

Languages and Algorithms for Artificial Intelligence (Third Module)

Between the Feasible and the Unfeasible

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The Border Between the Tractable and the Intractable

- ▶ Up to now, we have encountered (essentially speaking) two complexity classes, namely:
 - ▶ **P**, which contains those problems which can be solved in polynomial time, so the **tractable** ones.
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- ▶ It's now time to study the “border” between tractability and intractability:
 - ▶ Between **P** and **EXP**, one can define *many other* classes. i.e. there are many ways of defining a class **A** such that

$$\mathbf{P} \subseteq \mathbf{A} \subseteq \mathbf{EXP}$$

- ▶ This is a formidable tool to classify those problems in **EXP** for which *we do not know* whether they are in **P** (and there are *so many* of them).

Creating vs. Verifying

- Very often, the language we would like to classify can be written as follows:

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- In other words, the elements of \mathcal{L} are those strings for which we can find a *certificate* y (of polynomial length) such that the pair (x, y) passes the *test* $\mathcal{A} \subseteq \{0, 1\}^* \times \{0, 1\}^*$.

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- ▶ What if \mathcal{A} is itself decidable in polynomial time? Does this imply that \mathcal{L} is itself decidable in polynomial time?
 - ▶ *Not necessarily*: given x , we can check whether $x \in \mathcal{L}$ by checking whether $(x, y) \in \mathcal{A}$ for all possible possible y such that $|y| \leq p(|x|)$, of which however there are *exponentially* many.
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 - ▶ Of course this does *not* rule out other strategies to decide \mathcal{L} .
- ▶ The *take-away message* is thus the following: **crafting** a solution for the problem x (i.e., finding y) can potentially be more difficult than just **checking** y to be a solution to x .

The Complexity Class **NP**

- ▶ A language $\mathcal{L} \subseteq \{0, 1\}^*$ is in the class **NP** iff there exist a polynomial $p : \mathbb{N} \rightarrow \mathbb{N}$ and a polynomial time TM \mathcal{M} such that

$$\mathcal{L} = \{x \in \{0, 1\}^* \mid \exists y \in \{0, 1\}^{p(|x|)}. \mathcal{M}(\sqcup x, y \sqcup) = 1\}$$

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Theorem

$$\mathbf{P} \subseteq \mathbf{NP} \subseteq \mathbf{EXP}$$

Examples Problems in NP

1. Maximum Independent Set

- In its decision form, it asks whether a pair (\mathbb{G}, k) of an undirected graph and a natural number $k \in \mathbb{N}$ is such that $\mathbb{G} = (V, E)$ admits an independent set $W \subseteq V$ of cardinality at least k .

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2. Subset Sum

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- ▶ Given three numbers n, m, l , it asks whether n has a prime factor in the interval $[m, l]$.
- ▶ Certificate: it can be taken to be the prime number p : checking that $p \in [m, l]$ and that p divides n is easy. Instead, checking that p is prime requires a lot of work, but can indeed be done in polynomial time.

Examples Problems in NP

3. Decisional Linear Programming

- ▶ Given a sequence of m linear inequalities with rational coefficients over n variables (i.e. inequalities of the form $\sum_{i=1}^n a_i x_i \leq b$, where the coefficients a_1, \dots, a_n, b are in \mathbb{Q}), decide whether there is a rational assignment to the variables x_1, \dots, x_n which makes all the inequalities true.

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- ▶ Certificate: again, the assignments suffices.

Examples Problems in \mathbf{NP}

- ▶ Some of the aforementioned problems are also in \mathbf{P} :
 - ▶ *Decisional linear programming* can be proved to be in \mathbf{P} thanks to, e.g., the Ellipsoid algorithm.
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 - ▶ The *composite numbers* problem can be proved itself to be in **P**, thanks to a breakthrough recent result, namely the so-called AKS algorithm.
- ▶ All the other problems are currently **not known** to be in **P**.
 - ▶ Are they all equivalent in terms of their inherent computational difficulty?
 - ▶ Is there any way isolate those problems in **NP** whose difficulty is maximal, i.e. they are at least as hard as all other problems in **NP**?

Nondeterministic Turing Machines

- ▶ The class **NP** can also be defined using a variant of Turing machines, called the *nondeterministic* Turing machines (NDTM for short).
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- ▶ The only differences between a NDTM and an ordinary TM is that the former has:
 - ▶ Two transition functions δ_0 and δ_1 rather than just one. *At every step*, the machine chooses nondeterministically one between the two transition functions and proceed according to it
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 - ▶ A special state q_{accept} .
- ▶ We say that a NDTM M :
 - ▶ **Accepts** the input $x \in \{0, 1\}^*$ iff *there exists* one among the many possible evolutions of the machine M when fed with x which makes it reaching q_{accept} .
 - ▶ **Rejects** the input $x \in \{0, 1\}^*$ iff *none* of the aforementioned evolutions leads to q_{accept} .

Time-Bounded NDTMs

- ▶ We say that a NDTM M *runs in time* $T : \mathbb{N} \rightarrow \mathbb{N}$ iff for every $x \in \{0, 1\}^*$ and for every possible nondeterministic evolution, M reaches either the halting state or q_{accept} within $c \cdot T(|x|)$ steps, where $c > 0$.

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- ▶ For every function $T : \mathbb{N} \rightarrow \mathbb{N}$ and $\mathcal{L} \subseteq \{0, 1\}^*$, we say that $\mathcal{L} \in \mathbf{NDTIME}(T(n))$ iff there is a NDTM M working in time T and such that $M(x) = 1$ iff $x \in \mathcal{L}$.

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- ▶ All this being said, NDTMs, contrarily to TMs, are *not* meant to model any form of physically realisable machine.

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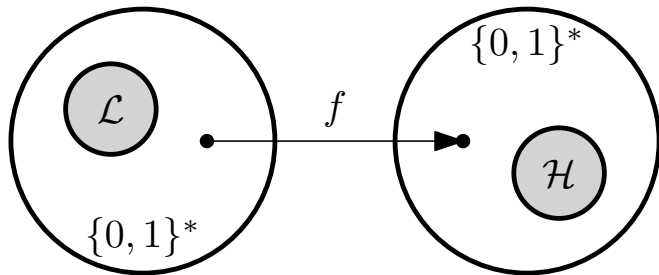
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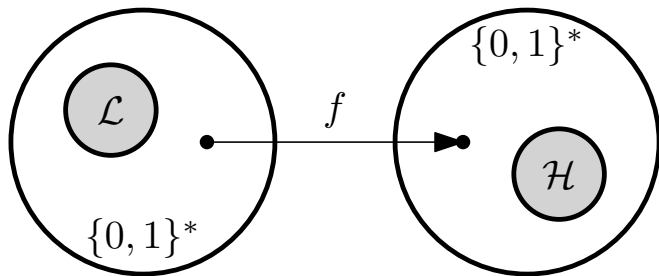
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- ▶ We need something else, namely a (pre-order) relation between languages such that two languages being in relation tells us something precise about the **relative** difficulty of deciding them.

Reductions



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- ▶ The language \mathcal{L} is said to be **polynomial-time reducible** to another language \mathcal{H} iff there is a polytime computable function $f : \{0, 1\}^* \rightarrow \{0, 1\}^*$ such that $x \in \mathcal{L}$ iff $f(x) \in \mathcal{H}$.
- ▶ In this case, we write $\mathcal{L} \leq_p \mathcal{H}$.

Reductions and Complexity

- ▶ If $\mathcal{L} \leq_p \mathcal{H}$, then \mathcal{H} is at least as difficult as \mathcal{L} , at least as far as classes like \mathbf{P} (or above it) are concerned.
 - ▶ If, e.g., $\mathcal{L} \leq_p \mathcal{H}$ and $\mathcal{H} \in \mathbf{P}$, then also $\mathcal{L} \in \mathbf{P}$: a way to decide if $x \in \mathcal{L}$ consists in translating it into $f(x)$ (which can be done in polynomial time), then checking whether $f(x) \in \mathcal{H}$.

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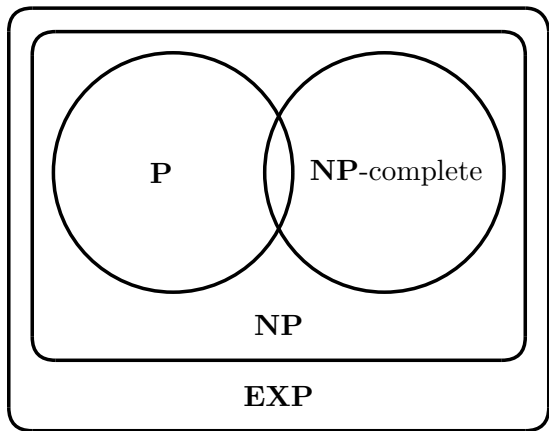
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- ▶ A language $\mathcal{H} \subseteq \{0, 1\}^*$ is said to be:
 - ▶ **NP-hard** if $\mathcal{L} \leq_p \mathcal{H}$ for every $\mathcal{L} \in \mathbf{NP}$.
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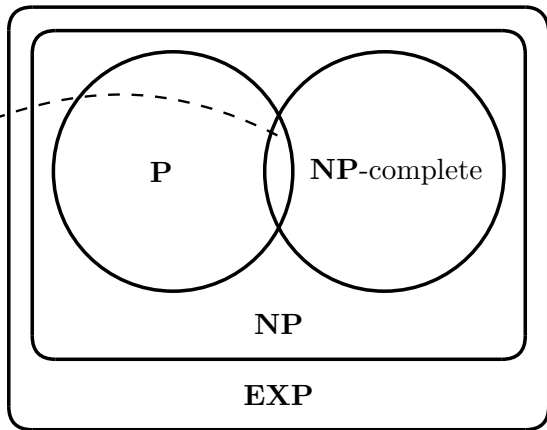
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Theorem

1. The relation \leq_p is a pre-order (i.e. it is reflexive and transitive).
2. If \mathcal{L} is **NP-hard** and $\mathcal{L} \in \mathbf{P}$, then $\mathbf{P} = \mathbf{NP}$.
3. If \mathcal{L} is **NP-complete**, then $\mathcal{L} \in \mathbf{P}$ iff $\mathbf{P} = \mathbf{NP}$.



Empty
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$$\mathbf{TMSAT} = \{(\alpha, x, 1^n, 1^t) \mid \exists u \in \{0, 1\}^n. \mathcal{M}_\alpha \text{ outputs } 1 \\ \text{on input } (x, u) \text{ within } t \text{ steps}\}$$

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- ▶ Although interesting from a purely theoretical perspective, the language **TMSAT** is very specifically tied to Turing Machines, and thus of no practical importance.

A Quick Recap on Propositional Logic

- ▶ Formulas of **propositional logic** are either:
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- ▶ Examples: $X \vee \neg X$, $X \wedge (Y \vee \neg Z)$, etc.

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- ▶ Formulas of **propositional logic** are either:
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- ▶ A formula F is **satisfiable** iff there is one ρ such that $\llbracket F \rrbracket_\rho = 1$.

The Cook-Levin Theorem

- ▶ A propositional formula F is said to be in **conjunctive normal form** (or a **CNF**) when it is a conjunction of disjunctions of *literals* (a literal being a variable or its negation).
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Theorem (Cook-Levin)

*The following two languages are **NP**-complete:*

$$\begin{aligned}\text{SAT} &= \{\lfloor F \rfloor \mid F \text{ is a satisfiable CNF}\} \\ \text{3SAT} &= \{\lfloor F \rfloor \mid F \text{ is a satisfiable 3CNF}\}\end{aligned}$$

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$$\varphi_x \in \mathbf{SAT} \Leftrightarrow \exists y \in \{0, 1\}^{p(|x|)}. \mathcal{M}(x, y) = 1$$

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- ▶ Finally, we need to show that $\mathbf{SAT} \leq_p 3\mathbf{SAT}$.

Proving a Problem Hard

- ▶ Suppose you are studying the complexity of a language \mathcal{L} , and you are convinced that the underlying problem is **hard**. How should you back your claim?
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- ▶ By proving that $\mathcal{L} \in \mathbf{NP}$?
 - ▶ Again, this **does not** mean much.
- ▶ By proving that \mathcal{L} is **NP**-complete?
 - ▶ **Yes**, this way you prove that the problem is not so hard (being in **NP**), but not so easy either (unless $\mathbf{P} = \mathbf{NP}$).

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2. That any other language $\mathcal{H} \in \mathbf{NP}$ is such that $\mathcal{H} \leq_p \mathcal{L}$.

- ▶ We can of course prove the statement directly.
- ▶ More often (e.g. when showing **3SAT** **NP**-complete), one rather proves that $\mathcal{J} \leq_p \mathcal{L}$ for a language \mathcal{J} which is already known to be **NP**-complete.
- ▶ This is correct, simply because \leq_p is transitive:

$$\begin{array}{ccccc} \vdots & & & & \\ \mathcal{H} & \xrightarrow{\leq_p} & \mathcal{J} & \xrightarrow{\leq_p} & \mathcal{L} \\ \vdots & & & & \end{array}$$

NP-complete Problems: Examples

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Theorem

The Decisional 0/1 Linear Programming Problem ILP is NP-complete

- ▶ There is an easy polytime reduction from SAT to ILP.

The Zoo of **NP**-complete Problems

- ▶ For any pair \mathcal{L}, \mathcal{H} of **NP**-complete problems, we have that

$$\mathcal{L} \leq_p \mathcal{H} \quad \mathcal{H} \leq_p \mathcal{L}$$

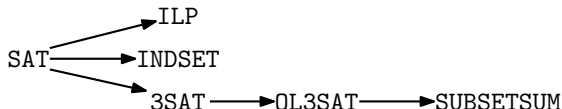
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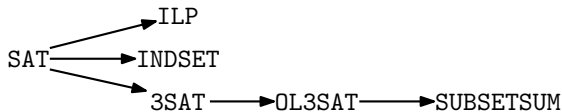


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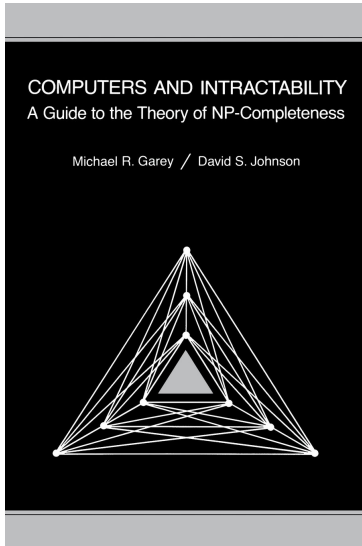
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- ▶ In fact, this graph is **huge**: thousands of different problems are known to be **NP**-complete

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- ▶ This is often **very useful**, because specialised tools for **SAT**, called SAT-solvers do exist.
 - ▶ They do not work in polynomial time.
 - ▶ Concretely, they work extremely well on a relatively large class of formulas.

Is This the End of The Story?

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$$\mathbf{L} \subseteq \mathbf{NL} \subseteq \mathbf{P} \subseteq \frac{\mathbf{NP}}{\mathbf{coNP}} \subseteq \dots \subseteq \mathbf{PH} \subseteq \mathbf{PSPACE} \subseteq \mathbf{EXP} \subseteq \dots$$

Thank You!

Questions?