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Robot Wiring Order

	Red	Motor 1A
	Orange	Motor 1B
	Yellow	Motor 2A
	Green	Motor 2B
	Blue	Motor 3A
	Violet	Motor 3B
	Gray	Motor 4A
	White	Motor 4B
	Black	GND
w/white	Red	5V
	Orange	SDA
	Yellow	SCL
	Green	XSHUT1
	Blue	XSHUT2
	Violet	XSHUT3
	Gray	XSHUT4
	White	Stepper A X Brown
	Black	Stepper B
w/Black	Red	Stepper C
	Orange	Stepper D X Brown/White
	Yellow	
	Green	
	Blue	
	Violet	
	Gray	
	White	X
	Black	X

Tested

Sensor 1
Red = Vin
Orange = GND
Green = SCL
Blue SDA
Yellow = XSHUT

Sensor 2
Red = Vin
Orange = GND
Green = SCL
Blue = SDA
Yellow = XSHUT

Sensor 3
Brown = Vin
White = XSHUT
Black = GND
Gray = SDA
Violet = SCL

Sensor 4
Brown = SDA
White = XSHUT
Black = SCL
Gray = GND
Violet = Vin

~~Unused~~

Light Blue
Black/Blue GND
Gold
Yellow/Green 5V

GND	DIR
VDD	STEP
1B	SLEEP
1A	RESET
2A	MS3
2B	MS2
GND	MS1
VMOT	EN

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Name _____ Sheet No. _____ of _____

For robot wiring Date 3/30/22

*orientation of bot is down from top with notch at top 

motor shield-
M1 - motor 1, top right
M2 - motor 2, bottom right
M3 - motor 3, bottom left
M4 - motor 4, top left

Vin - ±12V from rail/battery

Servo1 - raising servo, external ±5V from regulator

Servo2 - grabber servo, ±5V from shield

- running separate ±5V for servos
Gnd, Pwr, Signal

- all sensor lines passthrough to respective board pins

Hodge Podge board-
±12V - power rail
±5V - out
DC Driver - in1 - Pin 11
in2 - Pin 12
Out1 - motor 5
out2 - motor 5

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Name _____ Sheet No. _____ of _____

For _____ Date _____

Hedge Podge board cont.-

Stepper driver 1 -

1A - raising arm 1A
1B - raising arm 1B
2A - raising arm 2A
2B - raising arm 2B
Step - A1
Dir - A0

Stepper driver 2 -

1A - Base 1A
1B - Base 1B
2A - Base 2A
2B - Base 2B
Step - A3
Dir - A2