

# Shared Frailty Models

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Frailty Models: Theory & Practice  
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**Shared frailty models**

**Recurrent events**

**Estimation**

**Software overview**

# Shared frailty models

# Dependence structures

In time-to-event data, dependence between observations may arise from:

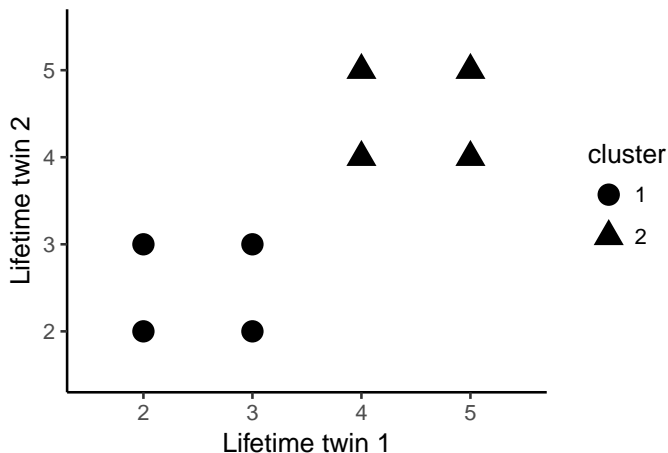
- ▶ Common events (several events happening at the same time)
  - ▶ competing risks, multi-state models
- ▶ Common (unobserved) risk (e.g. hidden covariates, genetics)
  - ▶ (shared) frailty models
- ▶ Event-related dependence (e.g. one infection may lead to more infections)
  - ▶ time-dependent covariates

The goal of a model is to be *biologically plausible*.

# Common risk

- ▶ Unobserved latent factors that are constant in time may affect lifetimes
- ▶ Conditional on the common risk factors, we may assume that observations are independent
- ▶ Since they are unobserved, they are treated as random
- ▶ An event within a cluster does not change the risk, but it changes our **knowledge** about the risk

# Common risk



# Event-related dependence

## Events might changes future risk

- ▶ lose one kidney, this might shorten the life of the second kidney
- ▶ after a car accident, it is likely that the driver is more careful
- ▶ one myocardial infarction might lead to a more healthy lifestyle

# Event-related dependence

## Events might changes future risk

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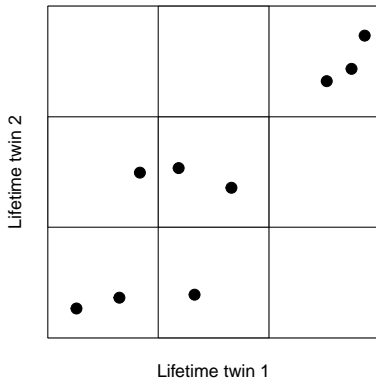
## More often, mixed causes

- ▶ bad driving skills are an increased risk (common risk), but an accident decreases future risk (event-related dependence)
- ▶ infections: infection decreases future risk for an individual but increases the risk for other individuals from the same family

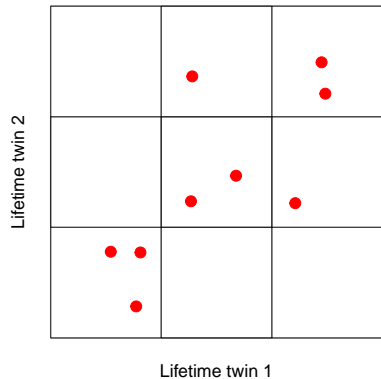


# Timing of dependence

Late dependence

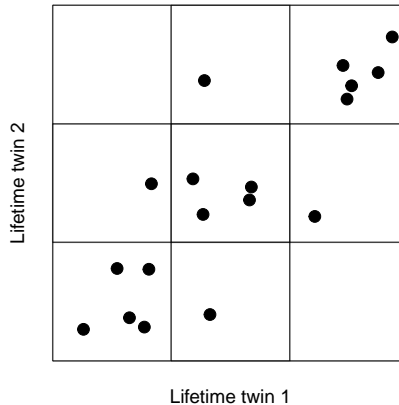


Early dependence



# Timing of dependence

Overall dependence



## About shared frailty

Shared frailty models are models for **common risk**.

- ▶ usually clustered failures and recurrent events data
- ▶ The frailty  $Z_i$  is said to be *shared* between the observations of cluster or individual  $i$
- ▶ Dependence within group  $i$  is induced by sharing  $Z_i$
- ▶ If  $Z_i$ 's show no variation, then the observations are independent

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### Points of interest

- ▶ How different are the clusters? (variability of  $Z$ )
- ▶ Regression coefficients (when dependence is just a nuisance)
- ▶ Prediction for a group after some events have been observed

# Clustered failures

Cluster  $i$ , observation  $j$ : hazard  $h_{ij}(t)$ .

## Approaches

- ▶ Stratify on the cluster (each cluster has a different baseline hazard)
- ▶ Add a fixed effect for each cluster (proportional hazards)
- ▶ Add a random effect for each cluster (*shared* frailty model)
- ▶ Try to avoid the correlation structure (*marginal* models)

# Fixed effects & stratification

**Fixed effects (FE) model:**

$$h_{ij}(t) = h_0(t) \exp(\beta^\top x_{ij} + \zeta_i)$$

with  $\zeta_1 = 0$  or **stratified (S) model:**

$$h_{ij}(t) = h_i(t) \exp(\beta^\top x_{ij})$$

- In (FE) the hypothesis of no heterogeneity is  $H_0 : \zeta_2 = \zeta_3 = \dots = \zeta_I = 0$ .

# Clustered failures

Problems:

- ▶ **(FE)** Must assume that number of individuals / group grows to  $\infty$  for the asymptotics to work (in linear models we use exact sum of squares for small samples for this reason)
- ▶ **(FE + S)** Cannot use covariates that are constant within groups
- ▶ **(FE & S)** Cannot quantify the strength of the dependence
- ▶ **(S)** Loss of information: Need more *events* / group in order to estimate  $h_i(t)$ ; otherwise, it is difficult to distinguish cluster effects from hazard effects.

Works well when cluster sizes are large, such as hospitals in multicenter studies (Hein will talk later about that).

# Clustered failures

Random effects model:

$$h_{ij}(t|Z_i) = h_0(t)Z_i \exp(\beta^\top x_{ij})$$

Here:

- ▶ clusters are a random sample from a population (of clusters)
- ▶ parameters of  $Z_i$  describe variation *between* clusters
- ▶ the hypothesis of no variation may be based on testing  $\text{Var}Z_i = 0$  (or  $Z_i$  having a degenerate distribution with  $P(Z_i = 1) = 1$ )
- ▶ only positive dependence within cluster



## Joint survivor function

Assume that there are  $J_i$  individuals  $j \in \{1, 2, \dots, J_i\}$  from the same cluster  $i$ , with conditional hazards

$$h_{ij}(t|Z_i) = Z_i h_{ij}(t)$$

and cumulative hazards

$$H_{ij}(t|Z_i) = Z_i \int_0^t h_{ij}(s) ds.$$

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The **joint survivor function** may be written as

$$S(t_1, \dots, t_{J_i}|Z) = P(T_{i1} > t_1, \dots, T_{iJ_i} > t_{J_i}|Z)$$

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$$S(t_1, \dots, t_{J_i}|Z) = \exp(-Z(H_{i1}(t_1) + \dots + H_{iJ_i}(t_{J_i})))$$

## Joint survivor function

The marginal joint survivor function is then:

$$\bar{S}(t_1, \dots, t_{J_i}) = E[\exp(-Z(H_{i1}(t_1) + \dots + H_{iJ_i}(t_{J_i})))]$$

## Joint survivor function

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- ▶ the likelihood contribution of cluster  $i$  is equal to the joint density of  $(T_{i1} \dots T_{iJ_i})$
- ▶ For a positive random variable,  $S(t) = P(X \geq t)$ ; the density is  $P(T = t) = \frac{d}{dt}S(t)$ .
- ▶ Assuming no censoring, the marginal density for times  $t_1, \dots, t_{J_i}$ :

$$f(t_1, \dots, t_{J_i}) = \frac{\partial^{J_i}}{\partial t_1 \dots \partial t_{J_i}} \bar{S}(t_1, \dots, t_{J_i})$$

# Likelihood

With censoring, the partial derivatives are taken only at *event* time points. Denote  $D_j = 1$  if  $t_j$  is an event. Then the marginal density of the *observed* event time points is:

$$f(t_1 \dots t_{J_i}; D_1 \dots D_{J_i}) = (-1)^{D \cdot} \prod_j h_j(t_j)^{D_j} \mathcal{L}^{(D \cdot)}(H_1(t_1) + \dots + H_{iJ_i}(t_{J_i}))$$

- ▶ Individual hazards contribute at event time points.
- ▶ The censored observations contribute to the total cumulative hazard, that is in the Laplace transform argument.

# Quantifying dependence

An identifiability assumption is made for the frailty distribution (usually,  $E[Z] = 1$ ).

## Different measures<sup>1</sup>

- ▶ the variability of  $Z$  (e.g.  $\text{Var}[Z]$  - most popular, or  $\text{Var}[\log Z]$ )
  - ▶  $\text{Var}[Z]$  - most popular, or  $\text{Var}[\log Z]$
- ▶ correlation-type measure
  - ▶ bivariate measures such as Kendall's  $\tau$  or median concordance
- ▶ the predicted survival or cumulative hazard
  - ▶ difficult to visualize for more than a few clusters

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<sup>1</sup>Hougaard (2000)

## General notes

- ▶ Early or late dependence? This is where different distributions for  $Z$  play a role
  - ▶ Gamma frailty emphasizes late dependence
  - ▶ Positive stable emphasizes early dependence
  - ▶ log-normal / inverse Gaussian somewhere in between

## Covariates

- ▶ covariates should usually be included, since the frailty explains unobserved variance due to common sources
- ▶ cluster-specific take out from the between-cluster (frailty) variation
- ▶ When cluster sizes are small (e.g. of size 2), marginal non-proportional hazards may appear as frailty! (as we saw in the univariate frailty case)



# Goodness-of-fit

## Likelihood ratio test

- ▶ Under no frailty (i.e. frailty variance 0) the limiting model is a Cox model
- ▶ The likelihood ratio test (LRT) can be used to test the null hypothesis  $H_0 : \text{Var}[Z] = 0$  vs  $H_A : \text{Var}[Z] > 0$
- ▶ Because the hypothesis is one sided, the asymptotic distribution of the likelihood ratio statistic follows a  $\frac{1}{2}\chi^2(1) + \frac{1}{2}\chi^2(0)$

## Commenges-Andersen score test

- ▶ A score test based on martingale residuals for  $H_0 : \text{Var}[Z] = 0$  was proposed by Commenges and Andersen (1995).
- ▶ implemented in frailtyEM

# Marginal modeling

## The coordinate-wise approach

- ▶ stratified Cox proportional hazards model with strata 1 the first observation from each cluster, strata 2 the second observation from each cluster, etc
- ▶ strata by covariate interaction
- ▶ for example: the Wei-Lin-Weissfeld (WLW) model for recurrent events data
- ▶ heavy assumptions on the censoring, not model based

# Marginal modeling

## The coordinate-wise approach

- ▶ stratified Cox proportional hazards model with strata 1 the first observation from each cluster, strata 2 the second observation from each cluster, etc
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## The working independence approach

- ▶ assume proportional hazards on the marginal hazards
- ▶ neglect dependence and fit a Cox proportional hazards model
- ▶ obtain standard errors from a sandwich estimator

# Recurrent events

# Models

Consider  $\lambda_i$  the *intensity* of a process that generates recurrent events. Specification is the same as the hazard:

$$\lambda_i(t|Z_i) = \lambda_0(t)Z_i \exp(\beta^\top x_i)$$

## Calendar time

- ▶ time origin: time since the start of the recurrent events process
- ▶ Conditional on  $Z_i$ , individual  $i$  is describe by a Poisson process
- ▶ also known as Andersen-Gill formulation

## Gap time

- ▶ time origin: time since previous event
- ▶ Conditional on  $Z_i$ , individual  $i$  is described by a renewal process

## Recurrent events representation

tstart	tstop	gap	event
0	1	1	1
1	3	2	1
3	7	4	0

```
Surv(tstart, tstop, event) # calendar time
```

```
[1] (0,1] (1,3] (3,7+]
```

```
Surv(gap, event) # gap time
```

```
[1] 1 2 4+
```

# Recurrent vs clusters

## Similarities

- ▶ the construction of the likelihood and estimation are technically the same as in the cluster case

## Differences

- ▶ the frailty represents *within-individual* homogeneity and *between-individual* heterogeneity
- ▶ event-related dependence can be accommodated using time-dependent covariates (e.g. time since previous event, number of previous events)<sup>2</sup>
- ▶ time aspect not as straight forward as before

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<sup>2</sup>Cook & Lawless (2007)

# Estimation



## Likelihood construction

The goal is to maximize the **observed data** likelihood (the marginal likelihood). The marginal contribution of an individual can be obtained by taking derivatives of the marginal survivor function:

$$\begin{aligned} L_i &= (-1)^{D_{i.}} \prod_j h_{ij}(t_{ij})^{D_{ij}} \mathcal{L}^{(D_{i.})}(H_{i1}(t_{i1}) + \dots H_{in_i}(t_{in_i})) \\ &= (-1)^{D_{i.}} \prod_j h_{ij}(t_{ij})^{D_{ij}} \mathcal{L}^{(D_{i.})}(H_{i.}) \end{aligned}$$

This can't be estimated directly because:

- ▶ the derivatives of the Laplace transform are usually difficult to calculate (except for the gamma frailty)
- ▶ the hazard involves one parameter at every event time point in the data

# EM Algorithm

The marginal likelihood can be written as

$$P(\text{data}_i) = \int_{\theta} P(\text{data}_i | Z_i) f_{\theta}(Z_i) dZ_i$$

The “complete data likelihood” is

$$P(\text{data}_i | Z_i) f_{\theta}(Z_i)$$

## Empirical Bayes estimates

The “posterior” distribution of  $Z_i$  can be obtained from Bayes’ theorem:

$$f(Z_i|\text{data}_i) = \frac{P(\text{data}_i|Z_i)f(Z_i)}{P(\text{data}_i)}$$

By replacing with the Laplace transforms, we obtain that

$$E[Z_i|\text{data}_i] = -\frac{\mathcal{L}^{(D_i+1)}(H_{i\cdot})}{\mathcal{L}^{(D_i)}(H_{i\cdot})}$$

Not available in closed form, except for the gamma frailty model:

$$E[Z_i|\text{data}_i] = \frac{\theta + D_{i\cdot}}{\theta + H_{i\cdot}}.$$

# EM Algorithm

## E step

- ▶ Calculate the expectation of the complete-data log-likelihood:

$$E_{Z_i} \log P(\text{data}_i | Z_i) + \log f_{\theta}(Z_i)$$

- ▶ in practice, calculate  $E[Z_i | \text{data}]$  and  $E[\log Z_i | \text{data}]$

## M step

- ▶ Maximize the complete data likelihood by treating the frailty as fixed
- ▶ A Cox-type likelihood and a term involving  $\theta$ .

# EM Algorithm

## Disadvantages of the EM algorithm:

- ▶  $E[Z_i|data]$  can be calculated by taking derivatives of the Laplace transform, but  $E[\log Z_i|data]$  is in general difficult to calculate
- ▶ Need  $f_{\theta}$  in closed form, that doesn't exist for PVF or positive stable

## We would like to

- ▶ not have to express the density in closed form
- ▶ no have to calculate  $E[\log Z_i|data_i]$  (can't be expressed as a function of derivatives of the Laplace transform)

# Profile EM algorithm

## General idea

- ▶ Apply the EM algorithm for fixed values of  $\theta$ , obtaining  $\widehat{\beta}_\theta, \widehat{h_0(\cdot)}_\theta$  that maximize the likelihood with  $\theta$  fixed,  $L_\theta(\beta, h_0(\cdot))$
- ▶ Maximize  $L_\theta(\beta, h_0(\cdot))$  in  $\theta$

## Advantages

- ▶ like the EM algorithm, we can use any distribution with a known Laplace transform
- ▶ implemented in the R package frailtyEM

# Other methods

## Penalized likelihood (survival)

- ▶ consider that  $Z_i$  are unknown variables (similar to fixed effects)
- ▶ then we could use a Cox model to estimate all the parameters, including  $Z_i$
- ▶ penalize the Cox partial likelihood so that  $Z_i$  follow either a gamma or log-normal distribution
- ▶ very fast, but only works in a limited number of scenarios

# Other methods

## Parametric models (parfm and frailtypack)

- ▶ take a parametric baseline hazard, so that  $h_0$  depends on a small number of parameters (e.g. Weibull, Gompertz, spline-based)
- ▶ attempt to directly maximize the marginal log-likelihood using numeric integration
- ▶ in practice works well for gamma and log-normal.



## Empirical Bayes estimates revisited

- ▶ In the univariate case, we used  $E[Z_i|T \geq t_i]$ , where  $t_i$  is the event or censoring time of individual  $i$ .
- ▶ In the multivariate case we have  $E[Z_i|\text{data}_i]$ , where  $\text{data}_i$  contains information about the whole survival and event history from cluster  $i$  at the end of follow-up
- ▶ In the univariate case, the marginal hazard of individual  $i$  is

$$\bar{h}_i(t) = E[Z_i|T \geq t]h_i(t)$$

- ▶ In the multivariate case, we can write the marginal hazard of individual  $(i, j)$  as

$$\bar{h}_{ij}(t) = E[Z_i|\text{data}_i(t)]h_{ij}(t)$$

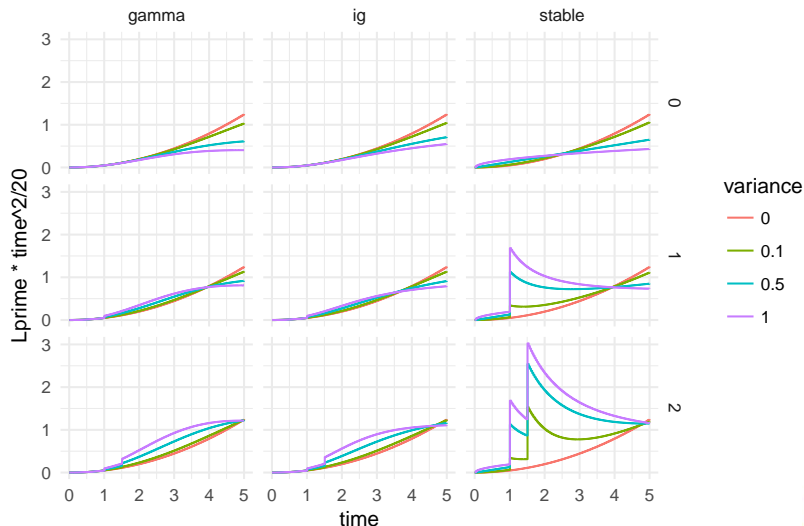
where  $\text{data}_i(t)$  is the information accumulated in the whole cluster  $i$  up to time  $t$ .

## Small example

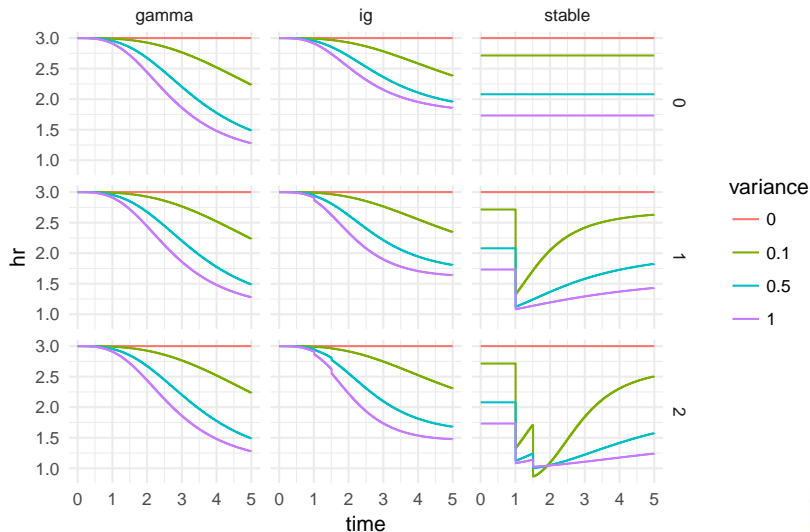
We take two individuals in the same logic as before, and 3 scenarios:

- ▶ Scenario 1: no events
- ▶ Scenario 2: one event at time 1
- ▶ Scenario 3: one event at time 1, one event at time 1.5

# Marginal hazard - baseline individual



# Marginal hazard ratios



## Final words

Before we go to software and applications. . .

- ▶ The PVF family of distributions is great, but in practice it is rarely used
- ▶ The standard are the gamma frailty and the log-normal frailty models (the latter is *not* in the PVF family)
  - ▶ gamma frailty is mostly for mathematical convenience, but there are also some theoretical arguments (Abbring & van den Berg 2007)
  - ▶ log-normal allows for negatively correlated frailty models (more about this, later)
- ▶ The positive stable distribution is advocated for by Hougaard, but in practice it is difficult to justify its use (and difficult to estimate)

# Software overview

## In short...

- ▶ In SAS and Stata, shared frailty models with a gamma or log-normal distributions can be estimated using the penalized likelihood method

# In R

## Semiparametric

- ▶ `survival::coxph` is the *de facto* standard for gamma and log-normal frailty models. It is very fast, but it lacks some features
- ▶ `coxme::coxme` fits log-normal frailty models including correlated frailty models.
- ▶ `frailtyEM::emfrail` (by Balan & Putter, 2017, wonder what they are up to?) aims to be a complete implementation of the EM algorithm with numerous methods for the user. However, it is slow when there are many events per individual.



# In R

## Parametric

- ▶ `frailtypack` has a lot of features for gamma and log-normal frailty modes, including spline-approximated baseline hazard;
- ▶ `parfm` is a simple package for parametric frailty models with more distributions, but it lacks some features

## Experimental

- ▶ `frailtySurv` implements a pseudo-maximum likelihood estimation technique, supports many distributions
- ▶ `phmm`, `frailtyHL`

## References

- ▶ Balan, T. A., & Putter, H. frailtyEM: an R Package for Estimating Semiparametric Shared Frailty Models.
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- ▶ Kalbfleisch, J. D., & Prentice, R. L. (2011). *The statistical analysis of failure time data*. John Wiley & Sons.