Military Institute of Science and Technology

# 4-bit microprocessor

**Course Name: Digital System Design Sessional**

**Course Code:** CSE-316

**Program:** CSE-20

**Session:** 2019-2020

**Group No: B3**

**Group members:**

Jamal Uddin Tanvin (202014016)

MD Rifat Islam (202014034)

Md Tausiful Haque (202014036)

Nurshat Fateh Ali (202014040)

Table of Contents

[4-bit microprocessor 0](#_Toc120990388)

[1. Introduction 2](#_Toc120990389)

[**1.1.** **Simple 4 Bit Micro Processor (SAP-1):** 2](#_Toc120990390)

[**1.2.** **Macro instruction set:** 2](#_Toc120990391)

[**1.3.** **Programming SAP-1:** 3](#_Toc120990392)

[2. Architecture 3](#_Toc120990393)

[**2.1.** **Block diagram:** 3](#_Toc120990394)

[3. Fetch cycle and active control signals 5](#_Toc120990395)

[4. Execution cycle and active control signals 5](#_Toc120990396)

[5. Design of execution Unit 6](#_Toc120990397)

[**5.1.** **Program counter, RAM, ALU:** 6](#_Toc120990398)

[**5.2.** **Registers (A, B, OUT, MAR, IR):** 8](#_Toc120990399)

[**5.3.** **MUX and Buffers:** 10](#_Toc120990400)

[**5.4.** **Required ICs for Execution Unit:** 12](#_Toc120990401)

[6. Design of Control Unit 12](#_Toc120990402)

[**6.1.** **Ring counter:** 12](#_Toc120990403)

[**6.2.** **Instruction decoder:** 13](#_Toc120990404)

[**6.3.** **Control Matrix:** 13](#_Toc120990405)

[**6.4.** **Required ICs for Control Unit:** 15](#_Toc120990406)

[7. Problem faced 15](#_Toc120990407)

[8. Future expansion 15](#_Toc120990408)

[The elaborated design of the project 16](#_Toc120990409)

[References 16](#_Toc120990410)

4-Bit Microprocessor

## Introduction

### **Simple 4 Bit Micro Processor (SAP-1):**

A 4 Bit Microprocessor is a processor that can processes 4-bit number simultaneously. The size of number that the processor can work with depends on the size of the ALU (Arithmetic Logic Unit). An n-bit microprocessor has an ALU of n bit. We can say that the size of ALU of a 4-bit microprocessor is 4 bits. SAP is simple microprocessor with ALU of 8 bits in length. In this project we will design a simple 4-bit microprocessor.

The Simple-As-Possible (SAP) computer is a simplified computer architecture designed for educational purposes. The SAP architecture serves as an example in Digital Computer Electronics for building and analyzing complex logical systems with digital electronics. Digital Computer Electronics successively develops three versions of this computer, designated as SAP-1, SAP-2, and SAP-3. Each of the last two build upon the immediate previous version by adding additional computational, flow of control, and input/output capabilities. SAP-2 and SAP-3 are fully Turing-complete. [1]

The SAP-1 computer is the first stage in this evolution and contains the necessities for a functional computer. Its primary purpose is to develop a basic understanding of how a computer works, interacts with memory and other parts of the system like input and output. The instruction set is very limited and is simple.

### **Macro instruction set:**

A macro instruction is a request to the assembler program to process a predefined sequence of instructions called a macro definition. From this definition, the assembler generates machine and assembler instructions, which it then processes as if they were part of the original input in the source module. [2]  It is a group of programming instructions that have been compressed into a simpler form and appear as a single instruction.

In SAP the control sequencer sends out control words, one during each T state or clock cycle. These words are like directions telling the rest of the computer what to do. Because they produce small steps in the data processing where each control word is called a **microinstruction**. The instructions we have been programming with (LDA, SUB, MOV…) are called **macroinstructions** to distinguish them from microinstructions. In SAP-1 each macroinstruction is consist of three microinstructions. In this project, we have designed the macroinstructions in such a way that they consist of 2 microinstructions each and, we have few macroinstructions which are not in SAP-1. The following macroinstructions are implemented in our project.

LDA, MOV, INR, AND, JM, OUT and HALT

### **Programming SAP-1:**

In SAP-1 we have LDA, ADD, SUB, OUT, HLT these macroinstructions. With these instructions we can easily make a program in Assembly language and then convert them in Machine code to write in the RAM. In SAP-1 we manually write the program in the RAM and execute it by giving clock pulse manually (Single Step) or automatically. In our project we also program our microprocessor same as SAP-1. In our case we have different instructions than SAP-1 but the process of programming is same. A simple program in SAP-1 is like below

10H – 22H + 28H

|  |  |  |
| --- | --- | --- |
| **Memory Addresses (RAM)** | **Assembly code** | **Machine code** |
| 00H | LDA 8H | 0000 1000 |
| 01H | SUB 9H | 0010 1001 |
| 02H | ADD AH | 0001 1011 |
| 03H | OUT | 1110 xxxx |
| 04H | HLT | 1111 xxxx |
| 05H |  |  |
| 06H |  |  |
| 07H |  |  |
| 08H | 10H | 0001 0000 |
| 09H | 22H | 0010 0010 |
| 0AH | 28H | 0010 1000 |
| 0BH |  |  |
| 0CH |  |  |
| 0DH |  |  |
| 0EH |  |  |
| 0FH |  |  |

Figure 1: Simple program in SAP-1

## Architecture

The architecture of SAP-1 is a bus organized computer. The architecture of our microprocessor project is same as SAP-1.

### **Block diagram:**

The block diagram of the architecture our microprocessor project is given further for better understanding.

Diagram, schematic

Description automatically generated

Figure 2: Block diagram of the Architecture

## Fetch cycle and active control signals

In our project we have total four T states. The fetch cycle has two T state, T1 and T2 as we have merged the increment state with memory state. So T1 does the job address state and T2 state does the job of both increment and memory state. The control signal state during fetch cycle is given below

Control word format:

Increase Program counter

Enable Program counter

Load program counter

Load MAR

Enable RAM

Load IR

Enable IR

Load Accumulator

Enable Accumulator

Increment (0) / AND (1)

Enable ALU

Load B register

Load Output register

|  |  |  |  |
| --- | --- | --- | --- |
| **Macro** | **State** | **CON(HEX)** | **Active** |
| Fetch |  | DE3 | *,* |
|  | 1663 | *, ,* |

## Execution cycle and active control signals

Among four T states in our project T3 and T4 states are for the execution cycle. The register transfer during the execution cycle depend on the particuler instruction being executed. In our project we have total 7 instructions. They are given below

|  |  |  |  |
| --- | --- | --- | --- |
| **Serial** | **OP code** | **Instruction** | **Function** |
| 1 | 0000 | LDA M | Load RAM data from memory address M to Accumulator |
| 2 | 0001 | MOV B, A | Move the 4-bit value to B register from A register |
| 3 | 0010 | INR A | Increment the value of Accumulator by 1 |
| 4 | 0011 | AND B | Perform AND operation on data of B register with accumulator and store the result in the A register |
| 5 | 0100 | JM M | Jump to designated memory address M if SF=1 |
| 6 | 0101 | OUT | Load data of Accumulator to output register |
| 7 | 0110 | HLT | Stop the program (No operation) |

The control signal state during execution cycle for each instruction is given below

|  |  |  |  |
| --- | --- | --- | --- |
| **Macro** | **State** | **CON(HEX)** | **Active** |
| LDA |  | 05A3 | , |
|  | 06C3 |  |
| MOV |  | 07F1 | , |
|  | 07E3 | NOP |
| INR |  | 07C7 | , |
|  | 07E3 | NOP |
| AND |  | 07CF | , *,* |
|  | 07E3 | NOP |
| JM  When SF=1 |  | 03A3 |  |
|  | 07E3 | NOP |
| OUT |  | 07F2 | , |
|  | 07E3 | NOP |
| HALT |  | 07E3 | NOP |
|  | 07E3 | NOP |

## Design of execution Unit

### **Program counter, RAM, ALU:**

In our project we have used IC 74LS193 as our program counter. IC 74LS193 is a synchronous 4-Bit Up Down Binary Counter with Dual clock.

For RAM (Random Access Memory) we have used IC 74LS189. As 74LS189 is a RAM but we needed store 8-bit data, so we took two RAM and shorted their address bit and made RAM with them.

For ALU (Arithmetic Logic Unit) we used IC 74LS181. As it offers lots of operations, we just used two operations (Increment, AND) toggling the two combinations of the selection bits with  **(**0 and 1).

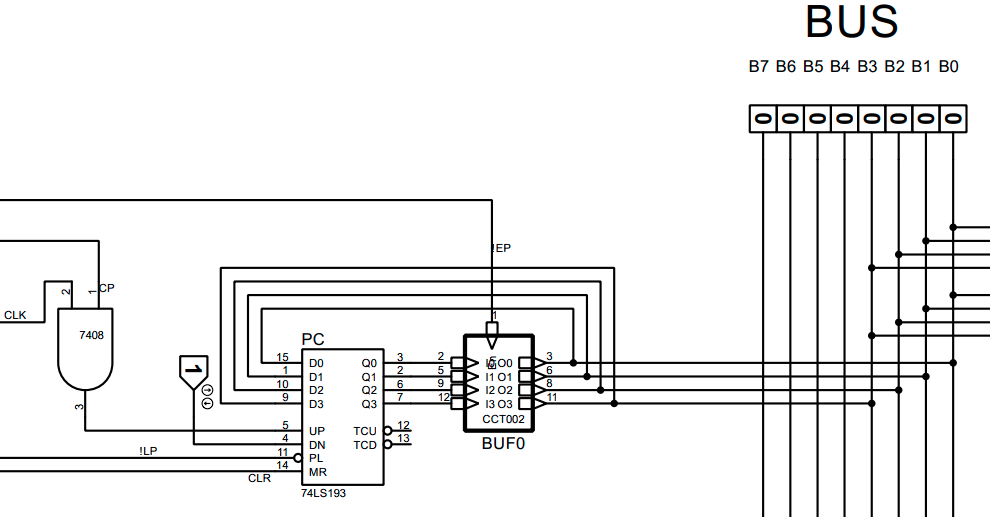


Figure 3: Design of Program Counter

Diagram, schematic

Description automatically generated

Figure 4: Design of RAM

Diagram, schematic

Description automatically generated

Figure 5: Design of ALU

### **Registers (A, B, OUT, MAR, IR):**

For register we have used IC 74LS173 which is a 4 bit register of Quad D-Type Flip-Flops with Tristate Outputs for Accumulator, B register, Output register, MAR, and IR. We used two registers for IR as it is of 8 bits in size.

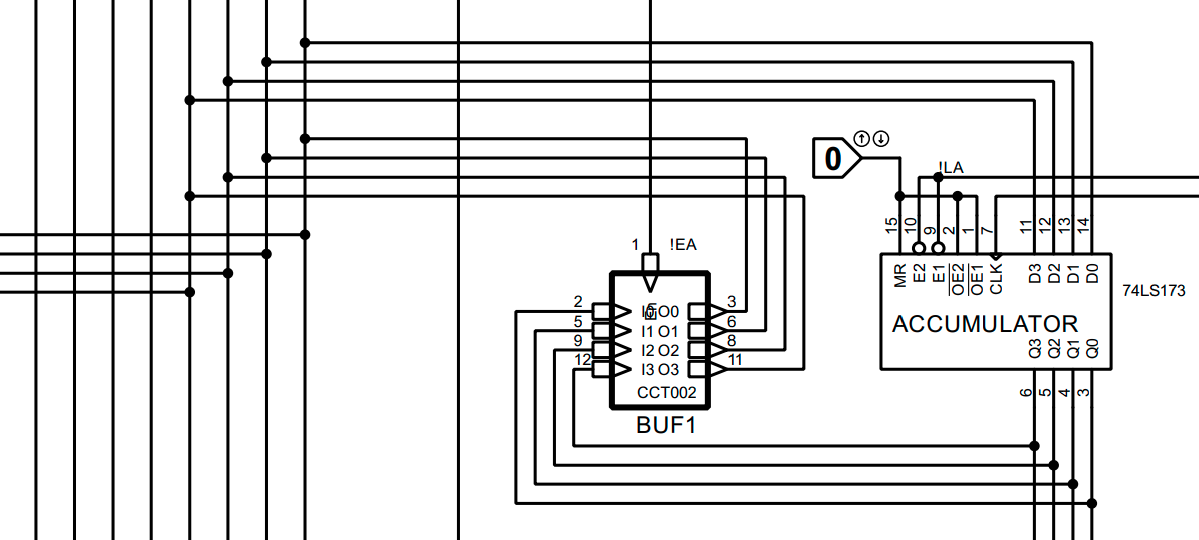


Figure 6: Design of Accumulator

A picture containing application

Description automatically generated

Figure 7: Design of B register

Diagram, schematic

Description automatically generated

Figure 8: Design of Output register

Diagram, schematic

Description automatically generated

Figure 9: Design of MAR

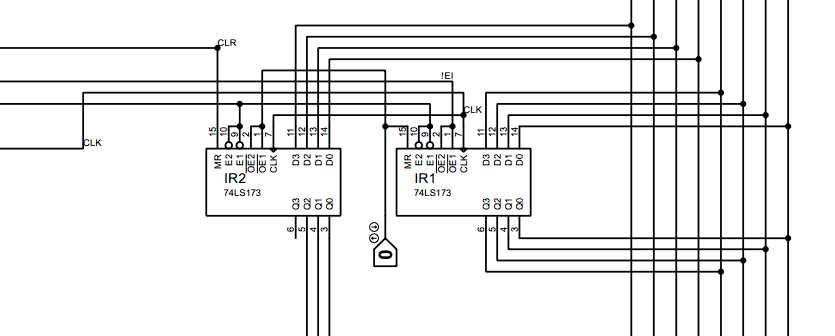


Figure 10: Design of IR

### **MUX and Buffers:**

We used IC 74LS157 which is Quadruple 1-of-2 Data Selectors/Multiplexers as our MUX. MUX is required for giving Address in the RAM from outside od the processor while programing the microprocessor. We used IC 74LS125 which is a Quadruple Bus Buffer Gate with Tristate Outputs for holding data. Buffer is used to convert an IC into 3 state from 2 state.

Diagram, schematic

Description automatically generated

Figure 11: Design of MUX

Diagram, schematic

Description automatically generated Diagram

Description automatically generated

Figure 12: Design of BUFFER

### **Required ICs for Execution Unit:**

|  |  |  |  |
| --- | --- | --- | --- |
| **IC** | **IC type** | **Function** | **Quantity** |
| 74LS193 | Synchronous 4-Bit Up Down Binary Counter with Dual clock | Program Counter | 1 |
| 74LS189 | 64-Bit Random Access Read/Write Memory | RAM | 2 |
| 74LS181 | Arithmetic Logic Unit | ALU | 1 |
| 74LS173 | Quad D-Type Flip-Flops with Tristate Outputs | 4 Bit Register | 6 |
| 74LS157 | Quadruple 1-of-2 Multiplexers | MUX | 1 |
| 74LS125 | Quadruple Bus Buffer Gate | BUFFER | 3 |
| 74LS04 | NOT Gate | Inverter | 2 |
| 74LS08 | AND Gate | AND | 1 |
| Total | | | 17 |

## Design of Control Unit

### **Ring counter:**

By the help of ring counter, we change our T states during fetch and execution cycle. We need a ring counter which can enable the states sequentially in a circular way. So, we made a Ring counter with JK flipflops (IC 74LS76) to do that job.

Diagram

Description automatically generated

Figure 13: Design of Ring counter

### **Instruction decoder:**

We must decode the instruction written in the RAM after fetching them after the fetch cycle to continue the process of our execution cycle. To do this we used IC 74LS138 which is a 3-Line to 8-Line Decoders/Demultiplexers. It decodes the opcodes and enables the corresponding line for that opcode.

Diagram, schematic

Description automatically generated

Figure 14: Design of Decoder

### **Control Matrix:**

Control matrix does the job of enabling or disabling the control signals of the execution unit. We have designed the control matrix with combinational circuit consist of AND, OR, NOR, and NOT gates. The functions for the signals are given below

Diagram, schematic

Description automatically generated

Figure 15: Design of Control Matrix

### **Required ICs for Control Unit:**

|  |  |  |  |
| --- | --- | --- | --- |
| **IC** | **IC type** | **Function** | **Quantity** |
| 74LS138 | 3-Line To 8-Line Decoders | Decoding | 1 |
| 74LS76 | JK Flipflop | Ring Counter | 2 |
| 74LS04 | NOT Gate | Inverter | 2 |
| 74LS08 | AND Gate | AND operation | 2 |
| 74LS32 | OR Gate | OR operation | 1 |
| 74LS32 | NOR Gate | NOR operation | 1 |
| Total | | | 9 |

## Problem faced

In this project of 4 Bit Microprocessor, we faced some significant problems. Although all the problem had been overcome by us. Some are given below

* The trainer boards didn’t have enough switch for all the signals and data inputs. So, we had to give those inputs by connecting wires manually to the ground or to the Vcc.
* We didn’t have RAM, so we had to use two RAM. Again, the RAM gives inverted outputs. So, we had to reinvert the outputs of the RAMs.
* The decoder that we use also gives inverted output. So, we had to reinvert those also.
* To do only two operations (Increment & AND) we had to manipulate the selection pin of the ALU so that we can do these two operations with only one control signal.
* There were lots of wires to be put on in the ICs, so that was a hard job.
* In this project we needed total 26 ICs. As a result, we needed two trainer boards. One for the execution unit and another for the control unit.
* As we used Ram so every time the power went of all the data written in it was destroyed. So, we had to write instructions repeatedly and that was quite time consuming.

## Future expansion

The microprocessor that we designed can easily be expended in future by adding new control signals and with some minor modification. But there is a problem. The control unit that we designed is Hardwired. So, it is quite too tough to change the design when a new instruction is implanted for the processor. We may have to change the whole control sequencer for that job. If we had a chance to make the control unit with microprogram method than it could easily expanded.

## The elaborated design of the project

We designed our project using Proteus 8 professional version 8.13 SP0. The pdsprj and pdf file of the design can be found in this link:

<https://github.com/Tanvin420/4-Bit_Microprocessor/>

# References

|  |  |
| --- | --- |
| [1] | "Wikipedia,"[Online].Available:https://en.wikipedia.org/wiki/Simple-AsPossible\_computer. |
| [2] | "IBM,"[Online].Available:https://www.ibm.com/docs/en/zos/2.2.0?topic=SSLTBW\_2.2.0/com.ibm.zos.v2r2.asma400/asmr102115.html. |