# Semi-supervised Learning with Deep Generative Models

Kingma et. al. (2014)

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CS 7180

#### **Motivating Question**

How can we model data of increasing size when obtaining label information is difficult?

#### High-level Answer

We can estimate missing label information by using a probabilistic model.

#### Most Relevant Previous Work

Pitelis, N., Russell, C., and Agapito, L. (2014). Semi-supervised learning using an unsupervised atlas. *In Proceedings of the European Conference on Machine Learning (ECML)*, volume LNCS 8725, pages 565 – 580.

- Observing that high-dimensional datasets often lie on or near manifolds of locally low rank can help avoid the curse of dimensionality
- Experiments show how using unlabelled data to learn the underlying manifold improves classifier accuracy when trained on limited labelled data
  - 1. **Unsupervised learning of the underlying manifold:** Approximate the manifold of data on the original space by fitting an atlas of low-dimensional overlapping affine charts.
  - 2. **Supervised training of an SVM:** Proposed a new family of Mercer Kernels for SVM-based supervised learning which uses soft-assignment of datapoints to the underlying low-dimensional affine charts to generate the kernels

#### Specifying the Probabilistic Model for Missing Labels

#### Kingma et. al. (2014)

- ▶ Data appears as pairs  $(\mathbf{X}, \mathbf{Y}) = \{(\mathbf{x}_1, y_1), ..., (\mathbf{x}_N, y_N)\}$  with the *i*-th observation  $x_i \in \mathbb{R}^D$  and a corresponding class label  $y_i \in \{1, ..., L\}$ 
  - Each pair of observations  $(x_i, y_i)$  has a corresponding latent variable  $z_i$
  - Empirical distribution over the labelled and unabelled subsets is referred to as  $\tilde{p}_I(\mathbf{x}, y)$  and  $\tilde{p}_u(\mathbf{x})$
- We can estimate  $y_i$  for  $x_i$  in distribution  $\tilde{p}_u(\mathbf{x})$  by finding the maximum probability of  $p(y_i)$  by using a set of features related to  $z_i$  and a predictive model
  - 1. Latent-feature discriminative model (M1)
  - 2. Generative semi-supervised model (M2)
  - 3. Stacked generative semi-supervised model (M1+M2)

# Bayes Rule is used when specifying M1 & M2

$$p(x,y) = p(x)p(y|x)$$

$$= p(y)p(x|y)$$

$$p(x|y) = \frac{p(x)p(y|x)}{p(y)}$$

for models M1 <sup>1</sup>, p(z|x), and M2 <sup>2</sup>; p(y|x)



<sup>&</sup>lt;sup>1</sup>Kingma et. al. (2014) equation (1)

<sup>&</sup>lt;sup>2</sup>Kingma et. al. (2014) equation (2)

## (M1) Latent-feature discriminative model

$$y \Leftarrow p(z|x) = \frac{p(z)p(x|z)}{p(x)}$$

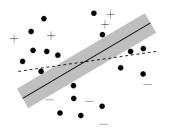
where

$$p(z) = \mathcal{N}(z|0,I)$$
 Gaussian distribution of  $z$  given a missing label  $y$   $p(x|z) = f(x;z,\theta)$  likelihood function, parameters  $\theta$  of a set of  $z$   $p(x) = \tilde{p_u}(x)$  unlabelled subset of  $x_i \in \mathbb{R}^D$ 

Kingma et. al. (2014) eq. (1)

# (M1) Predicting Class Labels y

Approximate samples from the posterior distribution over the latent variables p(z|x) are used as features to train a classifier that predicts class labels y



(transductive) SVM<sup>3</sup> finds the largest margin w.r.t. the training **and** the test vectors



<sup>&</sup>lt;sup>3</sup>See Figure 6.2 from Chapelle, O., B. Schölkopf, and A. Zien.

<sup>&</sup>quot;Semi-Supervised Learning." (2006).

# (M2) Generative semi-supervised model

$$p(y|\mathbf{x}) = \frac{p(\mathbf{x}|y)p(y)}{p(\mathbf{x})} \approx \frac{p_{\theta}(\mathbf{x}|y,\mathbf{z})p(y)}{p(\mathbf{x})}$$

where

$$p(y) = Cat(y|\pi)$$
 $p(\mathbf{z}) = \mathcal{N}(\mathbf{z}|\mathbf{0}, \mathbf{I})$ 
 $p_{\theta}(\mathbf{x}|y, z) = f(\mathbf{x}; y, \mathbf{z}, \theta)$ 
 $p(x)$ 

multinomial distribution, y can be latent Gaussian distribution of z when missing y likelihood function, nonlinear parameters all x in dist. of real numbers;  $x \in \mathbb{R}^D$ 

# Stacked generative semi-supervised model (M1 + M2)

#### Combine M1 and M2

- 1. Learn a new latent representation  $z_1$  from M1
- 2. Use embeddings from  $z_1$  instead of raw data x, to create a generative semi-supervised model M2

TODO: Add a picture or something here

#### Scaling Up: Lower Bound Objective

Lower Bound Objective<sup>4</sup>: computation of the exact posterior distribution is intractable for models M1 and M2

M1: 
$$q_{\phi}(z|x) = \mathcal{N}(z|u_{\phi}(x), \operatorname{diag}(\sigma_{\phi}^{2}(\mathbf{x})))$$
 (3)

M2: 
$$q_{\phi}(\mathbf{z}|y, \mathbf{x}) = \mathcal{N}(\mathbf{z}|\mu_{\phi}(y, \mathbf{x}), \operatorname{diag}(\sigma_{\phi}^{2}(\mathbf{x})));$$
  
 $q_{\phi}(y|\mathbf{z}) = \operatorname{Cat}(y|\pi_{\phi}(x)),$  (4)

where

$$\sigma_{\phi}(x)$$
 vector of standard deviations  $\pi_{\phi}(x)$  probability vector  $\mu_{\phi}(x), \sigma_{\phi}(x), \pi_{\sigma}(x)$  Maximum likelihood Priors (MLPs)



<sup>&</sup>lt;sup>4</sup>Kingma et. al. (2014) equations (3), (4)

# Scaling Up: M1 Model Objective

$$\log p_{\theta}(x) \geq \mathbb{E}_{q_{\phi}(z|x)}[\log p_{\theta}(x|z)] - \mathit{KL}[q_{\phi}(z|x)||p_{\theta}(z)] = -\mathcal{J}(x)$$

Equation 5

#### Scaling Up: M2 Model Objective

When  $y_i$  is observed for the  $(x_i, y_i)$  data pair, extend from M1

$$\log p_{\theta}(x) \ge \mathbb{E}_{q_{\phi}(z|x,y)}[\log p_{\theta}(x|y,z) + \log p_{\theta}(y) + \log p(z) - q_{\theta}(z|x,y)]$$
  
=  $-\mathcal{L}(x,y)$ 

In the case where  $y_i$  is missing,

$$egin{aligned} \log p_{ heta}(x) &\geq \mathbb{E}_{q_{\phi}(y,z|x)}[\log p_{ heta}(x|y,z) + \log p_{ heta}(y) \\ &\qquad + \log p(z) - \log q_{\phi}(y,z|x)] \\ &= \sum_{y} q_{\phi}(y|x)(-\mathcal{L}(x,y)) + \mathcal{H}(q_{\phi}(y|x)) \\ &= -\mathcal{U}(x) \end{aligned}$$

The bound on the marginal likelihood for the entire dataset is now<sup>5</sup>

$$\mathcal{J} = \sum_{(x,y) \sim \tilde{p}_{I}} \mathcal{L}(x,y) + \sum_{x \sim \tilde{p}_{u}} \mathcal{U}(x)$$

<sup>&</sup>lt;sup>5</sup>See Kingma et. al. (2014) equations 6-9



#### **Optimization Techniques**

- Not using the EM algorithm, that's interesting, why
- perform efficient joint inference that's easy to scale (pg. 7)
- Using AdaGrad

$$\nabla_{\{\theta,\phi\}} \mathbb{E}_{q_{\phi}(z|x)}[\log p_{\theta}(x|z)] = \mathbb{E}_{\mathcal{N}(\epsilon|0,l)}[\nabla_{\{\theta,\phi\}}\log p_{\theta}(x|\mu_{\theta}(x)+\sigma_{\phi}(x)\odot\epsilon)].$$

Kingma et. al. (2014) equation 11

## Optimization Algorithms

#### Algorithm 1 Learning in model M1

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#### Algorithm 2 Learning in model M2

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 \begin{split} & \textbf{while} \  \, \text{training()} \  \, \textbf{do} \\ & \mathcal{D} \leftarrow \text{getRandomMiniBatch()} \\ & y_i \sim q_\phi(y_i|\mathbf{x}_i) \quad \forall \{\mathbf{x}_i, y_i\} \notin \mathcal{O} \\ & \mathbf{z}_i \sim q_\phi(\mathbf{z}_i|y_i, \mathbf{x}_i) \\ & \mathcal{J}^\alpha \leftarrow \text{eq. (9)} \\ & (\mathbf{g}_\theta, \mathbf{g}_\phi) \leftarrow (\frac{\partial \mathcal{L}^\alpha}{\partial \theta}, \frac{\partial \mathcal{L}^\alpha}{\partial \phi}) \\ & (\theta, \phi) \leftarrow (\theta, \phi) + \Gamma(\mathbf{g}_\theta, \mathbf{g}_\phi) \\ & \text{end while} \\ \end{aligned}
```

#### Results: Benchmark Classification

Table 1: Benchmark results of semi-supervised classification on MNIST with few labels.

N	NN	CNN	TSVM	CAE	MTC	AtlasRBF	M1+TSVM	M2	M1+M2
100	25.81	22.98	16.81	13.47	12.03	8.10 (± 0.95)	11.82 (± 0.25)	11.97 (± 1.71)	3.33 (± 0.14)
600	11.44	7.68	6.16	6.3	5.13	_	5.72 (± 0.049)	$4.94 (\pm 0.13)$	$2.59 (\pm 0.05)$
1000	10.7	6.45	5.38	4.77	3.64	$3.68 (\pm 0.12)$	$4.24 (\pm 0.07)$	$3.60 (\pm 0.56)$	$2.40 (\pm 0.02)$
3000	6.04	3.35	3.45	3.22	2.57	- '	3.49 (± 0.04)	$3.92 (\pm 0.63)$	$2.18 (\pm 0.04)$

#### Results: Image Classification

Table 2: Semi-supervised classification on the SVHN dataset with 1000 labels.

KNN	TSVM	M1+KNN	M1+TSVM	M1+M2
77.93	66.55	65.63	54.33	36.02
$(\pm 0.08)$	$(\pm 0.10)$	(± 0.15)	$(\pm 0.11)$	$(\pm 0.10)$

Table 3: Semi-supervised classification on the NORB dataset with 1000 labels.

KNN	TSVM	M1+KNN	M1+TSVM
78.71	26.00	65.39	18.79
(± 0.02)	(± 0.06)	(± 0.09)	(± 0.05)

#### Discussion

You can use this model for a few things TODO: just summarize their discussion

Any questions? Thanks!