

# Assignment 2

## Linear Systems and Approximations

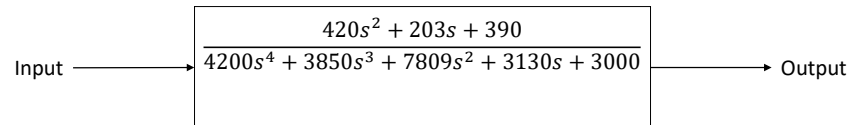
Nusair Islam

# 1. Transfer Function

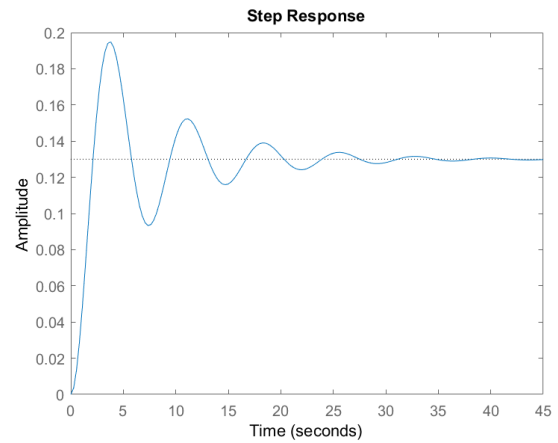
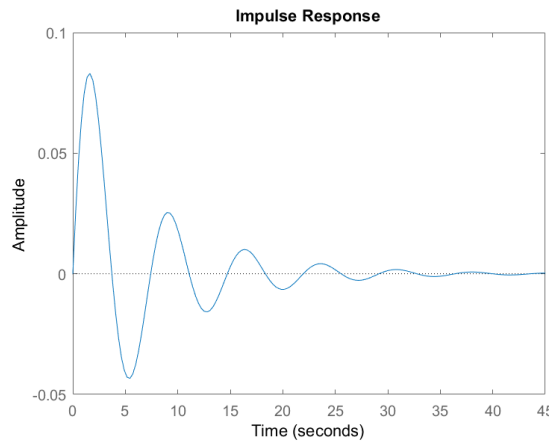
CONSTANTS:

- $M1 = 3$
- $M2 = 7$
- $M3 = 3$
- $M4 = 7$
- $K1 = 3$
- $K2 = 6$
- $K3 = 2$
- $B1 = 10$
- $B2 = 10$
- $B3 = 9$

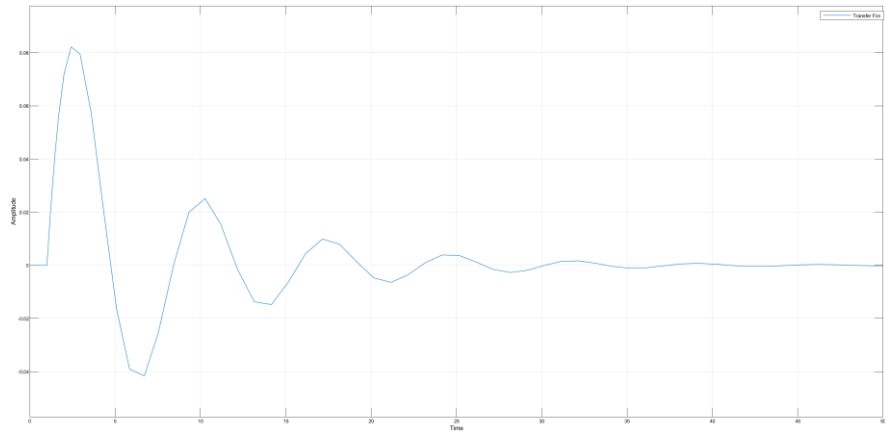
## TRANSFER FUNCTION



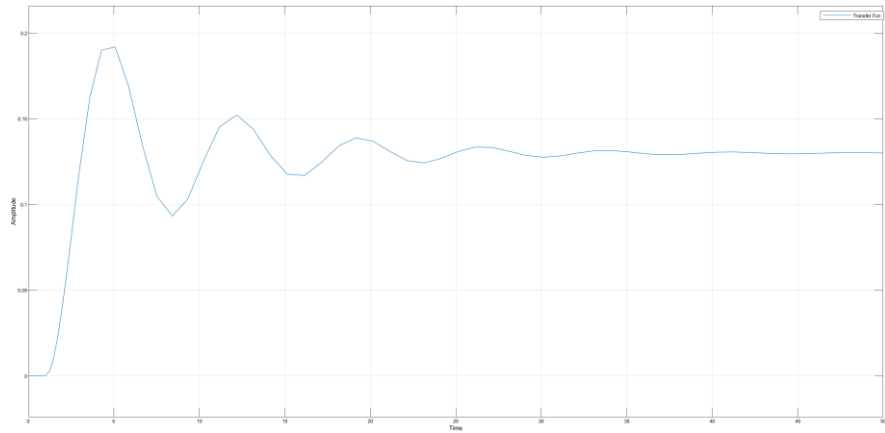
# 1. MATLAB Natural & Step Response



## 2. Simulink Natural Response



## 2. Simulink Step Response



3. When the output is  $v_1$ , and without doing ANY math

- a) I know the natural response will settle to 0 because after a certain amount of time the system will go back to steady state and the mass's velocity will go to 0. The energy put into the system will be damped with the dampers
- b) I know the step response will settle to 0 because the  $dF/dt = 0$ , the velocity of the spring  $v = 1/k * dF/dt$ , so the velocity of the spring will equal to 0, and the movement of the block will also be equal to 0.

3. When the output is  $x_1$ , and without doing ANY math

- a) I know the natural response will settle to 0 because from the previous question  $v_1$  will go to 0 because of damping. This means the system will go back to the previous state before the impulse, therefore the mass  $M_2$  will not change
- b) I know the step response will settle to a finite value because as we keep applying a constant force,  $M_4$  will be in a lower position than its original position. Since string length needs to be constant, when the system goes to steady state  $M_2$  will be the same distance away from  $M_4$ , and therefore in order to keep string length constant it must be lower in position, resulting in a changed  $x_1$

3. When the output is  $x_2$ , and without doing ANY math

- a) I know the natural response will settle to 0 because from the previous questions  $v_1$  will go to 0 because of damping. This means the system will go back to the previous state before the impulse, therefore the mass  $M_2$  will not change. It is the same principle as the last question.
- b) I know the step response will settle to a finite value because as we keep applying a constant force,  $M_4$  will be in a lower position than its original position. Since string length needs to be constant, when the system goes to steady state  $M_2$  will be the same distance away from  $M_4$ , and therefore in order to keep string length constant it must be lower in position, resulting in a changed  $x_2$ . It is the same principle as the last question.