

# Semi-supervised Learning with Deep Generative Models

Kingma et. al. (2014)

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CS 7180

# Motivating Question

How can we model data of increasing size when obtaining label information is difficult?

## High-level Answer

We can estimate missing label information by using a probabilistic model.

# Previous Work

TODO: Who did they cite?

Talk about previous work

# Specifying the Probabilistic Model for Missing Labels

- ▶ Data appears as pairs  $(\mathbf{X}, \mathbf{Y}) = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$  with the  $i$ -th observation  $x_i \in \mathbb{R}^D$  and a corresponding class label  $y_i \in \{1, \dots, L\}$ 
  - ▶ Each pair of observations  $(x_i, y_i)$  has a corresponding latent variable  $z_i$
  - ▶ Empirical distribution over the labelled and unlabelled subsets is referred to as  $\tilde{p}_l(\mathbf{x}, y)$  and  $\tilde{p}_u(\mathbf{x})$
- ▶ We can estimate  $y_i$  for  $x_i$  in distribution  $\tilde{p}_u(\mathbf{x})$  by finding the maximum probability of  $p(y_i)$  by using a set of features related to  $z_i$  and a predictive model
  1. **Latent-feature discriminative model (M1)**
  2. **Generative semi-supervised model (M2)**
  3. **Stacked generative semi-supervised model (M1+M2)**

## Bayes Rule is used when specifying M1 & M2

$$\begin{aligned}p(x, y) &= p(x)p(y|x) \\ &= p(y)p(x|y) \\ p(x|y) &= \frac{p(x)p(y|x)}{p(y)}\end{aligned}$$

for models M1 <sup>1</sup>,  $p(z|x)$ , and M2 <sup>2</sup>;  $p(y|x)$

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<sup>1</sup>Kingma et. al. (2014) equation (1)

<sup>2</sup>Kingma et. al. (2014) equation (2)

## (M1) Latent-feature discriminative model

$$y \Leftarrow p(z|x) = \frac{p(z)p(x|z)}{p(x)}$$

where

$p(z) = \mathcal{N}(z|0, I)$       Gaussian distribution of  $z$  given a missing label  $y$

$p(x|z) = f(x; z, \theta)$       likelihood function, parameters  $\theta$  of a set of  $z$

$p(x) = \tilde{p}_u(x)$       unlabelled subset of  $x_i \in \mathbb{R}^D$

Kingma et. al. (2014) eq. (1)

# (M1) Predicting Class Labels $y$

Approximate samples from the posterior distribution over the latent variables  $p(z|x)$  are used as features to train a classifier that predicts class labels  $y$

- ▶ (transductive) SVM
- ▶ multinomial regression

**TODO:** Add pictures or simulation here



## (M2) Generative semi-supervised model

$$p(y|\mathbf{x}) = \frac{p(\mathbf{x}|y)p(y)}{p(\mathbf{x})} \approx \frac{p_{\theta}(\mathbf{x}|y, \mathbf{z})p(y)}{p(\mathbf{x})}$$

where

$$p(y) = \text{Cat}(y|\pi)$$

multinomial distribution,  $y$  can be latent

$$p(\mathbf{z}) = \mathcal{N}(\mathbf{z}|\mathbf{0}, \mathbf{I})$$

Gaussian distribution of  $\mathbf{z}$  when missing  $y$

$$p_{\theta}(\mathbf{x}|y, \mathbf{z}) = f(\mathbf{x}; y, \mathbf{z}, \theta)$$

likelihood function, nonlinear parameters

$$p(\mathbf{x})$$

all  $\mathbf{x}$  in dist. of real numbers;  $\mathbf{x} \in \mathbb{R}^D$

# Stacked generative semi-supervised model ( $M1 + M2$ )

Combine M1 and M2

1. Learn a new latent representation  $z_1$  from M1
2. Use embeddings from  $z_1$  instead of raw data  $x$ , to create a generative semi-supervised model M2

**TODO:** Add a picture or something here

## Scaling Up: Lower Bound Objective

Lower Bound Objective<sup>3</sup>: computation of the exact posterior distribution is intractable for models M1 and M2

$$\text{M1: } q_{\phi}(z|x) = \mathcal{N}(z|u_{\phi}(x), \text{diag}(\sigma_{\phi}^2(\mathbf{x}))) \quad (3)$$

$$\begin{aligned} \text{M2: } q_{\phi}(\mathbf{z}|y, \mathbf{x}) &= \mathcal{N}(\mathbf{z}|\mu_{\phi}(y, \mathbf{x}), \text{diag}(\sigma_{\phi}^2(\mathbf{x}))); \\ q_{\phi}(y|\mathbf{z}) &= \text{Cat}(y|\pi_{\phi}(x)), \end{aligned} \quad (4)$$

where

$\sigma_{\phi}(x)$	vector of standard deviations
$\pi_{\phi}(x)$	probability vector
$\mu_{\phi}(x), \sigma_{\phi}(x), \pi_{\phi}(x)$	Maximum likelihood Priors (MLPs)

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<sup>3</sup>Kingma et. al. (2014) equations (3), (4)

# Scaling Up: M1 Model Objective

$$\log p_{\theta}(x) \geq \mathbb{E}_{q_{\phi}(z|x)}[\log p_{\theta}(x|z)] - KL[q_{\phi}(z|x)||p_{\theta}(z)] = -\mathcal{J}(x)$$

Equation 5

## Scaling Up: M2 Model Objective

When  $y_i$  is observed for the  $(x_i, y_i)$  data pair, extend from M1

$$\begin{aligned}\log p_{\theta}(x) &\geq \mathbb{E}_{q_{\phi}(z|x,y)}[\log p_{\theta}(x|y,z) + \log p_{\theta}(y) + \log p(z) - q_{\theta}(z|x,y)] \\ &= -\mathcal{L}(x, y)\end{aligned}$$

In the case where  $y_i$  is missing,

$$\begin{aligned}\log p_{\theta}(x) &\geq \mathbb{E}_{q_{\phi}(y,z|x)}[\log p_{\theta}(x|y,z) + \log p_{\theta}(y) \\ &\quad + \log p(z) - \log q_{\phi}(y,z|x)] \\ &= \sum_y q_{\phi}(y|x)(-\mathcal{L}(x, y)) + \mathcal{H}(q_{\phi}(y|x)) \\ &= -\mathcal{U}(x)\end{aligned}$$

The bound on the marginal likelihood for the entire dataset is now<sup>4</sup>

$$\mathcal{J} = \sum_{(x,y) \sim \tilde{p}_l} \mathcal{L}(x, y) + \sum_{x \sim \tilde{p}_u} \mathcal{U}(x)$$

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<sup>4</sup>See Kingma et. al. (2014) equations 6-9

# Optimization Techniques

- ▶ Not using the EM algorithm, that's interesting, why
  - ▶ perform efficient joint inference that's easy to scale (pg. 7)
- ▶ Using AdaGrad

$$\nabla_{\{\theta, \phi\}} \mathbb{E}_{q_{\phi}(z|x)} [\log p_{\theta}(x|z)] = \mathbb{E}_{\mathcal{N}(\epsilon|0, I)} [\nabla_{\{\theta, \phi\}} \log p_{\theta}(x|\mu_{\theta}(x) + \sigma_{\phi}(x) \odot \epsilon)].$$

Kingma et. al. (2014) equation 11

# Optimization Algorithms

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**Algorithm 1** Learning in model M1

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```
while generativeTraining() do
   $\mathcal{D} \leftarrow \text{getRandomMiniBatch}()$ 
   $\mathbf{z}_i \sim q_\phi(\mathbf{z}_i|\mathbf{x}_i) \quad \forall \mathbf{x}_i \in \mathcal{D}$ 
   $\mathcal{J} \leftarrow \sum_n \mathcal{J}(\mathbf{x}_i)$ 
   $(\mathbf{g}_\theta, \mathbf{g}_\phi) \leftarrow (\frac{\partial \mathcal{J}}{\partial \theta}, \frac{\partial \mathcal{J}}{\partial \phi})$ 
   $(\theta, \phi) \leftarrow (\theta, \phi) + \Gamma(\mathbf{g}_\theta, \mathbf{g}_\phi)$ 
end while
while discriminativeTraining() do
   $\mathcal{D} \leftarrow \text{getLabeledRandomMiniBatch}()$ 
   $\mathbf{z}_i \sim q_\phi(\mathbf{z}_i|\mathbf{x}_i) \quad \forall \{\mathbf{x}_i, y_i\} \in \mathcal{D}$ 
   $\text{trainClassifier}(\{\mathbf{z}_i, y_i\})$ 
end while
```

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**Algorithm 2** Learning in model M2

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```
while training() do
   $\mathcal{D} \leftarrow \text{getRandomMiniBatch}()$ 
   $y_i \sim q_\phi(y_i|\mathbf{x}_i) \quad \forall \{\mathbf{x}_i, y_i\} \notin \mathcal{O}$ 
   $\mathbf{z}_i \sim q_\phi(\mathbf{z}_i|y_i, \mathbf{x}_i)$ 
   $\mathcal{J}^\alpha \leftarrow \text{eq. (9)}$ 
   $(\mathbf{g}_\theta, \mathbf{g}_\phi) \leftarrow (\frac{\partial \mathcal{L}^\alpha}{\partial \theta}, \frac{\partial \mathcal{L}^\alpha}{\partial \phi})$ 
   $(\theta, \phi) \leftarrow (\theta, \phi) + \Gamma(\mathbf{g}_\theta, \mathbf{g}_\phi)$ 
end while
```

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# Results: Benchmark Classification

Table 1: Benchmark results of semi-supervised classification on MNIST with few labels.

$N$	NN	CNN	TSVM	CAE	MTC	AtlasRBF	M1+TSVM	M2	M1+M2
100	25.81	22.98	16.81	13.47	12.03	8.10 ( $\pm 0.95$ )	11.82 ( $\pm 0.25$ )	11.97 ( $\pm 1.71$ )	<b>3.33</b> ( $\pm 0.14$ )
600	11.44	7.68	6.16	6.3	5.13	–	5.72 ( $\pm 0.049$ )	4.94 ( $\pm 0.13$ )	<b>2.59</b> ( $\pm 0.05$ )
1000	10.7	6.45	5.38	4.77	3.64	3.68 ( $\pm 0.12$ )	4.24 ( $\pm 0.07$ )	3.60 ( $\pm 0.56$ )	<b>2.40</b> ( $\pm 0.02$ )
3000	6.04	3.35	3.45	3.22	2.57	–	3.49 ( $\pm 0.04$ )	3.92 ( $\pm 0.63$ )	<b>2.18</b> ( $\pm 0.04$ )



# Results: Image Classification

Table 2: Semi-supervised classification on the SVHN dataset with 1000 labels.

KNN	TSVM	M1+KNN	M1+TSVM	M1+M2
77.93 ( $\pm 0.08$ )	66.55 ( $\pm 0.10$ )	65.63 ( $\pm 0.15$ )	54.33 ( $\pm 0.11$ )	<b>36.02</b> ( $\pm 0.10$ )

Table 3: Semi-supervised classification on the NORB dataset with 1000 labels.

KNN	TSVM	M1+KNN	M1+TSVM
78.71 ( $\pm 0.02$ )	26.00 ( $\pm 0.06$ )	65.39 ( $\pm 0.09$ )	<b>18.79</b> ( $\pm 0.05$ )

# Discussion

You can use this model for a few things  
TODO: just summarize their discussion

**Any questions? Thanks!**