

## Uhlig's Toolkit

SFU

$$Y = C + I$$

$$Y = C + S$$

$$C + I = C + S$$

$$I = S$$

$$K_t \leq K_{t-1} + I_t - \delta K_{t-1}$$

$$\text{Max } U(x, y)$$

s.t.

$$xP_x + yP_y = M$$

$$\frac{U'_x}{U'_y} = \frac{P_x}{P_y}$$

محدودیت هایی:

$$P_t C_t + P_t I_t + P_t T_t + B_t + M_t = P_t W_t L_t + r_t K_{t-1} P_t \\ + (1+i_{t-1}) B_{t-1} + M_{t-1} + P_t D_t$$

محدودیت دیگر:

$$P_t G_t + (1+i_{t-1}) B_{t-1} = P_t T_t + M_t - M_{t-1} + B_t$$

$$P_t C_t + P_t I_t + P_t G_t = P_t W_t L_t + r_t P_t K_{t-1} + P_t D_t$$

$$C_t + I_t + G_t = w_t L_t + r_t K_{t-1} + D_t$$

$$Y_t = w_t L_t + r_t K_{t-1} + D_t = F(K_{t-1}, L_t)$$

$$Y_t = C_t + I_t + G_t$$

$$K_t = (1-\delta) K_{t-1} + I_t$$

طبقه بندی متغیرها:

$$Y_t = \alpha + \beta X_t + \varepsilon_t$$

$$Y_t = \hat{\alpha} + \hat{\beta} X_t + \hat{\varepsilon}_t$$

$$y(t)$$

$$E(\varepsilon_t) = 0$$

متغیرهای تصادفی و مطابق:

متغیرهای درین راه برداشت:

$$Y_t = \alpha + \beta X_t + \varepsilon_t$$

Control and state variables

متغیرهای متصل و معمولی: کن درین پایه متغیر و مختصات است

$$Y_t = \alpha + \beta Y_{t-1} + \varepsilon_t \quad \text{عادل خانه بریکارل (RBC)}$$

$$Y_t = a + b X_t + c X_t^2$$

(AR(1)) Auto Regression: خودرسان

برنحل عادله فضای میانی ایال:

$$Y_t = \alpha + \beta Y_{t-1} + \varepsilon_t, \quad E(\varepsilon_t) = 0 \quad \text{برنحل چندیا} \quad ①$$

$$Y_{t+1} = \alpha + \beta Y_{t-2} + \varepsilon_{t-1} \quad \text{برنحل عالم برقع} \quad ②$$

$$y_t = \alpha + \beta y_{t-1} + \varepsilon_t, \quad E(\varepsilon_t) = 0 \quad (1)$$

$$\hat{y}_{t+1} = \alpha + \beta y_{t-2} + \varepsilon_{t-1} \quad (2)$$

..... " " (3)

$$y_t = \alpha + \beta (\alpha + \beta y_{t-2} + \varepsilon_{t-1}) + \varepsilon_t$$

$$y_t = \alpha + \alpha \beta + \beta^2 y_{t-2} + \varepsilon_t + \beta \varepsilon_{t-1}$$

$$y_{t-2} = \alpha + \beta y_{t-3} + \varepsilon_{t-2}$$

$$y_t = \underbrace{\alpha + \alpha \beta + \alpha \beta^2 + \dots + \alpha \beta^t}_{\text{أجزاء}} + \underbrace{\beta^{t+1} y_{-1}}_{\text{جزء آخر}} + \underbrace{\varepsilon_t + \beta \varepsilon_{t-1} + \dots + \beta^t \varepsilon_0}_{\text{جزء آخر}}$$

$$E(y_t) = \alpha [1 + \beta + \beta^2 + \dots + \beta^t] + \beta^{t+1} \bar{y}_{-1}$$

$$E(y_t) = \alpha \frac{[1 - \beta^{t+1}]}{1 - \beta} + \beta^{t+1} \bar{y}_{-1}$$

$$\beta \begin{cases} < 1 \\ = 1 \\ > 1 \end{cases}$$

if  $\beta < 1$

$$\lim_{t \rightarrow \infty} E(y_t) = \lim_{t \rightarrow \infty} \alpha \frac{[1 - \beta^{t+1}]}{1 - \beta} + \lim_{t \rightarrow \infty} \beta^{t+1} \bar{y}_{-1}$$

$$= \frac{\alpha}{1 - \beta} + 0$$

$$E(y_t) = \frac{\alpha}{1 - \beta}$$

Steady State:

$$x_t = x_{t-1} = E_t x_{t+1} = \bar{x}$$

$$y_t = \alpha + \beta y_{t-1} + \varepsilon_t$$

$$\bar{y} = \alpha + \beta \bar{y} + \bar{\varepsilon}$$

$$(1 - \beta) \bar{y} = \alpha$$

$$\bar{y} = \frac{\alpha}{1 - \beta}$$

$\beta < 1$

$$y_t = \underbrace{\alpha [1 + \beta + \beta^2 + \dots + \beta^t]}_{\frac{\alpha}{1 - \beta}} + \underbrace{\beta^{t+1} y_{-1} + \varepsilon_t + \beta \varepsilon_{t-1} + \dots + \beta^t \varepsilon_0}_{\text{أجزاء}}$$

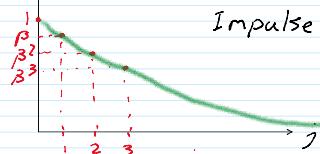
$$y_t = \frac{\alpha}{1 - \beta} + \varepsilon_t + \beta \varepsilon_{t-1} + \beta^2 \varepsilon_{t-2} + \dots$$

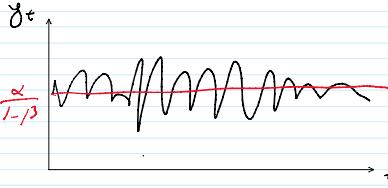
$$\frac{\partial y_t}{\partial \varepsilon_{t-j}} = \frac{\partial y_{t+j}}{\partial \varepsilon_t} = \beta^j \quad j \in [0, \infty)$$

Impulse Response

$$\frac{\partial y_{t+j}}{\partial \varepsilon_t}$$

Impulse Response Function





$\beta = 1$

$$\hat{y}_t = \frac{\alpha}{1-\beta} = \frac{\alpha}{1-1} = \frac{\alpha}{0} = \infty \quad 1-\beta = 0 \quad \text{no b rms}$$

$$y_t = \alpha [1 + \beta + \beta^2 + \dots + \beta^{t-1}] + \beta^{t-1} y_{t-1} + \varepsilon_t + \beta \varepsilon_{t-1} + \dots + \beta^{t-1} \varepsilon_0$$

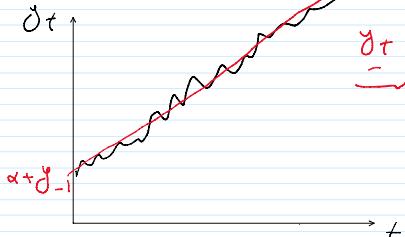
$$y_t = \alpha [1 + 1 + 1 + \dots + 1] + y_{t-1} + \varepsilon_t + \varepsilon_{t-1} + \dots + \varepsilon_0$$

$$y_t = \alpha (t+1) + y_{t-1} + \varepsilon_t + \varepsilon_{t-1} + \dots + \varepsilon_0$$

$$E(y_t) = \alpha (t+1) + y_{t-1}$$

lik  $E(y_t) = \infty$

$t \rightarrow \infty$



$\beta > 1$

$$\frac{1}{\beta} y_t = \frac{\alpha}{\beta} + \frac{\beta}{\beta} y_{t-1} + \frac{1}{\beta} \varepsilon_t$$

$$\frac{1}{\beta} y_t = \frac{\alpha}{\beta} + y_{t-1} + \frac{1}{\beta} \varepsilon_t$$

$$y_{t-1} = \frac{\alpha}{\beta} + \frac{1}{\beta} y_t - \frac{1}{\beta} \varepsilon_t$$

$$y_t = -\frac{\alpha}{\beta} + \frac{1}{\beta} y_{t-1} - \frac{1}{\beta} \varepsilon_{t-1}$$

$$y_t = -\frac{\alpha}{\beta} + \frac{1}{\beta} \left[ -\frac{\alpha}{\beta} + \frac{1}{\beta} y_{t-2} - \frac{1}{\beta} \varepsilon_{t-2} \right] - \frac{1}{\beta} \varepsilon_{t-1}$$

$$y_t = -\frac{\alpha}{\beta} \left[ 1 + \frac{1}{\beta} + \frac{1}{\beta^2} + \dots \right] + \frac{1}{\beta} y_{t-1} - \frac{1}{\beta} \left[ \varepsilon_{t-1} + \frac{1}{\beta} \varepsilon_{t-2} + \dots \right]$$

$$\beta > 1 \Rightarrow \frac{1}{\beta} < 1$$

$$y_t = \frac{-\frac{\alpha}{\beta}}{1 - \frac{1}{\beta}} - \frac{1}{\beta} \left[ \varepsilon_{t-1} + \frac{1}{\beta} \varepsilon_{t-2} + \dots \right]$$

$$y_t = \frac{\alpha}{1-\beta} - \frac{1}{\beta} \left[ \varepsilon_{t-1} + \frac{1}{\beta} \varepsilon_{t-2} + \dots \right]$$

$$E(y_t) = \frac{\alpha}{1-\beta}$$

$$\pi_t = \beta E_t \pi_{t+1} + \beta x_t$$

Current

$$\circ < \beta < 1$$

مقدمة في التحليل العشوائي والمتغيرات المدخلة

Predetermined and non-predetermined variables

$$n_t = \frac{\beta}{1+\beta} E_t n_{t+1} + \frac{1}{1+\beta} n_{t-1} + b_n$$

صل ساده اداری و مختص (RBC) می باشد

کارخانه (Factories):

۱) صرف نهاد (خانوار): سرمایه

۲) تأمینات: رزرو (امدادات)

Endowments ۳)

کارکردها ۴)

درودیم در صرف نهاد:

۱) کارخانه اجتماعی

۲) کارکنان، کارکنندگان

برآمدات

$$U = E \left[ \sum_{t=0}^{\infty} \beta^t \left( \frac{c_t^{1-\eta} - 1}{1-\eta} - \chi \frac{n_t^{1+\delta}}{1+\delta} \right) \right]$$

$\chi > 0$        $0 < \beta < 1$       سازمان دهنده

$$\beta = \frac{1}{1+f} \quad e^{\beta t}$$

تاخذ زمان و داشت

نیز سازمان دهنده

$$\eta > 0$$

$$\delta > 0 \quad \text{فرموده، مردمانه}$$

Frisch

سریده می شوند

$$C_t + I_t = w_t N_t + R_t K_{t-1}$$

$$Y_t = Z_t K_{t-1}^f N_t^{1-f}$$

$$f < 1$$

کارخانه های پیشگام

$$\frac{w}{w} M P_N + K M P_K = Y$$

$$w = M P_N, \quad R = M P_K$$

$$\begin{cases} C_t + I_t = Y_t = Z_t K_{t-1}^f N_t^{1-f} \\ K_t = (1-\delta) K_{t-1} + I_t \end{cases}$$

$$I_t = K_t - (1-\delta) K_{t-1}$$

$$C_t + K_t = Z_t K_{t-1}^f N_t^{1-f} + (1-\delta) K_{t-1}$$

$$C_t + K_t - K_{t-1} = \underbrace{Z_t}_{\Delta K_t} K_{t-1}^f N_t^{1-f} - \delta K_{t-1}$$

Technology Slack

TFP: Total Factor Productivity

$$\ln A_t = \ln A_0 + \ln \overline{Z}_t + \ln \overline{N}_t + \ln \overline{K}_t = \alpha + \beta \ln \overline{A}_t + \varepsilon_t$$

TFP: Total Factor Productivity

$$\log Z_t = (1-\psi) \log \bar{Z} + \psi \log Z_{t-1} + \varepsilon_t, \quad \varepsilon_t \sim i.i.d. N(0, \sigma^2)$$

$$Z_{t-1} = Z_t = E_t Z_{t+1} = \bar{Z}, \quad \bar{\varepsilon} = E(\varepsilon_t) = 0$$

$0 < \psi < 1$

$$\max_{C_t, N_t, K_t} \sum_{t=0}^{\infty} E_t^\beta \left[ \frac{C_t^{1-\eta} - 1}{1-\eta} \right]$$

s.t.

$$C_t + K_t = Z_t K_{t-1}^{\delta} N_t^{1-\delta} + (1-\delta) K_{t-1}, \quad N_t = 1$$

$$\log Z_t = (1-\psi) \log \bar{Z} + \psi \log Z_{t-1} + \varepsilon_t$$

$$K_{t-1} = Z_t$$

$$\varepsilon_t \sim i.i.d. N(0, \sigma^2)$$

$$L = E_t \sum_{t=0}^{\infty} \beta^t \left\{ \frac{C_t^{1-\eta} - 1}{1-\eta} + \lambda_t [Z_t K_{t-1}^{\delta} + (1-\delta) K_{t-1} - C_t - K_t] \right\}$$

$$\frac{\partial L}{\partial C_t} = \beta^t \{ C_t^{-\eta} - \lambda_t \} = 0 \quad (1) \quad \lambda_t = C_t^{-\eta}$$

$$\frac{\partial L}{\partial \lambda_t} = \beta \{ Z_t K_{t-1}^{\delta} + (1-\delta) K_{t-1} - C_t - K_t \} = 0 \quad (2)$$

$$\frac{\partial L}{\partial K_t} = -\beta^t \lambda_t + \beta^{t+1} E_t [\lambda_{t+1} (\delta Z_{t+1} K_t^{\delta-1} + (1-\delta))] = 0 \quad (3)$$

(1), (3)

$$C_t^{-\eta} = \beta E_t C_{t+1}^{-\eta} [\delta Z_{t+1} K_t^{\delta-1} + (1-\delta)]$$

$$(1) \quad \frac{C_t^{-\eta}}{\lambda_t} = 1$$

$$C_t^{-\eta} = \beta E_t C_{t+1}^{-\eta} [\delta Z_{t+1} K_t^{\delta-1} + (1-\delta)]$$

$$\frac{C_t^{-\eta}}{\beta E_t C_{t+1}^{-\eta}} = E_t [\delta Z_{t+1} K_t^{\delta-1} + (1-\delta)]$$

$$\frac{C_t^{-\eta}}{R_t - r_t} = [r_t + 1 - \delta]$$

$$\frac{C_t^{-\gamma}}{\beta E_t C_{t+1}^{-\gamma}} = \overbrace{[r_t + 1 - \delta]}^{\gamma}$$

$$r_t = E_t [\beta z_{t+1} k_t^{\delta-1}] + 1 - \delta$$

$$\left( \frac{C_t}{E_t C_{t+1}} \right)^{-\gamma} = \beta R_t$$

$$\frac{C_t}{E_t C_{t+1}} = (\beta R_t)^{-\frac{1}{\gamma}}$$

Epstein-Zin preference

$$\lim_{T \rightarrow \infty} E_T [\beta^T C_T^{-\gamma} K_T] = 0$$

Transversality condition

$$\textcircled{1} \quad 1 = E_t \left[ \beta \left( \frac{C_t}{C_{t+1}} \right)^\gamma R_{t+1} \right]$$

$$\textcircled{2} \quad C_t = Z_t K_{t-1}^{\delta} + (1-\delta) K_{t-1} - K_t$$

$$\textcircled{3} \quad R_t = \delta Z_t K_{t-1}^{\delta-1} + (1-\delta)$$

$$\textcircled{4} \quad \log Z_t = (1-\psi) \log \bar{Z} + \psi \log Z_{t-1} + \varepsilon_t$$

$$X_t = X_{t-1} = E_t X_{t+1} = \bar{X}$$

Steady State:

$$\textcircled{1} \quad 1 = \beta \left( \frac{\bar{C}}{\bar{Z}} \right)^\gamma \bar{R} \Rightarrow \bar{R} = \frac{1}{\beta}$$

$$\textcircled{2} \quad \bar{C} = \bar{Z} \bar{K}^{\delta} + (1-\delta) \bar{K} - \bar{K}$$

$$\textcircled{3} \quad \bar{R} = \delta \bar{Z} \bar{K}^{\delta-1} + (1-\delta)$$

$$\textcircled{4} \quad \bar{Z} = 1$$

مقدار  $\bar{Z}$  را از علائم زیر محاسبه می کنیم

$$\textcircled{1} \quad \bar{Z} = 1$$

$$\beta = \frac{1}{1+\delta} = \frac{1}{1+\gamma}$$

$$r = \delta$$

$$(2) \quad \bar{R} = \frac{1}{\beta}$$

$$(3) \quad \bar{k} = \left( \frac{\delta \bar{z}}{\bar{R} - 1 + \delta} \right)^{\frac{1}{1-\delta}}$$

$$(4) \quad \bar{y} = \bar{z} \bar{k}^{\delta}$$

$$(5) \quad \bar{c} = \bar{y} - \delta \bar{k} \Rightarrow \bar{y} = \bar{c} + \delta \bar{k}$$

The competitive Equilibrium:

$$\max_{C_t, K_t} E \left[ \sum_{t=0}^{\infty} \beta^t \frac{C_t^{1-\eta} - 1}{1-\eta} \right]$$

s.t.

$$C_t + I_t = w_t N_t^s + r_t K_t^s$$

$$N_t^s = 1$$

$$K_t^s = (1-\delta) K_{t-1}^s + I_t$$

$$\max_{N_t, K_{t-1}} \Pi_t = Z_t K_{t-1}^{\delta} N_t^{1-\delta} - w_t N_t^d - r_t K_{t-1}^d$$

$$N_t^s = N_t^d = N_t = 1$$

$$K_t^s = K_{t-1}^d = K_{t-1}$$

$$\checkmark C_t + K_t = Z_t K_{t-1}^{\delta} + (1-\delta) K_{t-1}$$

$$\begin{cases} Y_t = C_t + I_t \\ Y_t = Z_t K_{t-1}^{\delta} \\ K_t = (1-\delta) K_{t-1} + I_t \end{cases}$$

$$\frac{\partial \Pi_t}{\partial N_t} = (1-\delta) Z_t K_{t-1}^{\delta} N_t^{1-\delta} - w_t = 0$$

$$\frac{\partial \Pi_t}{\partial K_{t-1}} = \delta Z_t K_{t-1}^{\delta-1} N_t^{1-\delta} - r_t = 0$$

$$w_t = M_P N_t^{\frac{(1-\delta)Y_t}{N_t}} = (1-\delta) \frac{Z_t K_{t-1}^{\delta} N_t^{1-\delta}}{N_t}$$

$$r_t = M_A K_t = \delta \frac{Y_t}{N_t} = \delta \frac{Z_t K_{t-1}^{\delta} N_t^{1-\delta}}{N_t}$$

$$r_t = MPA_{K_t} = \beta \frac{y_t}{K_{t+1}} = \beta \frac{z_t K_{t-1}^{\alpha} N_t^{1-\alpha}}{K_{t+1}}$$

$$\textcircled{1} \frac{\partial L}{\partial \lambda_t} = w_t + r_t K_{t-1} + (1-\delta) - c_t - k_t = 0$$

$$\textcircled{2} \frac{\partial L}{\partial c_t} = \bar{c}_t^{\beta} - \lambda_t = 0$$

$$\textcircled{3} \frac{\partial L}{\partial K_t} = -\lambda_t + \beta E_t \lambda_{t+1} [r_t + (1-\delta)] = 0$$

$R_{t+1}$

$$X_t = A X_{t-1} + \varepsilon_t$$

$$\dot{x}_t = \frac{X_t - X_{t-1}}{X_{t-1}}$$

$$\dot{x}_t \approx \ln X_t - \ln X_{t-1} = \ln \frac{X_t}{X_{t-1}}$$

لهم - حفظكم الله من كل خراب

$$X_t = X_{t-1} = E_t X_{t+1} = \bar{X}$$

$$\textcircled{1} \hat{x}_t = \ln X_t - \ln \bar{X}$$

$$\hat{x}_t = \ln \frac{X_t}{X_{t-1}}$$

$$\hat{x}_t = \frac{X_t - \bar{X}}{\bar{X}} = \frac{X_t}{\bar{X}} - 1 = \hat{x}_t$$

$$\frac{X_t}{\bar{X}} = 1 + \hat{x}_t$$

$$\textcircled{2} \left. \begin{array}{l} X_t = \bar{X} (1 + \hat{x}_t) \\ Y_t = \bar{Y} (1 + \hat{y}_t) \end{array} \right\} \hat{x}_t \hat{y}_t \approx 0$$

$$\textcircled{1} \hat{x}_t = \ln \frac{X_t}{\bar{X}} \Rightarrow \frac{X_t}{\bar{X}} = e^{\hat{x}_t}$$

$$\textcircled{3} X_t = \bar{X} e^{\hat{x}_t}$$

$$Y_t = Z_t K_{t-1}^{\alpha} N_t^{1-\alpha}$$

$$\bar{Y} = \bar{Z} \bar{K}^{\alpha} \bar{N}^{1-\alpha}$$

$$\ln Y_t = \ln Z_t + \alpha \ln K_{t-1} + (1-\alpha) \ln N_t$$

$$\ln \bar{Y} = \ln \bar{Z} + \alpha \ln \bar{K} + (1-\alpha) \ln \bar{N}$$

$$\text{L.H.S.} \quad \ln \bar{Y} - \ln Z_t \quad \ln \bar{Y} + \alpha (\ln K_t - \ln \bar{K}) + (1-\alpha)$$

$$\ln \bar{Y} = \ln \bar{Z} + \alpha \ln \bar{K} + (1-\alpha) \ln \bar{N}$$

$$\ln Y_t - \ln \bar{Y} = (\ln Z_t - \ln \bar{Z}) + \alpha (\ln K_{t-1} - \ln \bar{K}) + (1-\alpha) (\ln N_t - \ln \bar{N})$$

$$\hat{\delta}_t = \hat{z}_t + \alpha \hat{k}_{t-1} + (1-\alpha) \hat{n}_t$$

$$Y_t = C_t + I_t$$

$$\bar{Y} = \bar{C} + \bar{I} \Rightarrow \frac{\bar{C}}{\bar{Y}} + \frac{\bar{I}}{\bar{Y}} = 1$$

$$\bar{Y}(1+\hat{\delta}_t) = \bar{C}(1+\hat{c}_t) + \bar{I}(1+\hat{i}_t)$$
~~$$\bar{Y} - \bar{Y} \hat{\delta}_t = \bar{C} - \bar{C} \hat{c}_t + \bar{I} - \bar{I} \hat{i}_t$$~~

$$\hat{\delta}_t = \frac{\bar{C}}{\bar{Y}} \hat{c}_t + \frac{\bar{I}}{\bar{Y}} \hat{i}_t$$

$$Y_t = a + X_t , \quad \bar{Y} = a + \bar{X}$$

$$\bar{Y}(1+\hat{\delta}_t) = a + \bar{X}(1+\hat{x}_t)$$

~~$$\bar{Y} + \bar{Y} \hat{\delta}_t = a + \bar{X} + \bar{X} \hat{x}_t$$~~

$$\bar{Y} \hat{\delta}_t = \bar{X} \hat{x}_t$$

$$\hat{\delta}_t = \frac{\bar{X}}{\bar{Y}} \hat{x}_t$$

$$X_t + a = (1-b) \frac{Y_t}{Z_t}$$

$$\bar{X} + a = (1-b) \frac{\bar{Y}}{\bar{Z}}$$

$$\ln(X_t + a) = \ln(1-b) + \ln Y_t - \ln Z_t$$

$$\widehat{(X_t + a)} = \hat{\delta}_t - \hat{z}_t$$

$$\widehat{X_t + a} = \frac{X_t + a - (\bar{X} + a)}{\bar{X} + a} = \frac{X_t - \bar{X}}{\bar{X} + a} \times \frac{\bar{X}}{\bar{X}}$$

$$\widehat{X_t + a} = \frac{\bar{X}}{\bar{X} + a} \left( \frac{X_t - \bar{X}}{\bar{X}} \right) = \frac{\bar{X}}{\bar{X} + a} \hat{x}_t = \hat{\delta}_t - \hat{z}_t$$

$$\textcircled{1} \quad 1 = \beta E_t \left( \frac{C_{t+1}}{C_t} \right)^{-\eta} R_{t+1}$$

$$1 = \beta \left( \frac{\bar{C}}{C} \right)^{-\eta} \bar{R}$$

$$a = \gamma [c_t - E_t c_{t+1}] + \hat{r}_{t+1}$$

$$\textcircled{2} \quad c_t = \bar{z}_t \underbrace{k_{t-1}^f}_{Y_t^f} + (1-\delta) k_{t-1} - k_t$$

$$Y_t = \bar{z}_t k_{t-1}^f$$

$$\bar{k}_{t-1} = l_n k_{t-1} - l_n \bar{k}$$

$$\hat{y}_t = \hat{z}_t + f \hat{k}_{t-1}$$

$$\bar{c} = \bar{Y} + (1-\delta) \bar{k} - \bar{k}$$

$$\bar{c} (1 - \hat{c}_t) = \bar{Y} (1 - \hat{y}_t) + (1-\delta) \bar{k} (1 - \hat{k}_{t-1}) - \bar{k} (1 - \hat{k}_t)$$

$$\hat{c}_t = \frac{\bar{Y}}{\bar{c}} \hat{y}_t + \frac{(1-\delta) \bar{k}}{\bar{c}} \hat{k}_{t-1} - \frac{\bar{k}}{\bar{c}} \hat{k}_t$$

$$\hat{z}_t = \frac{\bar{Y}}{\bar{c}} (\hat{z}_t + f \hat{k}_{t-1}) - \frac{(1-\delta) \bar{k}}{\bar{c}} \hat{k}_{t-1} - \frac{\bar{k}}{\bar{c}} \hat{k}_t$$

$$\textcircled{3} \quad R_t = f \bar{z}_t k_{t-1}^{f-1} + (1-\delta)$$

$$\bar{R} (1 - \hat{r}_t) = f \bar{z} \bar{k}^{f-1} (1 - \hat{z}_t + (f-1) \hat{k}_{t-1}) + (1-\delta)$$

$$\bar{R} \hat{r}_t = f \bar{z} \bar{k}^{f-1} (\hat{z}_t + (f-1) \hat{k}_{t-1})$$

$$\hat{r}_t = \frac{f \bar{z} \bar{k}^{f-1}}{\bar{R}} (\hat{z}_t + (f-1) \hat{k}_{t-1})$$

$$\hat{r}_t = (1 - \beta (1 - \delta)) (\hat{z}_t - (1 - \delta) \hat{k}_{t-1})$$

$$\textcircled{4} \quad \hat{z}_t = \psi \hat{z}_{t-1} + \varepsilon_t$$

$$\textcircled{1} \quad a = E_t \left[ \gamma (\hat{c}_t - \hat{c}_{t+1}) + \hat{r}_{t+1} \right]$$

$$\textcircled{2} \quad \hat{c}_t = \frac{\bar{Y}}{\bar{c}} \hat{z}_t + \frac{\bar{k}}{\beta \bar{c}} \hat{k}_{t-1} - \frac{\bar{k}}{\bar{c}} \hat{k}_t$$

$$\textcircled{3} \quad \hat{r}_t = (1 - \beta (1 - \delta)) (\hat{z}_t - (1 - \delta) \hat{k}_{t-1})$$

$$\textcircled{4} \quad \hat{z}_t = \psi \hat{z}_{t-1} + \varepsilon_t$$

حل سیم عادت بررسی متابنی

$$\hat{k}_t = v_{kk} \hat{k}_{t-1} + v_{kz} \hat{z}_t$$

$$\hat{r}_t = v_{rk} \hat{k}_{t-1} + v_{rz} \hat{z}_t$$

$$\hat{c}_t = v_{ck} \hat{k}_{t-1} + v_{cz} \hat{z}_t$$

$$E \hat{z}_{t+1} = \psi \hat{z}_t$$

$$\textcircled{2} \quad \hat{c}_t = (1 + \delta) \frac{\bar{k}}{C} \hat{z}_t + \frac{\bar{k}}{\beta C} \hat{k}_{t+1} - \frac{\bar{k}}{C} \hat{k}_t$$

$$\hat{c}_t = v_{ck} \hat{k}_{t+1} + v_{cz} \hat{z}_t = (1 + \delta) \frac{\bar{k}}{C} \hat{z}_t + \frac{\bar{k}}{\beta C} \hat{k}_{t+1} - \frac{\bar{k}}{C} (v_{kk} \hat{k}_t + v_{cz} \hat{z}_t)$$

$$v_{cz} = \frac{\bar{Y}}{C} - \frac{\bar{k}}{C} v_{kz}$$

$$v_{ck} = (\frac{1}{\beta} - v_{kk}) v_{kz}$$

$$\textcircled{3} \quad \hat{r}_t = (1 - \beta(1 - \delta))(\hat{z}_t - (1 - \gamma) \hat{k}_{t+1}) = v_{rk} \hat{k}_{t+1} + v_{rz} \hat{z}_t$$

$$v_{rk} = - (1 - \gamma) (1 - \beta(1 - \delta))$$

$$v_{rz} = 1 - \beta(1 - \delta)$$

$$\textcircled{1} \quad \eta = E_t [\eta (\hat{c}_t - \hat{c}_{t+1}) + \hat{r}_{t+1}]$$

$$= E_t [1 (v_{ck} \hat{k}_{t+1} + v_{cz} \hat{z}_t) - (v_{ck} \hat{k}_t + v_{cz} \hat{z}_{t+1}) + (v_{rk} \hat{k}_t + v_{rz} \hat{z}_{t+1})]$$

$$= (v_{rk} - \eta v_{ck}) \hat{k}_t + \eta v_{ck} \hat{k}_{t+1} + ((v_{rz} - \eta v_{cz}) \psi + v_{cz}) \hat{z}_t$$

$$= ((v_{rk} - \eta v_{ck}) v_{kk} + \eta v_{ck}) \hat{k}_{t+1}$$

$$+ ((v_{rk} - \eta v_{ck}) v_{kz} + (v_{rz} - \eta v_{cz}) \psi + \eta v_{cz}) \hat{z}_t$$

$$(v_{rk} - \eta v_{ck}) v_{kk} + \eta v_{ck} = 0$$

$$((v_{rk} - \eta v_{ck}) v_{kz} + (v_{rz} - \eta v_{cz}) \psi + \eta v_{cz}) = 0$$

$$= (- (1 - \beta(1 - \delta)) (1 - \gamma) - \eta (\frac{1}{\beta} - v_{kk}) \frac{\bar{k}}{C} v_{kk} + \eta (\frac{1}{\beta} - v_{kk}) \frac{\bar{k}}{C})$$

$$= v_{kk}^2 - \gamma v_{kk} + \frac{1}{\beta}$$

$$\gamma = (1 - \beta(1 - \delta)) (1 - \gamma) \frac{\bar{C}}{g_k} + 1 + \frac{1}{\beta}$$

$$v_{kk} = \frac{\gamma}{2} - \sqrt{\left(\frac{\gamma}{2}\right)^2 - \frac{1}{\beta}}$$

$$y_t = \alpha + f y_{t-1} + \varepsilon_t$$

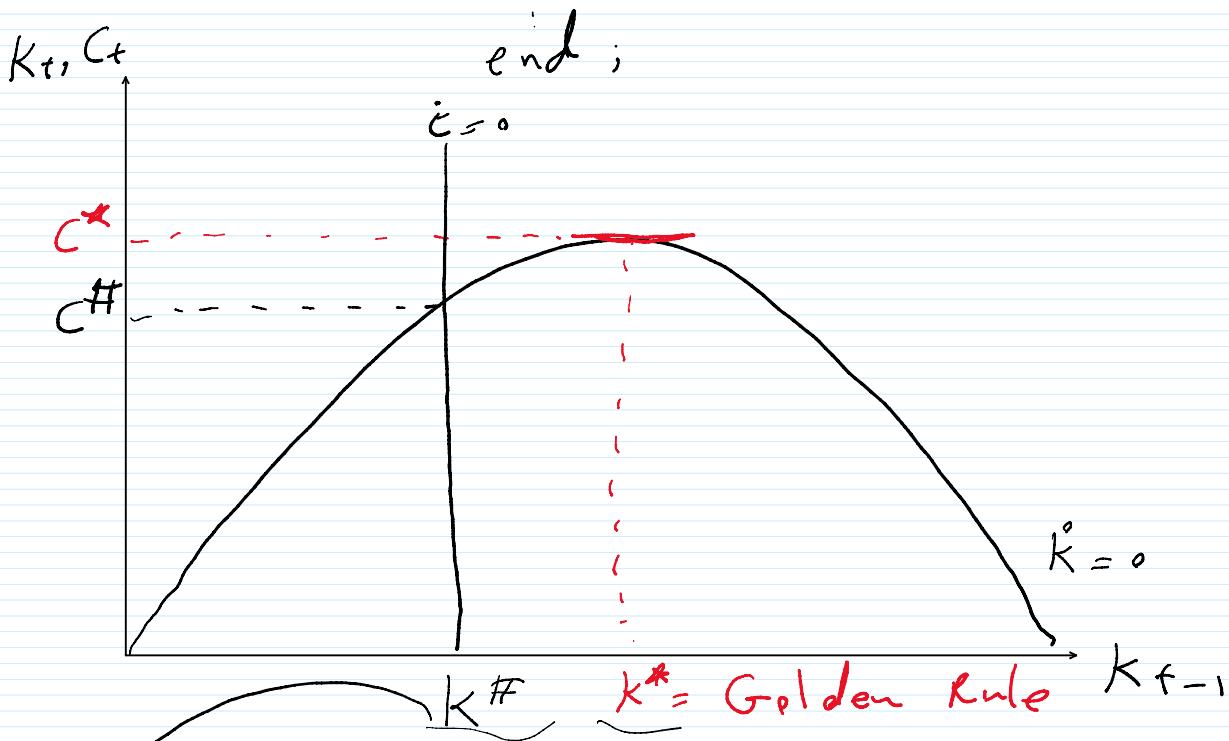
$$\hat{k}_t = \nu_{kk} \hat{k}_{t-1} + \nu_{kz} \frac{1}{2} t$$

$$C_t - h C_{t-1} \leq k_t$$

Dynare:

new in

Var       $\dot{C}_{t+1}$   
 varexo       $\dot{\nu}_{kk}$   
 parameters       $\nu_{kz}$   
 model(linear);



$$\frac{1}{1+f} = \beta = \frac{1}{R} = \frac{1}{1+\bar{r}}$$

$\bar{r} = f \rightarrow$  Deep Parameter

$$f > 0 \Rightarrow \bar{r} > 0$$

$$f > 0 \Rightarrow \bar{f} > 0$$

$$f = 0 \Rightarrow \bar{f} = 0$$

Exogenous nominal Rigidity:

Fixed prices:

$$Y = F(L), F'(\cdot) > 0, F''(\cdot) \leq 0$$

$$\checkmark Y = C$$

$$U = \sum_{t=0}^{\infty} \beta^t \left[ U(C_t) + \Gamma \left( \frac{M_t}{P_t} \right) - v(L_t) \right]$$

$\underbrace{U_t}_{\text{Utility}}$        $\underbrace{\Gamma \left( \frac{M_t}{P_t} \right)}_{\text{Real Money Balance}}$

Real Money Balance:  $\Gamma: \text{decreasing}$

$$c < \beta < 1$$

Search & Match

$$U(C_t) = \frac{C_t^{1-\theta}}{1-\theta}, \theta > 0$$

$$\Gamma \left( \frac{M_t}{P_t} \right) = \frac{\left( \frac{M_t}{P_t} \right)^{1-\chi}}{1-\chi}, \chi > 0$$

$$+ B_t + M_t = W_t L_t + (1 + i_{t-1}) B_{t-1} + M_{t-1}$$

$$\left( \frac{B_t}{P_t} \right) + \frac{M_t}{P_t} = \left( \frac{W_t}{P_t} \right) L_t + (1 + i_{t-1}) \frac{B_{t-1}}{P_t} + \frac{M_{t-1}}{P_t}$$

$$U = \sum_{t=0}^{\infty} \beta^t \left[ \frac{C_t^{1-\theta}}{1-\theta} + \frac{\left( \frac{M_t}{P_t} \right)^{1-\chi}}{1-\chi} - v(L_t) \right]$$

$$v = \sum_{t=0}^{\infty} \beta^t \left[ \frac{1-\theta}{1-\theta} + \frac{\gamma}{1-\chi} - v(L_t) \right]$$

$$c_t + m_t = w_t L_t + (1+i_{t-1}) \frac{b_{t-1}}{1+\pi_t} + \frac{m_{t-1}}{1+\pi_t}, \quad w_t = \frac{w_t}{P_t}$$

$$\frac{B_t}{P_t}, \quad \frac{B_{t-1}}{P_t} = \frac{B_{t-1}}{P_{t-1}} \cdot \frac{P_{t-1}}{P_t} = \frac{b_{t-1}}{P_t/P_{t-1}} = \frac{b_{t-1}}{1+\pi_t}$$

$$= \frac{P_t - P_{t-1}}{P_{t-1}} = \frac{P_t}{P_{t-1}} - 1 \Rightarrow \frac{P_t}{P_{t-1}} = 1 + \pi_t$$

$$\sum_{t=0}^{\infty} \beta^t \left[ \frac{c_t^{1-\theta}}{1-\theta} + \frac{m_t^{1-\chi}}{1-\chi} - v(L_t) + \lambda_t \left( w_t L_t + \frac{m_{t-1}}{1+\pi_t} \right. \right.$$

$$\left. \left. + i_{t-1} \right) b_{t-1} - c_t - b_t - m_t \right]$$

$$= c_t^{-\theta} - \lambda_t = 0$$

$$= m_t^{-\chi} - \lambda_t + \beta E_t \frac{\lambda_{t+1}}{1+\pi_{t+1}} = 0$$

$$= v'(L) - w_t \lambda_t = 0$$

$$= -\lambda_t + \beta E_t \frac{(1+i_t) \lambda_{t+1}}{1+\pi_{t+1}} = 0$$

max

s.t.

$$C_t + k$$

$$b_t =$$

$$n_t =$$

$$L = \sum_i$$

$$+ \frac{C(1+r)}{1+r}$$

$$\textcircled{1} \quad \frac{\partial L}{\partial C_t}$$

$$\textcircled{2} \quad \frac{\partial L}{\partial n_t}$$

$$\textcircled{3} \quad \frac{\partial L}{\partial L_t}$$

$$\textcircled{4} \quad \frac{\partial L}{\partial b_t}$$

$$\textcircled{5} \quad -1$$

$$1 \rightarrow 1' \in \mathcal{L}_{t+1}$$

$$\frac{\sqrt{(L)}}{C_t^{-\theta}} = \omega_t$$

$\epsilon^1$  nope

$$\beta E_t \frac{\lambda_{t+1}}{1 + \pi_{t+1}} = \frac{\lambda_t}{1 + i_t}$$

$$m_t^{-\lambda} = \lambda_t - \frac{\lambda_t}{1 + i_t} = \frac{i_t}{1 + i_t} C_t^{-\theta}$$

$$\frac{m_t^{-\lambda}}{C_t^{-\theta}} = \frac{i_t}{1 + i_t} \Rightarrow m_t^{-\lambda} = \frac{i_t}{1 + i_t} C_t^{-\theta} \quad \text{JGCGW}$$

$$C_t^{-\theta} = \beta E_t \underbrace{\frac{(1 + i_t)}{1 + \pi_{t+1}}}_{1 + r_{t+1}} C_{t+1}^{-\theta} \Rightarrow \text{JGCGW}$$

$$\approx 0.01$$

$$+ r_{t+1} = E_t \frac{1 + i_t}{1 + \pi_{t+1}} \quad \text{Fisher Eq.}$$



$$E_t r_{t+1} + E_t \pi_{t+1} = 1 + i_t$$

$$E_t r_{t+1} + E_t \pi_{t+1} + E_t r_{t+1} E_t \pi_{t+1} = 1 + i_t$$

$$r_{t+1} = i_t - E_t \pi_{t+1} + E_t r_{t+1} E_t \pi_{t+1}$$

$$\frac{\partial b_t}{\partial \lambda_t}$$

①, ③

④

①, ②, ④

①, ④

(1 +  $\epsilon$ )

1 +

$E_t$

$$\begin{aligned} Y &= C \\ Y &= C + S \\ S &= 0 \end{aligned}$$

$$Y_t = C_t$$

$$Y_t^{-\theta} = \beta \cdot E_t \left( \frac{(1+i_t)}{1+\pi_{t+1}} \right) Y_{t+1}^{-\theta}$$

New Keynesian IS

$$\bar{m}_t^{-\alpha} = \frac{i_t}{1+i_t} Y_t^{-\theta}$$

$$M_t = \frac{\bar{M}_t}{P_t} \quad M_t \approx 0$$

$$m_t^S = \frac{\bar{M}_t^S}{P_t} \quad M_t^S \approx 0$$

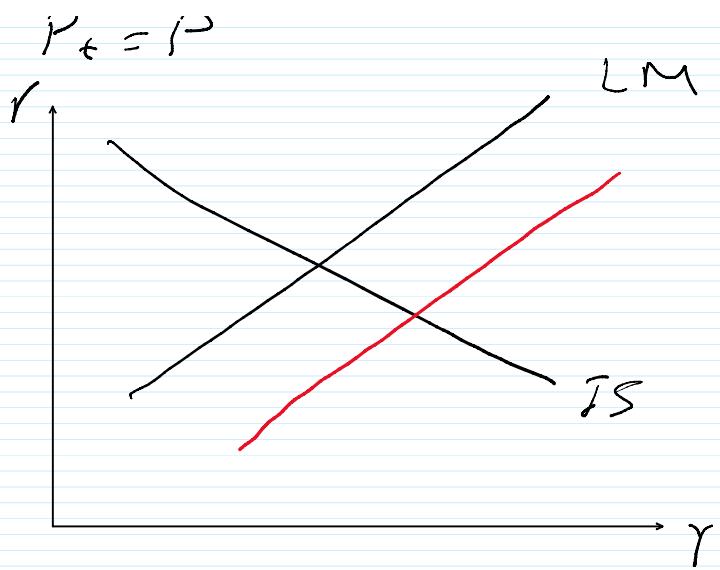
$$\bar{m}_t^S = m_t^d = \bar{m}_t$$

$$\bar{m}_t^{-\alpha} = \left( \frac{i_t}{1+i_t} \right) Y_t^{-\theta} \quad LM$$

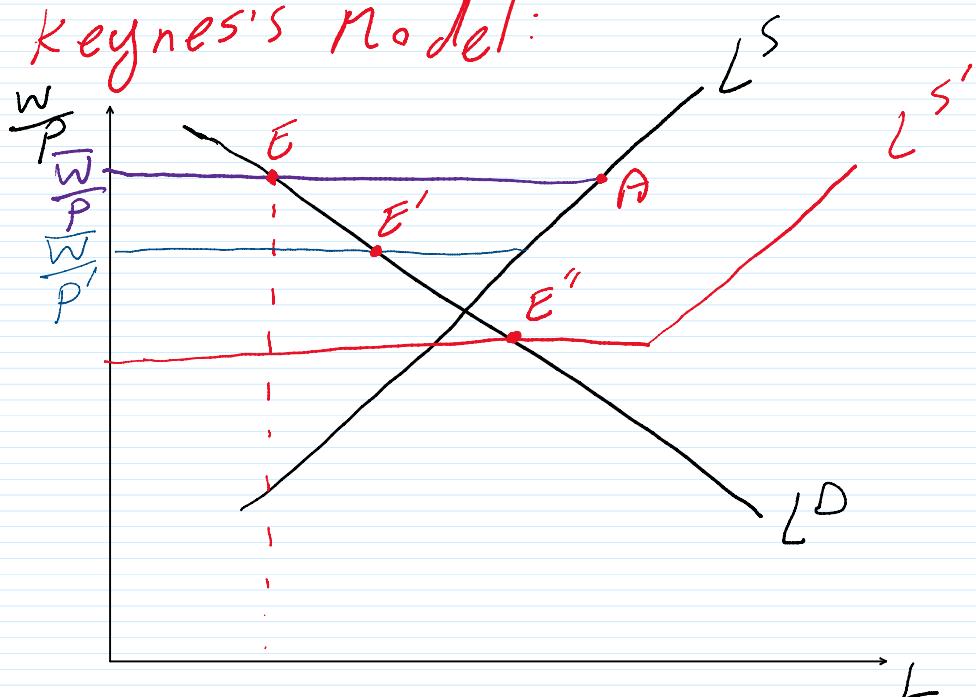
$$\Rightarrow \ln Y_t = \alpha + \ln E_t Y_{t+1} - \frac{1}{\theta} r \quad IS$$

$$\alpha = -\left(\frac{1}{\theta}\right) \ln \beta$$

$$P_t = \bar{P} \quad , \quad LM$$



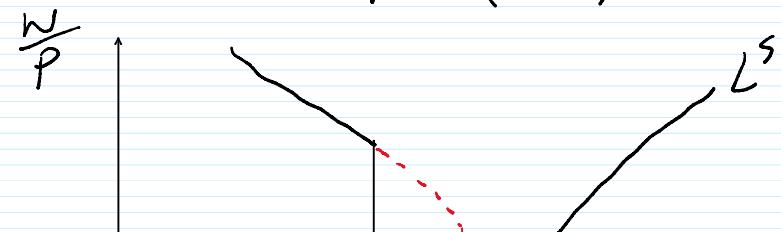
2: Keynes's Model:



$$L = L^s\left(\frac{w}{P}\right) \quad L^s'(.) > 0$$

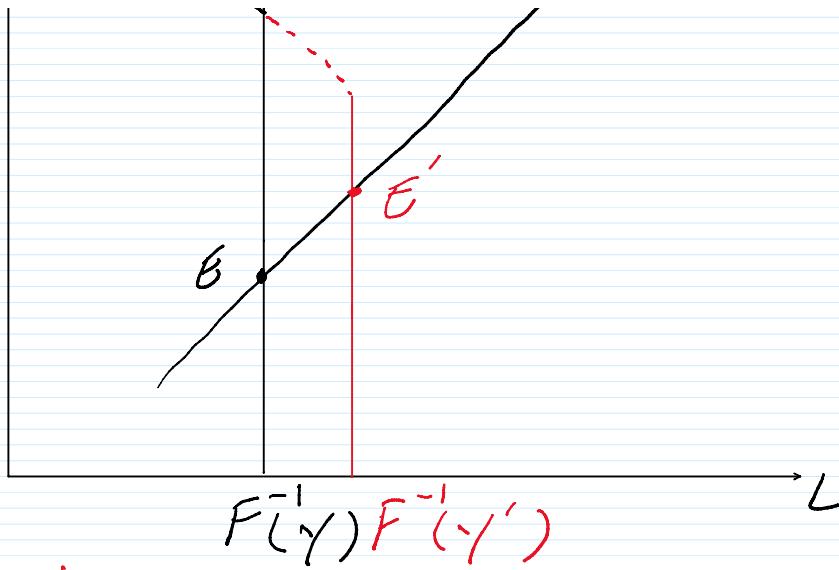
$$Y = F(L)$$

$$L = F^{-1}(Y)$$



Case 2

$$P' > P$$



sticky prices, flexible wages and Real  
Market imperfections:

$$\underbrace{U_t - E_t R_{t+1}}_{\text{GDP gap}} = f(U_t - \bar{U})$$

↓  
GDP gap

NAIRU

non-accelerating Inflation Rate of Unemployment

$$R_t - E_t R_{t+1} = g(Y_t - Y^P)$$

↓  
Wage gap

wage function

case 3:

Labor

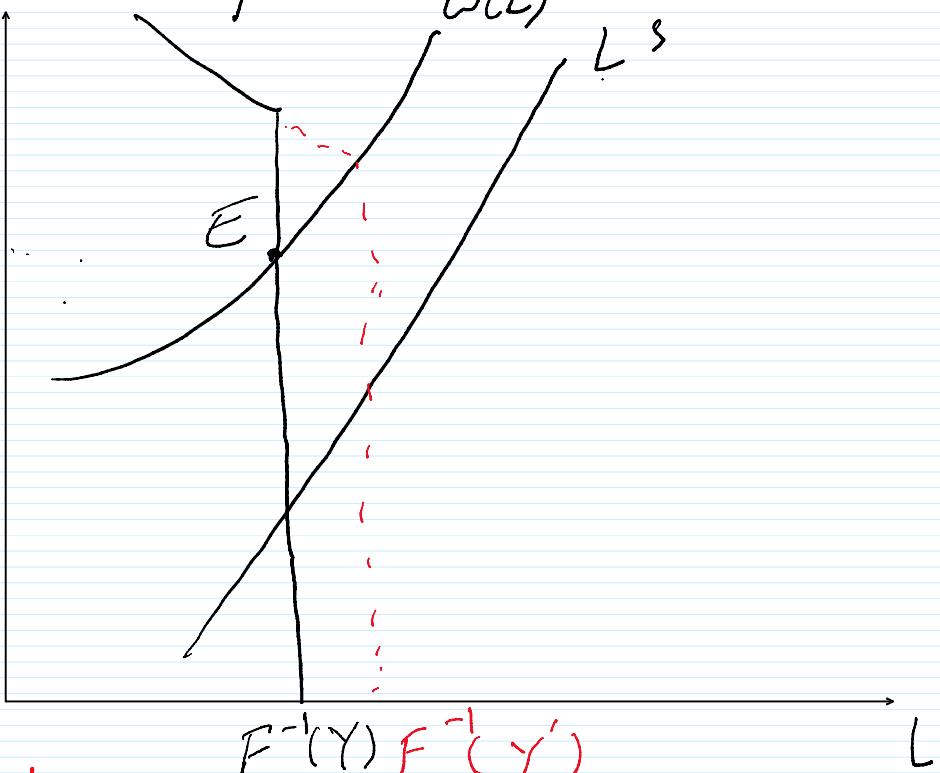
1

N

Efficiency

real-way

$$\frac{w}{P} = \omega(L) \quad \omega'(\cdot) > 0$$



Sticky Wage, Flexible Prices, and Competition:

$$P = MC$$

$$R = P(1 + \eta)$$

$$= \frac{1}{1+\eta} MC$$

$$- \frac{1}{1+\eta} > 1 \quad \text{markup}$$

real-way

$\frac{w}{P}$

Case 4: St.  
Imperfect

MR =

MC = M.

P:

$\eta <$

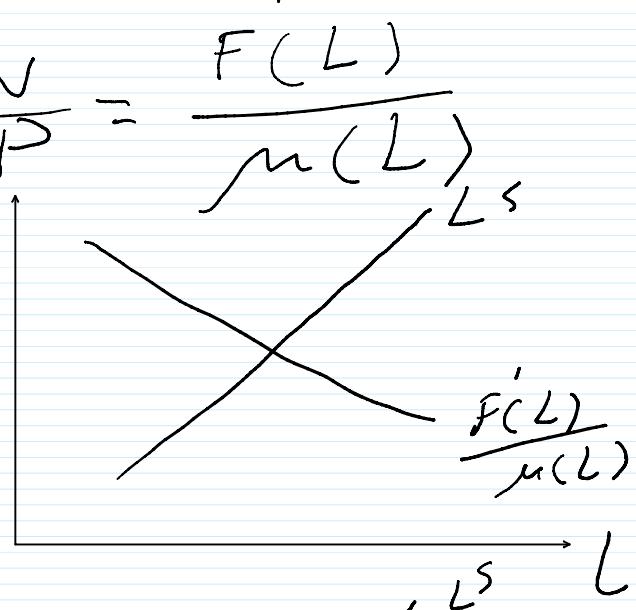
$$= \frac{1}{1 + \eta} > 1 \quad \text{markup}$$

$$\frac{Y}{L} = w$$

$$MP_L = \textcircled{w}$$

$$= \frac{w}{\frac{\partial Y}{\partial L}} = MC = \frac{\underbrace{w}_{MP_L}}{F'(L)}$$

$$D = \mu(L) \frac{w}{F'(L)}$$



h

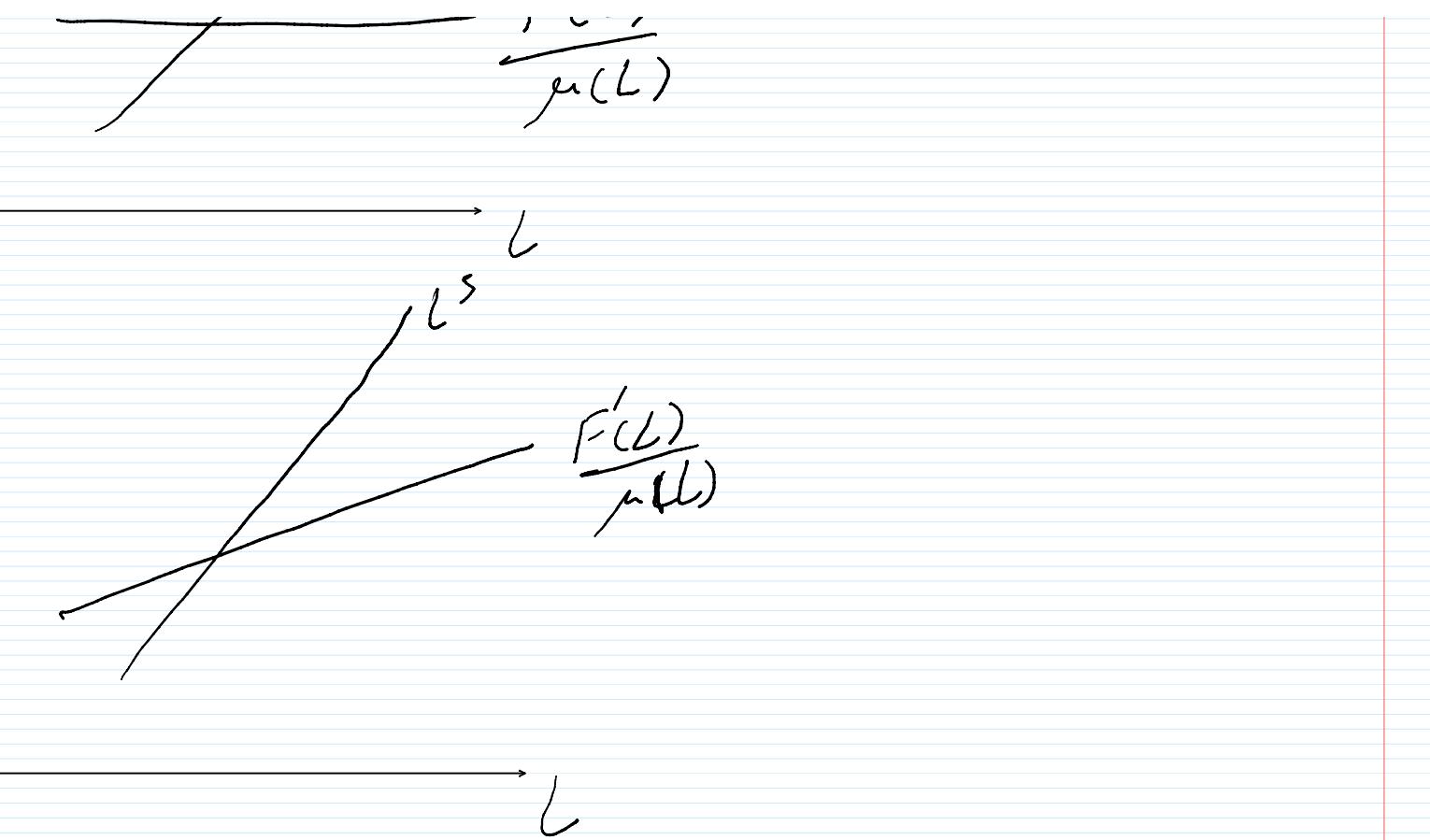
P<sub>2</sub>  
P<sub>1</sub>

P

J

w  
p

w  
p



$$E_t \pi_{t+1} = f(y_t - \bar{y})$$

$$\pi_t - \pi_{t-1} = f(\underbrace{y_t - \bar{y}}_{y_t}) = \lambda y_t \quad \text{IS. NKPC}$$

$$E_t \pi_{t+1} + \frac{1}{1+\phi} \pi_{t-1} + \lambda y_t$$

$r_t = b y_t$        $b > 0$ .      Taylor Rule

-      1      ,      ,  $F^S$        $\sigma$  -

$\frac{w}{p}$

$n_t -$

$n_t -$

$n$

$$n_t = \frac{\phi}{1 + \phi} \quad \{$$

$$r_t = E_t y_{t+1} - \frac{1}{\theta} r_t + u_t^{IS} \quad \theta > 0$$

$$x_t^{IS} = f_{IS} u_{t-1}^{IS} + e_t^{IS} \quad -1 < f_{IS} < 1$$

$$r_t = r_{t-1} + \lambda y_t$$

$$- \frac{1}{\theta} b y_t + u_t^{IS}$$

$$\frac{\theta}{\theta+b} E_t y_{t+1} + \underbrace{\frac{\theta}{\theta+b} u_t^{IS}}_{\phi}$$

$$E_t y_{t+1} + \phi u_t^{IS}$$

$$\frac{1}{\phi \beta^{IS}} u_t^{IS} + \lim_{S \rightarrow \infty} E_t y_{t+S}$$

y

l

r

$$y_t = E_t y_{t+1}$$

$$\left( \frac{\theta + b}{\theta} \right) y_t =$$

$$y_t = \frac{\phi}{\theta}$$

$$y_t = \phi$$

$$y_t = \frac{\phi}{1 -$$

$$\frac{b - \theta f_{IS}}{1 + \lambda \theta} u_t^{IS}$$

$$y_t + \frac{\lambda \theta}{\theta + b - \theta f_{IS}} u_t^{IS}$$



$$= E_t y_{t+1} - \frac{1}{\theta} (i_t - E_t \pi_{t+1}) + u_t^{IS}$$

$$= b_y y_t + b_\pi \pi_t + u_t^i$$

$$y_t = \frac{\theta}{\theta + e^{-x_t}}$$

$$\pi_t = \pi_t$$



$y_t$ :

$i_t$ :