1	25/2	4/3	11/3	18/	/3 2	5/3	1/4	8/4	15/4	22/-	29/4	6	/5 <i>'</i>	13/5	20/5	27/	5 3	/6	10/6	17/6	24/	6 1/	/7 	8/7	15/7	22	/7 2	29/7	5/8	12/8	19/	3 26	6/8 2	2/9	9/9	16/9	23/9	30/	9 7/	10 14	1/10 2 ⁻	1/10 2	8/10	4/11	11/11	18/1	25/1
Create Report & Initial Research																																															
Create CubeMX Project																																															
Begin C++ Project																																															
Design Muscle Mounts																	ł																														
Order 2 Muscle Components																																															
Build Single Muscle																																															
Perform Pressure Tests																																															
Design Electronic Valve Control																																															
Build Single Muscle with Mount																																															
Research Muscle Models																	ļ																														
Calculate Muscle Parameters	1																																														
Research PID Controller	1																i																														
Implement Simple PID for Testing	1																į																														
Evauate Performance of PID Controller	1																ļ																														
Research MPC Controller	1																																														
Design MPC for Muscle System	1																																														
Implement MPC for Muscle System	1																į																														
Tune MPC	1																																														
Evaluate Performance of MPC Controller	1																																														
Design Ankle Muscle Setup	1																																														
Build Ankle Muscle Setup	1																į																														
Implement Multi Muscle Control	1																																														
Risk Assesment	1																																														
Interim Report	1																																														
Interim Presentation	1																																														
Final Report	1																į																														
Final Presentation	1																ļ																														
Robocup	1																ļ																														