Nonparametric covariance estimation for longitudinal data via tensor product smoothing

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The data:

$$Y_i = (Y_{i1}, Y_{i2}, \dots, Y_{im})', \qquad i = 1, \dots, N$$

associated with measurement times

$$t_1 < t_2 < \cdots < t_m.$$

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 - Constrained optimization is a headache.
- ▶ The $\{t_{ij}\}$ may be suboptimal.
 - Observation times may not fall on a regular grid, may vary across subjects.
- ► More dimensions, more problems (maybe.)
 - Sample covariance matrix falls apart when m is large.

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Covariance dress-up: the modified Cholesky decomposition

$$Y = (Y_1, \ldots, Y_M)' \sim \mathcal{N}(0, \Sigma)$$
.

For any positive definite Σ , we can find T which diagonalizes Σ :

$$D = T\Sigma T', \quad T = \begin{bmatrix} 1 & 0 & \dots & & \\ -\phi_{21} & 1 & & & & \\ -\phi_{31} & -\phi_{32} & 1 & & & \\ \vdots & & & \ddots & & \\ -\phi_{M1} & -\phi_{M2} & \dots & -\phi_{M,M-1} & 1 \end{bmatrix}$$
(1)

The matrix T is the *Cholesy factor* of the precision matrix.

Now, for the cutest part:



Okay, really:

Imagine regressing Y_i on its predecessors:

$$y_{j} = \begin{cases} e_{1} & j = 1, \\ \sum_{k=1}^{j-1} \phi_{jk} y_{k} + \sigma_{j} e_{j} & j = 2, \dots, M \end{cases}$$
 (2)

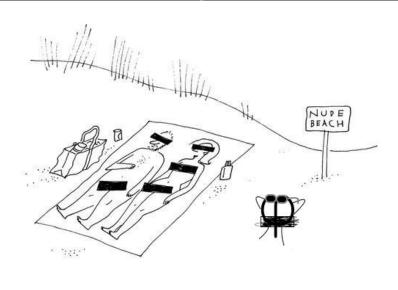
In matrix form:

$$e = TY, (3)$$

and taking covariances on both sides:

$$D = diag\left(\sigma_1^2, \dots, \sigma_M^2\right) = T\Sigma T'. \tag{4}$$

No constraints on the ϕ_{jk} s!



The regression model tool box: a deep treasure chest of luxury.

Model Y_j , e_j as

$$Y_j = Y(t_j), \quad e_j = e(t_j),$$

 $e(s) \sim \mathcal{WN}(0, 1),$

Swap the standard regression model 2 for a varying coefficient model:

$$\phi_{jk} = \phi\left(t_j, t_k\right),\,$$

$$y(t_j) = \sum_{k=1}^{j-1} \phi(t_j, t_k) y(t_k) + \sigma(t_j) e(t_j)$$
 (5)

The $\{\phi_{jk}\}$ are called generalized autoregressive parameters. The $\{\sigma_j^2\}$ are called the innovation variances.

(Iterated) penalized maximum likelihood estimation

- 1. Fix $\sigma_{ij}^2 = \sigma_{ij0}^2$, i = 1, ..., N, j = 1, ..., M.
- 2. Find $\phi_0 = \underset{\phi}{arg \ min} 2L_{\phi}\left(\phi, y_1, \dots, y_N\right) + \lambda J\left(\phi\right)$
- 3. Fix $\phi = \phi_0$.
- 4. Find $\sigma_0^2 = \underset{\sigma^2}{arg \ min} 2L_\sigma^2(\sigma^2, y_1, \dots, y_N) + \lambda J(\sigma^2)$

$$-2L_{\phi}(\phi, y_1, \dots, y_N) = \sum_{i=1}^{N} \sum_{j=2}^{m_i} \sigma_{ij0}^{-2} \left(y_{ij} - \sum_{k=1}^{j-1} \phi(t_{ij}, t_{ik}) y_{ik} \right)^2$$

Regularization of $\phi(s,t)$ is more intuitive if we transform the s-t axis.

Rotate the input axes:

$$l = s - t$$

$$m = \frac{1}{2} (s + t).$$

Then ϕ becomes

$$\phi^* (l, m) = \phi^* \left(s - t, \frac{1}{2} (s + t) \right)$$
$$= \phi (s, t).$$

Take $\hat{\phi}^*$ to be the minimizer of

$$-2L + \lambda J\left(\phi^*\right)$$

Smooth ANOVA models

Decompose

$$\phi^*(l,m) = \mu + \phi_1(l) + \phi_2(m) + \phi_{12}(l,m), \tag{7}$$

so Model 5 becomes

$$y(t_{j}) = \sum_{k=1}^{j-1} \left[\mu + \phi_{1}(l_{jk}) + \phi_{2}(m_{jk}) + \phi_{12}(l_{jk}, m_{jk}) \right] y(t_{k}) + \sigma(t_{j}) e(t_{j})$$
(8)

We can use B-splines to construct the model basis.

Represent the main effects as

$$\phi_{1}(l) = \sum_{c=1}^{c_{l}} B_{c}(l; q_{l}) \,\theta_{lc},$$

$$\phi_{2}(m) = \sum_{c'=1}^{c_{m}} B_{c'}(m; q_{m}) \,\theta_{mc'},$$
(9)

and the interaction term by the tensor product of the marginal bases ?? and ??:

$$\phi_{12}(l,m) = \sum_{c=1}^{c_l} \sum_{c'=1}^{c_m} B_c(l;q_l) B_{c'}(m;q_m) \theta_{cc'}$$
 (10)

PS-ANOVA model basis

In matrix notation, Model 8 becomes

$$E[Y|W] = WB\theta,$$

where W is the matrix of covariates holding the past values of Y, and B is the B-spline regression basis:

$$B = [1_p \mid B_l \mid B_m \mid B_{lm}] \tag{11}$$

where

$$B_{lm} = B_m \square B_l$$

$$\equiv (B_m \otimes 1'_{c_l}) \odot (1'_{c_m} \otimes B_l).$$

Difference penalty had to regulate.

For
$$f(x) = \sum_{i=1}^{p} B_i(x) \theta_i$$
, approximate

$$\int_{0}^{1} (f''(x))^{2} dx = \int_{0}^{1} \left\{ \sum_{i=1}^{p} B_{i}''(x) \theta_{i} \right\}^{2} dx$$

$$= k_{1} \sum_{i} (\Delta^{2} \theta_{i})^{2} + k_{2},$$
(12)

by

$$||D_2\theta||^2, \qquad D_2\theta = (\Delta^2\theta_1, \dots, \Delta^2\theta_{p-2})'$$

In general, approximate $\int_{0}^{1} (f^{(d)})^{2} dx$ with $||D_{d}\theta||^{2}$

PS-ANOVA Penalty

Estimate B-spline coefficients by minimizing

$$(Y - WB\theta)'(Y - WB\theta) + \theta'P\theta$$

where

$$P = \text{blockdiag}(0, P_1, P_2, P_{12}),$$
 (13)

$$P_{i} = \lambda_{i} D'_{d_{i}} D_{d_{i}}$$

$$P_{12} = \lambda_{3} D'_{d_{1}} D_{d_{1}} \otimes I_{c_{m}} + \lambda_{4} I_{c_{l}} \otimes D'_{d_{2}} D_{d_{2}}$$

Mixed model representation

In matrix notation, Model 8 is given by

$$E[Y|W] = WB\theta,$$

where W is the matrix of covariates holding the past values of Y, and B is the B-spline regression basis:

$$B = [1_p \mid B_l \mid B_m \mid B_{lm}] \tag{14}$$

$$B_{lm}\left(B_m\otimes 1'_{c_l}\right)\odot\left(1'_{c_m}\otimes B_l\right),$$

and

$$\theta = (\mu, \ \theta_l, \ \theta_l, \ \theta_{lm})'$$

Mixed model representation

Find transformation M to map

$$B \to [X \mid Z], \qquad \theta \to (\beta, \alpha)'$$

such that

$$BM = [X \mid Z], \qquad B\theta = X\beta + Z\alpha$$

Applying M to basis 11 and penalty ??, Model 8 becomes

$$Y = W(X\beta + Z\alpha) + e,$$

$$\alpha \sim \mathcal{N}(0, G), \quad e \sim \mathcal{N}(0, D)$$
(15)

The $\{\lambda_i\}$ become

$$\lambda_j = rac{\sigma^2}{ au_j^2}$$

where diag $(G) = \{\tau_i^2\}$.

Decomposition of ϕ^* for $d_l = d_m = 2$

	{1}	$\{m\}$	$\left\{ B_{j^{\prime}}\left(m ight) ight\}$
{1}	{1}	$\{m\}$	$\left\{ B_{j^{\prime}}\left(m ight) ight\}$
$\{l\}$	$\{l\}$	$l \times m$	$l \times \{B_{j'}(m)\}$
$\{B_{j}\left(l ight)\}$	$\{B_{j}\left(l\right)\}$	$m \times \{B_j(l)\}$	$\left\{ B_{j}\left(l\right) B_{j^{\prime}}\left(m ight) ight\}$

Nested PS-ANOVA

Re-express ϕ_{12} :

$$\phi_{12}\left(l,m
ight) = g_{1}\left(l
ight) \Big[\sum_{r=1}^{d_{m}-1}m^{r}\Big] + \Big[\sum_{r=1}^{d_{l}-1}l^{r}\Big]g_{2}\left(m
ight) + h\left(l,m
ight),$$

For $d_l = d_m = 2$,

$$\phi_{12}(l,m) = g_1(l) m + l g_2(m) + h(l,m)$$

with basis:

$$B = [1_p \mid B_1 \mid B_2 \mid B_3 \mid B_4 \mid B_5], \tag{16}$$

where

$$B_3 = m \square B_1$$

$$B_5 = B_2 \square B_1$$

$$B_4 = B_2 \square l$$

Nested PS-ANOVA