

Linear Prediction

Joseph Kleinhenz

Group Seminar, July 2017

Table of Contents

1 Introduction

2 Theory

3 Applications

- The Fourier transform involves integration over the whole real line
- A finite cutoff in the time domain introduces artifacts into the frequency domain
- Linear prediction is an ansatz for extrapolating time domain data to remove these finite time artifacts

Consider some signal $G(t)$ with Fourier transform $A(\omega)$

$$A(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} G(t) e^{-i\omega t} dt$$

If we only know $G(t)$ in some finite time window $[-\frac{T}{2}, \frac{T}{2}]$ then our Fourier transform becomes

$$D(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} G(t) \text{rect}(t/T) e^{-i\omega t} dt$$

where

$$\text{rect}(t) = \Theta\left(t + \frac{1}{2}\right) - \Theta\left(t - \frac{1}{2}\right)$$

Recalling that

$$\mathcal{F}\{f\} * \mathcal{F}\{g\} = \sqrt{2\pi} \mathcal{F}\{f \cdot g\}$$

we have

$$\begin{aligned} D(\omega) &= \frac{1}{\sqrt{2\pi}} \mathcal{F}\{G\} * \mathcal{F}\{\text{rect}(t/T)\} \\ &= \int_{-\infty}^{\infty} d\omega' \left[\frac{T}{2\pi} \text{sinc}\left(\frac{(\omega - \omega') T}{2}\right) \right] A(\omega') \\ &= KA \end{aligned}$$

So our data is given by the true result convolved with a singular kernel.

Table of Contents

1 Introduction

2 Theory

3 Applications

Green's functions

Often the objects we are interested in are Green's functions which have the structure

$$G(k, \omega) \sim \frac{1}{(\omega - \epsilon_k - \Sigma(k, \omega))}$$

We can Fourier transform this object to obtain

$$\begin{aligned} G(k, t) &\sim \int_{-\infty}^{\infty} d\omega G(k, \omega) e^{+i\omega t} \\ &\sim \sum_j c_j e^{i\omega_j t} \end{aligned}$$

where c_j, ω_j are the residues and poles of $G(k, \omega)$ in the upper complex plane

- If the self energy is not too complicated $G(k, t)$ will be given by a superposition of a small number of complex exponential terms
- Take this as ansatz, fit and extrapolate
- This can be done efficiently using **linear prediction**

The linear prediction ansatz is given by

$$x_n = \sum_{j=1}^N c_j e^{i\omega_j t_n}$$

which can be recast as an autoregressive model

$$x_n = - \sum_{k=1}^p a_k x_{n-k}$$

To get a_k and p in terms of c_j , ω_j and N plug the first equation into the second

$$\begin{aligned}\sum_{j=1}^N c_j e^{i\omega_j t_n} &= - \sum_{k=1}^p a_k \sum_{j=1}^N c_j e^{i\omega_j t_{n-k}} \\ &= - \sum_{j=1}^N c_j e^{i\omega_j t_n} \underbrace{\left(\sum_{k=1}^p a_k e^{-i\omega_j t_k} \right)}_{=-1}\end{aligned}$$

$$\implies \sum_{k=0}^p e^{-i\omega_j t_k} a_k = 0 \quad (a_0 = 1)$$

The previous equation can be written

$$M\mathbf{a} = \mathbf{0}$$

where $M \in \mathbb{C}^{N \times (p+1)}$ is given by

$$M_{jk} = e^{-i\omega_j t_k}$$

from this we see that when $p = N$ we have exactly one non-trivial solution. Note, the other N degrees of freedom associated with c_j are realized in terms of the initial conditions of the autoregressive model.

Fitting

In order to fit the model to some data \mathbf{x} we write down the autoregressive form of the equations as $Q\mathbf{a} = -\mathbf{x}$ where $Q \in \mathbb{C}^{N \times p}$ is given by

$$Q_{nk} = x_{n-k}$$

The normal equations then read

$$R\mathbf{a} = -\mathbf{r}$$

where

$$r_j = (Q^\dagger \mathbf{x})_j = \sum_n x_{n-j}^* x_n$$
$$R_{ji} = (Q^\dagger Q)_{ji} = \sum_n x_{n-j}^* x_{n-i}$$

are the autocorrelations of the signal

The normal equations can be rewritten as

$$\begin{aligned}\sum_k R_{jk} a_k &= \sum_k \sum_n x_{n-j}^* x_{n-k} a_k \\ &= \sum_n x_{n-j}^* \sum_k a_k x_{n-k} \\ &= - \sum_n x_{n-j}^* \tilde{x}_n \\ &= -r_j \\ &= - \sum_n x_{n-j}^* x_n\end{aligned}$$

where \tilde{x}_n is the prediction and x_n is the data.

\implies correlation of the prediction and the signal is equal to the autocorrelation of the signal

Table of Contents

1 Introduction

2 Theory

3 Applications

Applications

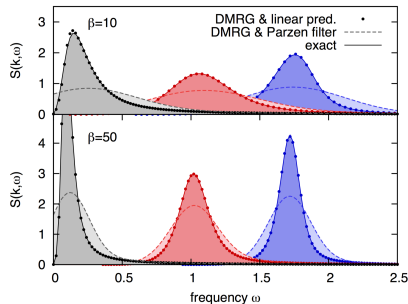
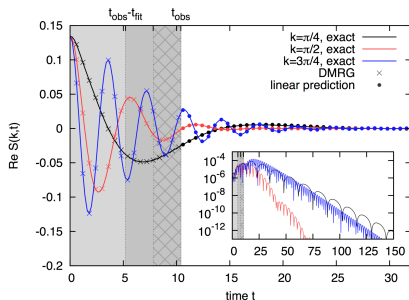


Figure: t-DMRG, Barthel (2009)

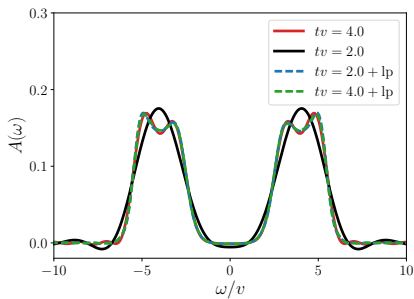
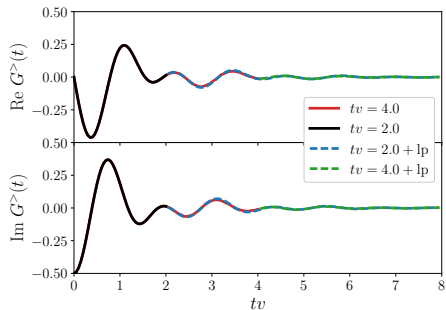


Figure: Realtime DMFT ($p = 9$, $t_{\text{fit}} = 1.0$)

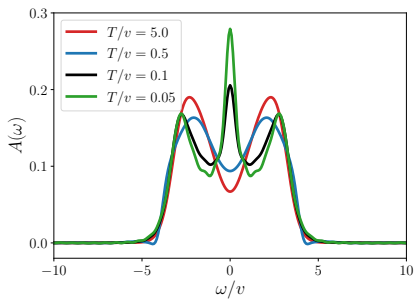
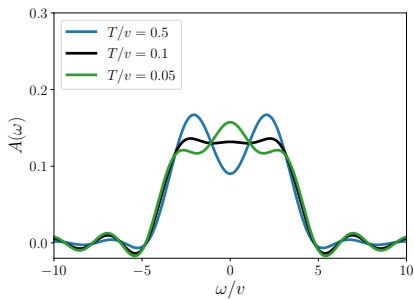
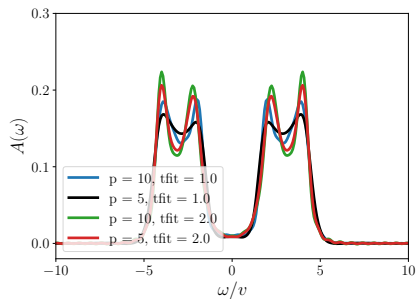
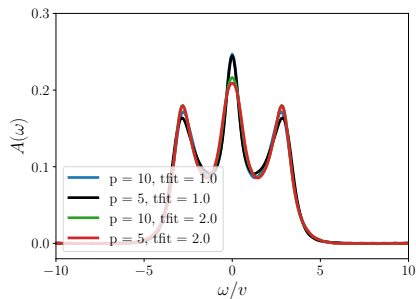


Figure: Realtime DMFT ($p = 9$, $t_{\text{fit}} = 1.0$)

Benchmarks



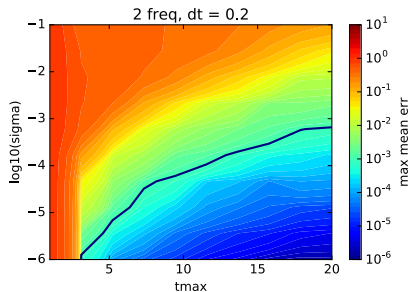
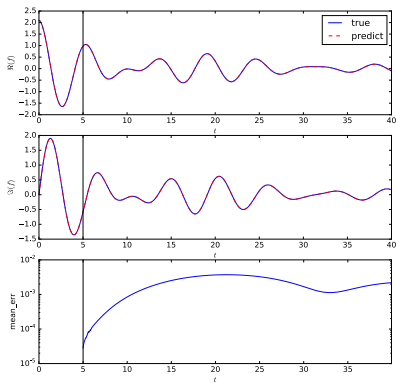


Figure: Noise tolerance

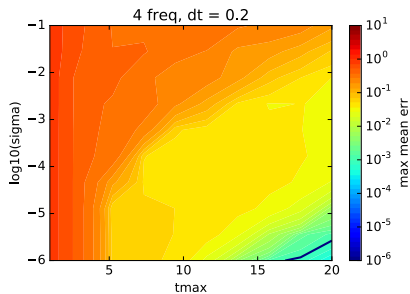
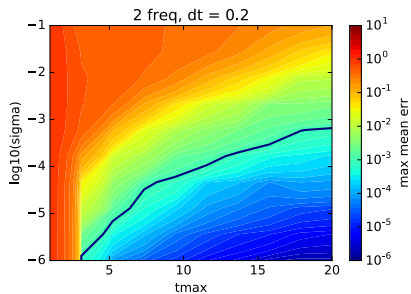


Figure: Number of Frequencies

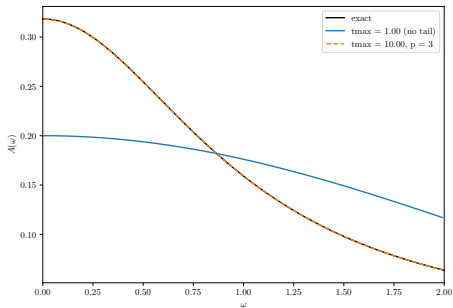
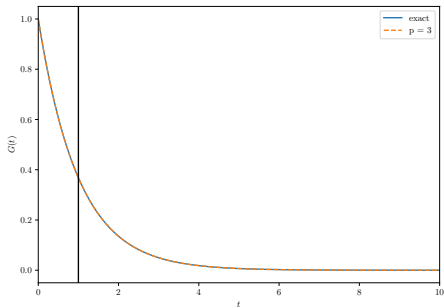


Figure: Lorentzian

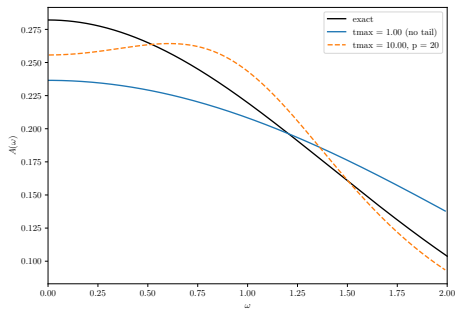
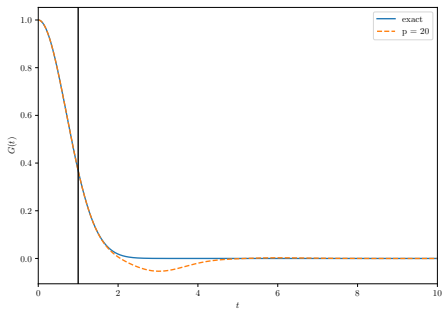


Figure: Gaussian

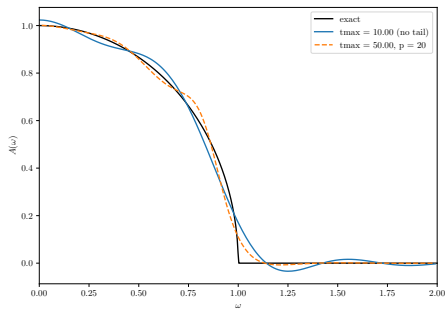
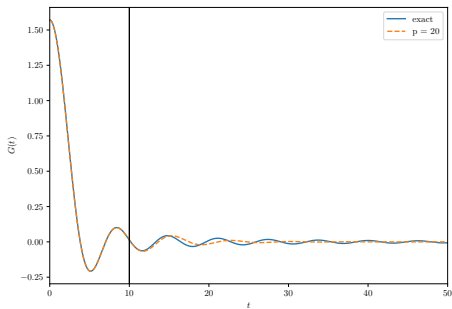


Figure: Semi-circular