

$$\mathcal{L} = B \int_{t=0}^{\infty} e^{-\beta t} \frac{c(t)}{1-\theta} dt + \lambda \left[k(n) + \int_{t=0}^{\infty} e^{-R(t)} w(t) e^{(n+g)t} dt - \int_{t=0}^{\infty} e^{-R(t)} \frac{(n+g)t}{c(t)\theta} dt \right]$$

$$B e^{-\beta t} \frac{1-\theta}{c(t)} - \lambda e^{-R(t)} e^{(n+g)t} = 0$$

$$\mathcal{L} = u(x, y) + \lambda(I - P_x n - P_y y)$$

$$u'_x - \lambda P_x = 0 \Rightarrow u_x = \lambda P_x \quad \frac{u'_x}{u_x} = \frac{P_x}{P_y}$$

$$u'_y - \lambda P_y = 0 \Rightarrow u_y = \lambda P_y$$

$$B e^{-\beta t} \frac{1-\theta}{c(t)} = \lambda e^{-R(t) + (n+g)t} \int_{t=0}^t r(\tau) d\tau$$

$$\ln B - \beta t - \theta \ln c(t) = \ln \lambda - R(t) + (n+g)t$$

$$-\beta - \theta \frac{\dot{c}(t)}{c(t)} = -r(t) + (n+g)$$

$$\frac{\dot{c}(t)}{c(t)} = \frac{r(t) - n - g - \beta}{\theta}$$

$$\beta = f - (L\theta)g - n$$

$$\frac{\dot{c}(t)}{c(t)} = \frac{r(t) - f - \theta g}{\theta} = \frac{r(t) - f}{\theta} - g$$

$$\text{since } \frac{\dot{c}(t)}{c(t)} = \frac{r(t) - f - \theta g}{\theta} = \frac{r(t) - f}{\theta} - g$$

$$\text{so } \frac{\dot{c}(t)}{c(t)} = \frac{\dot{A}(t)}{A(t)} + \frac{\dot{c}(t)}{c(t)} = \frac{r(t) - f}{\theta} = 0$$

$$\bar{c} = c_t = c_{t+1} \quad \text{Steady State}$$

$$r = f$$

$$B e^{-\beta t} \frac{1-\theta}{c(t)} \Delta c \quad \begin{array}{l} \text{جذب} \\ \text{ـ} \\ \Delta c \text{ از} \end{array}$$

$$B e^{-\beta(t+\Delta t)} \frac{1-\theta}{c(t+\Delta t)} \Delta c$$

$$c(t+\Delta t) = c(t) e^{\frac{\dot{c}(t)}{c(t)} \Delta t}$$

$$C(t + \Delta t) = C(t) e^{\frac{\dot{C}(t)}{C(t)} \Delta t}$$

$$\beta e^{-\beta(t + \Delta t)} C(t)^{-\theta} e^{-\frac{\dot{C}(t)}{C(t)} \theta \Delta t} \Delta C e^{(r(t) - n - g) \Delta t}$$

$$\beta e^{\cancel{\beta t}} \cancel{C(t)^{-\theta}} \Delta C = \beta e^{-\cancel{\beta(t + \Delta t)}} \cancel{C(t)^{-\theta}} e^{-\frac{\dot{C}(t)}{C(t)} \theta \Delta t} \cancel{\Delta C} e^{(r(t) - n - g) \Delta t}$$

$$1 = e^{-\beta \Delta t} e^{-\frac{\dot{C}(t)}{C(t)} \theta \Delta t} e^{(r(t) - n - g) \Delta t}$$

: ~~$\frac{\dot{C}(t)}{C(t)}$~~ \ln ~~variable~~

$$\circ = -\beta \cancel{\Delta t} - \frac{\dot{C}(t)}{C(t)} \theta \cancel{\Delta t} + (r(t) - n - g) \cancel{\Delta t}$$

$$\theta \frac{\dot{C}(t)}{C(t)} = r(t) - n - g - \beta$$

$$\frac{\dot{C}(t)}{C(t)} = \frac{r(t) - f - \theta g}{\theta}$$



State Variable

~~variable~~

$$\dot{C} = 0$$

$$\frac{\dot{C}(t)}{C(t)} = \frac{f(k(t)) - f - \theta g}{\theta} = 0$$

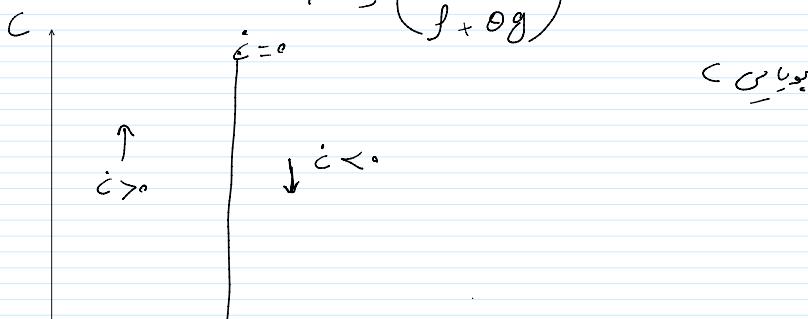
$$f(k) = f + \theta g$$

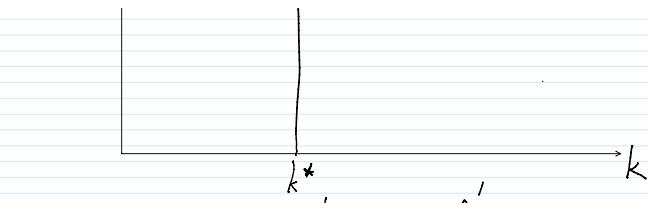
$$f(k) = k^\alpha$$

$$f'(k) = \alpha k^{\alpha-1} = f + \theta g$$

$$k^* = \left(\frac{f + \theta g}{\alpha} \right)^{\frac{1}{\alpha-1}}$$

$$k^* = \left(\frac{\alpha}{f + \theta g} \right)^{\frac{1}{1-\alpha}}$$

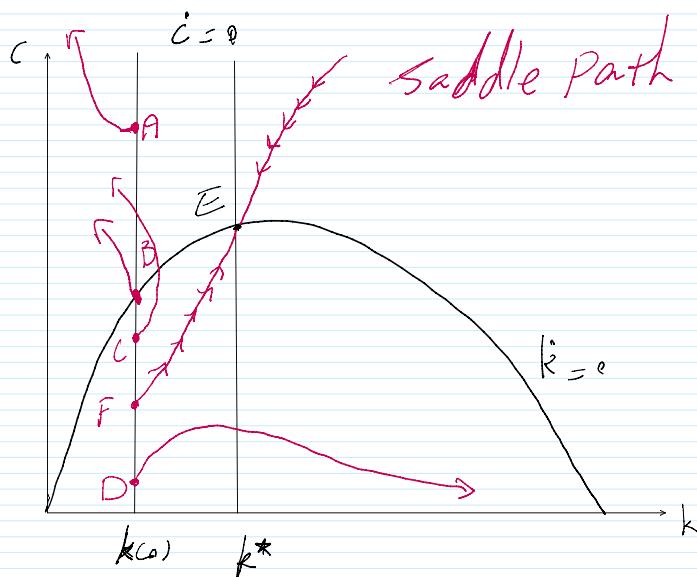
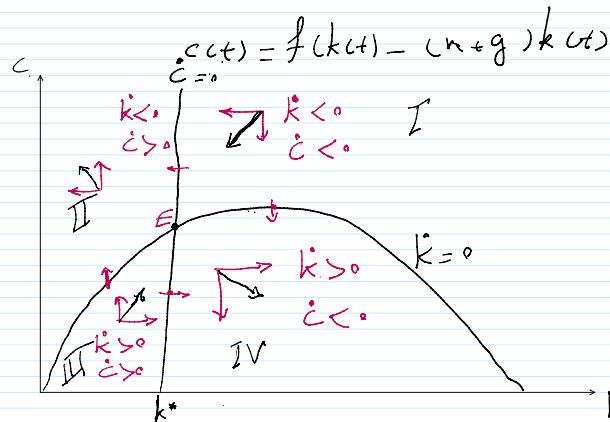




$\text{if } k < k^* \Rightarrow f'(k) > f'(k^*)$

$k \in \underline{\mathbb{C}}$

$$k_{ct} = f(k_{ct}) - c_{ct} - (n+g)k_{ct} = 0$$



$\curvearrowright \curvearrowright$

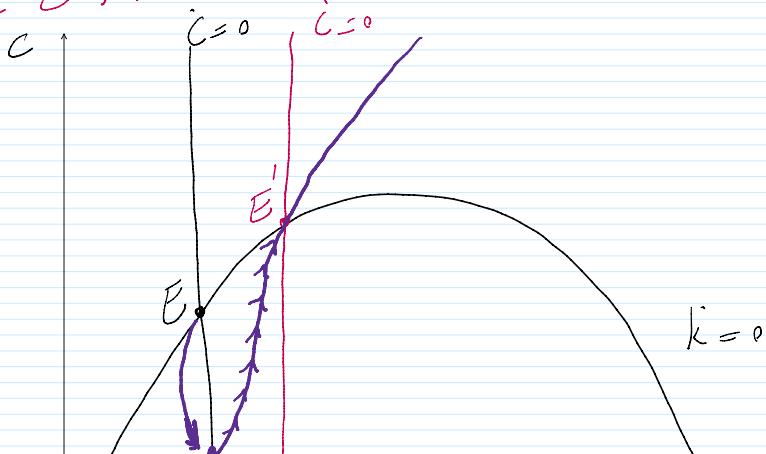
$$r = f$$

$$f'(k^*) = f$$

$$f'(k_G^*) = n$$

$$k_G^* > k^*$$

The Effects of a Fall in the Discount Rate

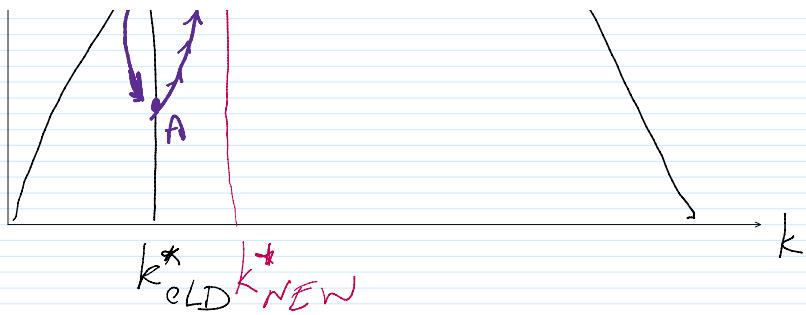


$$f'(k_{OLD}^*) = f_0$$

$$f'(k_{NEW}^*) = f_1$$

$$f_1 < f_0$$

$$k_{NEW}^* > k_{OLD}^*$$



$$k^*_{\text{NEW}} > k^*_{\text{OLD}}$$

The Rate of Adjustment and the Slope of Saddle Path

$$\dot{i} \approx \frac{\partial i}{\partial k} (k - k^*) + \frac{\partial i}{\partial c} (c - c^*)$$

$$\dot{k} \approx \frac{\partial k}{\partial k} (k - k^*) + \frac{\partial k}{\partial c} (c - c^*)$$

$$\tilde{k} = k - k^* \quad \tilde{c} = c - c^*$$

$$\dot{\tilde{c}} = \dot{c} \quad \dot{\tilde{k}} = \dot{k}$$

$$\dot{\tilde{c}} = \frac{\partial \dot{c}}{\partial k} \tilde{k} + \frac{\partial \dot{c}}{\partial c} \tilde{c}$$

$$\dot{\tilde{k}} = \frac{\partial \dot{k}}{\partial k} \tilde{k} + \frac{\partial \dot{k}}{\partial c} \tilde{c} \quad \leftarrow$$

$$\frac{\dot{c}}{c} = \frac{f'(k^*) - f - \theta g}{\theta} \quad \leftarrow$$

$$\dot{c} = \left[\frac{f'(k^*) - f - \theta g}{\theta} \right] c$$

$$\frac{\partial \dot{c}}{\partial c} = \frac{\partial \dot{\tilde{c}}}{\partial c} \quad c^*, k^*$$

$$\frac{\partial \dot{c}}{\partial k} = \frac{\partial \dot{\tilde{c}}}{\partial k}$$

$\cdot \quad \dot{c}'_1, \dot{c}_2, \quad f \quad \text{ag}$



$$\frac{\partial \dot{c}}{\partial c} = \frac{f'(k^*) - \theta g}{\theta} = 0 \quad \leftarrow$$

$$\frac{\partial \dot{c}}{\partial k} = \frac{f''(k^*) c^*}{\theta}$$

$$\dot{c} = \frac{f''(k^*) c^*}{\theta} \tilde{k}$$

$$\dot{k} = f(k) - c - (n+g)k$$

$$\frac{\partial \dot{k}}{\partial k} = f'(k^*) - (n+g)$$

$$\frac{\partial \dot{k}}{\partial c} = -1$$

$$\dot{k} \simeq [f'(k^*) - (n+g)] \tilde{k} - \tilde{c}$$

$$f'(k^*) = f + \theta g$$

$$\dot{k} \simeq [f + \theta g - (n+g)] \tilde{k} - \tilde{c}$$

$$\begin{aligned} \dot{k} &\simeq \beta \tilde{k} - \tilde{c} \\ \tilde{k} &\simeq f'(k^*) c^* \tilde{k} \end{aligned}$$

$$\frac{\overset{\circ}{c}}{\tilde{c}} \simeq \frac{f'(k^*) c^*}{\theta} \frac{\tilde{k}}{\tilde{c}}$$

$$\frac{\overset{\circ}{k}}{\tilde{k}} \simeq \beta - \frac{\tilde{c}}{\tilde{k}}$$

$$\frac{\overset{\circ}{c}}{\tilde{c}} \simeq \frac{f''(k^*) c^*}{\theta} \frac{\tilde{k}}{\tilde{c}}$$

$$\overset{\circ}{c} = \overset{\circ}{c}$$

$$\frac{\overset{\circ}{c}}{\tilde{c}} = \frac{\overset{\circ}{c}}{c - c^*}$$

$$\frac{\overset{\circ}{c}}{\tilde{c}} = \frac{\overset{\circ}{k}}{\tilde{k}}$$

$$\frac{\overset{\circ}{c}}{c} \neq \frac{\overset{\circ}{c}}{c - c^*}$$

$$\frac{\overset{\circ}{c}}{\tilde{c}} = \mu \simeq \frac{f''(k^*) c^*}{\theta} \frac{\tilde{k}}{\tilde{c}}$$

$$\frac{\overset{\circ}{c}}{\tilde{k}} = \frac{f''(k^*) c^*}{\theta} \cdot \frac{1}{\mu}$$

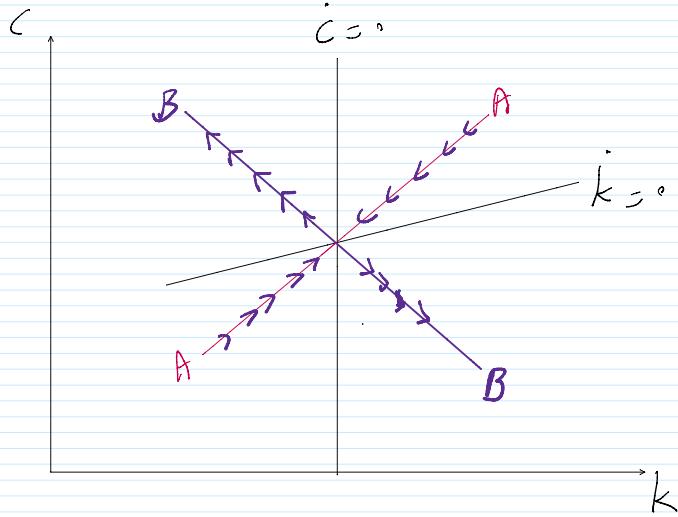
$$\mu \simeq \beta - \frac{\overset{\circ}{c}}{\tilde{k}}$$

$$\mu = \beta - \frac{f''(k^*) c^*}{\theta} - \frac{1}{\mu}$$



$$\mu^2 - \beta\mu + \frac{f'(k^*)c^*}{\theta} = 0$$

$$\mu = \frac{\beta \pm [\beta^2 - 4f'(k^*)k^*/\theta]^{1/2}}{2}$$



The Effects of Government Purchase:

$$Y = C + I + G$$

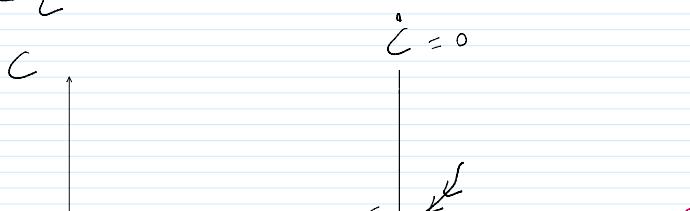
$$\dot{k}(t) = f(k(t)) - c(t) - G(t) - (n+g)k(t)$$

$$\int_{t=0}^{\infty} e^{-R(t)} c(t) e^{(n+g)t} dt \leq k(0) + \int_{t=0}^{\infty} e^{-R(t)} [w(t) - G(t)] e^{(n+g)t} dt$$

$$G(t) \leftarrow \boxed{f(t)}$$

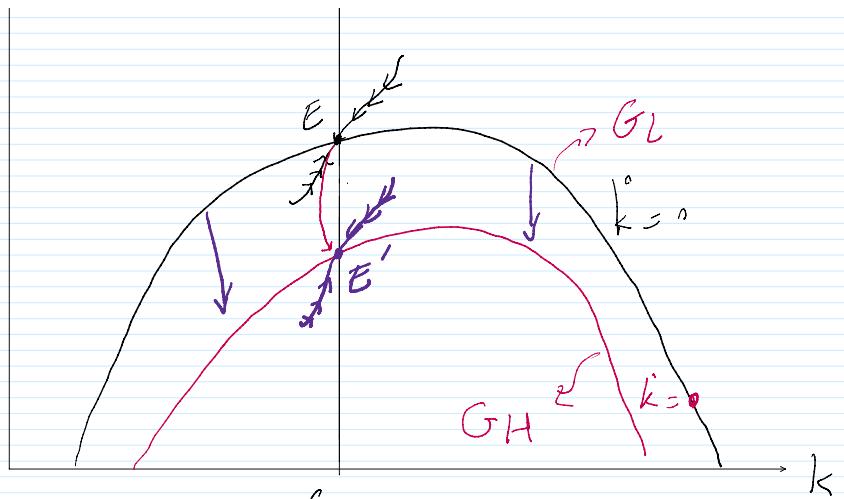
$$G_L \rightarrow G_H$$

$$G_H > G_L$$



$$G_H - G_L \geq \int_0^{\infty} e^{-R(t)} [w(t) - G(t)] e^{(n+g)t} dt$$

ℓ_t



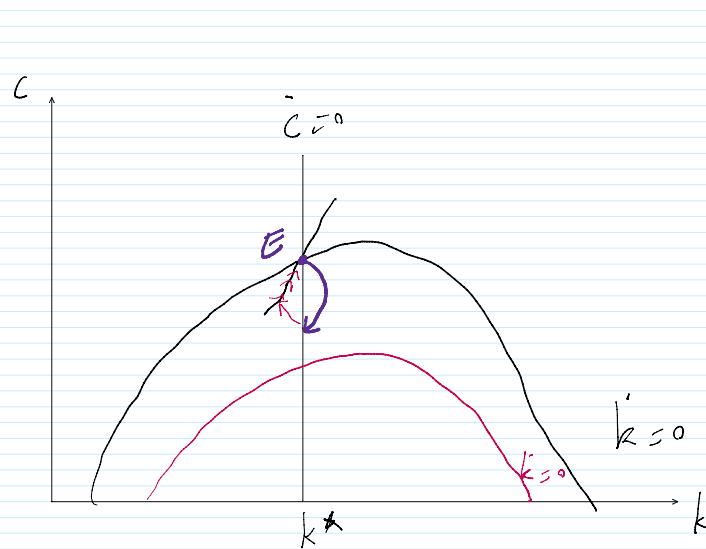
$$G_H \sim G_L \text{ if } \dots$$

$$\dot{c} = 0 \quad f'(k^*) = f + \theta g$$

$$k = 0 \quad f(k^*) - c^* - G^* - (n + g)k^* = r$$

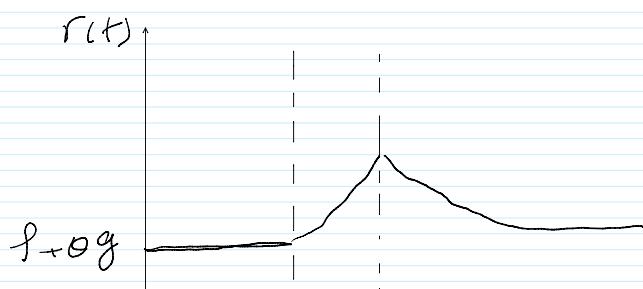
$$c^* = f(k^*) - G^* - (n + g)k^*$$

$G_L^* \rightarrow G_H^*$

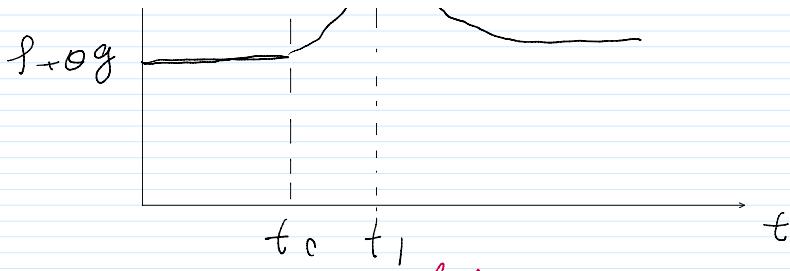


$$G_H \sim G_L \text{ if } \dots$$

Consumption Smoothing



$$r(t) = f'(k(t))$$



The Diamond Model:

Overlapping-generations

Übungsschein

$$c(t) \quad \text{new}$$

$$c_t \quad \text{new}$$

$$L_t = (1+n) L_{t-1}$$

$$c_{1t}, c_{2t}$$

$$U_t = \frac{c_{1t}}{1-\theta} + \frac{1}{1+\delta} \frac{c_{2,t+1}}{1-\theta} \quad \theta > 0, \delta > -1$$

↑ ALD

↑ new

$$\frac{1}{1+\delta} > 1 \quad 1 + \delta < 1$$

$$\delta < 0$$

$$A_t = (1+g) A_{t-1}$$

$$Y_t = F(K_t, A_t L_t)$$

$$y_t = f(k_t)$$

$$r_t = f'(k_t)$$

$$w_t = f(k_t) - k f'(k_t)$$

$$K_{t+1} = w_t A_t L_t - c_{1t} L_t = (w_t A_t - c_{1t}) L_t$$

↗ , ↗

$$K_{t+1} = w_t A_t L_t - c_{1t} L_t = (w_t A_t - c_{1t}) L_t$$

$$S_t = I_t = K_{t+1} - K_t + \delta K_t$$

~~\rightarrow~~

$$I_t = K_{t+1} = (w_t A_t - c_{1t}) L_t$$

$$c_{1t}, c_{2t}$$

~~choose~~

$$K_{t+1} = (1 - \delta) K_t + I_t$$

Household Behavior:

$$c_{2t+1} = (1 + r_{t+1})(w_t A_t - c_{1t})$$

$$\frac{c_{2t+1}}{1 + r_{t+1}} = w_t A_t - c_{1t}$$

$$c_{1t} + \frac{c_{2t+1}}{1 + r_{t+1}} = w_t A_t$$

$$\text{Max } U_t = \frac{c_{1t}^{1-\theta}}{1-\theta} + \frac{1}{1+\rho} \frac{c_{2t+1}^{1-\theta}}{1-\theta}$$

S.t.

$$c_{1t} + \frac{c_{2t+1}}{1 + r_{t+1}} = w_t A_t$$

$$L = \frac{c_{1t}^{1-\theta}}{1-\theta} + \frac{1}{1+\rho} \frac{c_{2t+1}^{1-\theta}}{1-\theta} + \lambda \left[A_t w_t - \left(c_{1t} + \frac{1}{1+r_{t+1}} c_{2t+1} \right) \right]$$

$$\frac{\partial L}{\partial c_{1t}} = c_{1t}^{-\theta} - \lambda = 0 \Rightarrow \lambda = c_{1t}^{-\theta}$$

$\partial C_{1,t}$

$$\frac{\partial L}{\partial C_{2,t}} = \frac{1}{1+\delta} C_{2,t+1} - \frac{\lambda}{1+r_{t+1}} = 0$$

$$\frac{\partial L}{\partial \lambda} = A_t w_t - \left(C_{1,t} + \frac{1}{1+r_{t+1}} C_{2,t+1} \right) = 0$$

$$\frac{C_{1,t}^{-\theta}}{1+r_{t+1}} = \frac{1}{1+\delta} C_{2,t+1}^{-\theta}$$

$$C_{1,t}^{-\theta} = (1+r_{t+1}) \left[\frac{1}{1+\delta} C_{2,t+1}^{-\theta} \right]$$

$$C_{1,t} = \left(\frac{1+\delta}{1+r_{t+1}} \right)^{\frac{1}{\theta}} C_{2,t+1}$$

$$C_{2,t+1} = \left(\frac{1+r_{t+1}}{1+\delta} \right)^{\frac{1}{\theta}} C_{1,t}$$

$$C_{1,t} + \frac{1}{1+r_{t+1}} C_{2,t+1} = w_t A_t$$

$$C_{1,t} + \frac{1}{1+r_{t+1}} \left(\frac{1+r_{t+1}}{1+\delta} \right)^{\frac{1}{\theta}} C_{1,t} = w_t A_t$$

$$C_{1,t} + \frac{(1+r_{t+1})^{\frac{1-\theta}{\theta}}}{(1+\delta)^{\frac{1}{\theta}}} C_{1,t} = w_t A_t$$

\star

$$\underbrace{\left[\frac{(1+\delta)^{\frac{1}{\theta}} + (1+r_{t+1})^{\frac{1-\theta}{\theta}}}{(1+\delta)^{\frac{1}{\theta}}} \right]}_{\rightarrow} C_{1,t} \simeq w_t A_t$$

$$\underbrace{(1+\delta)^{\frac{1}{\theta}}}_{\text{Z}}$$

$$\cancel{\text{if}} \quad S_t = w_t A_t - c_{1:t} = w_t A_t - \frac{1}{Z} w_t A_t = \left(\frac{-1}{Z} \right) w_t A_t$$

$$Z c_{1:t} = w_t A_t \Rightarrow c_{1:t} = \frac{1}{Z} w_t A_t$$

$$S(r) = \frac{(1+r)^{\frac{1-\theta}{\theta}}}{(1+\delta)^{\frac{1}{\theta}} + (1+r)^{\frac{1-\theta}{\theta}}} \quad ; \text{like this}$$

$$c_{1:t} = (1 - S(r_{t+1})) A_t + w_t$$

$$\Delta = (1+r)^{\frac{1-\theta}{\theta}} \quad \frac{\partial S(r)}{\partial r}$$

$$S(r) = \frac{\Delta}{(1+\delta)^{\frac{1}{\theta}} + \Delta}$$

$$\frac{\partial S(r)}{\partial r} = \frac{\partial S(r)}{\partial \Delta} \cdot \frac{\partial \Delta}{\partial r} =$$

$$\frac{\partial S(r)}{\partial \Delta} = \frac{(1+\delta)^{\frac{1}{\theta}} + \cancel{\Delta} - \cancel{\Delta}}{(1+\delta)^{\frac{1}{\theta}} + \Delta)^2}$$

$$\frac{\partial \Delta}{\partial r} = \frac{1-\theta}{\theta} (1+r)^{\frac{1-2\theta}{\theta}}$$

$$\Delta = (1+r)^{\frac{1-\theta}{\theta}}$$

$$\frac{\partial S(r)}{\partial r} = \frac{(1+\delta)^{\frac{1}{\theta}}}{[(1+\delta)^{\frac{1}{\theta}} + \Delta]^2} \cdot \frac{1-\theta}{\theta} (1+r)^{\frac{1-2\theta}{\theta}}$$

(+)

(+)

(+)

$v_t A_t$

$v_c z$

$\frac{2\theta}{\theta}$

$$\text{if } \theta < 1 \quad \frac{\partial S(r)}{\partial r} < 0$$

$$\text{if } \theta > 1 \quad \frac{\partial S(r)}{\partial r} > 0$$

$$\text{if } \theta = 1 \quad \frac{\partial S(r)}{\partial r} = 0$$

The Dynamics of Model:

$$K_{t+1} = w_t A_t L_t - C_{1t} L_t = (w_t A_t - C_{1t}) L_t$$

$$K_{t+1} = s(r_{t+1}) \cdot A_t w_t L_t$$

$$K_{t+1} = \frac{K_{t+1}}{A_{t+1} L_{t+1}} = \frac{s(r_{t+1}) A_t w_t L_t}{A_{t+1} L_{t+1}} = \frac{s(r_{t+1}) w_t}{\frac{A_{t+1}}{A_t} \frac{L_{t+1}}{L_t}}$$

$$K_{t+1} = \frac{s(r_{t+1}) w_t}{(1+g)(1+n)} = \frac{1}{(1+g)(1+n)} s(f'(k_t)) [f(k_t) - k_t]$$

$$k_{t+1} = k_t = k$$

$$y = f(k_t) = k_t^\alpha \Rightarrow f'(k_t) = \alpha k_t^{\alpha-1}$$

$$\theta = 1$$

$$s(r) = \frac{(1+r)^{\frac{1-\theta}{\theta}}}{(1+f)^{\frac{1}{\theta}} + (1+r)^{\frac{1-\theta}{\theta}}} = \frac{1}{1+f+1} = \frac{1}{2}$$

$$f(k_t)]$$

$$+ f$$

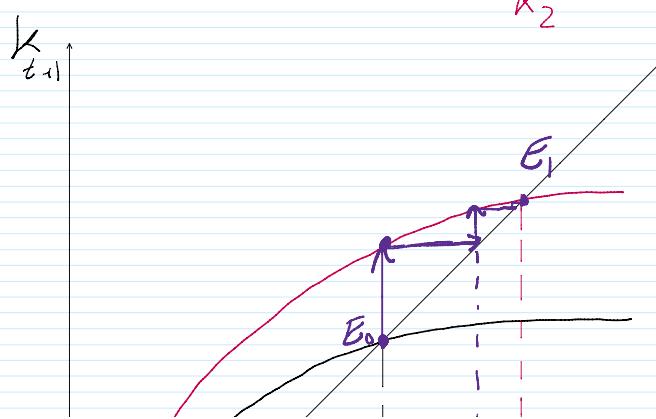
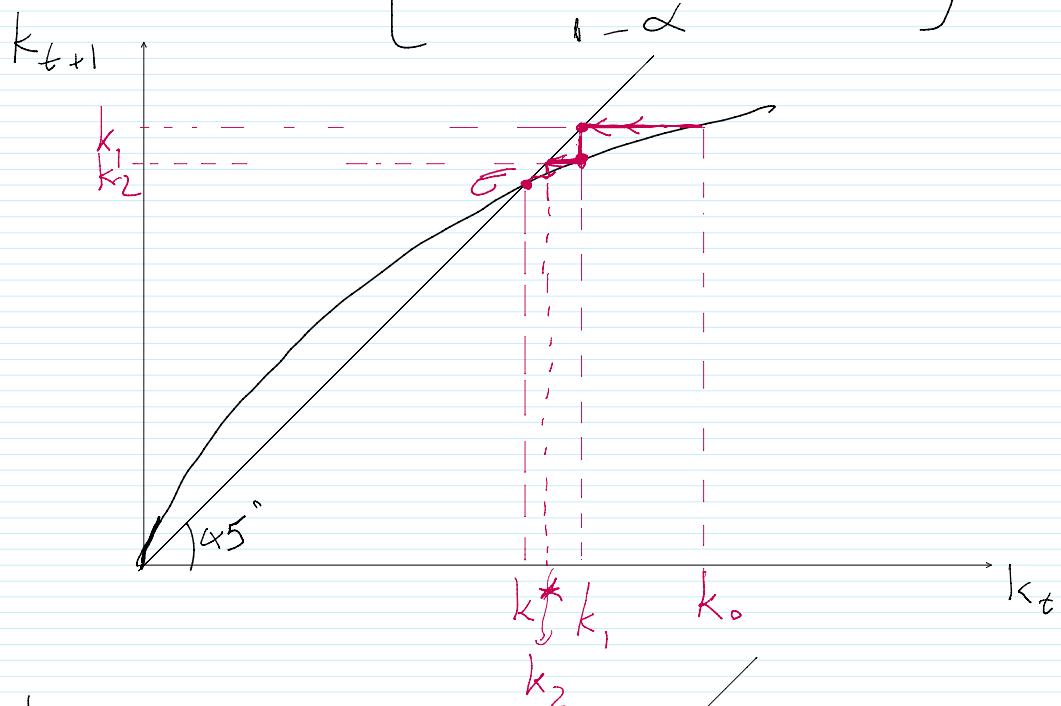
$$s(r) = \frac{1}{(1+\delta)^{\frac{1-\theta}{\theta}} + (1+r)^{\frac{1-\theta}{\theta}}} = \frac{1}{1+\delta+1} \quad 2$$

$$k_{t+1} = \frac{1}{(1+g)(1+n)} \frac{1}{2+\delta} \left[k_t^\alpha - k_t \underbrace{\alpha k_t^{\alpha-1}}_{\alpha k_t^{\alpha-1}} \right]$$

$$k_{t+1} = \frac{(1-\alpha)}{(1+g)(1+n)(2+\delta)} k_t^\alpha$$

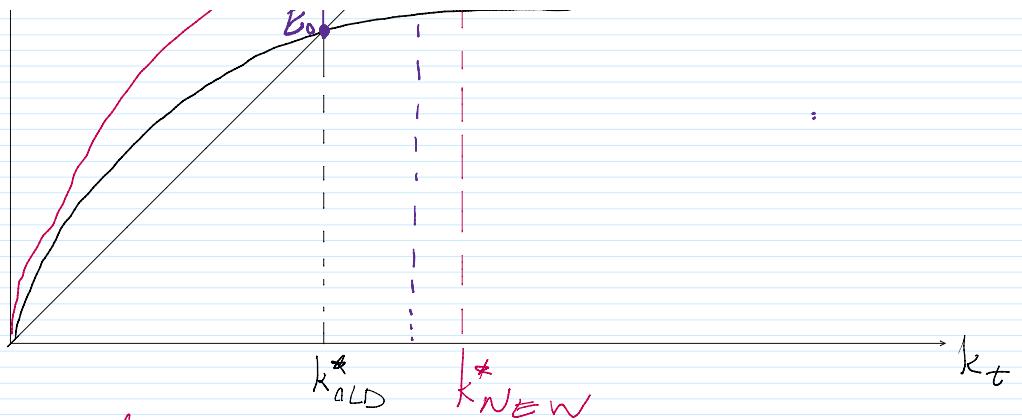
$$k^* = k_{t+1} = k_t \Rightarrow k^* = \frac{(1+g)(1+n)(2+\delta)}{1-\alpha}$$

$$k^* = \left[\frac{(1+g)(1+n)(2+\delta)}{1-\alpha} \right]^{\frac{1}{1-\alpha}}$$



+ f

}



The Speed of Convergence:

$$k_{t+1} = \frac{(1-\alpha)}{(1+n)(1+g)(2+\delta)} k_t^\alpha$$

$$k^* = \frac{(1-\alpha)}{(1+n)(1+g)(2+\delta)} k^* \alpha$$

$$k^* = \left[\frac{1-\alpha}{(1+n)(1+g)(2+\delta)} \right]^{\frac{1}{1-\alpha}}$$

$$\delta^* = \left(\frac{1-\alpha}{(1+n)(1+g)(2+\delta)} \right)^{\frac{\alpha}{1-\alpha}}$$

$$k_{t+1} \approx k^* + \left(\frac{dk_{t+1}}{dk_t} \Big|_{k=k^*} \right) (k_t - k^*)$$

$$k_{t+1} - k^* \approx \lambda (k_t - k^*)$$

λ is the slope of the tangent line at k^*

$$k_{t+1} - k^* \approx \lambda^t (k_0 - k^*)$$

$$\lambda = \frac{dk_{t+1}}{dk_t} \Big|_{k_t=k^*} = \frac{\alpha(1-\alpha)}{(1+n)(1+g)(2+\delta)} k^{*\alpha-1}$$

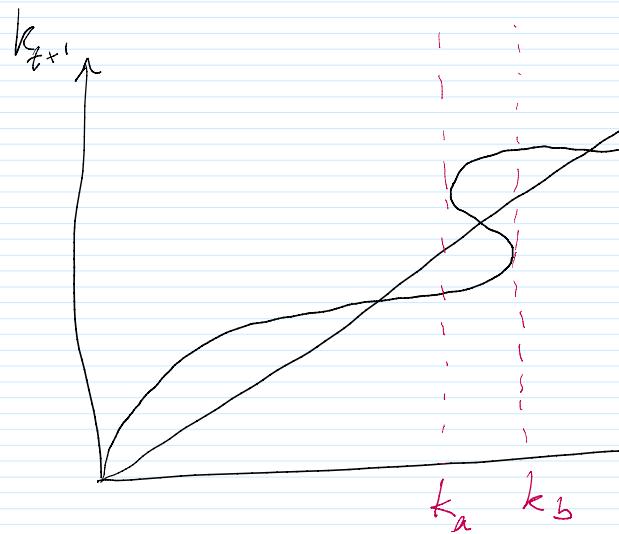
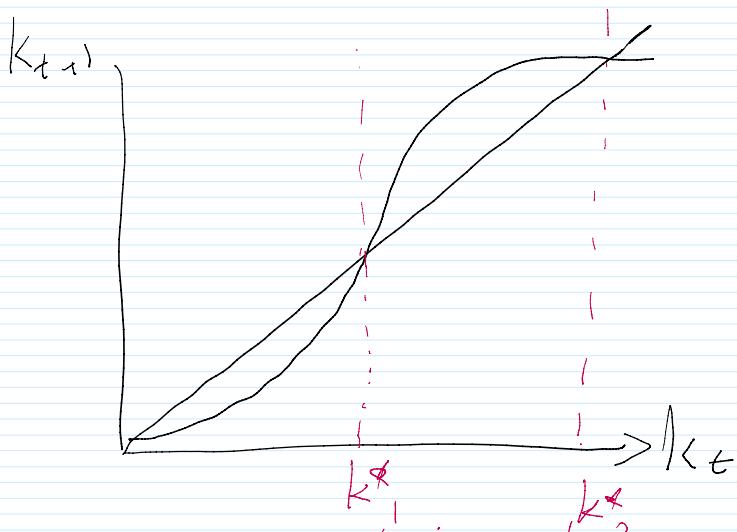
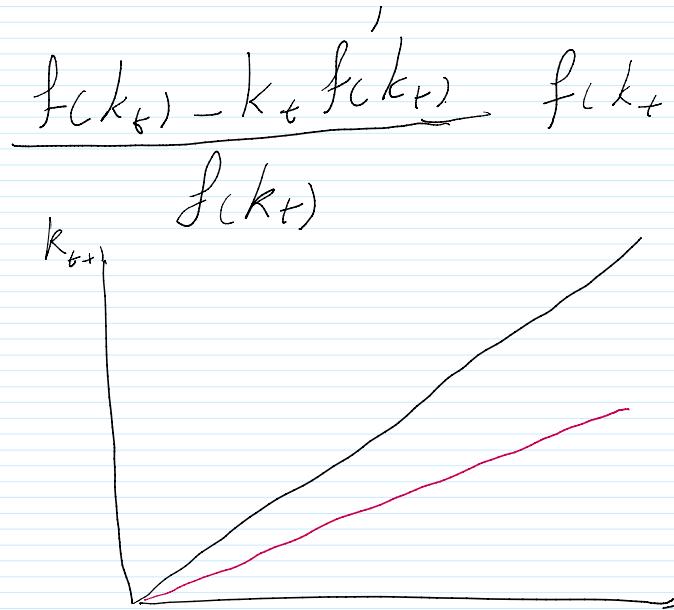
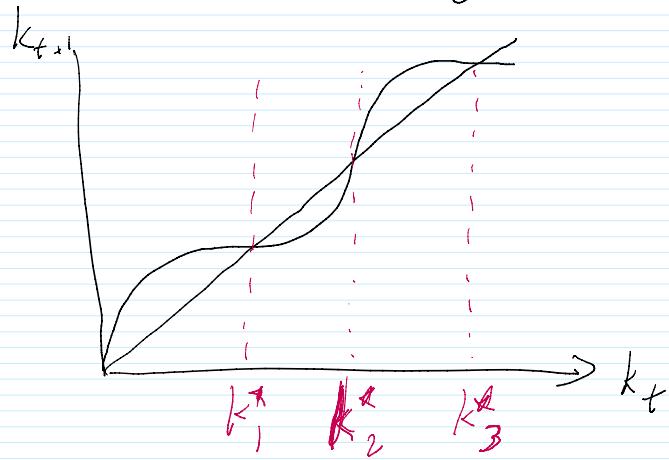
~~$$\lambda = \alpha \frac{(1-\alpha)}{(1+n)(1+g)(2+\delta)} \left[\frac{1-\alpha}{(1+n)(1+g)(2+\delta)} \right]$$~~

$$\lambda = \alpha$$

$$\frac{\alpha - 1}{1 - \alpha}$$

The General Case:

$$k_{t+1} = \frac{1}{(1+n)(1+g)} s(f'(k_{t+1}))$$

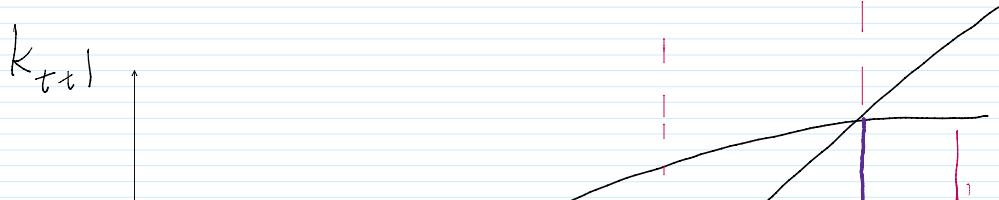


Government in the Diamond Model:

$$G_t = T_t$$

$$(1-\alpha)k_t^\alpha - G_t$$

$$k_{t+1} = \frac{1}{(1+n)(1+g)(2+\beta)} [(1-\alpha)k_t^\alpha - G_t]$$



)

k_+

$\rightarrow k_+$



