Structure from Motion in Mojo

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"Feels like Python, runs like C"

Mojo is a statically-typed (read: fast) language that aims to be a *superset* of python (read: easy)

It attempts solve the two-language problem.

Project Goal:

- 1. Evaluate Mojo's claims on CV problems
- 2. Reimplement SfM in a straightforward manner for others.

```
@value
@register passable("trivial")
struct Landmark:
    var val: mc.Vector3d
   @always inline
    @staticmethod
    fn dim() -> Int:
        return 3
    @always inline
    @staticmethod
    fn identity() -> Self:
        return Self {val: mc.Vector3d(0, 0, 0, 0)}
    fn invert (self) -> Self:
        return Self(-self.val)
    fn inv(self) -> Self:
        return ~self
```

Mojo Pros

SPEED

REPL

Static Executable Generation

```
(moca) tpool@taylor-dell-laptop:~/mojo_ws/tmp$ mojo build main.mojo
(moca) tpool@taylor-dell-laptop:~/mojo_ws/tmp$ ls
main main.mojo
(moca) tpool@taylor-dell-laptop:~/mojo_ws/tmp$ ./main
Hello, World!
```

Python Interop/Similar Syntax

```
from python import Python

def main():
    np = Python.import_module("numpy")
    x = np.arange(4)
    y = np.ones_like(x)
    z = np.matmul(x, y)
    print(z)
```

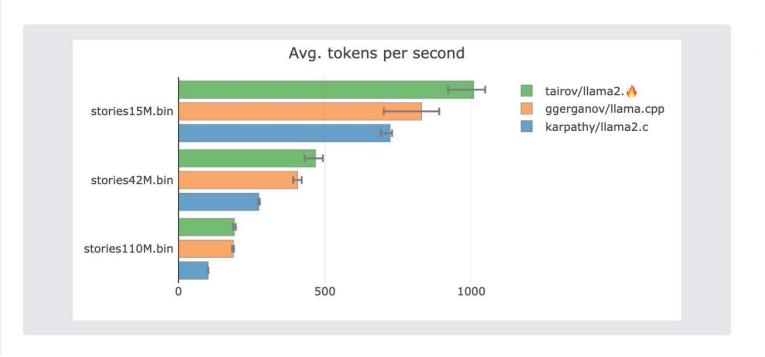
Missing in Mojo

- Static Inheritance
- Borrow Checker
- Set/Dictionary
- Linear Algebra
- No package manager

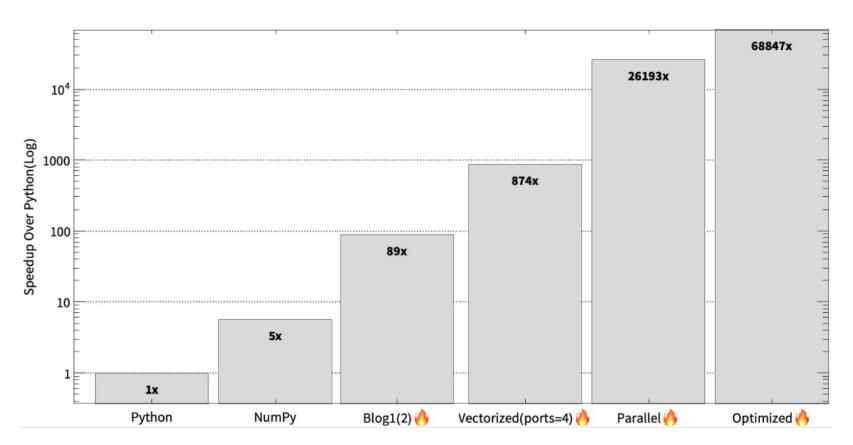
```
value
     struct Set[type: AnyType, hash: fn (type) -> Int]:
         var n: Int
         var elements: DynamicVector[type]
         var exists: Tensor[DType.bool]
         fn init (inout self, n: Int):
             self.n = n
             self.elements = DynamicVector[type](n)
             self.exists = Tensor[DType.bool](n)
         fn add(inout self, x: type):
12
13
             let e = hash(x)
             if self.exists[e]:
                 return
             else:
                 self.elements.push back(x)
17
                 self.exists[e] = True
         fn contains(self, x: type) -> Bool:
             let e = hash(x)
21
             return self.exists[e]
```

Benchmarks - Llama2 (Others)

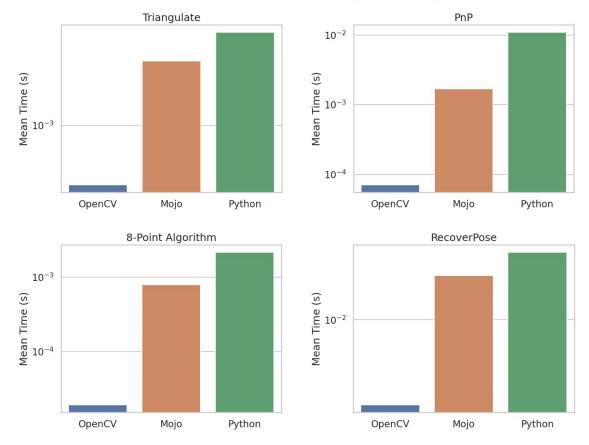
Llama2 Inference on Mac M1 Max, multi-threaded / CPU-only



Benchmarks - Mandelbrot (Others)



Benchmarks - Computer Vision (Ours)



Benchmarks - Interpretations

Why weren't we seeing such large improvements?

Naive linear algebra implementations

Our Structure from Motion Implementation

Used COLMAP for scene graph generation

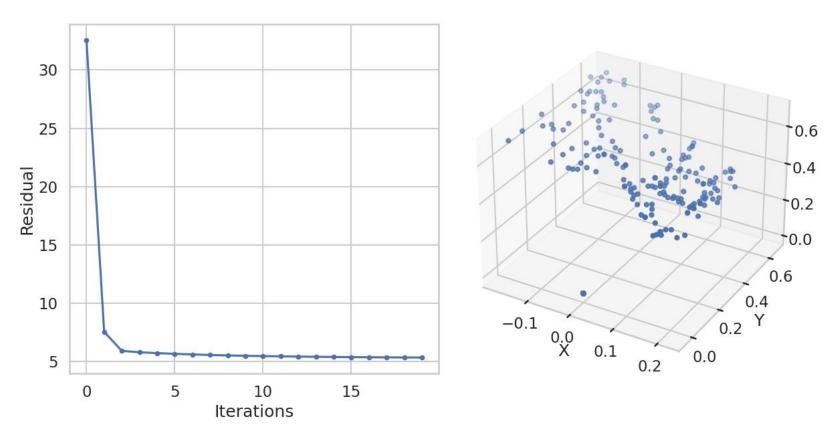
Our backend implementation includes:

- SE3 / SO3 implementation
- Basic linear algebra library
- CV estimation functions
 - Fundamental & essential matrix, PnP, triangulation
- Levenberg-Marquardt
- All necessary bookkeeping for SfM (nontrivial!)
- Full test coverage of all systems



taylorpool/moca

Preliminary Results



Key Takeaways

Mojo isn't ready for primetime... yet. However,

- It really is easier & faster to code in than C++
- You can import any python code, but interoperability with python objects is difficult at the moment
- Eventually may be a better option than rather a split C++/Python codebase

Also

SfM bookkeeping is hard. Like, really nontrivial.