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Contents 11 9.4 EquivalentGainAnalysisUsing Frequency Response: DescribingFunctions 678 9.4.1

Stability Analysis Using Describing Functions 685 A 9.5 Analysis and Design Based on Stability 690
9.5.1 The Phase Plane 690 9.5.2 Lyapunov Stability Analysis 697 9.5.3 The Circle Criterion 703 9.6
Historical Perspective 710 Summary 711 Review Questions 711 Problems 712 10
Control System Design: Principles and Case

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FEEDBACK EXAMPLES 5. dynamics in the system (parameter errors, unmodeled effects, etc). The algorithm that computes the control action as a function of the sensor values is often called a control law. The system can be influenced externally by an operator who introduces command signals to the system.

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Feedback Control of Dynamic Systems. Yves Briere yves.briere@isae.fr I. Introduction Introduction • Aim of the course – Give a general overview of classical and modern control theory – Give a general overview of modern control tools

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PID feedback control. The field of control theory can be divided into two branches: Linear control theory – This applies to systems made of devices which obey the superposition principle, which means roughly that the output is proportional to the input. They are governed by linear differential equations.

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