General

Name Inductrix
Model Image INDUCT.jpg

Throttle Source: THR Trim idle only: No Warning: No Reversed: No

Trims Step: Fine Display: Never Extended: No

Center Beep None **Switch** None

Warnings

Pot Warnings Mode: OFF

Other Extended Limits: No Display Checklist: No Global Functions:

Yes

| Timers | Time | Switch | Countdo | wn Min.call | Persist | |
|--------|----------|--------|---------|-------------|---------|--|
| Tmr1 | 00:03:15 | L04 | Voice | Yes | OFF | |
| Tmr2 | 00:00:00 | OFF | Silent | No | OFF | |
| Tmr3 | 00:00:00 | OFF | Silent | No | OFF | |

Modules

Internal Radio Protocol: OFF

System

External Radio Protocol: DIY Multiprotocol Module Channels: 1-6 Receiver: 7

Module Radio protocol: DSM Subtype: DSM2 1F Option value: 0

Trainer port Mode: Master/Jack

Flight modes

| Flight mode | Switc | hF.In | F.Ou | ıt Trml | R TrmE | TrmT | Trm/ | Trm5 | 5 Trm6 |
|-------------|-------|-------|-------|---------|--------|-------|-------|-------|--------|
| FM0 | | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| FM1 | | 0 | 0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM2 | | 0 | 0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM3 | | 0 | 0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM4 | | 0 | 0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM5 | | 0 | 0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM6 | | 0 | 0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM7 | | 0 | 0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM8 | | 0 | 0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| Global vars | GV1 | GV2 | GV3 | GV4 | GV5 | GV6 | GV7 | GV8 | GV9 |
| Name | | | | | | | | | |
| Unit | | | | | | | | | |
| Prec | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| Min | -1024 | -1024 | -1024 | -1024 | -1024 | -1024 | -1024 | -1024 | -1024 |
| Max | 1024 | 1024 | 1024 | 1024 | 1024 | 1024 | 1024 | 1024 | 1024 |
| Popup | N | N | N | N | N | N | N | N | N |
| Flight mode | | | | | | | | | |
| FM0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| FM1 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| | | | | | | | | | |

| FM2 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
|--|---|--|--|--|---|------------------|--------------------------|--|--------------------|
| FM3 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM4 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM5 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM6 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM7 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| FM8 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 | FM0 |
| Inputs | | | | | | | | | |
| I1:Thr | Th | r Weigl | ht(+10 | 0%) | | | | | |
| I2:Ail | Ail ' | Weight | (+100 | %) | | | | | |
| I3:Ele | Ele | Weigh | t(+100 |)%) | | | | | |
| I4:Rud | Ru | d Weig | ht(+10 | 00%) | | | | | |
| Mixers | | | | | | | | | |
| CH1:Rol | | | ght(+1 | - | | | | | |
| CH2:Pit | I3: | Ele We | eight(+ | 100%) | | | | | |
| CH3:Thr | I1: | Thr W | eight(+ | -100%) |) | | | | |
| CH4:Yaw | I4:Rud Weight(+100%) | | | | | | | | |
| CH5:Arm | MAX Weight(+100%) Świtch(!L04) [disarm] | | | | | | | | |
| | | | | 100%) | Switch(| (L04) [| arm] | | |
| CH6:Fmd | SE | Weigh | t(+100 | <u>(%)</u> | | | | | |
| Outputs | | | | | | | | | |
| о ш ср ш со | | | | | | | | | |
| Channel | Subtr | im Mi | n l | Max | Dire | ect C | urve | PPM | Linear |
| | Subtr -0.3% | | | Max +100.0 | | | urve | PPM 1500 | Linear N |
| Channel CH1:Rol CH2:Pit | -0.3% -2.3% | -10 -10 | 0.0% · | +100.0 +100.0 | % NOR % NOR | \ \ | urve | 1500 1500 | |
| Channel CH1:Rol | -0.3% | -10 -10 6 -10 | 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 | % NOR % NOR % NOR | \ \ \ | urve | 1500 1500 1500 | N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw | -0.3% -2.3% +0.0% +0.0% | -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 +100.0 | % NOR % NOR % NOR % NOR | \ \ \ | urve | 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr | -0.3% -2.3% +0.0% +0.0% +0.0% | -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 | % NOR % NOR % NOR % NOR | \ \ \ | urve | 1500 1500 1500 1500 1500 | N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw | -0.3% -2.3% +0.0% +0.0% | -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 +100.0 | % NOR % NOR % NOR % NOR % NOR | \ \ \ \ | urve | 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm | -0.3% -2.3% +0.0% +0.0% +0.0% | -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 +100.0 +100.0 | % NOR % NOR % NOR % NOR % NOR | \ \ \ \ | urve | 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw | -0.3% -2.3% +0.0% +0.0% +0.0% +0.0% | -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 +100.0 +100.0 | % NOR % NOR % NOR % NOR % NOR % NOR | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 | -0.3% -2.3% +0.0% +0.0% +0.0% +0.0% (Edge I1:The | -10 -10 -6 -10 -10 -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 +100.0 +100.0 +100.0 | % NOR % NOR % NOR % NOR % NOR % NOR | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 L3 | -0.3% -2.3% +0.0% +0.0% +0.0% +0.0% (Edge I1:The | -10 -10 -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 +100.0 +100.0 +100.0 | % NOR % NOR % NOR % NOR % NOR % NOR | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 L3 L4 | -0.3% -2.3% +0.0% +0.0% +0.0% +0.0% (Edge I1:The L01 Al Sticky | -10 -10 -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 +100.0 +100.0 -100.0 | % NOR % NOR % NOR % NOR % NOR MNOR | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 L3 | -0.3% -2.3% +0.0% +0.0% +0.0% +0.0% (Edge I1:The L01 Al Sticky | -10 -10 -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 +100.0 +100.0 +100.0 | % NOR % NOR % NOR % NOR % NOR MNOR | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 L3 L4 L5 Special Fu | -0.3% -2.3% +0.0% +0.0% +0.0% (Edge I1:The L01 Al Stickye (L02 | -10 -10 -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% 0.0% | +100.0 +100.0 +100.0 +100.0 +100.0 -100.0 | % NOR % NOR % NOR % NOR % NOR MNOR | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 L3 L4 L5 Special Full SF1 | -0.3% -2.3% +0.0% +0.0% +0.0% (Edge I1:The L01 Al Stickye (L02 nctio | -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% (0.6:0 E | +100.0 +100.0 +100.0 +100.0 +100.0 -100.0 -100.0 | % NOR % NOR % NOR % NOR % NOR AND SF | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 L3 L4 L5 Special Full SF1 SF2 | -0.3% -2.3% +0.0% +0.0% +0.0% (Edge I1:The L01 Al Stickye (L02 nctio !L04 - L04 - | -10 -10 -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% 0.0% F (c) | +100.0 +100.0 +100.0 +100.0 +100.0 -6])) A | % NOR % NOR % NOR % NOR % NOR AND SF | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 L3 L4 L5 Special Full SF1 SF2 SF3 | -0.3% -2.3% +0.0% +0.0% +0.0% +0.0% (Edge I1:Thi L01 Al Stickyi (L02 nctio | -10 -10 -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% 0.0% F (rack (erack (erack (a | +100.0 +100.0 +100.0 +100.0 +100.0 (A) SH (A) SH (A | % NOR % NOR % NOR % NOR % NOR AND SF | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 L3 L4 L5 Special Fu SF1 SF2 SF3 SF4 | -0.3% -2.3% +0.0% +0.0% +0.0% +0.0% itche (Edge I1:Thi L01 Al Sticky((L02 nctio !L04 - SE↑ - SE I | -10 -10 -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% 0.0% (a.6:0) F rack (erack (erack (arack (hirack (hirack (hirack)) | +100.0 +100.0 +100.0 +100.0 +100.0 -100.0 -6])) A | % NOR % NOR % NOR % NOR % NOR AND SF | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 L3 L4 L5 Special Ful SF1 SF2 SF3 SF4 SF5 | -0.3% -2.3% +0.0% +0.0% +0.0% +0.0% (Edge I1:Thi L01 Al Stickyi (L02 nctio !L04 - L04 - SE↑ - SE I SE↓ - | -10 -10 -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% 0.0% F (ack (erack (arack (hirack (arack (arac | +100.0 +100.0 +100.0 +100.0 +100.0 +100.0 .6])) A | % NOR % NOR % NOR % NOR % NOR AND SF | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |
| Channel CH1:Rol CH2:Pit CH3:Thr CH4:Yaw CH5:Arm CH6:Fmd Logical Sw L1 L2 L3 L4 L5 Special Fu SF1 SF2 SF3 SF4 | -0.3% -2.3% +0.0% +0.0% +0.0% +0.0% (Edge I1:Thi L01 Al Stickyi (L02 nctio !L04 - L04 - SE↑ - SE I SE↓ - | -10 -10 -10 -10 -10 -10 -10 -10 -10 -10 | 0.0% 0.0% 0.0% 0.0% 0.0% 0.0% (a.6:0) F rack (erack (erack (arack (hirack (hirack (hirack)) | +100.0 +100.0 +100.0 +100.0 +100.0 +100.0 .6])) A | % NOR % NOR % NOR % NOR % NOR AND SF | \\\\\\\\\\\ | | 1500 1500 1500 1500 1500 1500 | N N N N |

| SF7 | L05 - Reset (Timer1) | | | | |
|---------------|---|--|--|--|--|
| Telemetry | | | | | |
| Protocol | FrSky S.PORT | | | | |
| RSSI Alarms | Low: < 45; Critical: < 42; Telemetry audio: Enable | | | | |
| Altimetry | Vario source: | | | | |
| | Vario limits > Sink max: -10; Sink min: -0.5; Climb in: 0.5; Climb max: 10; Center silent: No | | | | |
| Top Bar | Volts source: None; Altitude source: None | | | | |
| Multi sensors | Enable | | | | |