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Fanuc Robot LR Mate, High Performance Type Teach Pendant, Operators Manual, Language ENGLISH, Pages 339, B-80204E/01, X2 Fanuc Robot LR Mate 100, 100I & 120I Series (R-J2 Mate Controller) LR Tool, Setup and Operations Manual, Language ENGLISH, Pages 601, B-80694EN-11/01, X1

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section presents safety precautions related to the handling of machine tools. Before attempting to

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OPERATOR'S MANUAL - i-Logic

tool, the machine itself, the workpiece, or cause injury to the operator. 2 Manual reference position return After switching on the power, perform manual reference position return as required. If the machine is operated without first performing manual reference position return, it may behave unexpectedly. Stroke check is not possible before manual

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Model Specifications Motion range (Maximum speed) Note 1) During short distance motions, the axis speed may not reach the maximum value stated. Note 2) Angle mounting needs J1 and J2 axis motion range restriction according with the payload, except for LR Mate 200iD/4S, /4SC and /4SH. Note 3\(\text{O}\)Compliant with ISO9283.

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