

Memo

To: Xiaoli Zhang and Mollie Brombaugh

From: Ben Pacheco and Tessa Haws

Team #: N-424

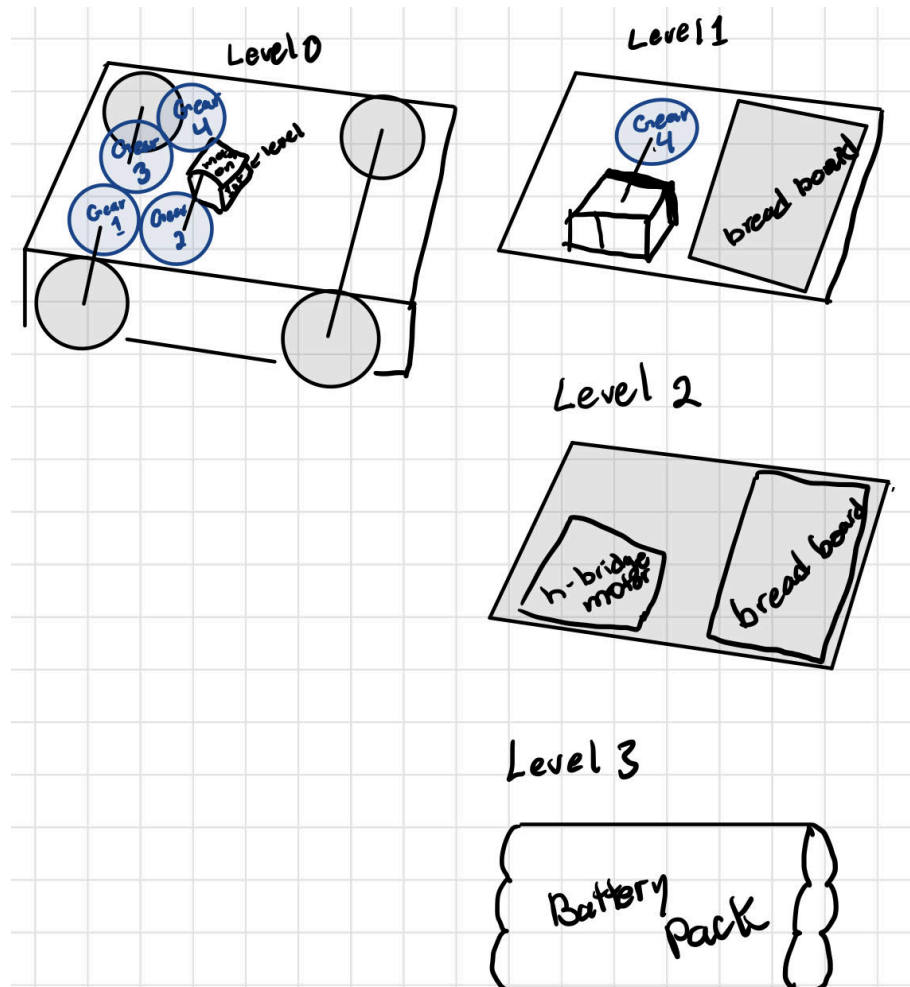
Date: October 11, 2024

Re: Lab 3: Robot navigation in the maze (Velocity control)

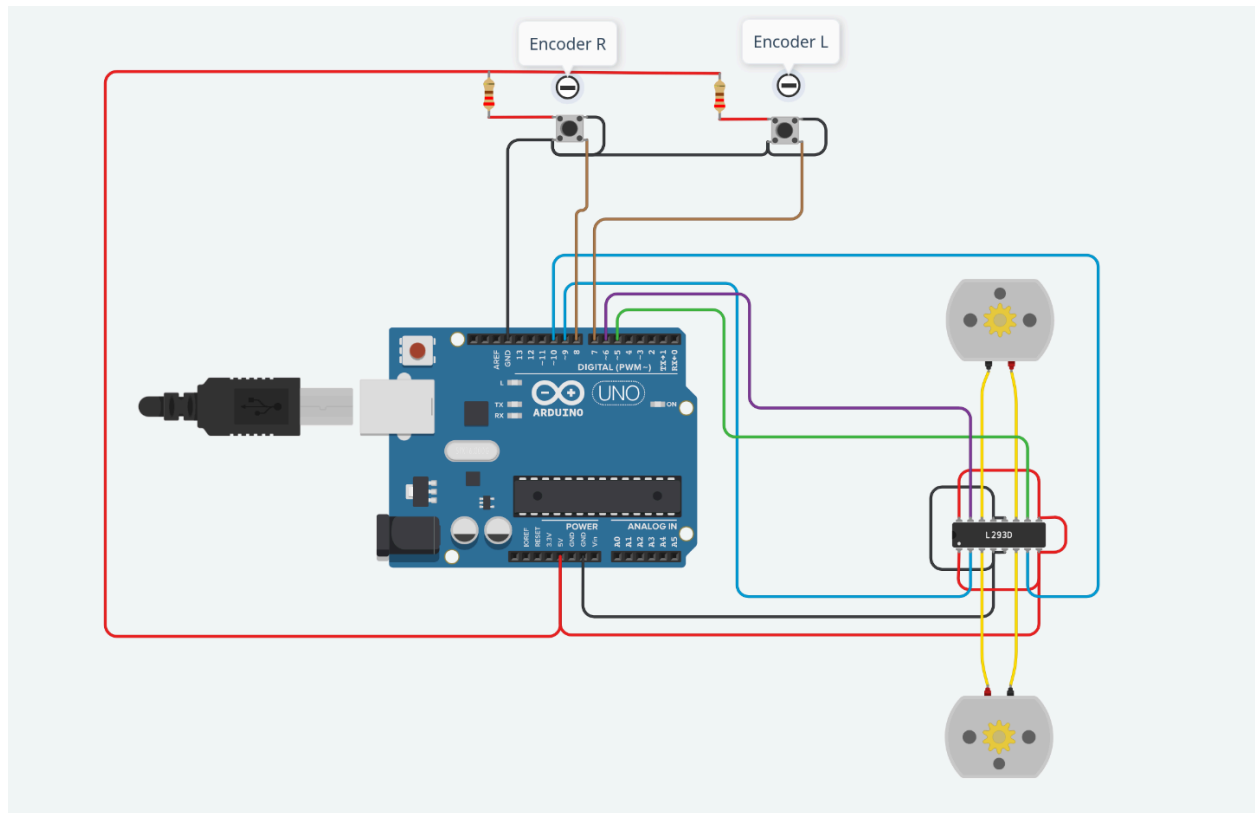
Overall Plan

Our plan is to copy our tuned values over to the new code so we can implement the new features and then continue tuning.

Mechanical



Electrical



Flowchart

