

Nonparametric Covariance Estimation for Longitudinal Data

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Background

Let

$$Y = (y_1, \dots, y_p)', \quad (t_1, \dots, t_p)'$$

denote the random vector of observations and their associated measurement times, where

$$\text{Cov}(Y) = \Sigma = [\sigma_{ij}]$$

- Dimensionality: the number of parameters is quadratic in p .

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- Observation times may be irregular or subject-specific.

The Modified Cholesky decomposition

For any positive definite Σ , there exists a unique lower-triangular matrix $C = [c_{ij}]$, $c_{ii} > 0$:

$$\Sigma = CC',$$

Let $D^{1/2} = \text{diag}(c_{11}, \dots, c_{pp})$, $L = D^{-1/2}C$, then

$$\Sigma = LDL'.$$

The **modified Cholesky decomposition** (MCD) of Σ is given by

$$D = T\Sigma T', \tag{I}$$

where $T = L^{-1}$. The lower triangular entries of T are *unconstrained*.

Statistical Interpretation of (T, D)

Let \hat{y}_t be the linear least-squares predictor of y_t based on previous measurements y_{t-1}, \dots, y_1 and $\epsilon_t = y_t - \hat{y}_t$ denote the corresponding mean zero prediction error with variance $\text{Var}(\epsilon_t) = \sigma_t^2$. We can find unique scalars ϕ_{tj} :

$$y_t = \begin{cases} \epsilon_t, & t = 1 \\ \sum_{j=1}^{t-1} \phi_{tj} y_j + \epsilon_t, & t = 2, \dots, p, \end{cases}$$

where $D = \text{Cov}(\epsilon) = \text{diag}(\sigma_1^2, \dots, \sigma_p^2)$. Then

$$\underbrace{\begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_{p-1} \\ \epsilon_p \end{bmatrix}}_{\epsilon} = \underbrace{\begin{bmatrix} 1 & & & & \\ -\phi_{21} & 1 & & & \\ -\phi_{31} & -\phi_{32} & 1 & & \\ \vdots & & & \ddots & \\ -\phi_{p1} & -\phi_{p2} & \dots & -\phi_{p,p-1} & 1 \end{bmatrix}}_T \underbrace{\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_{p-1} \\ y_p \end{bmatrix}}_Y$$

Taking the covariance on both sides gives the MCD (1).

The coefficients and prediction error variances of successive regressions are unconstrained.

The **generalized autoregressive parameters** ϕ_{tj} and **log innovation variances** $\log \sigma_j^2$

are unconstrained but

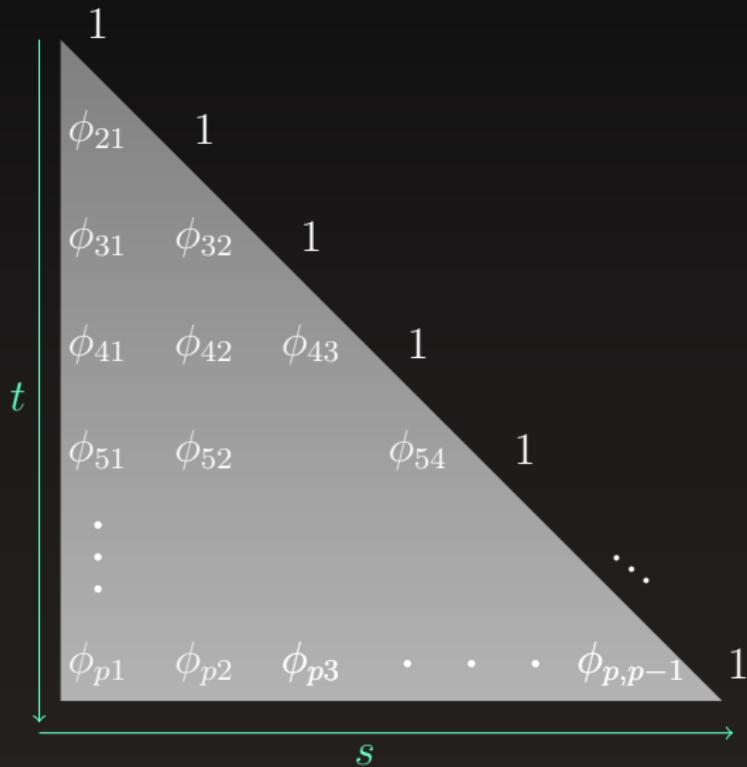
$$\hat{\Sigma}^{-1} = \hat{T}' \hat{D}^{-1} T$$

	y_1	y_2	y_3	\dots	y_{p-1}	y_p
	1					
	ϕ_{21}	1				
	ϕ_{31}	ϕ_{32}	1			
	:	:				
	ϕ_{p1}	ϕ_{p2}	\dots	\dots	$\phi_{p,p-1}$	1
	σ_1^2	σ_2^2	\dots	\dots	σ_{p-1}^2	σ_p^2

is guaranteed to be positive definite.

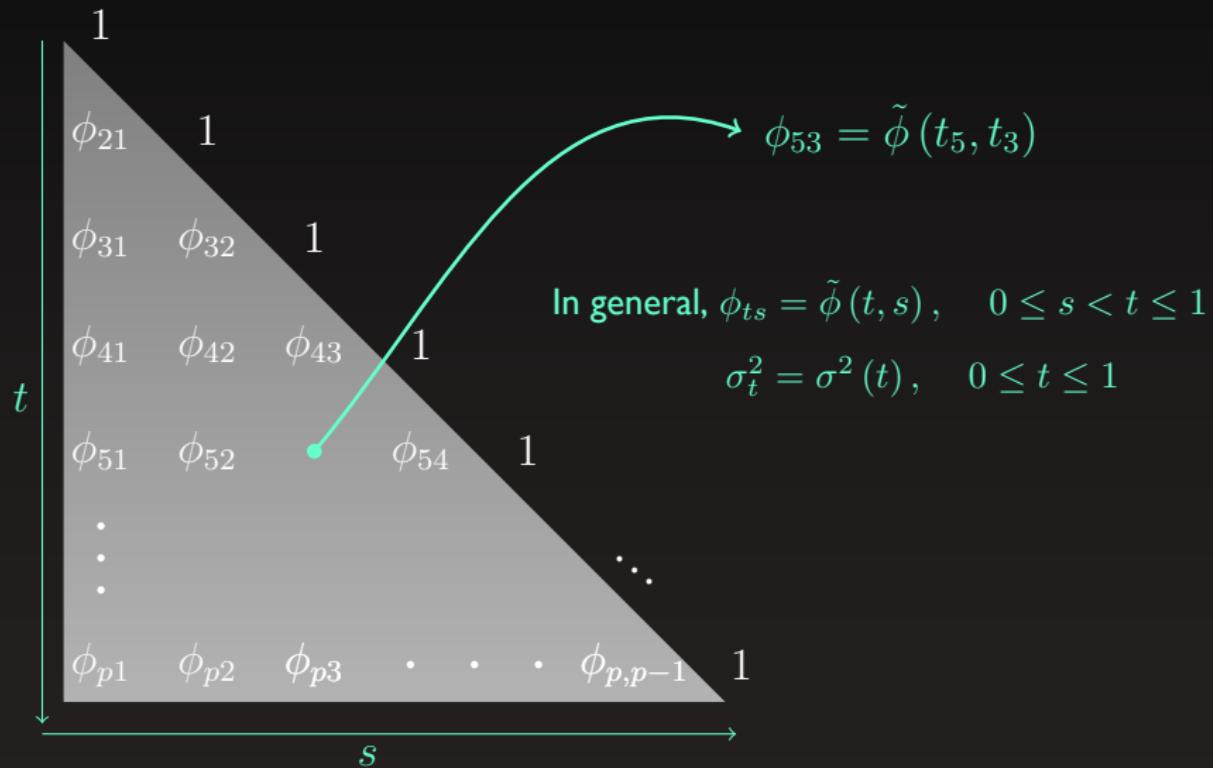
Accommodating Unbalanced Data

Treating ϕ as a continuous bivariate function.



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A functional varying coefficient model for ϕ

Assume measurements $Y_i = (y_{i1}, \dots, y_{ip_i})'$ arise from $Y(t)$ observed at

$$t_i = \{t_{i1} < \dots < t_{ip_i}\} \subset \mathcal{T} = [0, 1]$$

$$\boxed{y(t_{ij}) = \sum_{k < j} \tilde{\phi}(t_{ij}, t_{ik}) y(t_{ik}) + \epsilon(t_{ij}), \quad \begin{matrix} i = 1, \dots, N \\ j = 2, \dots, p_i, \end{matrix}}$$

where $\epsilon(t) \sim N(0, \sigma^2(t))$. Transform $l = t - s$, $m = \frac{t+s}{2}$, let

$$\phi(l, m) = \phi\left(t - s, \frac{1}{2}(s + t)\right) = \tilde{\phi}(t, s),$$

so that

$$-2\ell(\phi, \sigma^2 | Y_1, \dots, Y_N) = \sum_{i=1}^N \sum_{j=2}^{p_i} \left[\log \sigma_{ij}^2 + \frac{1}{\sigma_{ij}^2} \left(y_{ij} - \sum_{k < j} \tilde{\phi}(t_{ij}, t_{ik}) y_{ik} \right)^2 \right]$$

Hilbert spaces for univariate functions

An example: the cubic smoothing spline

The cubic smoothing spline corresponds to model space

$$\mathcal{H} = W_2[0, 1] = \{f : [0, 1] \rightarrow \mathbb{R} \mid f, f' \text{ abs cnts}, \int (f''(x))^2 dx < \infty\}.$$

and is the solution to the penalized least squares problem with

$$J(f) = \int_0^1 (f''(x))^2 dx.$$

Equip \mathcal{H} with inner product such that $\mathcal{H} = \mathcal{H}_0 \oplus \mathcal{H}_1$ where $J(f) = 0$ for $f \in \mathcal{H}_0$.

- \mathcal{H} has corresponding reproducing kernel $K = K_0 + K_1$.
- Take functions in **null space** $\mathcal{H}_0 = \{\text{linear or constant functions}\}$ to be null models.
- $J(f) = \|P_1 f\|^2$ corresponds to the squared norm of the projection of f to \mathcal{H}_1 .

One-way functional ANOVA models

Given

1. averaging operator $A(f) = \int_0^1 f(x)dx$,
2. basis $k_1(\cdot)$ for linear functions in \mathcal{H}_0 such that $A(k_1) = 0$,

\mathcal{H} admits decomposition

$$\begin{aligned}\mathcal{H} &= \{1\} \oplus \{k_1(\cdot)\} \oplus \mathcal{H}_1 \\ &= \text{mean} \oplus \underset{\text{main effect}}{\text{parametric}} \oplus \underset{\text{main effect}}{\text{nonparametric}}\end{aligned}$$

and representation

$$f(x) = c_0 + c_1 k_1(x) + f_1(x); \quad f \in \mathcal{H}$$

where $c_0, c_1 \in \mathbb{R}$ and $f_1 \in \mathcal{H}_1$.

A Two-way functional ANOVA Model for ϕ

via tensor product

Let

$$\phi \in \mathcal{H} = \mathcal{H}^{[l]} \otimes \mathcal{H}^{[m]}$$

constructed from building blocks

$$\mathcal{H}^{[l]} = \{1\} \oplus \{k_1(l)\} \oplus \mathcal{H}_1^{[l]}$$

$$\mathcal{H}^{[m]} = \{1\} \oplus \mathcal{H}_1^{[m]}.$$

with RK K . The subspaces of \mathcal{H} define unique decomposition

$$\phi(l, m) = \mu + \phi_1(l) + \phi_2(m) + \phi_{12}(l, m).$$

$\{1\}$	$\{k_1\}$	$\mathcal{H}_1^{[l]}$
$\{1\}$	p -main effect	np -main effect
np -main effect	$np \times p$ -interaction	$np \times np$ -interaction

Penalized log likelihood for ϕ

Define transformed pairs of observation times

$$\begin{aligned}\mathbf{v}_{ijk} &= (t_{ij} - t_{ik}, \frac{1}{2}(t_{ij} + t_{ik})) = (l_{ijk}, m_{ijk}), \\ V &= \bigcup_{i,j,k} \{\mathbf{v}_{ijk}\} = \left\{ \mathbf{v}_1, \dots, \mathbf{v}_{|V|} \right\}.\end{aligned}$$

Fixing $\sigma_{ij}^2 = \sigma^2(t_{ij})$, find ϕ minimizing

$$-2\ell(\phi|Y_1, \dots, Y_N, \sigma^2) + \lambda J(\phi) = \sum_{i=1}^N \sum_{j=2}^{p_i} \frac{1}{\sigma_{ij}^2} \left(y_{ij} - \sum_{k < j} \phi(\mathbf{v}_{ijk}) y_{ik} \right)^2 + \lambda J(\phi) \quad (2)$$

where $J(\phi) = \|P_1\phi\|^2$ and $\mathbf{v}_{ijk} \in \mathcal{V} = [0, 1]^2$,

A Representer Theorem

Theorem

Let $\{\nu_1, \dots, \nu_{\mathcal{N}_0}\}$ span \mathcal{H}_0 , the null space of $J(\phi) = \|P_1\phi\|^2$. Let B denote the $|V| \times \mathcal{N}_0$ matrix having i^{th} column equal to ν_i evaluated at the observed $\mathbf{v} \in V$, and assume that B has full column rank. Then the minimizer ϕ_λ of (2) is given by

$$\phi_\lambda(\mathbf{v}) = \sum_{i=1}^{\mathcal{N}_0} d_i \nu_i(\mathbf{v}) + \sum_{j=1}^{|V|} c_j K_1(\mathbf{v}_j, \mathbf{v}), \quad (3)$$

where $K_1(\mathbf{v}_j, \mathbf{v})$ denotes the reproducing kernel for \mathcal{H}_1 evaluated at \mathbf{v}_j , the j^{th} element of V .

Obtaining the solution ϕ_λ

By the Representer Theorem, (2) becomes

$$-2\ell(c, d | \tilde{Y}, \tilde{B}, \tilde{K}_V) + \lambda J(\phi) = [\tilde{Y} - \tilde{B}d - \tilde{K}_V c]' [\tilde{Y} - \tilde{B}d - \tilde{K}_V c] + \lambda c' K_V c,$$

where

$$Y = (Y'_1, Y'_2, \dots, Y'_N)' = (y_{12}, y_{13}, \dots, y_{1p_1}, \dots, y_{N2}, \dots, y_{Np_N})',$$

$$D = \text{diag}(\sigma_{12}^2, \sigma_{13}^2, \dots, \sigma_{1p_1}^2, \dots, \sigma_{N2}^2, \dots, \sigma_{Np_N}^2)$$

$$X = [X'_1 \quad X'_2 \quad \dots \quad X'_N]'$$

X_i = $(p_i - 1) \times |V|$ matrix of AR covariates for Subject i ,

K_V = $|V| \times |V|$ matrix with (i, j) element $K_1(v_i, v_j)$

B = $|V| \times \mathcal{N}_0$ matrix with (i, j) element $\nu_j(v_i)$

and $\tilde{Y} = D^{-1/2}Y$, $\tilde{B} = D^{-1/2}XB$, $\tilde{K}_V = D^{-1/2}XK_V$.

Obtaining the solution ϕ_λ

Setting derivatives equal to zero, for fixed λ , c and d satisfy

$$\begin{bmatrix} \tilde{B}' \tilde{Y} \\ \tilde{K}'_v \tilde{Y} \end{bmatrix} = \underbrace{\begin{bmatrix} \tilde{B}' \tilde{B} & \tilde{B}' \tilde{K}_v \\ \tilde{K}'_v \tilde{B} & \tilde{K}'_v \tilde{K}_v + \lambda K_v \end{bmatrix}}_{C'C} \begin{bmatrix} d \\ c \end{bmatrix}$$
$$\implies \begin{bmatrix} \hat{d} \\ \hat{c} \end{bmatrix} = C^{-1}(C')^{-1} \begin{bmatrix} \tilde{B}' \\ \tilde{K}'_v \end{bmatrix} \tilde{Y}.$$

The fitted values are given by $\widehat{Y} = \tilde{A}_{\lambda, \theta} \tilde{Y}$, where the smoothing matrix is

$$\tilde{A}_{\lambda, \theta} = \begin{bmatrix} \tilde{B} & \tilde{K}_v \end{bmatrix} C^{-1}(C')^{-1} \begin{bmatrix} \tilde{B}' \\ \tilde{K}'_v \end{bmatrix}$$

and can be used to compute model selection criteria.

A RKHS Framework for $\log \sigma^2$

For fixed $\phi(\cdot)$, let $Z_i = (z_{i1}, \dots, z_{ip_i})'$, $z_{ij} = \epsilon_{ij}^2$, where

$$\epsilon_{ij} = y_{ij} - \sum_{k < j} \phi(\mathbf{v}_{ijk}) y_{ik}.$$

The log likelihood of the squared working innovations Z_1, \dots, Z_N coincides with a Gamma distribution with scale parameter $\alpha = 2$:

$$-2\ell(\sigma^2 | Z_1, \dots, Z_N) = \sum_{i=1}^N \sum_{j=1}^{p_i} \eta_{ij} + \sum_{i=1}^N \sum_{j=1}^{p_i} z_{ij} e^{-\eta_{ij}},$$

where $\eta_{ij} = \eta(t_{ij}) = \log \sigma^2(t_{ij})$.

A RKHS Framework for $\log \sigma^2$

Take the estimator of $\eta(t) = \log \sigma^2(t) \in \mathcal{H}$ to minimize

$$-2\ell(\eta|Z_1, \dots, Z_N) + \lambda J(\eta) = \sum_{i=1}^N \sum_{j=1}^{p_i} \eta(t_{ij}) + \sum_{i=1}^N \sum_{j=1}^{p_i} z_{ij} e^{-\eta(t_{ij})} + \lambda J(\eta).$$

Let $\mathcal{T} = \bigcup_{i,j} \{t_{ij}\}$. By Theorem I, the minimizer has the form

$$\eta_\lambda(t) = \sum_{i=1}^{\mathcal{N}_0} d_i \nu_i(t) + \sum_{j=1}^{|\mathcal{T}|} c_j K_1(t_j, t),$$

where $\{\nu_i\}$ span \mathcal{H}_0 , $K_1(t_j, t)$ is the RK for \mathcal{H}_1 evaluated at t_j , the j^{th} element of \mathcal{T} .

Simulation Studies

1. Simulations with complete data varying

- generating model Σ
- number of subjects $N = 50, 100$
- dimension $p = 10, 20, 30$

to compare performance to the oracle estimator, Polynomial MCD GLM
 $\hat{\Sigma}_{poly}$, the sample covariance matrix $S = [s_{ij}]$, Shrinkage estimators S^ω, S^λ

2. Simulations with unbalanced data to study robustness to missing or irregular data

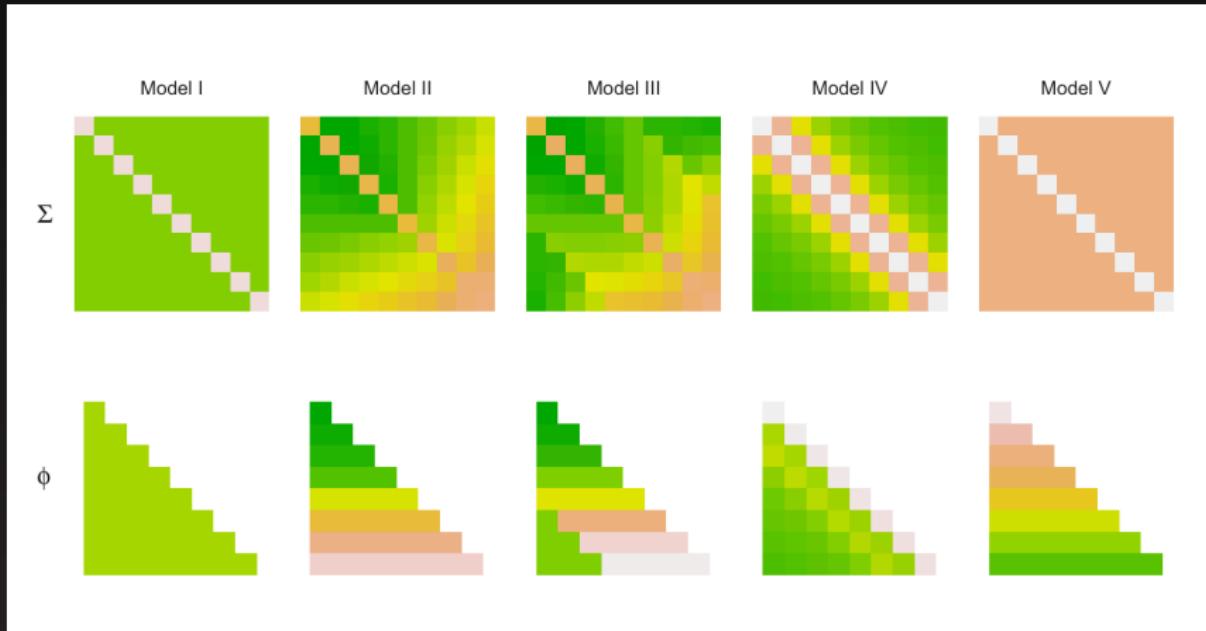
- generating model Σ
- dimension $p = 10, 20$
- proportion of missing data 10%, 20%, 30%

Use Monte Carlo simulation to estimate risk $R(\Sigma, \hat{\Sigma}) = E_\Sigma [\Delta(\Sigma, \hat{\Sigma})]$
under loss functions

$$\Delta_1(\Sigma, \hat{\Sigma}) = \text{tr} \left((\Sigma^{-1} \hat{\Sigma} - I)^2 \right), \quad \Delta_2(\Sigma, \hat{\Sigma}) = \text{tr} \left(\Sigma^{-1} \hat{\Sigma} \right) - \log |\Sigma^{-1} \hat{\Sigma}| - p$$

Simulation Studies

Data Generation Models



Simulation Studies

Data Generation Settings

I. $\Sigma = \mathbf{I}$

$$\phi(t, s) = 0, 0 \leq s < t \leq 1$$

$$\sigma^2(t) = 1, 0 \leq t \leq 1$$

II. $\Sigma = T^{-1}DT'^{-1}$

$$\phi(t, s) = t - \frac{1}{2}, 0 \leq t \leq 1$$

$$\sigma^2(t) = 0.1^2, 0 \leq t \leq 1$$

III. $\Sigma = T^{-1}DT'^{-1}$

$$\phi(t, s) = \begin{cases} t - \frac{1}{2}, & t - s \leq 0.5 \\ 0, & t - s > 0.5 \end{cases}$$

$$\sigma^2(t) = 0.1^2, 0 \leq t \leq 1$$

IV. $\Sigma = [\sigma_{ij}]$

$$\sigma_{ij} = \left(1 + \frac{(t_i - t_j)^2}{2k^2}\right)^{-1}$$

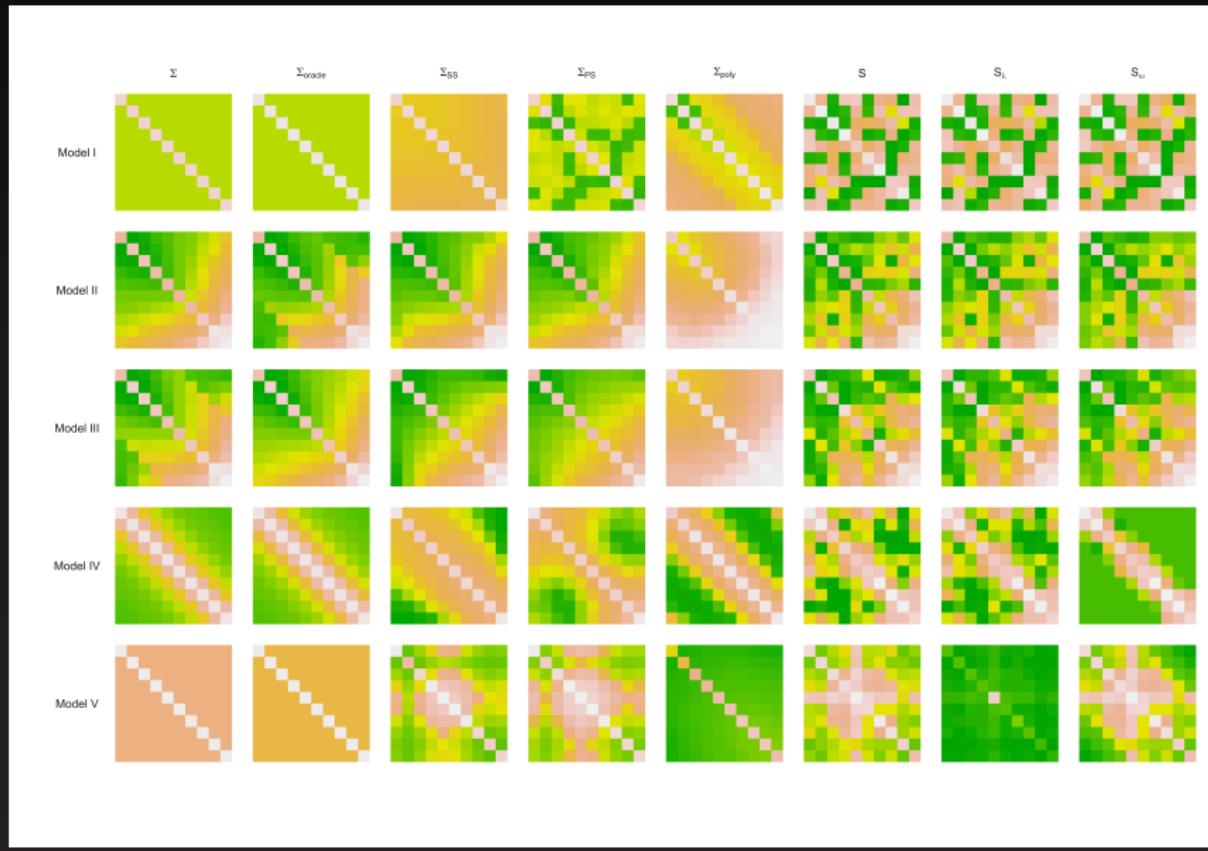
$$k = 0.6, 0 < t_i, t_j < 1$$

V. $\Sigma = \rho \mathbf{J} + (1 - \rho) \mathbf{I}$,
 $\rho = 0.7$

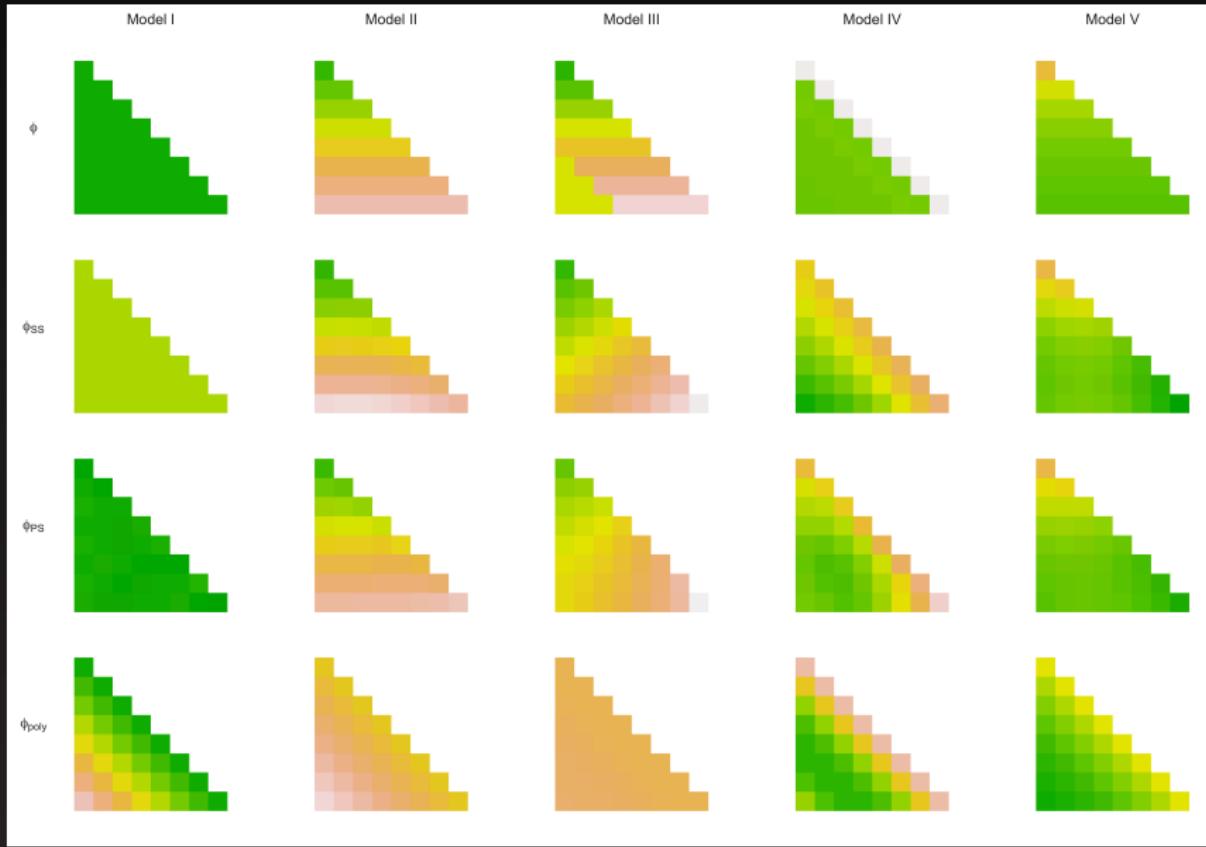
$$\phi(t, s) = \frac{\rho}{1 + (t-2)\rho}, t = 2, \dots, p$$

$$\sigma^2(t) = 1 - \frac{(\max(t, 2) - 2)\rho^2}{1 + (\max(t, 2) - 2)\rho}$$

Simulation Studies

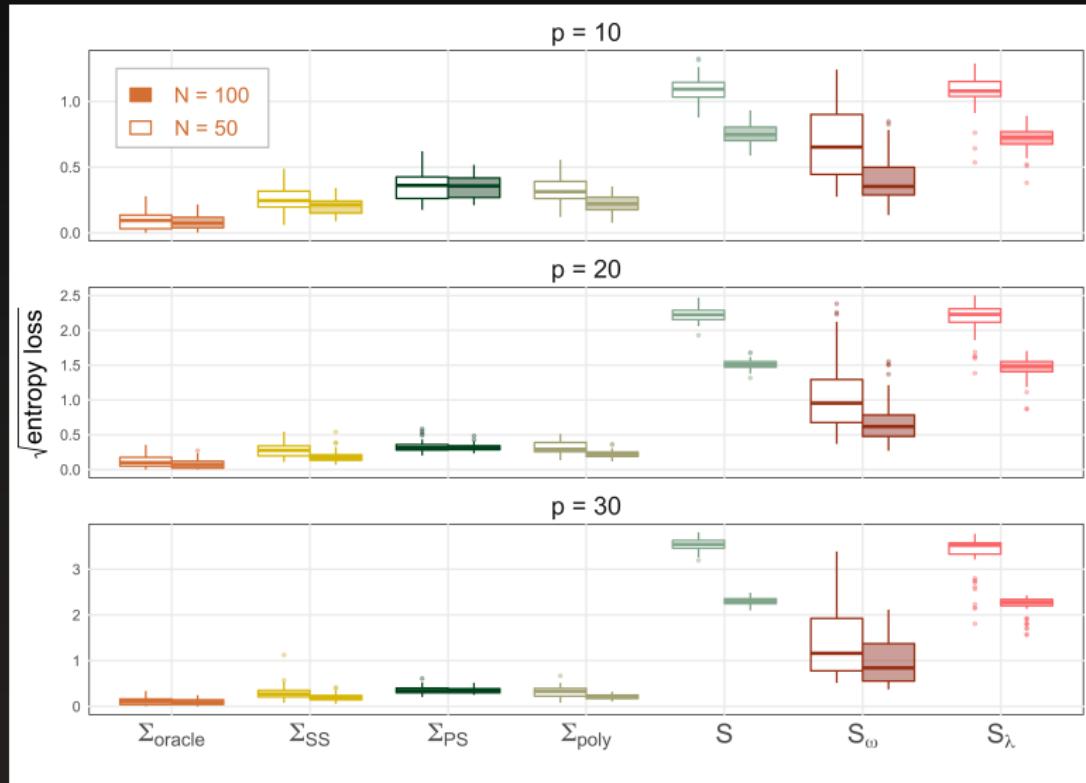


Simulation Studies



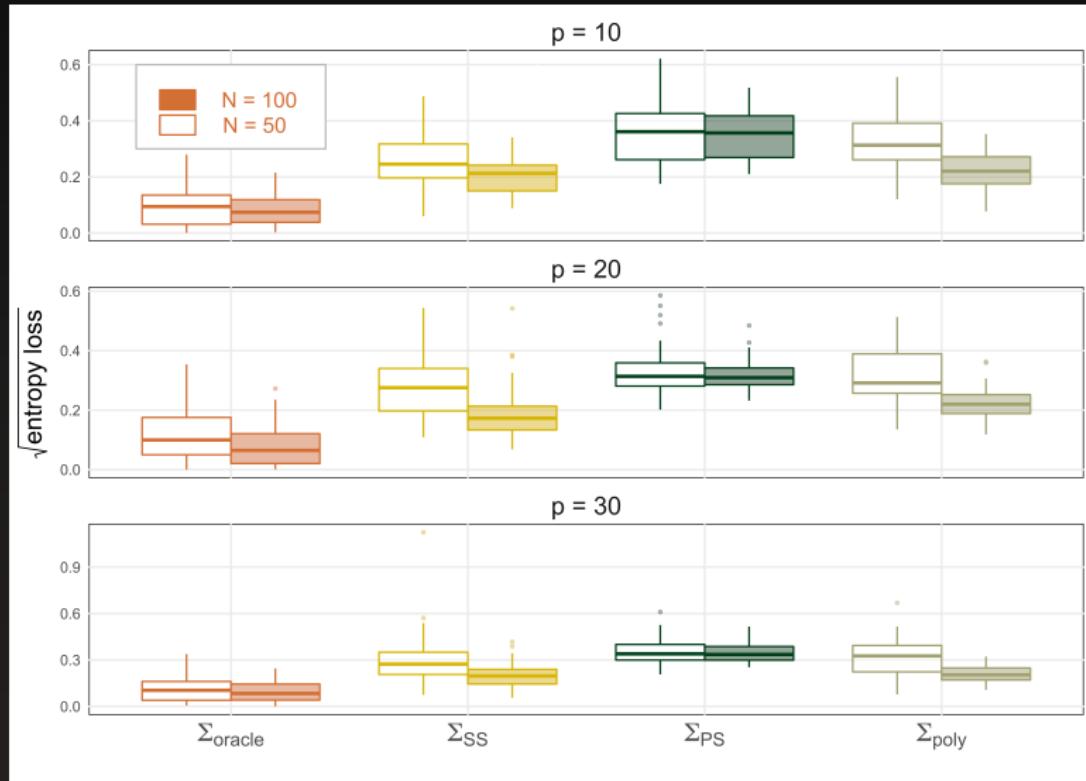
Simulation Studies

Results with complete data: Model I



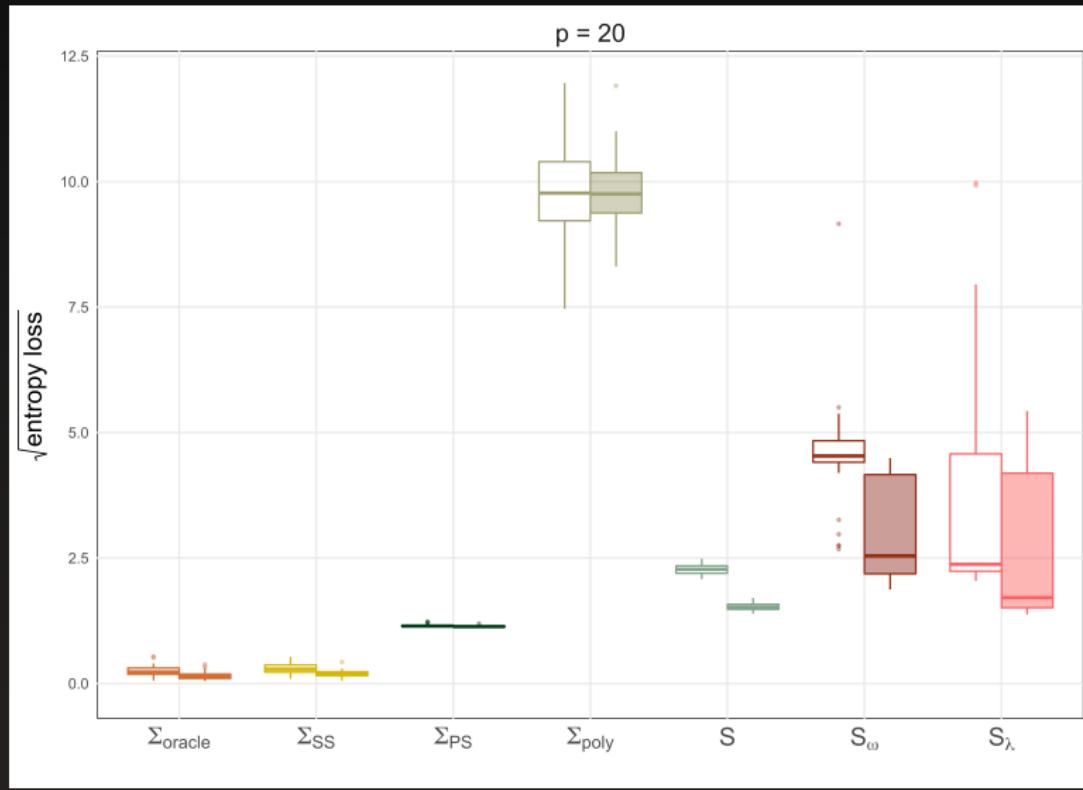
Simulation Studies

Results with complete data: Model I



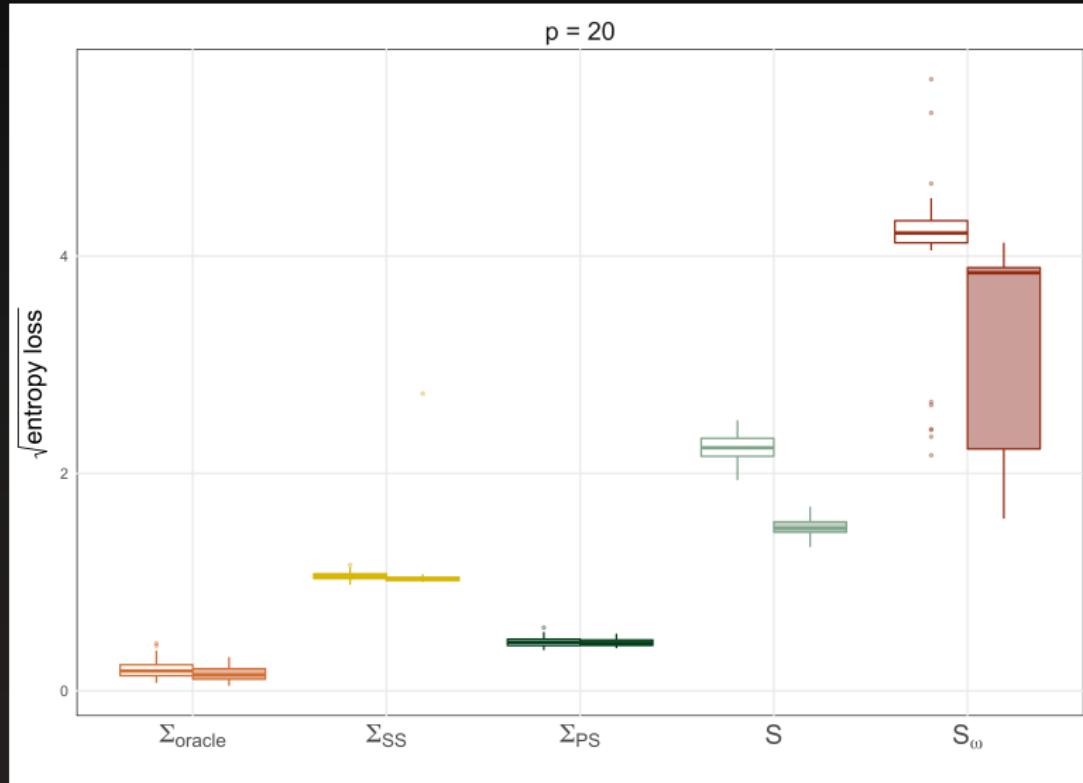
Simulation Studies

Results with complete data: Model II



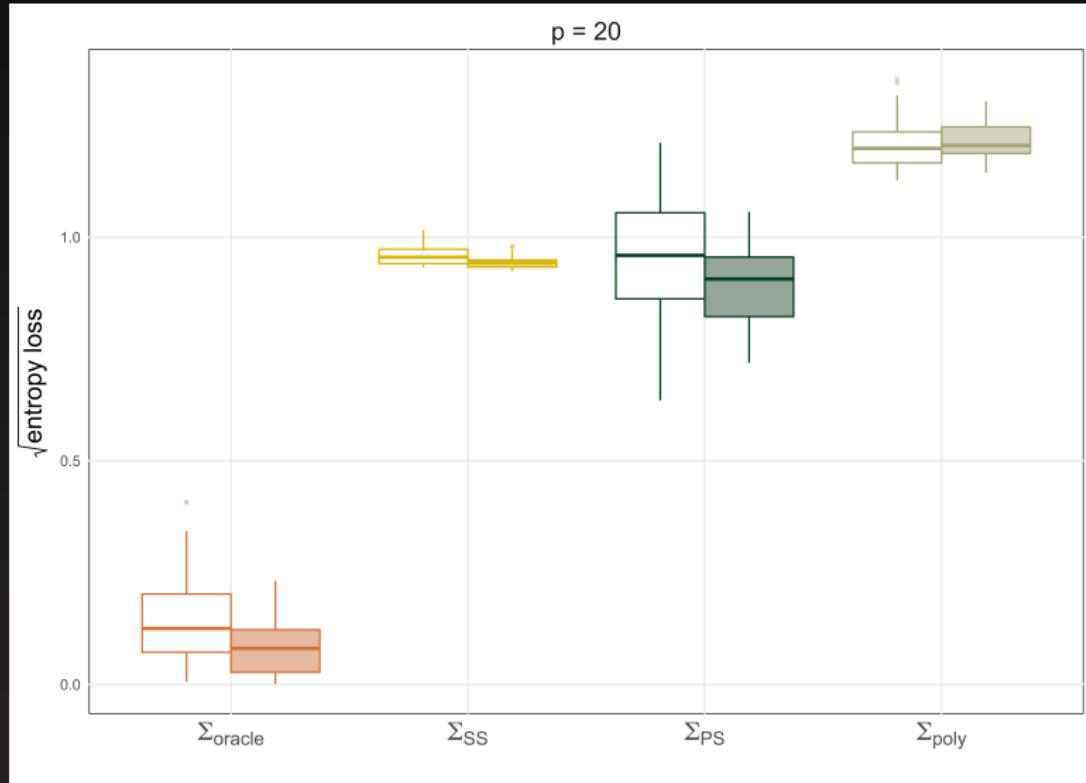
Simulation Studies

Results with complete data: Model III



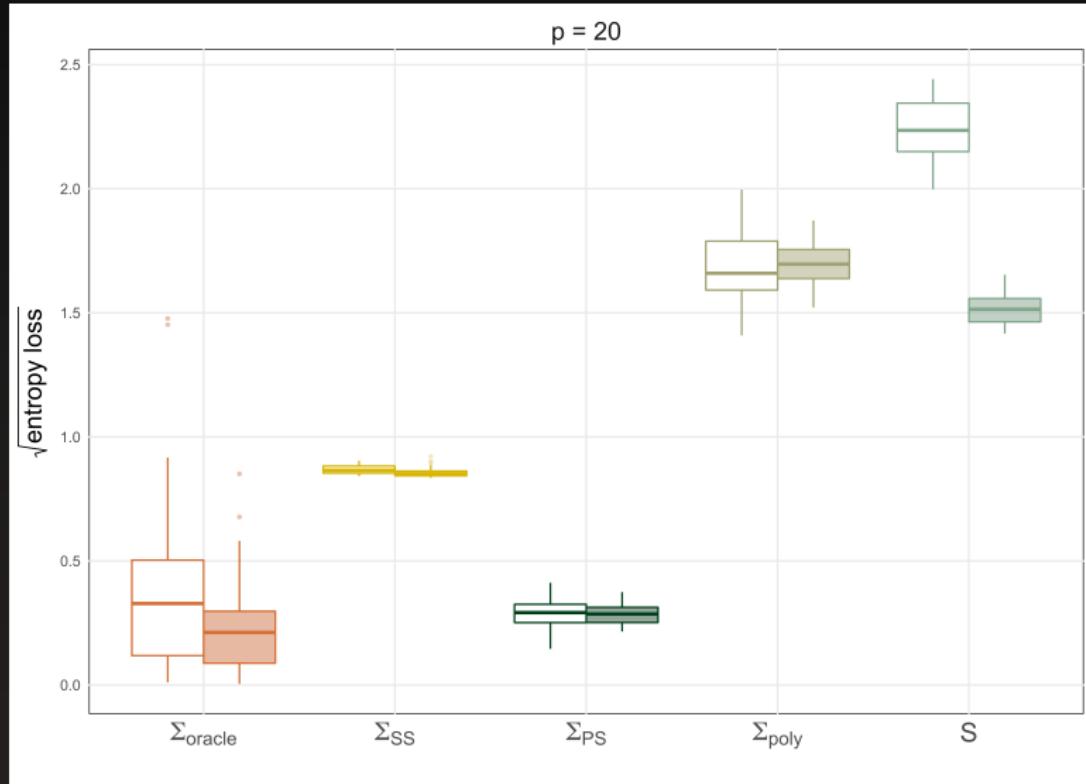
Simulation Studies

Results with complete data: Model IV



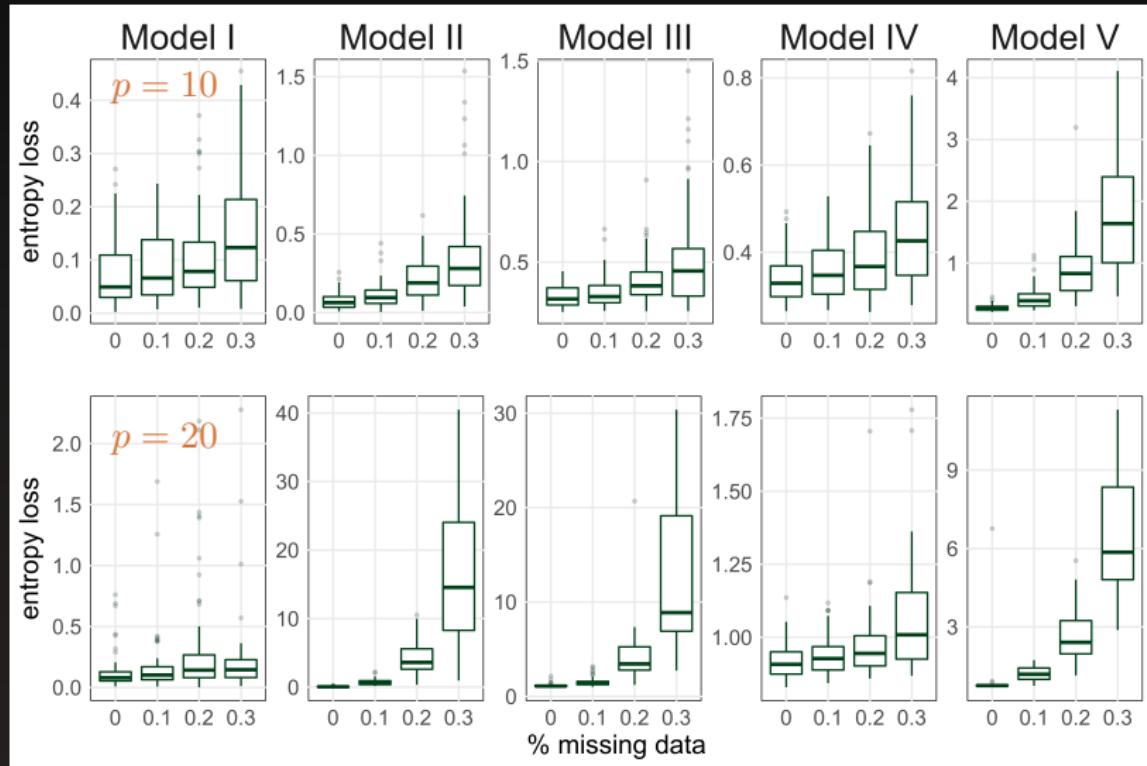
Simulation Studies

Results with complete data: Model V



Simulation Studies

Results with incomplete data, $N = 50$



Thank you!

For additional detail, writing, code, or questions, you can find me here:

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Parametric Models for the Cholesky Decomposition

Pourahmadi (2000), Pan and Mackenzie (2003) suggest modeling ϕ_{tj} , σ_t^2 with covariates, letting

$$\begin{aligned}\phi_{jk} &= x'_{jk} \gamma \\ \log \sigma_j^2 &= z'_j \lambda.\end{aligned}$$

Common choices for the covariates x_{jk} and z_j are

$$\begin{aligned}x'_{jk} &= (1, t_j - t_k, (t_j - t_k)^2, \dots, (t_j - t_k)^{d-1})', \\ z'_j &= (1, t_j, \dots, t_j^{q-1}).\end{aligned}$$

Polynomial orders d and q are tuning parameters chosen by a model selection criterion (BIC, AIC).

Applying Elementwise Shrinkage to S

Tapering Estimators

- **The Banded Sample Covariance Matrix**

$$B_k(S) = [s_{ij} \mathbf{1}(|i - j| \leq k)] = R_B * S, \quad 0 < k < p.$$

- **The Tapered Sample Covariance Matrix**

$$S^\omega = [\omega_{ij}^k s_{ij}] ,$$

where $0 < k < p$, and if $k_h = k/2$

$$\omega_{ij}^k = k_h^{-1} [(k - |i - j|)_+ - (k_h - |i - j|)_+] .$$

- **Soft Thresholding Estimator:**

$$S^\lambda = [\mathbf{sign}(s_{ij})(s_{ij} - \lambda)_+]$$

» Simulations