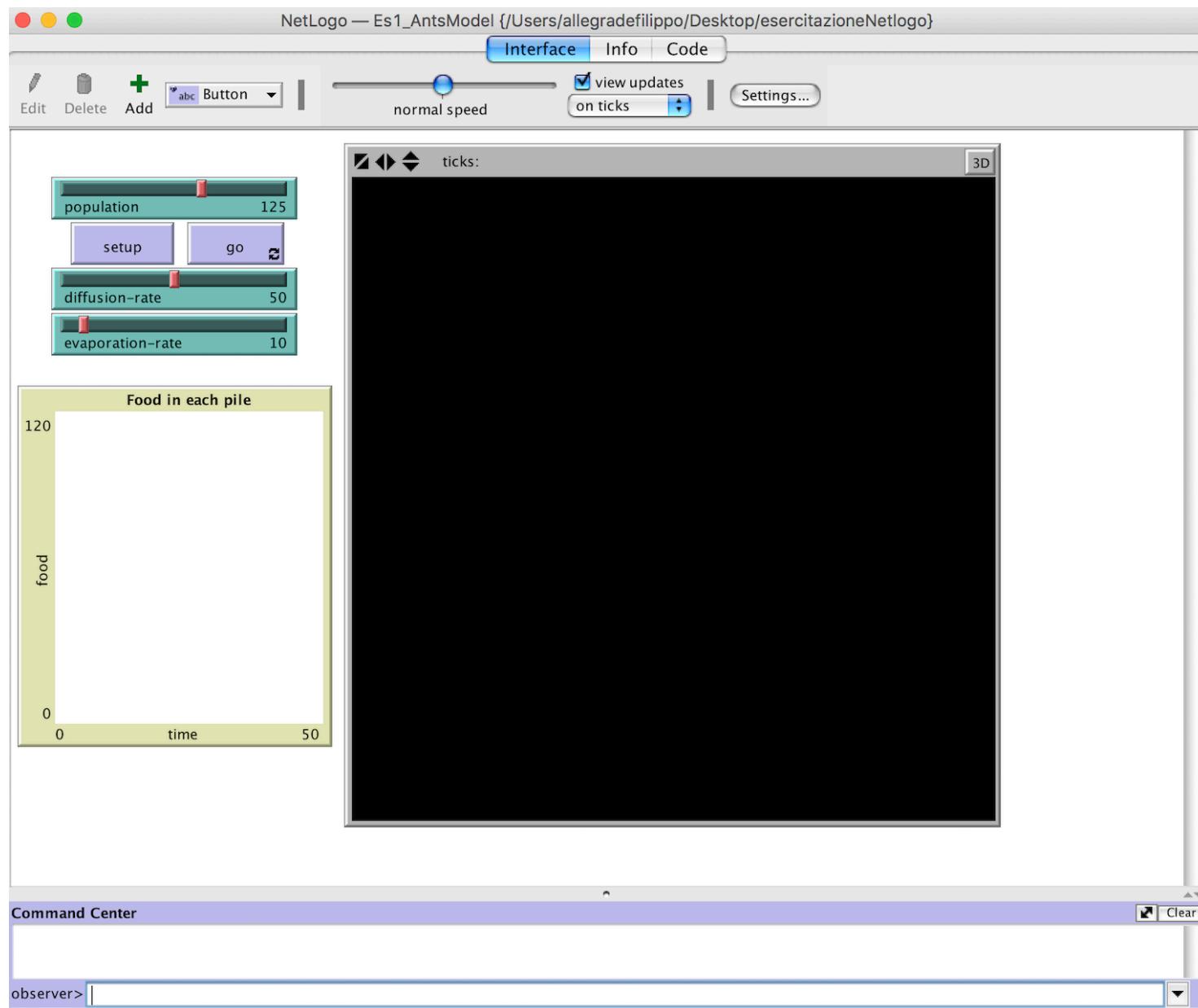
1. Open an existing model .nlogo



2. Choose the model of the first exercise (i.e.) Es\_1\_AntsModel.nlogo



# Es\_1\_AntsModel.nlogo

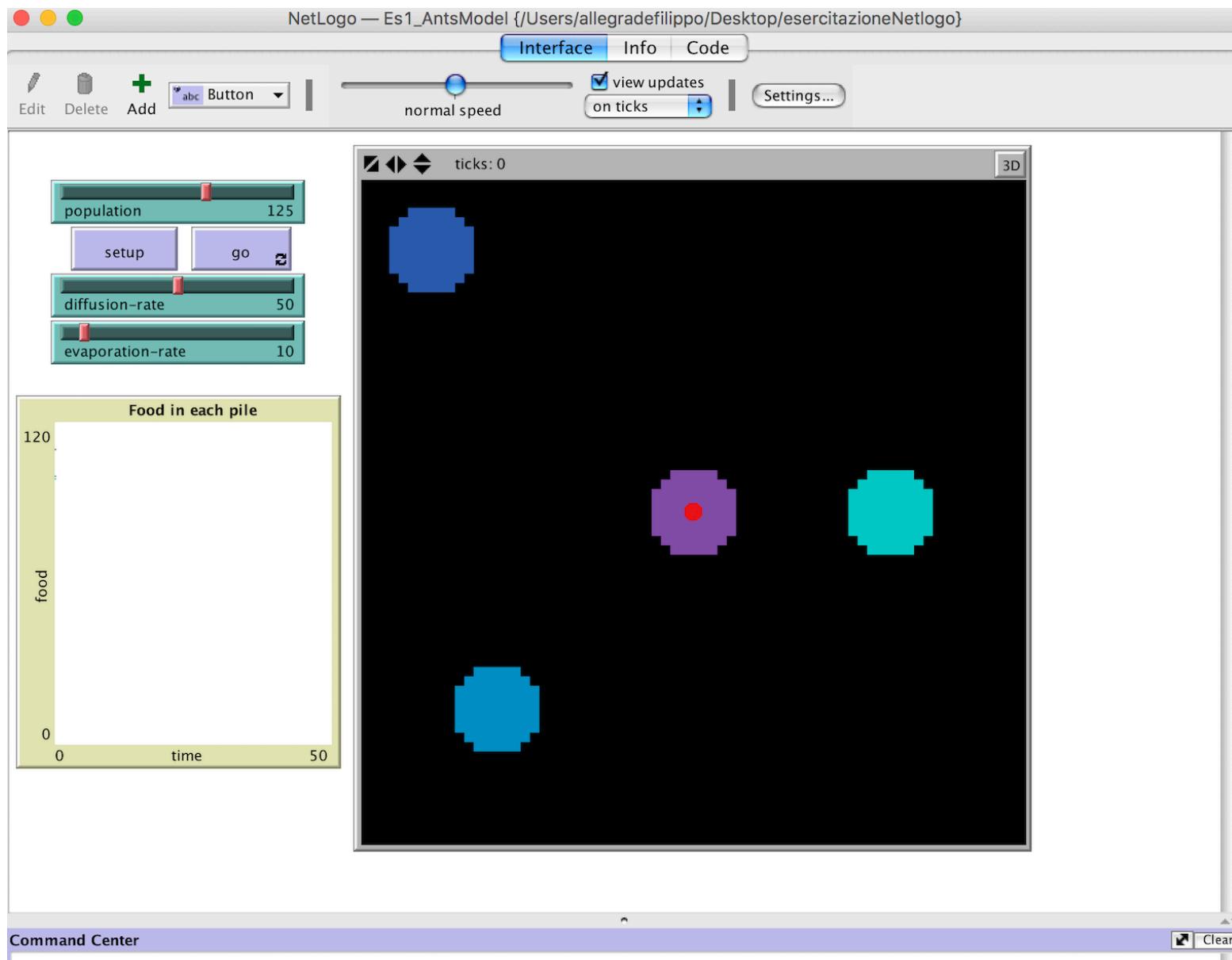


# Exercise 1

## Ants Model

- When an ant finds a piece of food, it carries the food back to the nest, dropping a chemical as it moves
- When other ants “sniff” the chemical, they follow the chemical toward the food
- As more ants carry food to the nest, they reinforce the chemical trail

# Es\_1\_AntsModel.nlogo

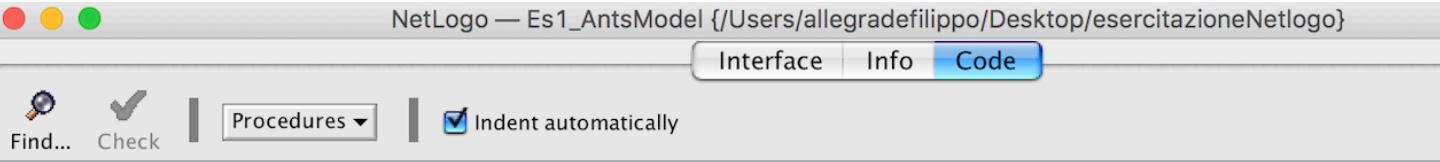


# Exercise 1

## Model Usage

- Click the SETUP button to set up the ant nest (in violet, at center) and three piles of food then click the GO button to start the simulation.
  - The chemical is shown in a green-to-white gradient.
- The EVAPORATION-RATE slider controls the evaporation rate of the chemical. The DIFFUSION-RATE slider controls the diffusion rate of the chemical.
- If you want to change the number of ants, move the POPULATION slider before pressing SETUP

# Es\_1\_AntsModel.nlogo



NetLogo — Es1\_AntsModel {/Users/allegreadefilippo/Desktop/esercitazioneNetlogo}

Interface | Info | **Code**

Find... Check | Procedures ▾ |  Indent automatically

```
patches-own [
    chemical      ;;; amount of chemical on this patch
    food          ;;; amount of food on this patch (0, 1, or 2)
    nest?         ;;; true on nest patches, false elsewhere
    nest-scent    ;;; number that is higher closer to the nest
    food-source-number ;;; number (1, 2, or 3) to identify the food sources
]

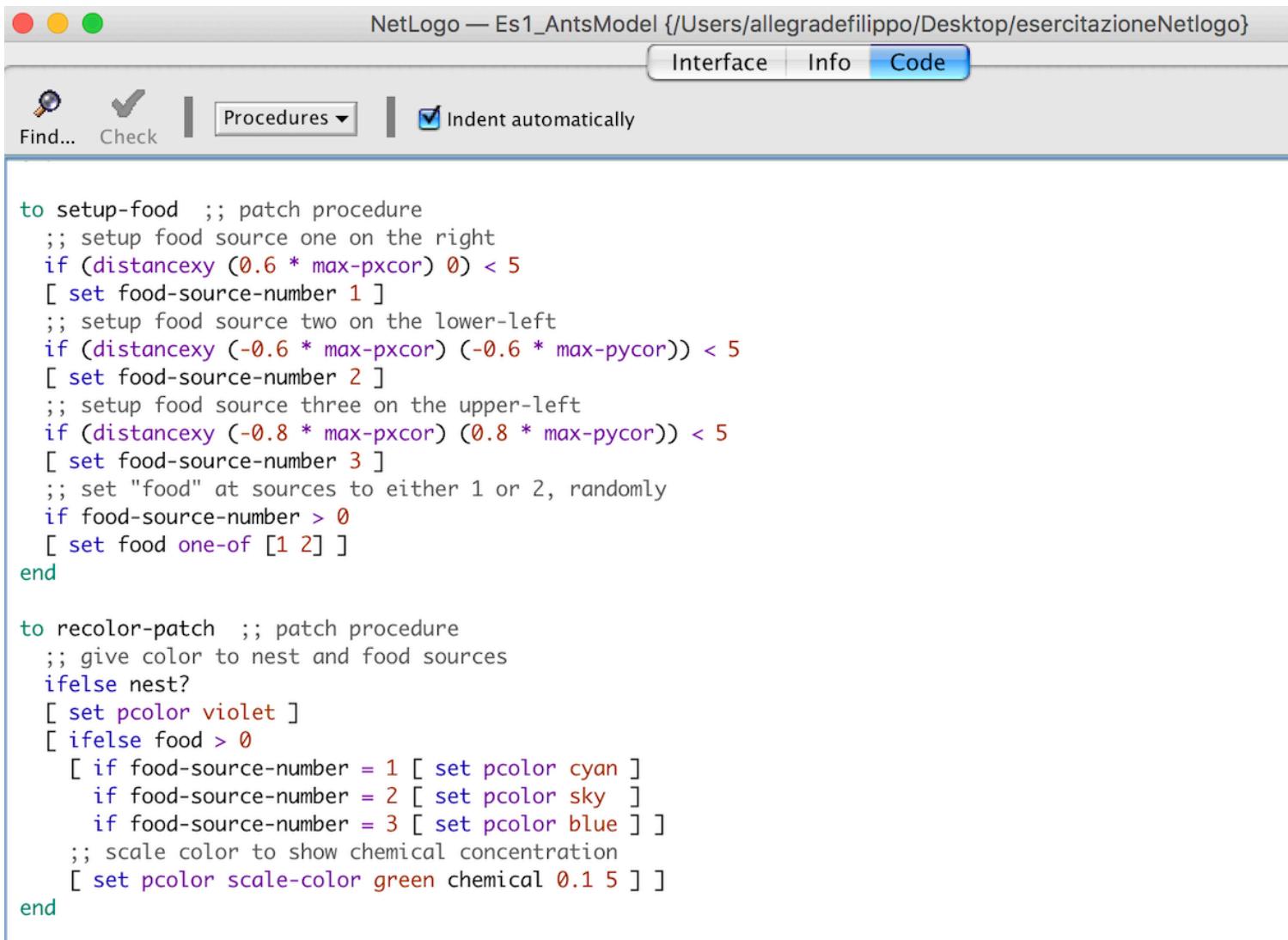
;;;;;;
;;; Setup procedures ;;
;;;;;;

to setup
  clear-all
  set-default-shape turtles "bug"
  crt population
  [ set size 2      ;; easier to see
    set color red ] ;; red = not carrying food
  setup-patches
  reset-ticks
end

to setup-patches
  ask patches
  [ setup-nest
    setup-food
    recolor-patch ]
end

to setup-nest ; patch procedure
  ;; set nest? variable to true inside the nest, false elsewhere
  set nest? (distancexy 0 0) < 5
  ;; spread a nest-scent over the whole world -- stronger near the nest
  set nest-scent 200 - distancexy 0 0
end
```

# Es\_1\_AntsModel.nlogo

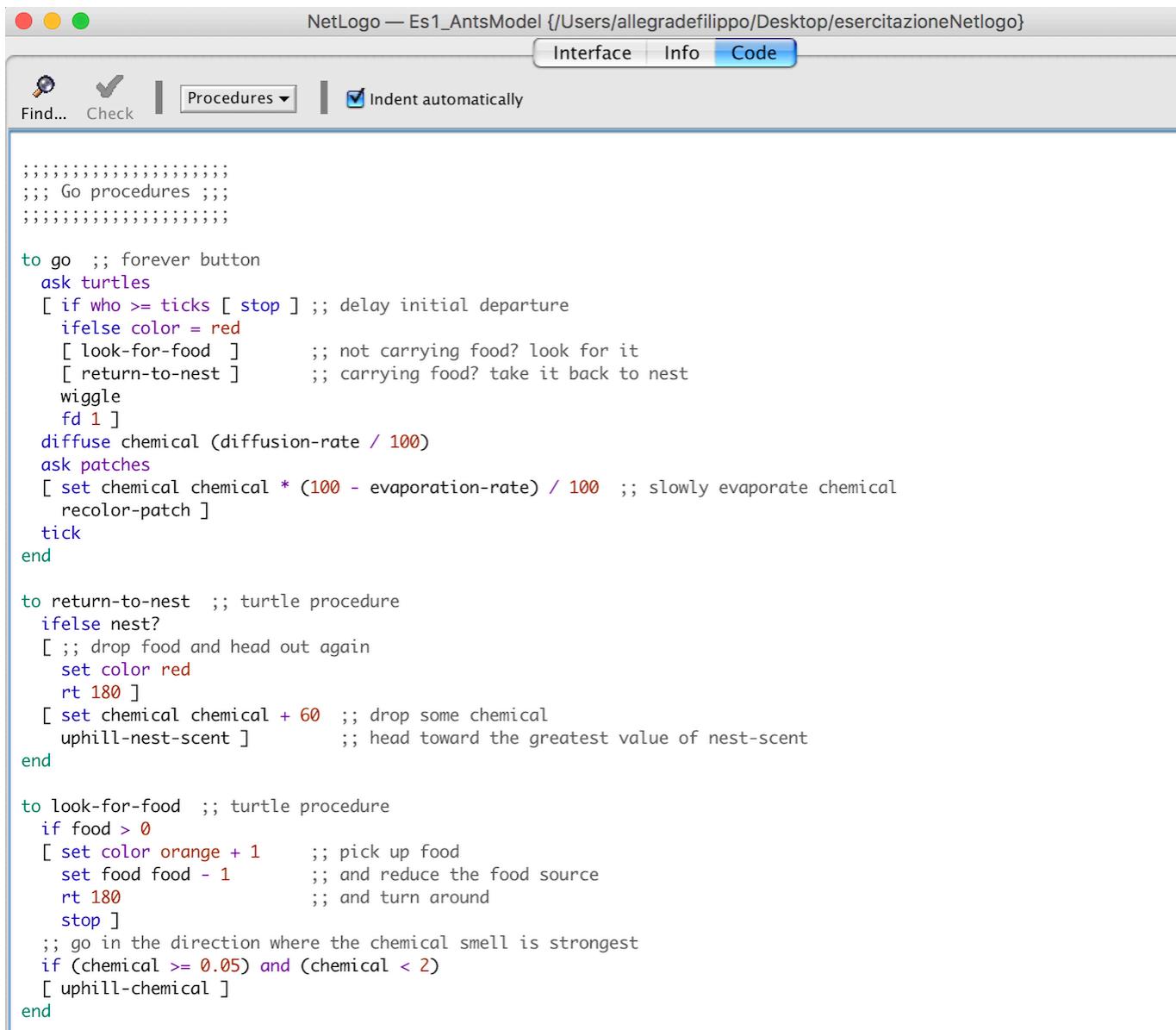


The screenshot shows the NetLogo interface with the title "NetLogo — Es1\_AntsModel {/Users/allegreadefilippo/Desktop/esercitazioneNetlogo}". The "Code" tab is selected. The code window contains the following NetLogo code:

```
to setup-food  ;; patch procedure
  ;; setup food source one on the right
  if (distancexy (0.6 * max-pxcor) 0) < 5
    [ set food-source-number 1 ]
  ;; setup food source two on the lower-left
  if (distancexy (-0.6 * max-pxcor) (-0.6 * max-pycor)) < 5
    [ set food-source-number 2 ]
  ;; setup food source three on the upper-left
  if (distancexy (-0.8 * max-pxcor) (0.8 * max-pycor)) < 5
    [ set food-source-number 3 ]
  ;; set "food" at sources to either 1 or 2, randomly
  if food-source-number > 0
    [ set food one-of [1 2] ]
end

to recolor-patch  ;; patch procedure
  ;; give color to nest and food sources
  ifelse nest?
    [ set pcolor violet ]
  ifelse food > 0
    [ if food-source-number = 1 [ set pcolor cyan ]
      if food-source-number = 2 [ set pcolor sky ]
      if food-source-number = 3 [ set pcolor blue ] ]
    ;; scale color to show chemical concentration
    [ set pcolor scale-color green chemical 0.1 5 ] ]
end
```

# Es\_1\_AntsModel.nlogo



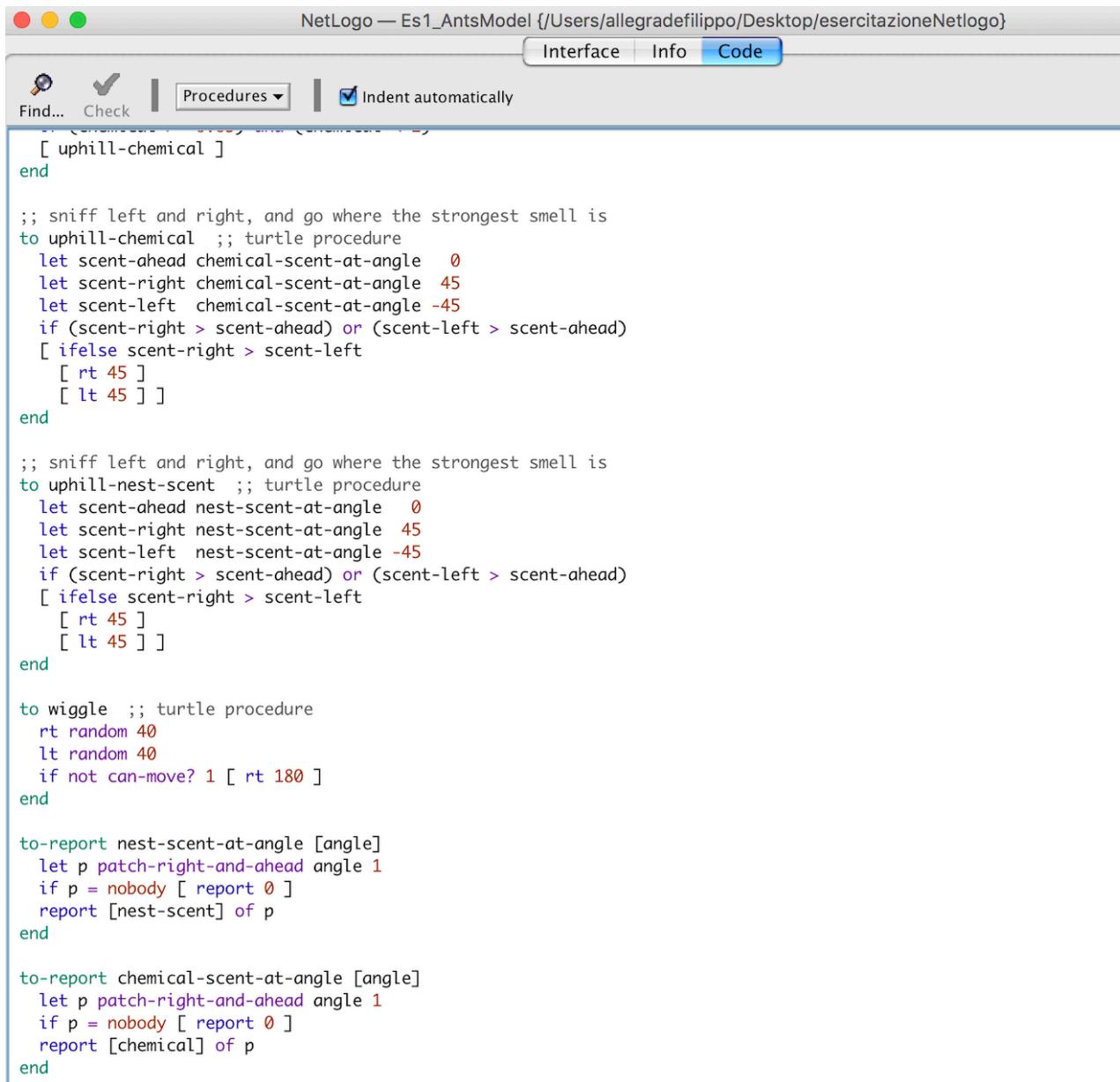
The screenshot shows the NetLogo interface with the title "NetLogo — Es1\_AntsModel {/Users/allegreadefilippo/Desktop/esercitazioneNetlogo}" at the top. Below the title is a toolbar with icons for Find..., Check, Procedures (with a dropdown menu), and a checkbox for "Indent automatically". The main area is the "Code" tab, which displays the following NetLogo code:

```
;;;;;;;;
;;; Go procedures ;;
;;;;;;;;
to go ;; forever button
  ask turtles
    [ if who >= ticks [ stop ] ;; delay initial departure
      ifelse color = red
        [ look-for-food ]      ;; not carrying food? look for it
        [ return-to-nest ]     ;; carrying food? take it back to nest
      wiggle
      fd 1 ]
    diffuse chemical (diffusion-rate / 100)
    ask patches
      [ set chemical chemical * (100 - evaporation-rate) / 100 ;; slowly evaporate chemical
        recolor-patch ]
    tick
  end

to return-to-nest ;; turtle procedure
  ifelse nest?
    [ ;; drop food and head out again
      set color red
      rt 180 ]
    [ set chemical chemical + 60 ;; drop some chemical
      uphill-nest-scent ]      ;; head toward the greatest value of nest-scent
  end

to look-for-food ;; turtle procedure
  if food > 0
    [ set color orange + 1      ;; pick up food
      set food food - 1        ;; and reduce the food source
      rt 180                  ;; and turn around
      stop ]
    ;; go in the direction where the chemical smell is strongest
    if (chemical >= 0.05) and (chemical < 2)
      [ uphill-chemical ]
  end
```

# Es\_1\_AntsModel.nlogo



The screenshot shows the NetLogo interface with the title bar "NetLogo — Es1\_AntsModel {/Users/allegreadefilippo/Desktop/esercitazioneNetlogo}" and tabs "Interface", "Info", and "Code" (which is selected). Below the tabs are buttons for "Find...", "Check", "Procedures", and "Indent automatically". The main window displays the following NetLogo code:

```
[ uphill-chemical ]
end

;; sniff left and right, and go where the strongest smell is
to uphill-chemical ;; turtle procedure
  let scent-ahead chemical-scent-at-angle 0
  let scent-right chemical-scent-at-angle 45
  let scent-left chemical-scent-at-angle -45
  if (scent-right > scent-ahead) or (scent-left > scent-ahead)
  [ ifelse scent-right > scent-left
    [ rt 45 ]
    [ lt 45 ] ]
end

;; sniff left and right, and go where the strongest smell is
to uphill-nest-scent ;; turtle procedure
  let scent-ahead nest-scent-at-angle 0
  let scent-right nest-scent-at-angle 45
  let scent-left nest-scent-at-angle -45
  if (scent-right > scent-ahead) or (scent-left > scent-ahead)
  [ ifelse scent-right > scent-left
    [ rt 45 ]
    [ lt 45 ] ]
end

to wiggle ;; turtle procedure
  rt random 40
  lt random 40
  if not can-move? 1 [ rt 180 ]
end

to-report nest-scent-at-angle [angle]
  let p patch-right-and-ahead angle 1
  if p = nobody [ report 0 ]
  report [nest-scent] of p
end

to-report chemical-scent-at-angle [angle]
  let p patch-right-and-ahead angle 1
  if p = nobody [ report 0 ]
  report [chemical] of p
end
```

# Exercise 1

## Things to notice

- The ant colony generally exploits the food source in order, starting with the food closest to the nest, and finishing with the food most distant from the nest
- It is more difficult for the ants to form a stable trail to the more distant food, since the chemical trail has more time to evaporate and diffuse before being reinforced

# Exercise 1

## Things to notice

- Once the colony finishes collecting the closest food, the chemical trail to that food naturally disappears, freeing up ants to help collect the other food sources.
  - The more distant food sources require a larger “critical number” of ants to form a stable trail.
- The consumption of the food is shown in a plot.
  - The line colors in the plot match the colors of the food piles.

# Exercise 1

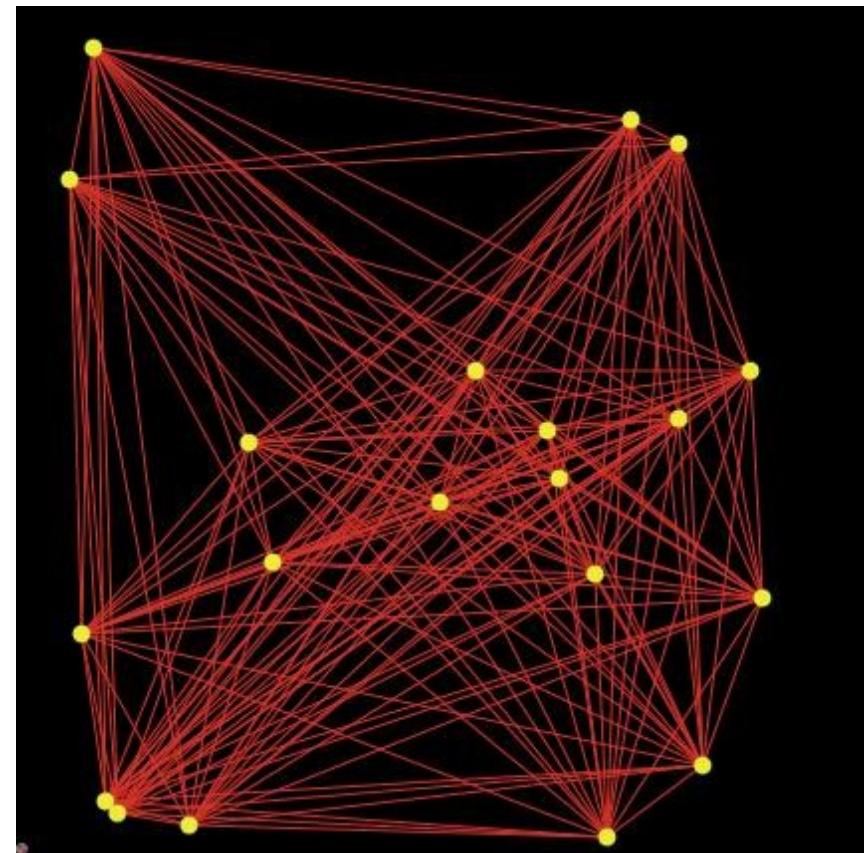
## Model Extensions

1. Try different placements for the food sources
  - What happens if two food sources are equidistant from the nest?
2. In this project, the ants use a “trick” to find their way back to the nest: they follow the “nest scent.”
  - Real ants use a variety of different approaches to find their way back to the nest.
  - Try to implement some alternative strategies.
3. In the uphill-chemical procedure, the ant “follows the gradient” of the chemical. That is, it “sniffs” in three directions, then turns in the direction where the chemical is strongest.
  - Try variants of the uphill-chemical procedure, changing the number and placement of “ant sniffs.”

# Exercise 2

## Ant Colony Optimization e TSP

- Goal: implementing the Ant System algorithm<sup>1</sup> and use it to solve the Traveling Salesman Problem
- Based on the observation of ants behaviour
  - Positive feedback based on pheromone tracks which reinforce the best solution components



<sup>1</sup> Dorigo, M., Maniezzo, V., and Colorni, A., *The Ant System: Optimization by a colony of cooperating agents*. *IEEE Transactions on Systems, Man, and Cybernetics Part B: Cybernetics*, Vol. 26, No. 1. (1996), pp. 29-41.

<http://citeseer.ist.psu.edu/dorigo96ant.html>

# Exercise 2

## Ant Colony

- As you already know
  - Ants leave a pheromone trail while going from the nest to food sources (and vice versa)
  - Ants tend to choose (with higher probability) routes with greater amount of pheromones
  - Cooperative interaction which leads to an emergent behaviour, that is finding the shortest path

# Exercise 2

## ACO

- Probabilistic model (*pheromone* model) used to recreate the pheromone trails left by ants
- Ants incrementally build the component of a solution
- Ants perform stochastic steps on a fully connected graph (*construction graph*)
- Constraints used to obtain a feasible solution

# Exercise 2

## ACO and TSP

- A possible model for TSP:
  - The graph nodes are the city to visit (the components of a solution)
  - The edges are the connections between the cities
  - A solution is a Hamiltonian circuit in the graph
  - Constraints are used to avoid loops, so that an ant can visit a city exactly once

# Exercise 2

## Information sources

- Edges or vertexes (or both) have two information:
  - Pheromone  $\tau$ , which stands in for natural trail left by ants and represents the long term memory of ants in relation to the global search process
  - Heuristic value  $\eta$ , i.e. the a priori knowledge on the problem

# Exercise 2

## ACO System

- The ants follow a path on the construction graph and build a solution
- They used a transition (probabilistic) rule to choose the next node to visit
- Both pheromone and heuristic are taken into account
- Pheromone values are adjusted based on the quality of the solution found