Nonparametric covariance estimation for longitudinal data via tensor product smoothing

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The data:

$$Y_i = (Y_{i1}, Y_{i2}, \dots, Y_{iM_i})', \qquad i = 1, \dots, N$$

associated with measurement times

$$t_1 < t_2 < \cdots < t_{M_i}$$
.

Goal: estimate

$$Cov(Y) = \Sigma$$

- ► Covariance matrices (and their estimates) should be positive definite.
 - Constrained optimization is a headache.
- ▶ The $\{t_{ij}\}$ may be suboptimal.
 - Observation times may not fall on a regular grid, may vary across subjects.
- ▶ More dimensions, more problems (maybe.)
 - Sample covariance matrix falls apart when m is large

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- ► Covariance matrices (and their estimates) should be positive definite. A cute little reparameterization ⇒ unconstrained estimation, meaningful interpretation
- ► The $\{t_{ij}\}$ may be messy. Frame covariance estimation as function estimation.
- ► More dimensions, more problems (maybe.)



Figure: Regulate like Nate Dogg.

Covariance dress-up: the modified Cholesky decomposition

$$Y = (Y_1, \ldots, Y_M)' \sim \mathcal{N}(0, \Sigma)$$
.

For any positive definite Σ , we can find T which diagonalizes Σ :

$$D = T\Sigma T', \quad T = \begin{bmatrix} 1 & 0 & \dots & & \\ -\phi_{21} & 1 & & & \\ -\phi_{31} & -\phi_{32} & 1 & & \\ \vdots & & & \ddots & \\ -\phi_{M1} & -\phi_{M2} & \dots & -\phi_{M,M-1} & 1 \end{bmatrix}$$

Now, for the cutest part:



Okay, really:

Regress Y_j on $Y_{(1:j-1)} = (Y_1, \dots, Y_{j-1})'$:

$$y_{j} = \begin{cases} e_{1} & j = 1, \\ \sum_{k=1}^{j-1} \phi_{jk} y_{k} + \sigma_{j} e_{j} & j = 2, \dots, M \end{cases}$$
 (1)

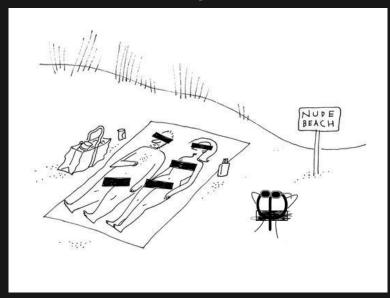
In matrix form:

$$e = TY, (2)$$

and taking covariances on both sides:

$$D = diag\left(\sigma_1^2, \dots, \sigma_M^2\right) = T\Sigma T'. \tag{3}$$

No constraints on the ϕ_{jk} s!



The regression model tool box is a deep, luxurious toolbox.

$$Y_j \longrightarrow Y(t_j)$$
 $e_j \longrightarrow e(t_j)$
 $\phi_{jk} \longrightarrow \phi(t_j, t_k)$ $\sigma_j^2 \longrightarrow \sigma^2(t_j)$

$$y(t_j) = \sum_{j=1}^{j-1} \phi(t_j, t_k) y(t_k) + \sigma(t_j) e(t_j),$$
 (4)

where

$$e(s) \sim \mathcal{WN}(0,1)$$

Regularization of $\phi(s,t)$ is more intuitive if we transform the s-t axis.

$$l = s - t$$
$$m = \frac{1}{2}(s + t)$$

Reparameterize ϕ :

$$\phi(s,t) = \phi^*(l,m) = \phi^*\left(s-t, \frac{1}{2}(s+t)\right)$$

Take $\hat{\phi}^*$ to be the minimizer of

$$-2L_{\phi}(\phi, y_1, \dots, y_N) = \sum_{i=1}^{N} \sum_{j=2}^{m_i} \sigma_{ij0}^{-2} \left(y_{ij} - \sum_{k=1}^{j-1} \phi(t_{ij}, t_{ik}) y_{ik} \right)^2$$

Smooth ANOVA models

Decompose

$$\phi^*(l,m) = \mu + \phi_1(l) + \phi_2(m) + \phi_{12}(l,m), \qquad (6)$$

so Model 4 becomes

$$y(t_{j}) = \sum_{k=1}^{j-1} \left[\mu + \phi_{1}(l_{jk}) + \phi_{2}(m_{jk}) + \phi_{12}(l_{jk}, m_{jk}) \right] y(t_{k}) + \sigma(t_{j}) e(t_{j})$$

Approximate ϕ_1 , ϕ_2 , ϕ_{12} with B-splines.

$$\phi_{1}(l) = \sum_{c=1}^{c_{l}} B_{c}(l; q_{l}) \,\theta_{lc} = B_{l}\theta_{l},$$

$$\phi_{2}(m) = \sum_{c'=1}^{c_{m}} B_{c'}(m; q_{m}) \,\theta_{mc'} = B_{m}\theta_{m}$$

$$\phi_{12}(l, m) = \sum_{c=1}^{c_{l}} \sum_{c'=1}^{c_{m}} B_{c}(l; q_{l}) \,B_{c'}(m; q_{m}) \,\theta_{cc'} = B_{lm}\theta_{lm}$$
(7)

$$B_{lm} = B_m \square B_l$$

$$\equiv (B_m \otimes 1'_{c_l}) \odot (1'_{c_m} \otimes B_l)$$

Difference penalty had to regulate.

For
$$f(x) = \sum_{i=1}^{p} B_i(x) \theta_i$$
, approximate

$$\int_{0}^{1} (f''(x))^{2} dx = \int_{0}^{1} \left\{ \sum_{i=1}^{p} B_{i}''(x) \theta_{i} \right\}^{2} dx$$

$$= k_{1} \sum_{i} (\Delta^{2} \theta_{i})^{2} + k_{2},$$
(8)

by

$$||D_2\theta||^2$$
, $D_2\theta = (\Delta^2\theta_1, \dots, \Delta^2\theta_{p-2})'$

In general, approximate
$$\int_{0}^{1} (f^{(d)})^{2} dx$$
 with $||D_{d}\theta||^{2}$

PS-ANOVA Penalty

$$B \equiv [1_p \mid B_l \mid B_m \mid B_{lm}], \qquad \theta \equiv (\theta_l, \theta_m, \theta_{lm})'$$

Find θ minimizing

$$(Y - WB\theta)'(Y - WB\theta) + \theta'P\theta$$

$$P = \begin{bmatrix} \lambda_l D'_{d_l} D_{d_l} \\ P_l \end{bmatrix}$$

$$\frac{\lambda_l D'_{d_l} D_{d_l}}{P_m}$$

$$\tau_l D'_{d_l} D_{d_l} \otimes I_{c_m} + \tau_m I_{c_l} \otimes D'_{d_m} D_{d_m}$$

$$P_{l_m}$$

PS-ANOVA Penalty

$$B \equiv [1_p \mid B_l \mid B_m \mid B_{lm}], \qquad \theta \equiv (\theta_l, \theta_m, \theta_{lm})'$$

Find θ minimizing

$$(Y - WB\theta)' D^{-1} (Y - WB\theta) + \theta' P\theta \tag{9}$$

$$P = \begin{bmatrix} \lambda_l D'_{d_l} D_{d_l} \\ P_l \end{bmatrix}$$

$$\frac{\lambda_l D'_{d_l} D_{d_l}}{P_m}$$

$$\tau_l D'_{d_l} D_{d_l} \otimes I_{c_m} + \tau_m I_{c_l} \otimes D'_{d_m} D_{d_m}$$

$$P_{l_m}$$

Mixed model representation

Find transformation $Q = [Q_n \mid Q_s]$ to map

$$BQ = \begin{bmatrix} BQ_n \mid BQ_s \end{bmatrix} \qquad Q'\theta = (\beta', \alpha')'$$

= $\begin{bmatrix} X \mid Z \end{bmatrix} \qquad = ((Q'_n\theta)', (Q'_s\theta)')'$

to reparameterize the ill-posed Model 9 as

$$Y = W(X\beta + Z\alpha) + e$$

$$\alpha \sim \mathcal{N}(0, G),$$

$$e \sim \mathcal{N}(0, D)$$
(10)

Mixed model representation

Decomposition of ϕ^* for $d_l = d_m = 2$

	{1}	$\{m\}$	$\left\{ B_{j^{\prime}}\left(m ight) ight\}$
{1}	{1}	$\{m\}$	$\left\{ B_{j^{\prime}}\left(m ight) ight\}$
$\{l\}$	$\{l\}$	$l \times m$	$l \times \{B_{j'}(m)\}$
$\{B_{j}\left(l\right)\}$	$\{B_{j}\left(l\right)\}$	$m \times \{B_j(l)\}$	$\left\{ B_{j}\left(l\right) B_{j^{\prime}}\left(m ight) ight\}$

Re-express ϕ_{12} :

$$\phi_{12}(l,m) = g_1(l) \left[\sum_{r=1}^{d_{m-1}} m^r \right] + \left[\sum_{r=1}^{d_l-1} l^r \right] g_2(m) + h(l,m),$$

For $d_l = d_m = 2$,

$$\phi_{12}(l,m) = g_1(l) \ m + l \ g_2(m) + h(l,m)$$

with basis:

$$B = [1_p \mid B_1 \mid B_2 \mid B_3 \mid B_4 \mid B_5], \tag{11}$$

where

$$B_3 = m \square B_1 \qquad B_5 = B_2 \square B_1$$

$$B_4 = B_2 \square l$$

$$P = \text{blockdiag}(0, P_1, P_2, P_3, P_4, P_5),$$
 (12)

Re-express ϕ_{12} :

$$\phi_{12}(l,m) = g_{lr}(l) \left[\sum_{r=1}^{d_{m-1}} m^r \right] + \left[\sum_{r=1}^{d_l-1} l^{r'} \right] g_{mr'}(m) + h(l,m),$$

For $d_l = d_m = 2$,

$$\phi_{12}(l,m) = g_{l1}(l) \ m + l \ g_{m1}(m) + h (l,m)$$

with basis:

$$B = [1_p \mid B_1 \mid B_2 \mid B_3 \mid B_4 \mid B_5], \tag{13}$$

where

$$B_3 = m \square B_1 \qquad B_5 = B_2 \square B_1$$

$$B_4 = B_2 \square l$$

$$P = blockdiag(0, P_1, P_2, P_3, P_4, P_5)$$

Remove the redundant columns, and give each penalized component its own random effect:

B