Decentralised location verification system

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B.A.(Mod.) Computer Science Final Year Project, April 2016 Supervisor: Stephen Barrett

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Goals:

▶ False location claims must be detectable.

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- ▶ False location claims must be detectable.
- Privacy protecting.
- Cannot rely on any centralised resources.
- Capable of running in the background on mobile devices.

Background

There are **no** known existing decentralised location proof systems.

Existing centralised solutions: hardware and/or software

3 distinct entities:

- ► Mobile node
- ► Miner node M
- ▶ Verifier node



Mobile node

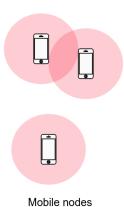


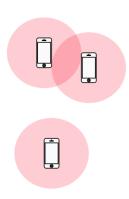
Mobile node



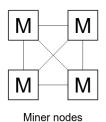


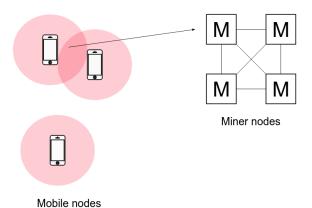
Mobile nodes

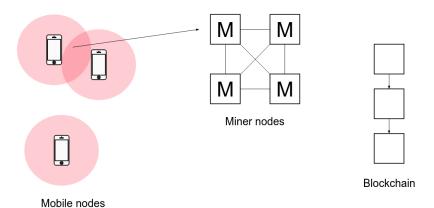


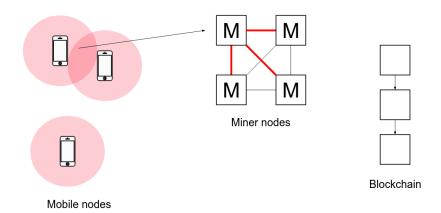


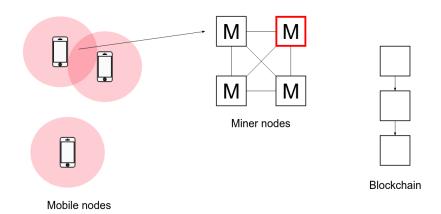
Mobile nodes

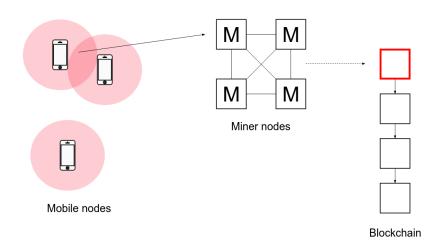


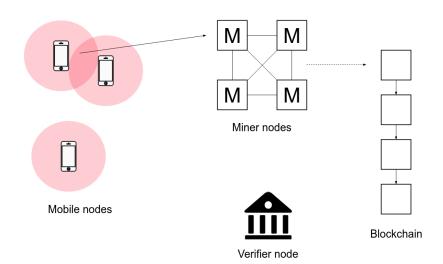


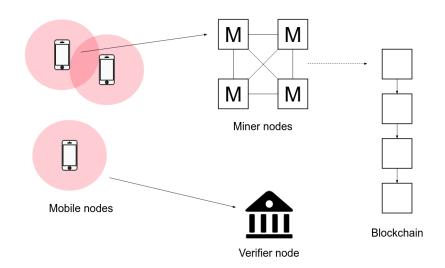


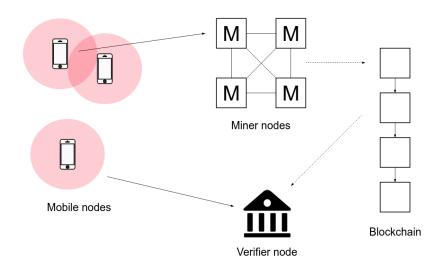


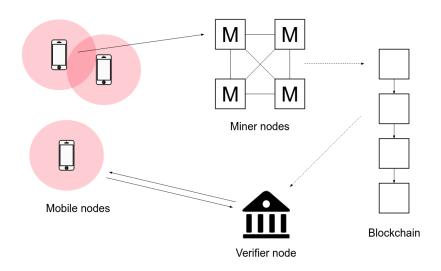












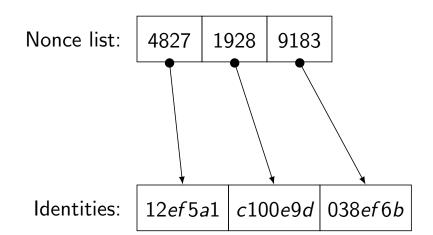
Design Identities

Used to anonymously identify a node in a transaction.

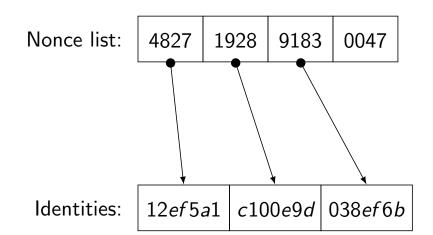
Balancing goals:

- ► False location claims must be detectable.
- Privacy protecting.

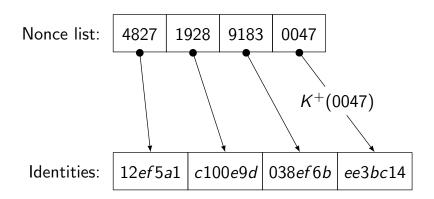
Identities: Nonce Lists



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Identities: Duplication

Identity duplication is unavoidable in a decentralised system.

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ID	Contents
ffa0	
ffa1	
ffa2	T_{A4}
ffa3	
ffa4	T _{B87}

Identities: Duplication

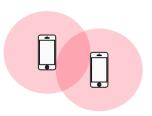
Identity duplication is unavoidable in a decentralised system.

ID	Contents	
ffa0		
ffa1		
ffa2	T_{A4} , T_{C102}	
ffa3		
ffa4	T _{B87}	

Design Transactions

Transactions are created when two mobile nodes physically meet.

▶ Ad-hoc bluetooth connection between the nodes.



Design Transactions II

Node A

Transactions II

n

Node A

m

Transactions II

m

Transactions II

Node A $\mathcal{K}_A^+, \mathcal{K}_A^ \mathcal{N}L_A$

Mode B

Transactions II

n Node A Node B $K_A^+, K_A^ NL_A$ $ID_{An} = K_A^+(NL_A[n])$

Transactions II

nNode A K_A^+ , $K_A^ NL_A$ ID_{An} ts_A

m

Transactions II

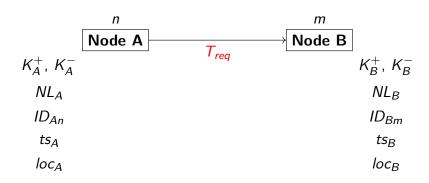
n Node A K_A^+ , $K_A^ NL_A$ ID_{An} ts_A loc_A

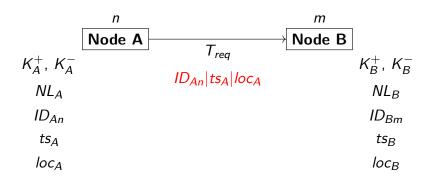
m

Transactions II

	n	
	Node A	
K_A^+ , K_A^-		
$NL_{\mathcal{A}}$		
ID_{An}		
$ts_{\mathcal{A}}$		
loc_A		

 $egin{aligned} egin{aligned} egin{aligned} egin{aligned} K_B^+,\ K_B^- \ NL_B \ ID_{Bm} \ ts_B \ Ioc_B \end{aligned}$

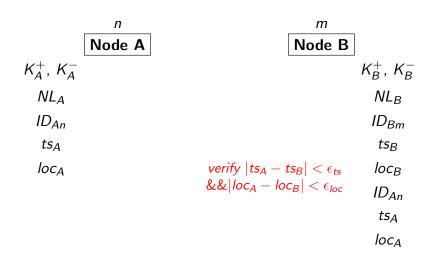


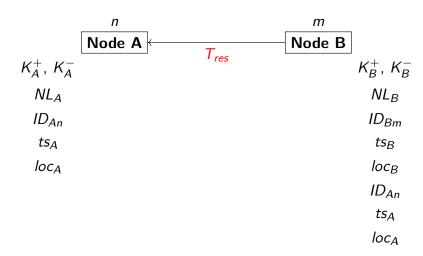


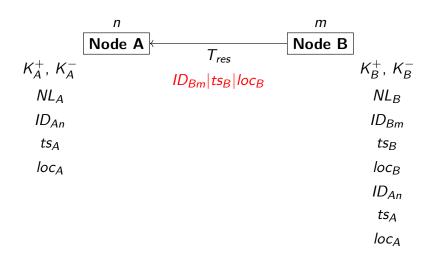
Transactions II

NNode A K_A^+ , $K_A^ NL_A$ ID_{An} ts_A loc_A

m Node B K_B^+ , $K_B^ NL_B$ ID_{Bm} ts_B loc_B ID_{An} ts_A loc_A







Transactions II

	n Node A
K_A^+ , K_A^-	
NL_A	
ID_{An}	
$ts_{\mathcal{A}}$	
loc_A	
ID_{Bm}	
ts_B	
loc_B	

m Node B $K_B^+, K_B^ NL_B$ ID_{Bm} ts_B loc_B ID_{An} ts_A loc_A

	n	<i>m</i>
	Node A	Node B
K_A^+ , K_A^-		K_B^+ , K_B^-
$NL_{\mathcal{A}}$		NL_B
ID_{An}		ID_{Bm}
$ts_{\mathcal{A}}$		ts _B
loc_A	verify $ ts_A - ts_B < \epsilon_{ts}$	loc_B
ID_{Bm}	$\&\& loc_A - loc_B < \epsilon_{loc}$	ID_{An}
ts_B		$ts_{\mathcal{A}}$
loc_B		loc_A