Semi-supervised Learning with Deep Generative Models

Kingma et. al. (2014)

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CS 7180

Motivating Question

How can we model data of increasing size when obtaining label information is difficult?

High-level Answer

We can estimate missing label information by using a probabilistic model.

Most Relevant Previous Work

Pitelis, N., Russell, C., and Agapito, L. (2014). Semi-supervised learning using an unsupervised atlas. *In Proceedings of the European Conference on Machine Learning (ECML)*, volume LNCS 8725, pages 565 – 580.

- Observing that high-dimensional datasets often lie on or near manifolds of locally low rank can help avoid the curse of dimensionality
- Experiments show how using unlabelled data to learn the underlying manifold improves classifier accuracy when trained on limited labelled data
 - 1. **Unsupervised learning of the underlying manifold:** Approximate the manifold of data on the original space by fitting an atlas of low-dimensional overlapping affine charts.
 - 2. **Supervised training of an SVM:** Proposed a new family of Mercer Kernels for SVM-based supervised learning which uses soft-assignment of datapoints to the underlying low-dimensional affine charts to generate the kernels

Specifying the Probabilistic Model for Missing Labels

Kingma et. al. (2014)

- ▶ Data appears as pairs $(\mathbf{X}, \mathbf{Y}) = \{(\mathbf{x}_1, y_1), ..., (\mathbf{x}_N, y_N)\}$ with the *i*-th observation $x_i \in \mathbb{R}^D$ and a corresponding class label $y_i \in \{1, ..., L\}$
 - Each pair of observations (x_i, y_i) has a corresponding latent variable z_i
 - Empirical distribution over the labelled and unabelled subsets is referred to as $\tilde{p}_I(\mathbf{x}, y)$ and $\tilde{p}_u(\mathbf{x})$
- We can estimate y_i for x_i in distribution $\tilde{p}_u(\mathbf{x})$ by finding the maximum probability of $p(y_i)$ by using a set of features related to z_i and a predictive model
 - 1. Latent-feature discriminative model (M1)
 - 2. Generative semi-supervised model (M2)
 - 3. Stacked generative semi-supervised model (M1+M2)

Bayes Rule is used when specifying M1 & M2

$$p(x,y) = p(x)p(y|x)$$

$$= p(y)p(x|y)$$

$$p(x|y) = \frac{p(x)p(y|x)}{p(y)}$$

for models M1 ¹, p(z|x), and M2 ²; p(y|x)



¹Kingma et. al. (2014) equation (1)

²Kingma et. al. (2014) equation (2)

(M1) Latent-feature discriminative model

$$y \Leftarrow p(z|x) = \frac{p(z)p(x|z)}{p(x)}$$

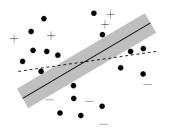
where

$$p(z) = \mathcal{N}(z|0,I)$$
 Gaussian distribution of z given a missing label y $p(x|z) = f(x;z,\theta)$ likelihood function, parameters θ of a set of z $p(x) = \tilde{p_u}(x)$ unlabelled subset of $x_i \in \mathbb{R}^D$

Kingma et. al. (2014) eq. (1)

(M1) Predicting Class Labels y

Approximate samples from the posterior distribution over the latent variables p(z|x) are used as features to train a classifier that predicts class labels y



(transductive) SVM³ finds the largest margin w.r.t. the training **and** the test vectors



³See Figure 6.2 from Chapelle, O., B. Schölkopf, and A. Zien.

[&]quot;Semi-Supervised Learning." (2006).

(M2) Generative semi-supervised model

$$p(y|\mathbf{x}) = \frac{p(\mathbf{x}|y)p(y)}{p(\mathbf{x})} \approx \frac{p_{\theta}(\mathbf{x}|y,\mathbf{z})p(y)}{p(\mathbf{x})}$$

where

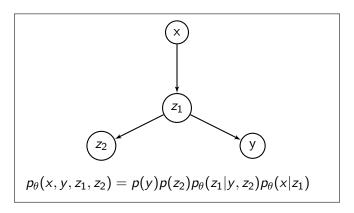
$$p(y) = Cat(y|\pi)$$
 $p(\mathbf{z}) = \mathcal{N}(\mathbf{z}|\mathbf{0}, \mathbf{I})$
 $p_{\theta}(\mathbf{x}|y, z) = f(\mathbf{x}; y, \mathbf{z}, \theta)$
 $p(x)$

multinomial distribution, y can be latent Gaussian distribution of z when missing y likelihood function, nonlinear parameters all x in dist. of real numbers; $x \in \mathbb{R}^D$

Stacked generative semi-supervised model (M1 + M2)

Combine M1 and M2

- 1. Learn a new latent representation z_1 from M1
- 2. Use embeddings from z_1 instead of raw data x, to create a generative semi-supervised model M2



Scaling Up: Lower Bound Objective

Lower Bound Objective⁴: computation of the exact posterior distribution is intractable for models M1 and M2

M1:
$$q_{\phi}(z|x) = \mathcal{N}(z|u_{\phi}(x), \operatorname{diag}(\sigma_{\phi}^{2}(\mathbf{x})))$$
 (3)

M2:
$$q_{\phi}(\mathbf{z}|y, \mathbf{x}) = \mathcal{N}(\mathbf{z}|\mu_{\phi}(y, \mathbf{x}), \operatorname{diag}(\sigma_{\phi}^{2}(\mathbf{x})));$$

 $q_{\phi}(y|\mathbf{z}) = \operatorname{Cat}(y|\pi_{\phi}(x)),$ (4)

where

$$\sigma_{\phi}(x)$$
 vector of standard deviations $\pi_{\phi}(x)$ probability vector $\mu_{\phi}(x), \sigma_{\phi}(x), \pi_{\sigma}(x)$ Maximum likelihood Priors (MLPs)



⁴Kingma et. al. (2014) equations (3), (4)

Scaling Up: M1 Model Objective

Variational bound $\mathcal{J}(x)$ on the marginal likelihood of a single data point is 5

$$\log p_{\theta}(x) \geq \mathbb{E}_{q_{\phi}(z|x)}[\log p_{\theta}(x|z)] - \mathcal{K}L[q_{\phi}(z|x)||p_{\theta}(z)] = -\mathcal{J}(x)$$

Approximate posterior is used as a feature extractor for the labelled data set, and the features used for training the classifier



Scaling Up: M2 Model Objective

When y_i is observed for the (x_i, y_i) data pair, extend from M1

$$\log p_{\theta}(x) \ge \mathbb{E}_{q_{\phi}(z|x,y)}[\log p_{\theta}(x|y,z) + \log p_{\theta}(y) + \log p(z) - q_{\theta}(z|x,y)]$$

= $-\mathcal{L}(x,y)$

In the case where y_i is missing,

$$egin{aligned} \log p_{ heta}(x) &\geq \mathbb{E}_{q_{\phi}(y,z|x)}[\log p_{ heta}(x|y,z) + \log p_{ heta}(y) \\ &\qquad + \log p(z) - \log q_{\phi}(y,z|x)] \\ &= \sum_{y} q_{\phi}(y|x)(-\mathcal{L}(x,y)) + \mathcal{H}(q_{\phi}(y|x)) \\ &= -\mathcal{U}(x) \end{aligned}$$

The bound on the marginal likelihood for the entire dataset is now⁶

$$\mathcal{J} = \sum_{(x,y) \sim \tilde{p}_{I}} \mathcal{L}(x,y) + \sum_{x \sim \tilde{p}_{u}} \mathcal{U}(x)$$

⁶See Kingma et. al. (2014) equations 6-9



Optimization Techniques

- Not using the EM algorithm, that's interesting, why
- perform efficient joint inference that's easy to scale (pg. 7)
- Using AdaGrad

$$\nabla_{\{\theta,\phi\}} \mathbb{E}_{q_{\phi}(z|x)}[\log p_{\theta}(x|z)] = \mathbb{E}_{\mathcal{N}(\epsilon|0,l)}[\nabla_{\{\theta,\phi\}}\log p_{\theta}(x|\mu_{\theta}(x)+\sigma_{\phi}(x)\odot\epsilon)].$$

Kingma et. al. (2014) equation 11

Optimization Algorithms

Algorithm 1 Learning in model M1

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Algorithm 2 Learning in model M2

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 \begin{split} & \textbf{while} \  \, \text{training()} \  \, \textbf{do} \\ & \mathcal{D} \leftarrow \text{getRandomMiniBatch()} \\ & y_i \sim q_\phi(y_i|\mathbf{x}_i) \quad \forall \{\mathbf{x}_i, y_i\} \notin \mathcal{O} \\ & \mathbf{z}_i \sim q_\phi(\mathbf{z}_i|y_i, \mathbf{x}_i) \\ & \mathcal{J}^\alpha \leftarrow \text{eq. (9)} \\ & (\mathbf{g}_\theta, \mathbf{g}_\phi) \leftarrow (\frac{\partial \mathcal{L}^\alpha}{\partial \theta}, \frac{\partial \mathcal{L}^\alpha}{\partial \phi}) \\ & (\theta, \phi) \leftarrow (\theta, \phi) + \Gamma(\mathbf{g}_\theta, \mathbf{g}_\phi) \\ & \text{end while} \\ \end{aligned}
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Results: Benchmark Classification

Table 1: Benchmark results of semi-supervised classification on MNIST with few labels.

N	NN	CNN	TSVM	CAE	MTC	AtlasRBF	M1+TSVM	M2	M1+M2
100	25.81	22.98	16.81	13.47	12.03	8.10 (± 0.95)	11.82 (± 0.25)	11.97 (± 1.71)	3.33 (± 0.14)
600	11.44	7.68	6.16	6.3	5.13	_	5.72 (± 0.049)	$4.94 (\pm 0.13)$	$2.59 (\pm 0.05)$
1000	10.7	6.45	5.38	4.77	3.64	$3.68 (\pm 0.12)$	$4.24 (\pm 0.07)$	$3.60 (\pm 0.56)$	$2.40 (\pm 0.02)$
3000	6.04	3.35	3.45	3.22	2.57	- '	3.49 (± 0.04)	$3.92 (\pm 0.63)$	$2.18 (\pm 0.04)$

Results: Image Classification

Table 2: Semi-supervised classification on the SVHN dataset with 1000 labels.

KNN	TSVM	M1+KNN	M1+TSVM	M1+M2
77.93	66.55	65.63	54.33	36.02
(± 0.08)	(± 0.10)	(± 0.15)	(± 0.11)	(± 0.10)

Table 3: Semi-supervised classification on the NORB dataset with 1000 labels.

KNN	TSVM	M1+KNN	M1+TSVM
78.71	26.00	65.39	18.79
(± 0.02)	(± 0.06)	(± 0.09)	(± 0.05)

Discussion

You can use this model for a few things TODO: just summarize their discussion

Any questions? Thanks!